

```
#include <stdlib.h>
#include <string.h>
#include <ctype.h>
```

```
#define MAXPAROLA 30
#define MAXRIGA 80
```

```
int main(int argc, char *argv[])
{
    int freq[MAXPAROLA]; /* vettore di contatori
delle frequenze delle lunghezze delle parole */
    char riga[MAXRIGA];
    int i, inizio, lunghezza;
    FILE *f;
```

```
for(i=0; i<MAXPAROLA; i++)
    freq[i]=0;
```

```
if(argc != 2)
```

```
{
    fprintf(stderr, "ERRORE, serve un parametro con il nome del file\n");
    exit(1);
}
```

```
f = fopen(argv[1], "r");
if(f==NULL)
```

```
{
    fprintf(stderr, "ERRORE, impossibile aprire il file %s\n", argv[1]);
    exit(1);
}
```

```
while( fgets( riga, MAXRIGA, f ) != NULL )
```



Graph

Applications of Graph-Search Algorithms

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Dipartimento di Automatica e Informatica

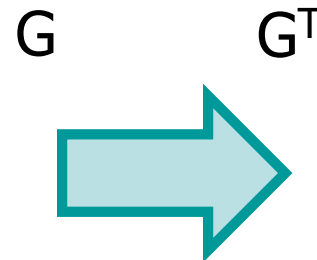
Politecnico di Torino

Reverse graph

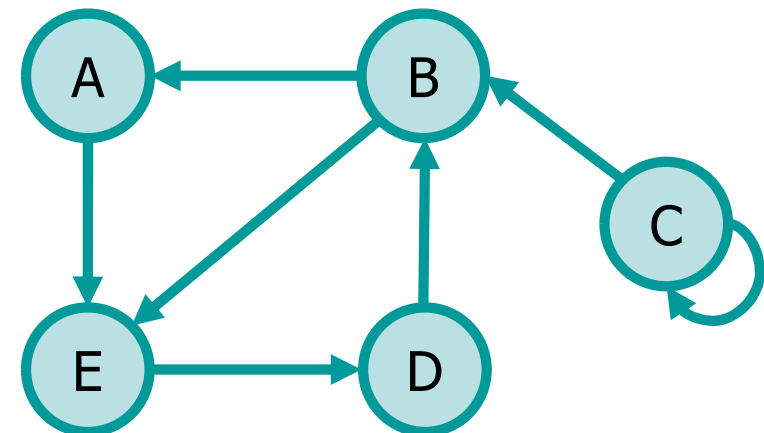
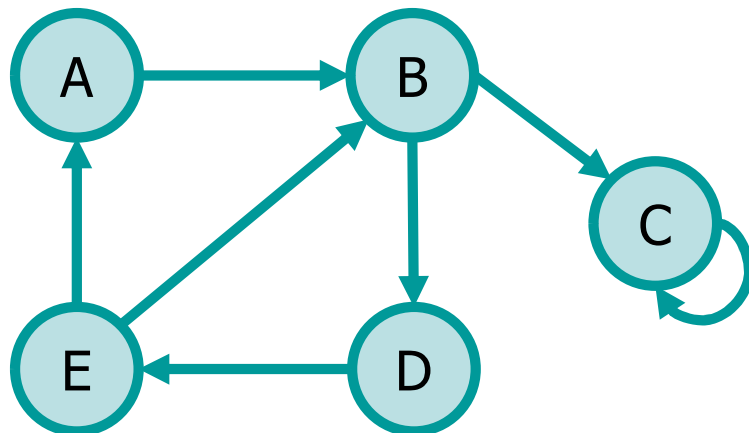
- ❖ Given a directed graph $G = (V, E)$
 - Its reverse (or transpose) graph
 - $G^T = (V, E^T)$
- is such that
 - If $(u, v) \in E$ then $(v, u) \in E^T$

