

# From Separation Logic to Staged Logic and Beyond

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# Research Done

1990-1999 : Program Transformation

2000-2006 : Advanced Type Systems

2007-2019 : SLEEK/HIP (Separation Logic)

2020- Temporal Effects/Incorrectness Logic

Staged Logic for HO-Functions

Continuations (Alge Effects + Shift/Reset)

Concurrency Verification (re-looking)

Type Safety via Hoare Logic (in progress)

# Research Highlights

Data structures verification via Separation Logic (VMCAI07)

Pre/Post Specification for Loops (in HIP/SLEEK)

Termination and Non-Termination Specification (ICFEM15, PLDI15)

Immutability Specification (OOPSLA11)

Specification Inference (ASIAN06, SAC10, CAV14, APLAS13)

Concurrency Verification (PEPM15, TASE23)

Staged Logics for Higher-Order Functions (FM24, ICFP24)

Hoare Logic for Type-Safety and Race Freedom (draft paper)

Hoare Logic for Bug Finding (in progress)

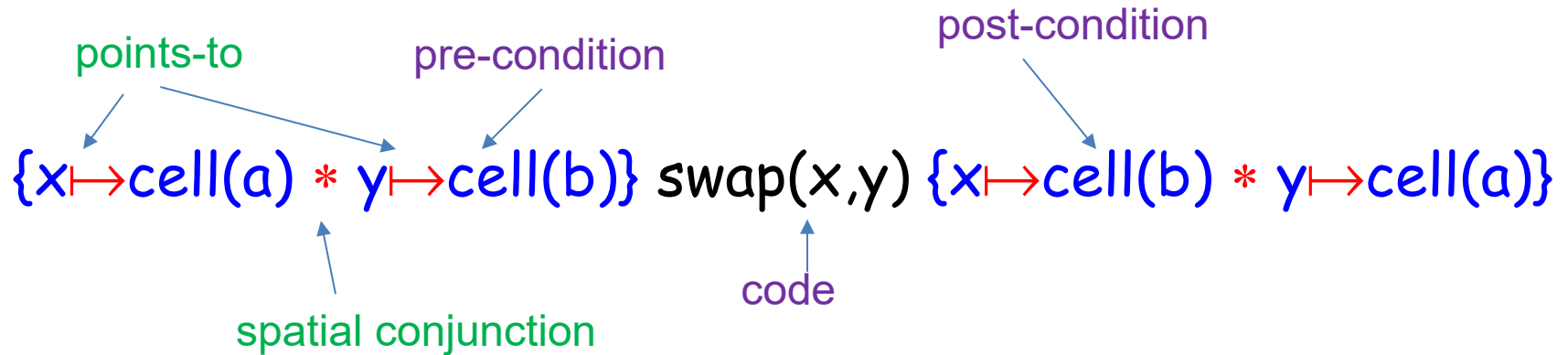
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# Verification via Separation Logic

VMCAI07

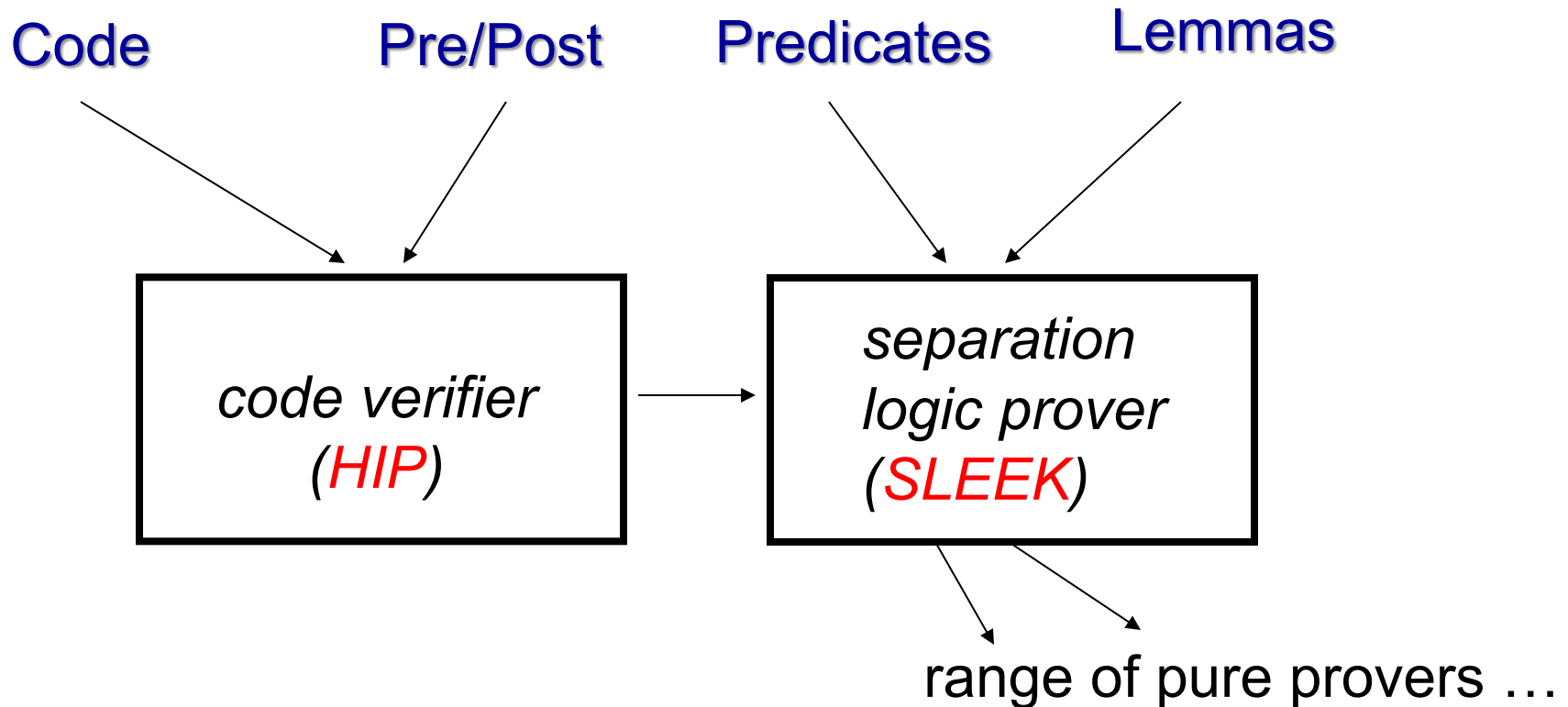
# Separation Logic Basics

data cell { int val }



$\{x \mapsto \text{cell}(a) \wedge x = y\} \text{ swap}(x, y) \{x \mapsto \text{cell}(a) \wedge x = y\}$

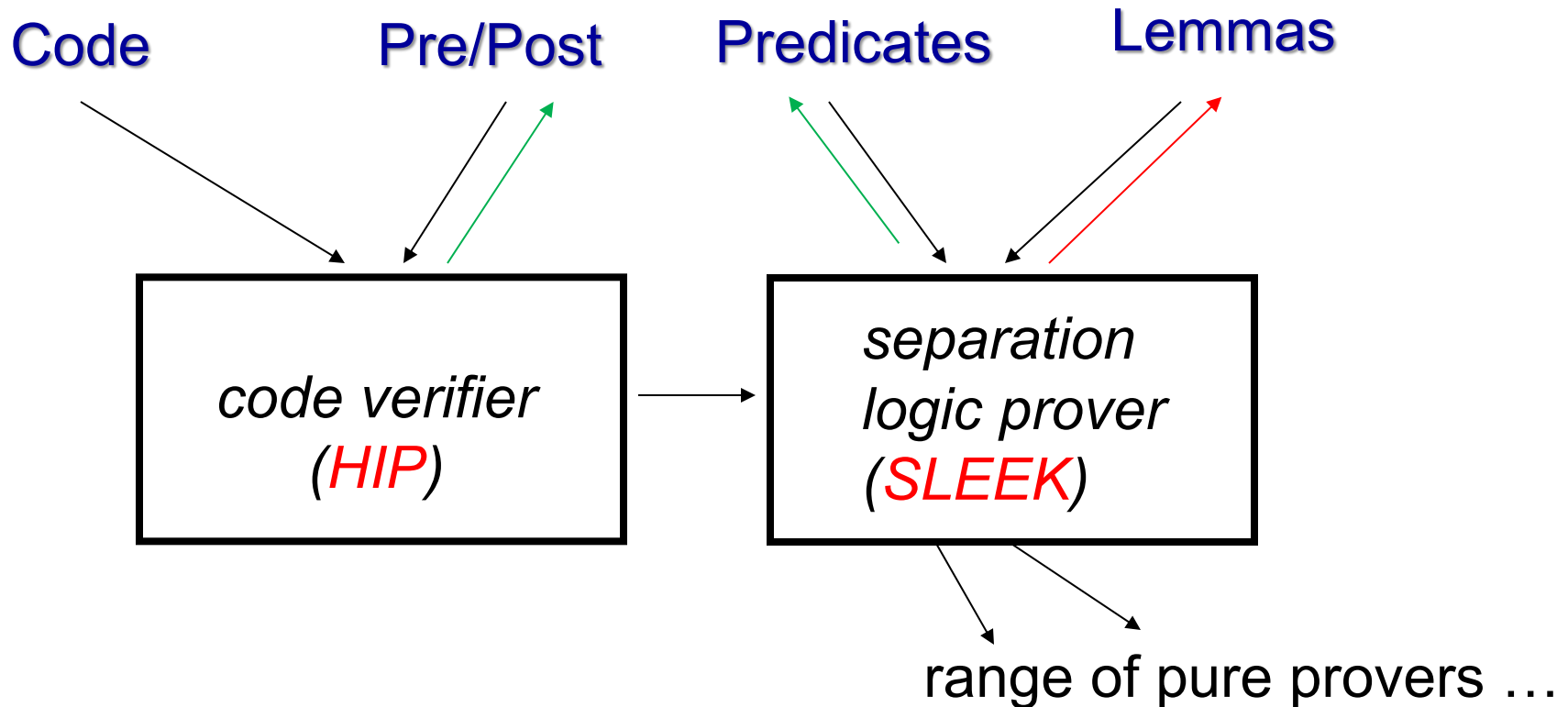
# Verification System



*Omega, MONA, Isabelle, Coq, SMT, Redlog, MiniSAT, Mathematica*

# Inference System

[CAV14, APLAS13]  
[ASIAN06, CAV11]



*Omega, MONA, Isabelle, Coq, SMT, Redlog, MiniSAT, Mathematica*

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Abstraction via

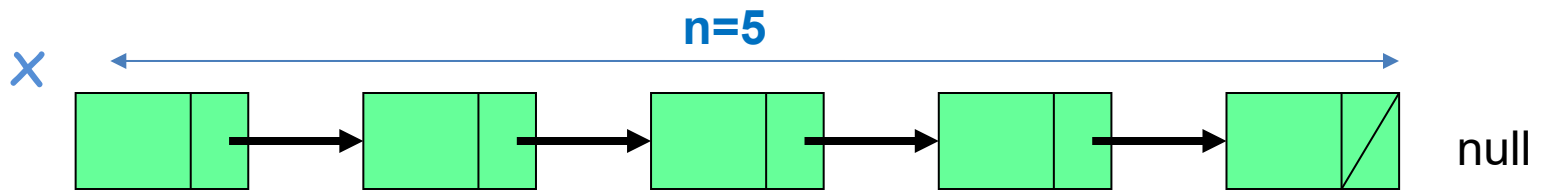
# Inductive Predicates



# Predicate : Linked-List with Size

data node { int val; node next }

Example of Singly Linked List :  $ll(x,n)$



$$ll(x,n) \equiv x = \text{null} \wedge n = 0$$

$$\vee \exists q . x \mapsto \text{node}(\_,q) * ll(q,n-1)$$

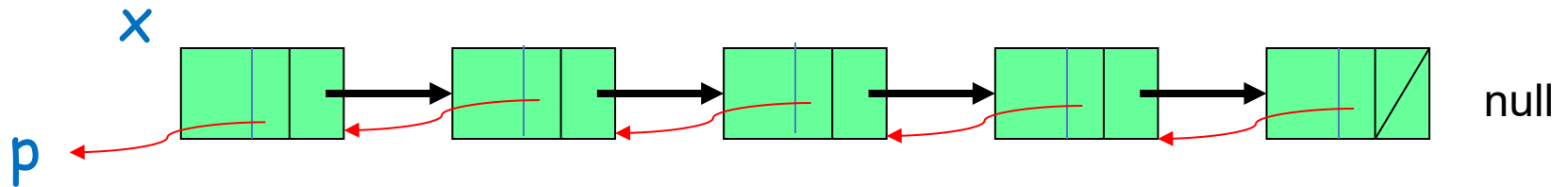
$$\text{inv } n \geq 0 ;$$

Flexible abstraction – captures just **acyclic** shape and **length** of list here

# Doubly Linked-List

data node2 { int val; node2 prev, node2 next }

Example of Doubly Linked List :  $dll(x,p)$



$dll(x,p) \equiv x = \text{null}$

$\vee \exists q . x \mapsto \text{node2}(\_,p,q) * dll(q,x)$

Handles must-aliasing well ..

# AVL Tree

data node2 { int val; node2 prev, node2 next }

$\text{avl}(x, h) \equiv x = \text{null} \wedge h = 0$

$\vee \exists p, q . x \mapsto \text{node2}(\_, p, q) * \text{avl}(p, h_1) * \text{avl}(q, h_2)$   
 $\wedge h = 1 + \max(h_1, h_2) \wedge -1 \leq h_1 - h_2 \leq 1$

$\text{inv } h \geq 0$

Above captures height and near-balancing.