Example

	A	B	C	D	E
A	0	1	0	0	0
B	0	0	1	1	0
C	0	0	1	0	0
D	0	0	0	0	1
E	1	1	0	0	0



	A	B	C	D	E
A	0	0	0	0	1
B	1	0	0	0	1
C	0	1	1	0	0
D	0	1	0	0	0
E	0	0	0	1	0



Implementation (with adjacency matrix)

```
graph_t *graph_transpose (graph_t *g) {  
    graph_t *h;  
    int i, j;  
  
    h = (graph_t *) util_calloc (1, sizeof (graph_t));  
    h->nv = g->nv;  
    h->g = (vertex_t *) util_calloc (g->nv, sizeof(vertex_t));  
    for (i=0; i<h->nv; i++) {  
        h->g[i] = g->g[i];  
        h->g[i].rowAdj = (int *) util_calloc (h->nv, sizeof(int));  
        for (j=0; j<h->nv; j++) {  
            h->g[i].rowAdj[j] = g->g[j].rowAdj[i];  
        }  
    }  
  
    return h;  
}
```

Transpose
the matrix

Implementation (with adjacency list)

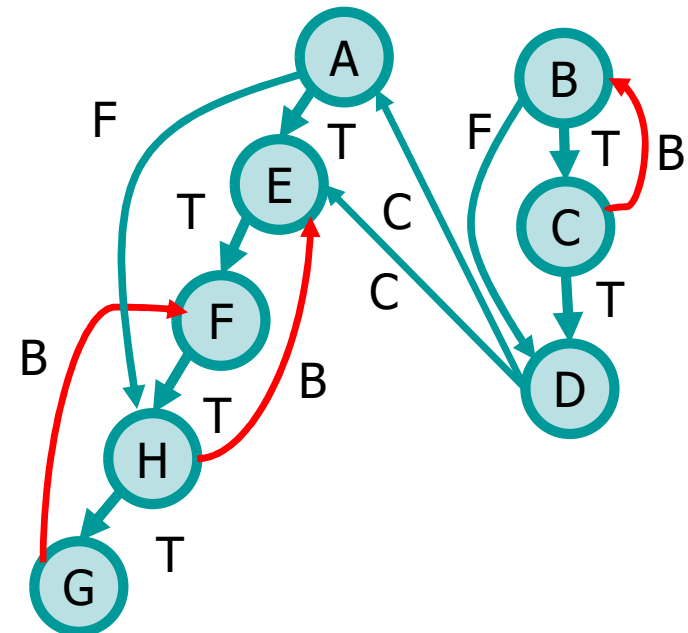
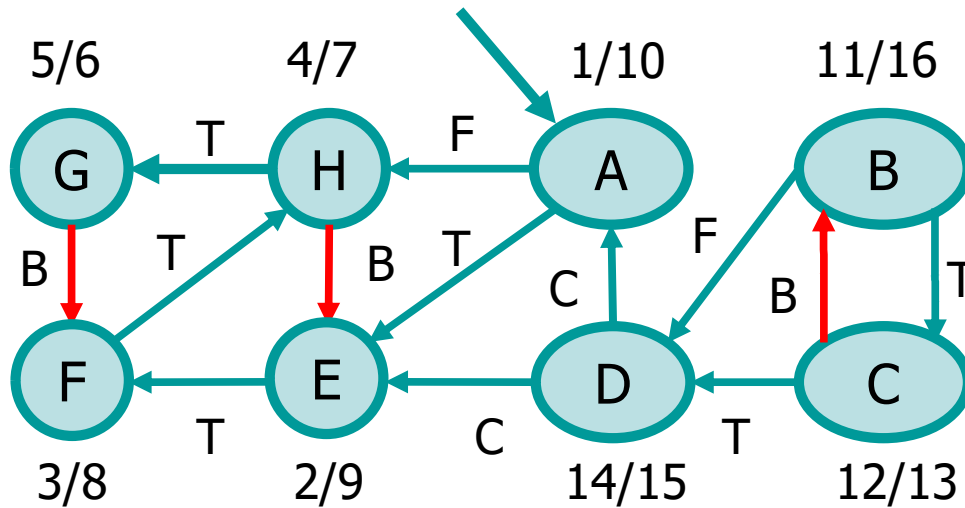
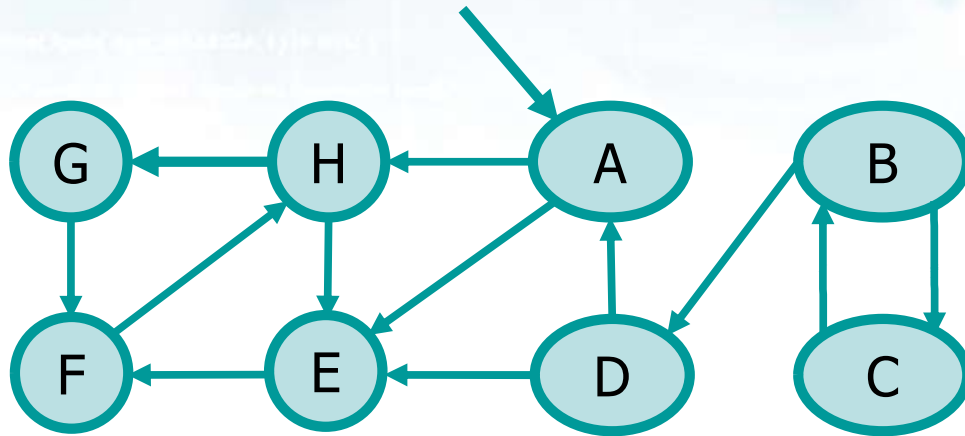
```
graph_t *graph_transpose (graph_t *g) {
    graph_t *h = NULL;
    vertex_t *tmp;
    edge_t *e;
    int i;
    h = (graph_t *) util_calloc (1, sizeof(graph_t));
    h->nv = g->nv;
    for (i=h->nv-1; i>=0; i--)
        h->g = new_node (h->g, i);
    tmp = g->g;
    while (tmp != NULL) {
        e = tmp->head;
        while (e != NULL) {
            new_edge (h, e->dst->id, tmp->id, e->weight);
            e = e->next;
        }
        tmp = tmp->next;
    }
    return h;
}
```

Insert a new
edge

Loop detection

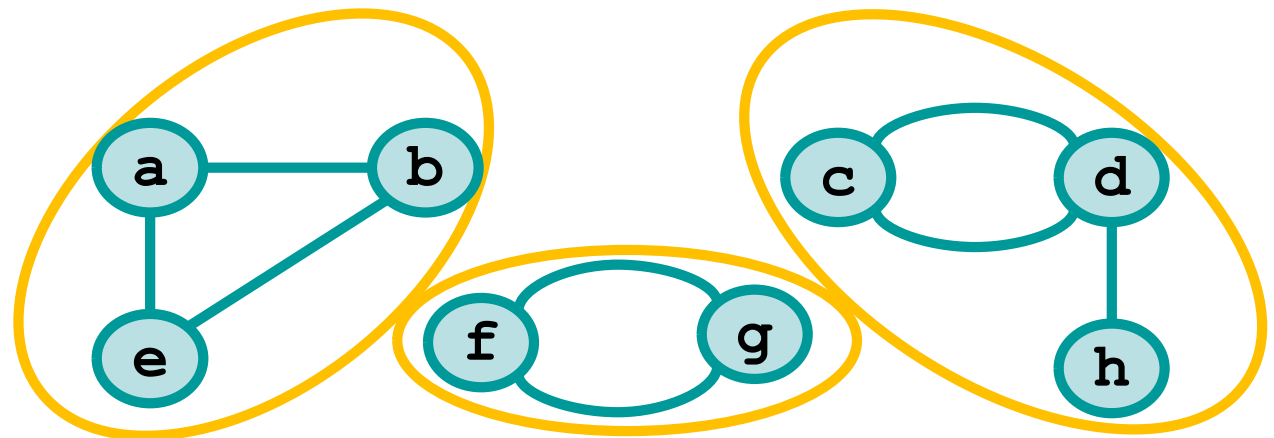
- ❖ Given a graph $G = (V, E)$
 - The graph is acyclic **if and only if** in a DFS there are no edges labelled **backward** (B)