How can sortedness be captured ?

# AVL Tree (non-empty)

Sortedness can be captured with

- (i) two extra parameters, and
- (ii) use of non-empty AVL trees

$$\begin{aligned} \text{avl}(x, h, mn, mx) &\equiv x \mapsto \text{node2}(mn, \text{null}, \text{null}) \wedge h=1 \wedge mn=mx \\ &\vee \exists p, q . x \mapsto \text{node2}(mx, p, \text{null}) * \text{avl}(p, h_1, mn, mx_1) \\ &\quad \wedge h=1+h_1 \wedge mx_1 \leq mx \\ &\vee \exists p, q . x \mapsto \text{node2}(mn, \text{null}, q) * \text{avl}(q, h_2, mn_2, mx) \\ &\quad \wedge h=1+h_2 \wedge mn \leq mn_2 \\ &\vee \exists p, q . x \mapsto \text{node2}(v, p, q) * \text{avl}(p, h_1, mn, mx_1) \\ &\quad * \text{avl}(q, h_2, mn_2, mx) \wedge h=1+\max(h_1, h_2) \wedge mx_1 \leq v \leq mn_2 \\ \text{inv } h &\geq 1 \wedge mn \leq mx \end{aligned}$$

# AVL Tree (possibly empty)

Alternatively, we can more succinctly capture it using fictional min and max values

- (i) fictional min and max values;
- (ii) trees with a possibly null scenario.

$$\text{avl}(x, h, mn, mx) \equiv \dots \boxed{x = \text{null} \wedge h = 0 \wedge mn = \infty \wedge mx = -\infty}$$

$$\begin{aligned} &\vee \exists p, q . x \mapsto \text{node2}(v, p, q) * \text{avl}(p, h_1, mn_1, mx_1) \\ &* \text{avl}(q, h_2, mn_2, mx_2) \wedge h = 1 + \max(h_1, h_2) \wedge mx_1 \leq v \leq mn_2 \\ &\quad \wedge mn = \min(mn_1, v) \wedge mx = \max(mx_2, v) \\ &\text{inv } h \geq 0 \wedge (h > 0 \rightarrow \min \leq \max) \end{aligned}$$

Asankhaya Sharma, Shengyi Wang, Andreea Costea, Aquinas Hobor, Wei-Ngan Chin:  
**Certified Reasoning with Infinity.** FM 2015: 496-513

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# Modular Verification

# Code - A Function and its Loop

```
int length(node xs)
```

```
{ int n=0;  
  while (xs!=null)
```

```
  { xs = xs.next;  
    n = n+1 };  
  return n;  
}
```

# Adding Pre/Post Specs

```
int length(node xs)
```

*per-method spec*

```
// req  ll<xs,m>
```

```
// ens[r] ll<xs,m>  $\wedge$  r=m;
```

```
{ int n=0;
```

```
  while (xs!=null)
```

*pre/post for loops*

```
    // req ll<xs,m>
```

**xs, n**= original values at pre

```
    // ens ll<xs,m>  $\wedge$  xs'=null  $\wedge$  n'=n+m;
```

**xs', n'**= latest values

```
    { xs = xs.next;
```

```
      n = n+1 };
```

```
    return n;
```

```
}
```

## Other Improvements?

- Immutability annotation (OOPSLA11)
- Termination/Non-Termination (PLDI15)
- Structured Specification (FM11)



# Immutable Borrow Annotation

```
int length(node xs)
// req  ll<xs,m>@l
// ens[r] r=m;
{ int n=0;
  while (xs!=null)
    // req ll<xs,m>@l
    // ens xs'=null  $\wedge$  n'=n+m;
    { xs = xs.next;
      n = n+1 };
  return n;
}
```

@l to indicate immutable  
(read-only) borrow

## Benefit

- Precise and Concise
- Functional Correctness

Cristina David, Wei-Ngan Chin:

Immutable specifications for more concise and precise verification. OOPSLA 2011: 359-374

# Termination/Non-Termination

```
int length(node xs)
```

```
  // req   $ll<xs,m>@l \wedge \text{Term}[]$ 
```

```
  // ens[r]   $r=m$ ;
```

```
  // req   $clist<xs>@l \wedge \text{Loop}$ 
```

```
  // ens[r]   $\text{false}$ ;
```

```
{ int n=0;
```

```
  while (xs!=null)
```

```
    // req  $ll<xs,m>@l \wedge \text{Term}[m]$ 
```

```
    // ens  $xs'=null \wedge n'=n+m$ ;
```

```
    // req  $clist<xs>@l \wedge \text{Loop}$ 
```

```
    // ens   $\text{false}$ ;
```

```
    { xs = xs.next; n = n+1 };
```

```
    return n;
```

```
}
```

**Term[..]** for termination proving


**Loop** for non-termination proving

**MayLoop** for unknown status [PLDI15]

*structured spec [FM11]*

Ton Chanh Le, Shengchao Qin , Wei-Ngan Chin:

**Termination and non-termination specification inference.** PLDI 2015: 489-498

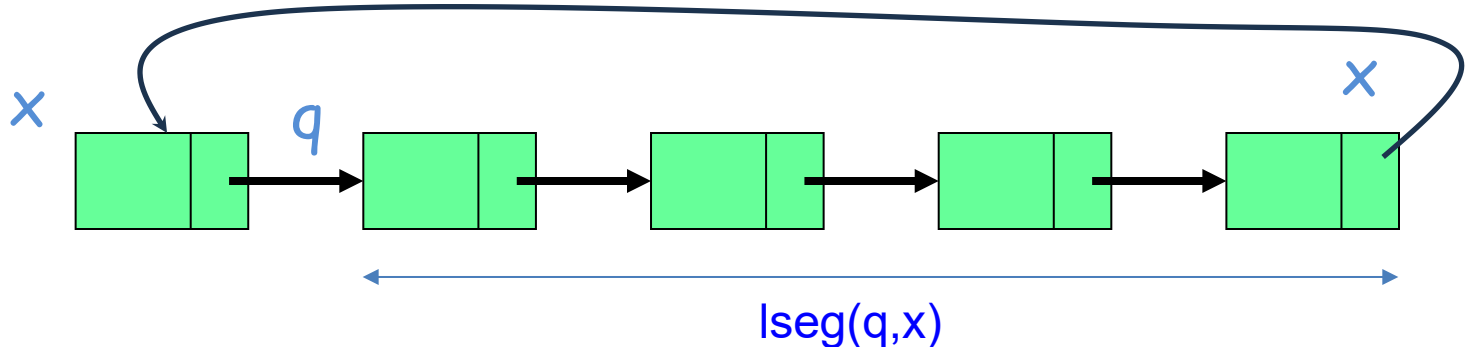
Cristian Gherghina, Cristina David, Shengchao Qin , Wei-Ngan Chin:

**Structured Specifications for Better Verification of Heap-Manipulating Programs.** FM 2011: 386-401

# Circular List

data node { int val; node next }

Example of Circular List :  $\text{clist}(x)$



$\text{clist}(x) \equiv x \mapsto \text{node}(\_,q) * \text{lseg}(q,x) \text{ inv } x \neq \text{null} ;$

$\text{lseg}(x,p) \equiv x=p \vee x \mapsto \text{node}(\_,q) * \text{lseg}(q,p) \wedge x \neq p$

**lemma**  $\text{lseg}(x,q) * q \mapsto \text{node}(\_,x) \Rightarrow \text{clist}(q)$

# Summary of SLEEK/HIP/Heifer

- High degree of automation
- Proof search through lemmas, multi-specs
- Leverage on existing pure provers
- Support for Inference (CAV14, APLAS13)
- Support for Concurrency Reasoning (PEPM15,...)
- Support for Higher-Order Functions (FM24,...)
- Hoare Logic for Bug Confirmation (on-going)
- Hoare Logic for Type Safety (on-going)

# Higher-Order Functions [FM24]

## Staged Specification Logic for Verifying Higher-Order Imperative Programs

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**Abstract.** Higher-order functions and imperative states are language features supported by many mainstream languages. Their combination is expressive and useful, but complicates specification and reasoning, due to the use of yet-to-be-instantiated function parameters. One inherent limitation of existing specification mechanisms is its reliance on *only two stages* : an initial stage to denote the precondition at the start of the method and a final stage to capture the postcondition. Such two-stage specifications force *abstract properties* to be imposed on unknown function parameters, leading to less precise specifications for higher-order methods. To overcome this limitation, we introduce a novel extension to Hoare logic that supports *multiple stages* for a call-by-value higher-order language with ML-like local references. Multiple stages allow the behavior of unknown function-type parameters to be captured abstractly as uninterpreted relations; and can also model the repetitive behavior of each recursion as a separate stage. In this paper, we define our staged logic with its semantics, prove its soundness and develop a new automated higher-order verifier, called Heifer, for a core ML-like language.

*Effectful higher-order programs*  
*Concurrency reasoning potential*

# What is Separation Logic?

$$D ::= \text{emp} \mid x \mapsto t(..) \mid D_1 * D_2 \mid D_1 \vee D_2 \\ \mid \text{pred}(..) \\ \mid D \wedge \text{pure}$$

## Pre/Post Spec

$$\text{req } D_{\text{pre}} \quad \text{ens}[r] D_{\text{post}}$$

## What is Staged Logic?

$$S ::= \text{req } D \mid \text{ens}[r] D \mid S_1 ; S_2 \mid f(v^*) \mid S_1 \vee S_2 \\ \mid S_1 \wedge S_2 \text{ // multi pre/post} \\ \mid S_1 * S_2 \mid \dots \text{ // for concurrency}$$

# Staged Logic for Methods

update(x,n) =  $x := !x + n$

update  $::: \text{req } x \mapsto a ; \text{ens}[r] x \mapsto a + n / \backslash r = ()$

cas(x,v,n)

cas  $::: \text{req } x \mapsto a ; \text{ens}[r] x \mapsto n \wedge r \wedge a = v \vee x \mapsto a \wedge \neg r \wedge a \neq v$

*points-to without (cell) type constructor*



## How about higher-order functions?

compose(g,f,x) =  $g(f(x))$

compose  $::: \text{ens}[r] \exists a . f(x,a); g(a,r)$

# Hoare Rules with Staged Logics

$$\begin{array}{c}
 \frac{\Phi_1 \sqsubseteq \Phi_3 \quad \{ \Phi_3 \} e \{ \Phi_4 \} \quad \Phi_4 \sqsubseteq \Phi_2}{\{ \Phi_1 \} e \{ \Phi_2 \}} \text{Conseq} \qquad \frac{\{ \Phi_1 \} e \{ \Phi_2 \}}{\{ \Phi; \Phi_1 \} e \{ \Phi; \Phi_2 \}} \text{Frame} \\
 \\
 \frac{}{\{ \Phi \} x \{ \Phi; \mathbf{ens}[x] \mathit{emp} \}} \text{Var} \qquad \frac{\text{fresh } r \quad v ::= c \mid \mathit{nil} \mid x_1 :: x_2}{\{ \Phi \} v \{ \Phi; \exists r. \mathbf{ens}[r] r = v \}} \text{Val} \\
 \\
 \frac{\text{fresh } r}{\{ \Phi \} \mathit{ref } x \{ \Phi; \exists r. \mathbf{ens}[r] r \mapsto x \}} \text{Ref} \\
 \\
 \frac{\text{fresh } a, \mathit{res}}{\{ \Phi \} !x \{ \Phi; \exists a, \mathit{res}. \mathbf{req } x \mapsto a; \mathbf{ens}[\mathit{res}] x \mapsto a \wedge \mathit{res} = a \}} \text{Deref} \\
 \\
 \frac{}{\{ \Phi \} x_1 := x_2 \{ \Phi; \mathbf{req } x_1 \mapsto \_; \mathbf{ens}[\_] x_1 \mapsto x_2 \}} \text{Assign} \\
 \\
 \frac{\{ \Phi; \mathbf{ens}[\_] x \} e_1 \{ \Phi_1 \} \quad \{ \Phi; \mathbf{ens}[\_] \neg x \} e_2 \{ \Phi_2 \}}{\{ \Phi \} \text{if } x \text{ then } e_1 \text{ else } e_2 \{ \Phi_1 \vee \Phi_2 \}} \text{If} \\
 \\
 \frac{\text{fresh } x \quad \{ \Phi \} e_1 \{ \exists r. \Phi_1[r] \} \quad \{ [r := x] \Phi_1 \} e_2 \{ \Phi_2 \}}{\{ \Phi \} \text{let } x = e_1 \text{ in } e_2 \{ \exists x. \Phi_2 \}} \text{Let} \\
 \\
 \frac{\text{fresh } \mathit{res} \quad \{ \mathbf{ens}[\_] \mathit{Pure}(\Phi) \} e \{ \exists r'. \Phi_p[r'] \} \quad ([r' := r] \Phi_p) \sqsubseteq \Phi_s}{\{ \Phi \} \mathit{fun } (x^*) \exists r. \Phi_s[r] \rightarrow e \{ \Phi; \exists \mathit{res}. \mathbf{ens}[\mathit{res}] \mathit{res} = \lambda (x^*, r) \rightarrow \Phi_s \}} \text{Lambda} \\
 \\
 \frac{\text{fresh } r}{\{ \Phi \} f(x^*) \{ \Phi; \exists r. f(x^*, r) \}} \text{Call} \qquad \frac{}{\{ \Phi \} \mathit{assert } D \{ \Phi; \mathbf{req } D @ R \}} \text{Assert}
 \end{array}$$



# Hoare Proof (1) for foo

$\text{foo}(x) = \text{let } () = x := !x + 1 \text{ in } x := !x + 2$

$\text{foo}(x) ::: \text{req } x \mapsto a ; \text{ens}[r] x \mapsto a + 3$

---

$\{\text{ens emp}\} x := !x + 1 \{\text{ens emp}; \text{req } x \mapsto a; \text{ens } x \mapsto a + 1\}$  [Call]