Example



Connection in undirected graphs

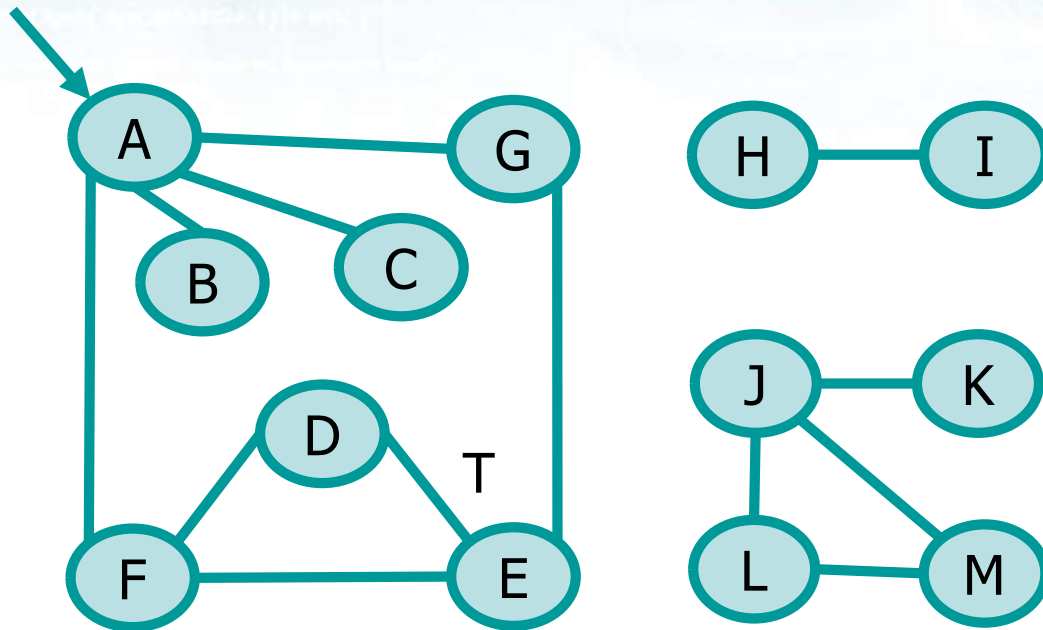
- ❖ An undirected graph is said to be connected iff
 - $\forall v_i, v_j \in V$ there exists a path p such that $v_i \rightarrow_p v_j$
- ❖ In an undirected graph
 - Connected component
 - Maximal connected subgraph, that is, there is no superset including it which is connected
 - Connected undirected graph
 - Only one connected component



Connected components

- ❖ In an undirected graph
 - Each tree of the DFS forest is a connected component
 - Connected component can be represented as an array that stores an integer identifying each connected component
 - Node identifiers serve as indexes of the array