---

$\{\text{ens emp}\} x := !x + 1 \{\text{req } x \mapsto a; \text{ens } x \mapsto a + 1\}$  [Conseq]

---

$\{\text{req } x \mapsto a; \text{ens } x \mapsto a + 1\} x := !x + 2 \{..\}; \text{req } x \mapsto c; \text{ens } x \mapsto c + 2\}$  [Call]

---

$\{\text{req } x \mapsto a; \text{ens } x \mapsto a + 1\} x := !x + 2 \{\text{req } x \mapsto a; \text{ens } x \mapsto a + 3\}$  [Conseq]

---

$\{\text{ens emp}\} \text{let } () = x := !x + 1 \text{ in } x := !x + 2 \{\text{req } x \mapsto a; x \mapsto a + 3\}$  [Let]

---

# Hoare Proof (2) for foo

$\text{foo}(x) = \text{let } () = x := !x + 1 \text{ in } x := !x + 2$

$\text{foo}(x) ::: \text{req } x \mapsto a ; \text{ens}[r] x \mapsto a + 3$

$\{ \text{ens } x \mapsto a \} x := !x + 1 \{ \text{ens } x \mapsto a ; \text{req } x \mapsto b ; \text{ens } x \mapsto b + 1 \}$	[Call]
$\{ \text{ens } x \mapsto a \} x := !x + 1 \{ \text{ens } x \mapsto a + 1 \}$	[Conseq]
$\{ \text{ens } x \mapsto a + 1 \} x := !x + 2 \{ \text{ens } x \mapsto a + 1 ; \text{req } x \mapsto c ; \text{ens } x \mapsto c + 2 \}$	[Call]
$\{ \text{ens } x \mapsto a + 1 \} x := !x + 2 \{ \text{ens } x \mapsto a + 3 \}$	[Conseq]
$\{ \text{ens } x \mapsto a \} \text{let } () = x := !x + 1 \text{ in } x := !x + 2 \{ \text{ens } x \mapsto a + 3 \}$	[Let]

# Hoare Proof for compose

$\text{compose}(g,f,x) = \text{let } y = f(x) \text{ in } g(y)$

$\text{compose}(g,f,x) ::= \exists y. f(x,y);g(y,r)$

---

$\{ \text{ens emp} \} f(x) \{ \text{ens emp}; f(x,r_1) \}$  [Call]

---

$\{ \text{ens emp} \} f(x) \{ f(x,r_1) \}$  [Conseq]

---

$\{ f(x,y) \} g(y) \{ f(x,y);g(y,r) \}$  [Call]

---

$\{ \text{ens emp} \} \text{let } y = f(x) \text{ in } g(y) \{ \exists y. f(x,y);g(y,r) \}$  [Let]

---

# Summarizing Higher-Order Calls

$\text{compose}(g, f, x) = g(f(x))$

$\text{compose} :: \text{ens}[r] \exists a . f(x, a); g(a, r)$

$\text{compose}(\backslash() . x := !x + 2, \backslash x . x := !x + 1, x)$

$::: (\text{req } x \mapsto a; \text{ens } x \mapsto a + 1); (\text{req } x \mapsto b; \text{ens } x \mapsto b + 2)$

$\sqsubseteq \text{req } x \mapsto a; \text{ens } b = a + 1; \text{ens } x \mapsto b + 2$

$\sqsubseteq \text{req } x \mapsto a; \text{ens } x \mapsto a + 3$

$\text{compose}(\backslash() . !x + 3, \backslash x . x := !x + 1, x)$

$::: (\text{req } x \mapsto a; \text{ens } x \mapsto a + 1); (\text{req } x \mapsto b @ I; \text{ens}[r] r = b + 3)$

$\sqsubseteq \text{req } x \mapsto a; \text{ens } x \mapsto a + 1 \wedge b = a + 1; \text{ens}[r] r = b + 3$

$\sqsubseteq \text{req } x \mapsto a; \text{ens}[r] x \mapsto a + 1 \wedge r = a + 4$

# Subsumption vs Refinement

Refinement Calculus [Back, Carrol Morgan et al]

$$\text{spec} \sqsubseteq_r \text{mixed}_1 \sqsubseteq_r \dots \sqsubseteq_r \text{mixed}_n \sqsubseteq_r \text{code}$$

Specification Subsumption

$$\text{code} :: \text{spec}_1 \sqsubseteq \text{spec}_2 \sqsubseteq \dots \sqsubseteq \text{spec}_n \sqsubseteq \text{spec}$$

# Specification Subsumption

$\text{compose}(g, f, x) = g(f(x))$

$\text{compose} ::= \text{ens}[r] \exists a . f(x, a); g(a, r)$

$\text{compose}(\backslash() . y := !y + 2, \backslash x . x := !x + 1, x)$

*free variable*

$::: \text{req } x \mapsto a; \text{ens } x \mapsto a + 1; \text{req } y \mapsto b; \text{ens } y \mapsto b + 2;$

$\sqsubseteq \text{req } x \mapsto a; \text{req } y \mapsto b; \text{ens } x \mapsto a + 1; \text{ens } y \mapsto b + 2;$

$\sqsubseteq \text{req } x \mapsto a * y \mapsto b; \text{ens } x \mapsto b + 2 * y \mapsto b + 2;$

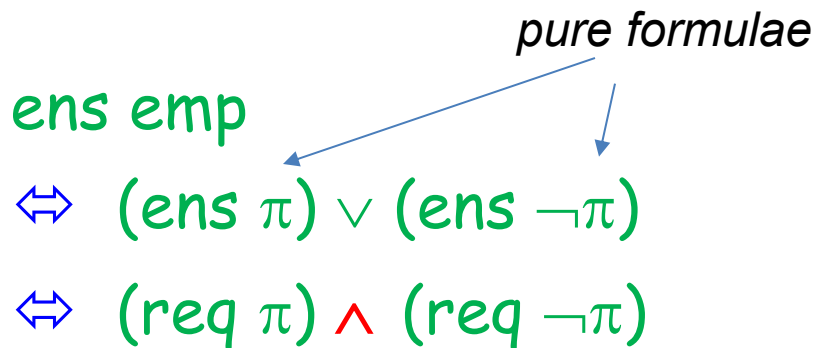
Specification **subsumption** reduce to a more abstract form.

# Specification Equivalence

Using classical reasoning with pure formulae.

$$\begin{array}{l} \text{ens emp} \\ \Leftrightarrow (\text{ens } \pi) \vee (\text{ens } \neg\pi) \\ \Leftrightarrow (\text{req } \pi) \wedge (\text{req } \neg\pi) \end{array}$$

*pure formulae*



Specification **equivalence** can be used to *simplify* to an equivalent form without losing precision.

# Specification Equivalence

$\text{compose}(g, f, x) = g(f(x))$

$\text{compose} ::= \text{ens}[r] \exists a . f(x, a); g(a, r)$

$\text{compose}(\backslash() . y := !y + 2, \backslash x . x := !x + 1, x)$

$::: (\text{req } x \mapsto a; \text{ens } x \mapsto a + 1); (\text{req } y \mapsto b; \text{ens } y \mapsto b + 2);$

$\Leftrightarrow (\text{req } x \mapsto a; \text{ens } x \mapsto a + 1); \text{req } x = y \wedge \text{req } x \neq y;$   
 $(\text{req } y \mapsto b; \text{ens } y \mapsto b + 2);$

:

$\Leftrightarrow \text{req } x \mapsto a * y \mapsto b; \text{ens } x \mapsto a + 1 * y \mapsto b + 2;$   
 $\wedge \text{req } x \mapsto a \wedge x = y; \text{ens } x \mapsto a + 3;$



# Recursive HO Methods

```
let rec foldr f a l =  
  match l with  
  | [] => a  
  | h :: t =>  
    f h (foldr f a t)
```

Our staged logic solution using **precise** spec

$$\begin{aligned} \text{foldr}(f, a, l, rr) = \\ & \mathbf{ens}[rr] \, l = [] \wedge rr = a \\ & \vee \exists x, r, l_1 . \mathbf{ens}[-] \, l = x :: l_1 ; \\ & \quad \text{foldr}(f, a, l_1, r); f(x, r, rr) \end{aligned}$$

# Recursion + Exceptions

## Problem : Handling Exceptions

```
let foldr_ex3 l = foldr (fun x r -> if x >= 0 then x+r  
                                   else raise Exc()) l 0
```

## Our Solution via Re-Summarization

$$\text{foldr\_ex3}(l, \text{res}) \sqsubseteq \mathbf{ens}[\text{res}] \text{allPos}(l) \wedge \text{sum}(l, \text{res}) \vee (\mathbf{ens}[_] \neg \text{allPos}(l); \text{Exc}())$$
$$\text{allPos}(l) = (l = []) \vee (\exists x, l_1. l = x :: l_1 \wedge \text{allPos}(l_1) \wedge x \geq 0)$$

# Problem : mutation of list

```
let foldr_ex1 l = foldr (fun x r -> let v = !x  
                                     in x := v+1; v+r) l 0
```

## Our Solution via Re-Summarization

$$\begin{aligned} \text{foldr\_ex1}(l, res) &\sqsubseteq \exists xs. \mathbf{req} \text{List}(l, xs) ; \exists ys. \\ &\quad \mathbf{ens}[res] \text{List}(l, ys) \wedge \text{mapinc}(xs, ys) \wedge \text{sum}(xs, res) \\ \text{mapinc}(xs, ys) &= (xs = [] \wedge ys = []) \vee (\exists x, xs_1, ys_1. xs = x :: xs_1 \wedge ys = (x+1) :: ys_1 \\ &\quad \wedge \text{mapinc}(xs_1, ys_1)) \\ \text{List}(l, rs) &= (\text{emp} \wedge l = []) \vee (\exists x, rs_1, l_1. x \mapsto r * \text{List}(l_1, rs_1) \wedge l = x :: l_1 \wedge rs = r :: rs_1) \end{aligned}$$

# Problem : stronger assertion

```
let foldr_ex2 l = foldr (fun x r -> assert(x+r>=0);x+r) l 0
```

## Our Solution via Re-Summarization

$$\text{foldr\_ex2}(l, res) \sqsubseteq \mathbf{req} \text{ allSPos}(l) ; \mathbf{ens}[res] \text{ sum}(l, res)$$
$$\text{allSPos}(l) = (l = []) \vee (\exists x, r, l_1. l = x :: l_1 \wedge \text{allSPos}(l_1) \wedge \text{sum}(l, r) \wedge r \geq 0)$$

# Algebraic Effects [ICFP24]

## Specification and Verification for Unrestricted Algebraic Effects and Handling

*Support for monadic coding  
and system libraries*

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Programming with user-defined effects and effect handlers has many practical use cases involving imperative effects. Additionally, it is natural and powerful to use multi-shot effect handlers for non-deterministic or probabilistic programs that allow backtracking to compute a comprehensive outcome. Existing works for verifying effect handlers are restricted in one of three ways: i) permitting multi-shot continuations under pure setting; ii) allowing heap manipulation for only one-shot continuations; or iii) allowing multi-shot continuations with heap-manipulation but under a restricted frame rule.

This work proposes a novel calculus called *Effectful Specification Logic (ESL)* to support unrestricted effect handlers, where zero-/one-/multi-shot continuations can co-exist with imperative effects and higher-order constructs. *ESL* captures behaviors in stages, and provides precise models to support invoked effects, handlers and continuations. To show its feasibility, we prototype an automated verification system for this novel specification logic, prove its soundness, report on useful case studies, and present experimental results. With this proposal, we have provided an extended specification logic that is capable of modeling arbitrary imperative higher-order programs with algebraic effects and continuation-enabled handlers.

CCS Concepts: • **Theory of computation** → **Logic and verification**; **Program specifications**.

Additional Key Words and Phrases: Multi-shot Continuations, Separation Logic, Automated Verification, Effectful Specification Logic

# User-defined Effects and Handlers

```
effect E : string

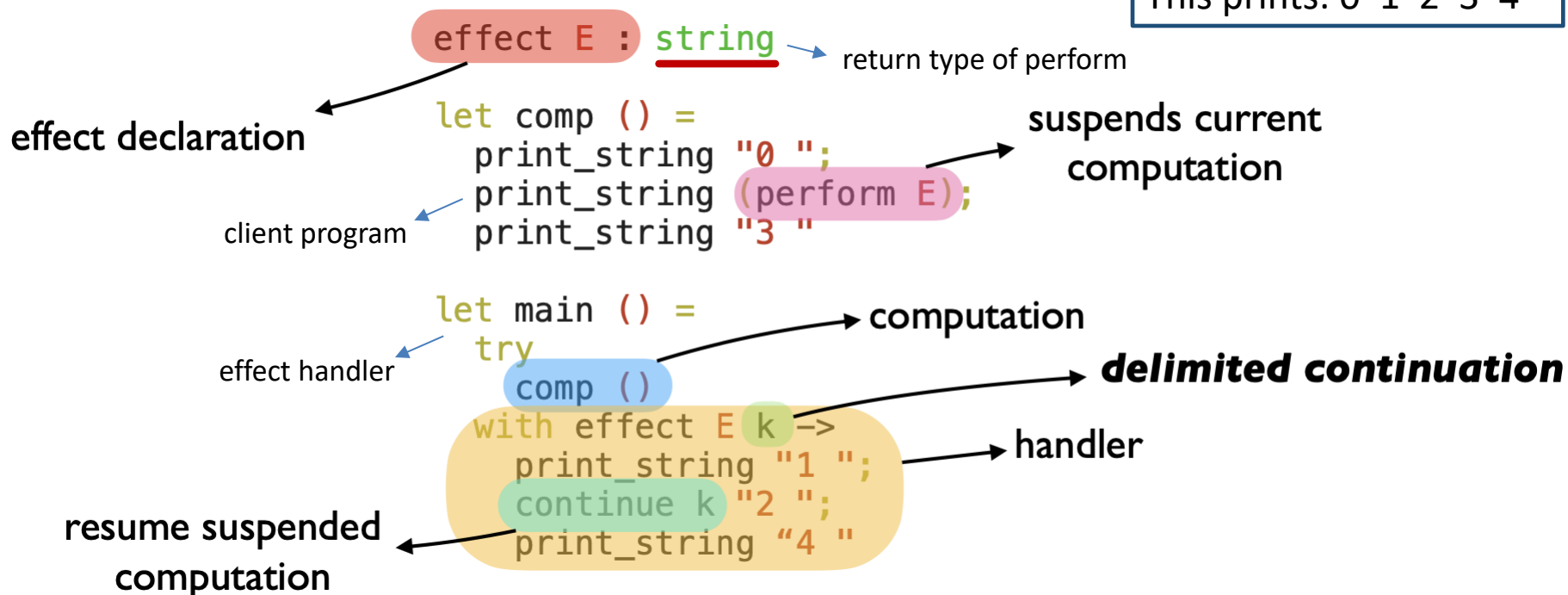
let comp () =
  print_string "0 ";
  print_string (perform E);
  print_string "3 "

let main () =
  try
    comp ()
  with effect E k ->
    print_string "1 ";
    continue k "2 ";
    print_string "4 "
```

*Example taken from “Effect Handlers in Multicore OCaml” slides by KC Sivaramakrishnan.*

# User-defined Effects and Handlers

This prints: 0 1 2 3 4



Example taken from "Effect Handlers in Multicore OCaml" slides by KC Sivaramakrishnan.

# Effects for Concurrency

```
effect Fork : (unit -> unit) -> unit
effect Yield : unit

let fork f = perform (Fork f)
let yield () = perform Yield

let run main =
  ... (* assume queue of continuations *)
  let run_next () =
    match dequeue () with
    | Some k -> continue k ()
    | None -> ()
  in
  let rec spawn f =
    match f () with
    | () -> run_next () (* value case *)
    | effect Yield k -> enqueue k; run_next ()
    | effect (Fork f) k -> enqueue k; spawn f
  in
  spawn main
```

Also, `async/await`=  
`promise`, `lock`, `condition`  
`suspense` (for concurrency  
lib cooperations

*Example taken from "Effect Handlers in Multicore OCaml" slides by KC Sivaramakrishnan.*



# Our Solution: Effectful Specification Logic (ESL)

- Fully modular per-method verification (no global assumption)
- Sequencing,  $\varphi_1 ; \varphi_2$
- Uninterpreted relations for *unhandled effects* and unknown functions,  $E(x, r)$
- Reducible *try-catch logic constructs*
- Normalization: compact each sequence of pre/post stages, via bi-abduction
- Use *re-summarization* (lemma) when handling recursive generated effects

result

input

(ESL)  $\varphi ::= \text{req } P \mid \text{ens}[r] Q \mid \varphi; \varphi \mid \varphi \vee \varphi \mid \exists x^*; \varphi \mid$   
 $E(x, r) \mid f(x^*, r) \mid \text{try}[\delta](\varphi) \text{ catch } \mathcal{H}_\Phi$

$D, P, Q ::= \sigma \wedge \pi$

$\sigma ::= \text{emp} \mid x \mapsto y \mid \sigma * \sigma \mid \dots$

# Motivating Example

```
1  effect Label: int
2
3
4  let callee () : int
5  = let x = ref 0 in
6    let ret = perform Label in
7    x := !x + 1;
8    assert (!x = 1);
9    ret
```

$\vdash \exists x . \text{ens } x \mapsto 0; \text{Label}(\text{ret}); \text{req } x \mapsto a \wedge a = 0; \text{ens}[\text{ret}] x \mapsto a + 1;$

$\Leftrightarrow \exists x . \text{ens } x \mapsto 0; \text{Label}(\text{ret}); \text{req } x \mapsto 0; \text{ens}[\text{ret}] x \mapsto 1;$

## Motivating Example (zero shot)

```
10 let zero_shot () : int
11    $\Phi_{\text{zero\_shot}(ret)} =$ 
12      $\exists x ; (x \mapsto 0 \wedge ret = -1, \text{Norm}(ret))$ 
13   = match callee () with
14     | effect Label k -> -1
```

Fig. 4. A zero-shot handler with Spec.

$::: \exists x . \text{ens}[r] x \mapsto 0 \wedge r = -1;$

## Motivating Example (one-shot)

```
14 let one_shot () : int
15    $\Phi_{one\_shot}(r) = \exists x; (x \mapsto r \wedge r=1, \text{Norm}(r))$ 
16   = match callee () with
17   | effect Label k ->
18       continue k 1
```

Fig. 5. Specifications for a one-shot handler.

$::: \exists x . \text{ens}[r] \ x \mapsto 1 \wedge r=1;$

## Motivating Example (multi-shot)

```
19 let multi_shot () : int
20    $\Phi_{multi\_shot}(\_) = req\ (false)$ 
21   = match callee () with
22   | effect Label k ->
23     let _ = continue k 1 in continue k 2
```

Fig. 6. Specifications for a multi-shot handler.

**::: req false;** // due to possible assertion failure

# Static Try-Catch Reduction Rules

$$\begin{array}{c}
 \frac{(x \rightarrow \Phi_n) \in \mathcal{H}_\Phi}{\text{try}[\delta](\mathcal{N}[r]) \text{ catch } \mathcal{H}_\Phi \rightsquigarrow \mathcal{N}[r]; \Phi_n[r/x]} \quad [\mathcal{R}\text{-Normal}] \\
 \\
 \frac{\mathcal{E} = \mathcal{N}; \textcolor{red}{E}(x, r) \quad \textcolor{red}{E} \notin \text{dom}(\mathcal{H}_\Phi)}{\text{try}[\delta](\mathcal{E}; \theta) \text{ catch } \mathcal{H}_\Phi \rightsquigarrow \mathcal{E}; \text{try}[\delta](\theta) \text{ catch } \mathcal{H}_\Phi} \quad [\mathcal{R}\text{-Skip}] \\
 \\
 \frac{\mathcal{E} = \mathcal{N}; f(x^*, r') \quad (f(y^*, r) = \Phi_f) \in \mathcal{P}}{\text{try}[\delta](\mathcal{E}; \theta) \text{ catch } \mathcal{H}_\Phi \rightsquigarrow \text{try}[\delta](\mathcal{N}; \Phi_f[x^*/y^*, r'/r]; \theta) \text{ catch } \mathcal{H}_\Phi} \quad [\mathcal{R}\text{-Unfold}] \\
 \\
 \frac{\mathcal{E} = \mathcal{N}; \textcolor{red}{E}(x, r) \quad \textcolor{red}{E} \in \text{dom}(\mathcal{H}_\Phi) \quad (x' \rightarrow \Phi_n) \in \mathcal{H}_\Phi \quad \Phi = \theta[r_1]; \Phi_n[r_1/x']}{\text{try}[s](\mathcal{E}; \theta) \text{ catch } \mathcal{H}_\Phi \rightsquigarrow \text{try}[s](\mathcal{E} \# \Phi) \text{ catch } \mathcal{H}_\Phi} \quad [\mathcal{R}\text{-Shallow}] \\
 \\
 \frac{\mathcal{E} = \mathcal{N}; \textcolor{red}{E}(x, r) \quad \textcolor{red}{E} \in \text{dom}(\mathcal{H}_\Phi) \quad \text{try}[d](\theta) \text{ catch } \mathcal{H}_\Phi \rightsquigarrow \Phi}{\text{try}[d](\mathcal{E}; \theta) \text{ catch } \mathcal{H}_\Phi \rightsquigarrow \text{try}[d](\mathcal{E} \# \Phi) \text{ catch } \mathcal{H}_\Phi} \quad [\mathcal{R}\text{-Deep}] \\
 \\
 \frac{\mathcal{E} = \mathcal{N}; \textcolor{red}{E}(x, r) \quad (\textcolor{red}{E}(y)k \rightarrow \Phi) \in \mathcal{H}_\Phi \quad \Phi' = \Phi[x/y, (\lambda(r, r_c) \rightarrow \Phi[r_c])/k]}{\text{try}[\delta](\mathcal{E} \# \Phi[r_c]) \text{ catch } \mathcal{H}_\Phi \rightsquigarrow \mathcal{N}; \Phi'} \quad [\mathcal{R}\text{-Eff-Handle}] \\
 \\
 \frac{\mathcal{E} = \mathcal{N}; f(x^*, r') \quad (\text{rec } f(y^*, r) = \Phi_f) \in \mathcal{P} \quad \text{fst}(\Phi_f) \in \text{dom}(\mathcal{H}_\Phi) \quad (\text{try}[\delta](f(y^*, r) \# \Phi) \text{ catch } \mathcal{H}_\Phi \sqsubseteq \Phi_{\text{inv}}) \in \mathcal{P}}{\text{try}[\delta](\mathcal{E} \# \Phi_c) \text{ catch } \mathcal{H}_\Phi \rightsquigarrow \mathcal{N}; \Phi_{\text{inv}}[x^*/y^*, r'/r, \Phi_c/\Phi]} \quad [\mathcal{R}\text{-Lemma-App}]
 \end{array}$$

Fig. 22. Reduction Rules for Try-Catch Constructs

# Conclusion : Follow-Up Goals

- Put past research results into **practice**.
- Build **practical** automated program verifier.
- Contact me if you wish to collaborate with us on the above project 😊

# Research Tools Built

HIP/SLEEK: A formal verification system for imperative programs (C/Java/C++)

<https://github.com/hipsleek/hipsleek>

- Heifer: A formal verification system for higher-order programs (OCaml)

<https://github.com/hipsleek/Heifer>

- Songbird: An automated theorem prover for Separation Logic

<https://songbird-prover.github.io/>

*Mostly research prototypes.*



# Formal Semantics for Separation Logic

$S, h \models \sigma \wedge \pi$     *iff*     $\llbracket \pi \rrbracket_S$  and  $S, h \models \sigma$

$S, h \models \text{emp}$     *iff*     $\text{dom}(h) = \{\}$

$S, h \models x \mapsto y$     *iff*     $\text{dom}(h) = \{S(x)\}$  and  $h(S(x)) = \llbracket y \rrbracket_S$

$S, h \models \sigma_1 * \sigma_2$     *iff*     $\exists h_1 h_2. h_1 \circ h_2 = h$  such that  $S, h_1 \models \sigma_1$  and  $S, h_2 \models \sigma_2$

# Formal Semantics for Staged Logic

$S, h \rightsquigarrow S, h_2, \text{Norm}(-) \models \mathbf{req} \sigma \wedge \pi$	<i>iff</i> $h = h_1 \circ h_2$ and $S, h_1 \models \sigma \wedge \pi$
$S, h \rightsquigarrow S, h, \text{Err} \models \mathbf{req} \sigma \wedge \pi$	<i>iff</i> $\forall h_1. h_1 \subseteq h \Rightarrow S, h_1 \not\models \sigma \wedge \pi$
$S, h \rightsquigarrow S, h, R \models \mathbf{req} (\sigma \wedge \pi) @ R$	<i>iff</i> $S, h \rightsquigarrow S, h_1, R \models \mathbf{req} (\sigma \wedge \pi)$
$S, h \rightsquigarrow S, h \circ h_1, \text{Norm}(r) \models \mathbf{ens}[r] \sigma \wedge \pi$	<i>iff</i> $S, h_1 \models \sigma \wedge \pi$ and $\text{dom}(h_1) \cap \text{dom}(h) = \{\}$
$S, h \rightsquigarrow S_1, h_1, R \models f(x^*, r)$	<i>iff</i> $S(f) = \text{fun}(y^*) \Phi[r'] \rightarrow e,$ $S, h \rightsquigarrow S_1, h_1, R \models [r' := r][y^* := x^*] \Phi$
$S, h \rightsquigarrow S_1, h_1, R \models \exists x. \Phi$	<i>iff</i> $\exists v. S[x := v], h \rightsquigarrow S_1, h_1, R \models \Phi$
$S, h \rightsquigarrow S_2, h_2, R \models \Phi_1; \Phi_2$	<i>iff</i> $S, h \rightsquigarrow S_1, h_1, \text{Norm}(r) \models \Phi_1,$ $S_1, h_1 \rightsquigarrow S_2, h_2, R \models \Phi_2$
$S, h \rightsquigarrow S_1, h_1, \top \models \Phi_1; \Phi_2$	<i>iff</i> $S, h \rightsquigarrow S_1, h_1, \top \models \Phi_1$
$S, h \rightsquigarrow S_3, h_3, \text{Norm}(r_3) \models \Phi_1 \vee \Phi_2$	<i>iff</i> $\exists h_1, h_2, r_1, r_2. S, h \rightsquigarrow S_1, h_1, \text{Norm}(r_1) \models \Phi_1$ and $S, h \rightsquigarrow S_2, h_2, \text{Norm}(r_2) \models \Phi_2,$ and $(S_3, h_3, r_3) \in \{(S_1, h_1, r_1), (S_2, h_2, r_2)\}$
$S, h \rightsquigarrow S_1, h_1, \top \models \Phi_1 \vee \Phi_2$	<i>iff</i> $S, h \rightsquigarrow S_1, h_1, \top \models \Phi_1$ or $S, h \rightsquigarrow S_1, h_1, \top \models \Phi_2$