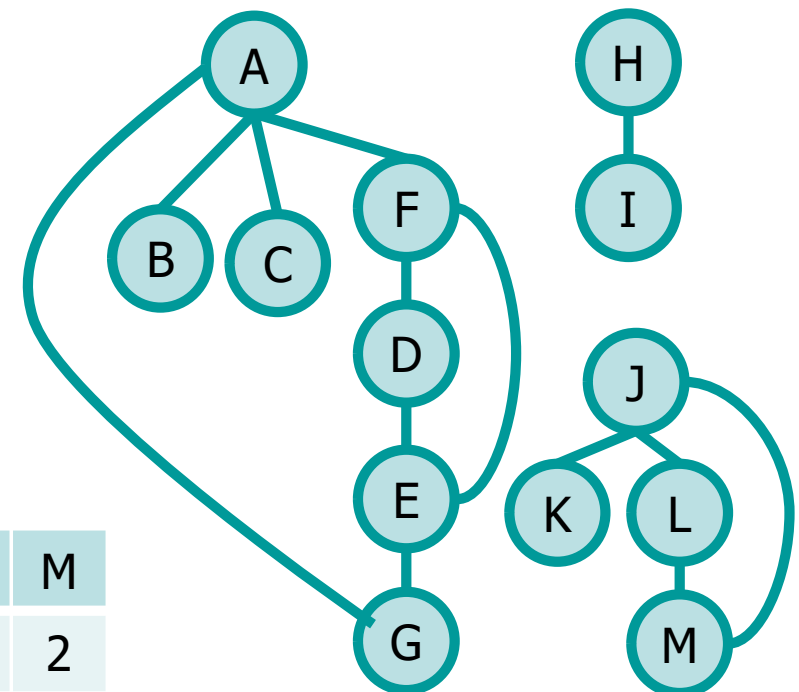
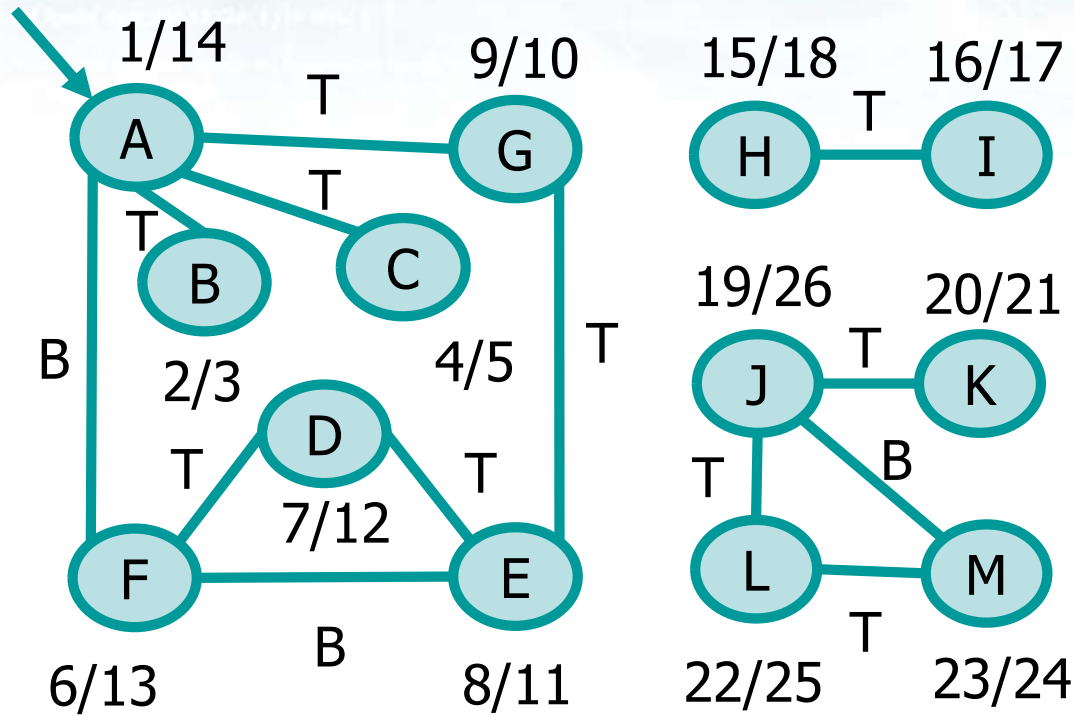
Example



A	B	C	D	E	F	G	H	I	J	K	L	M

Connected
Component Ids

Solution



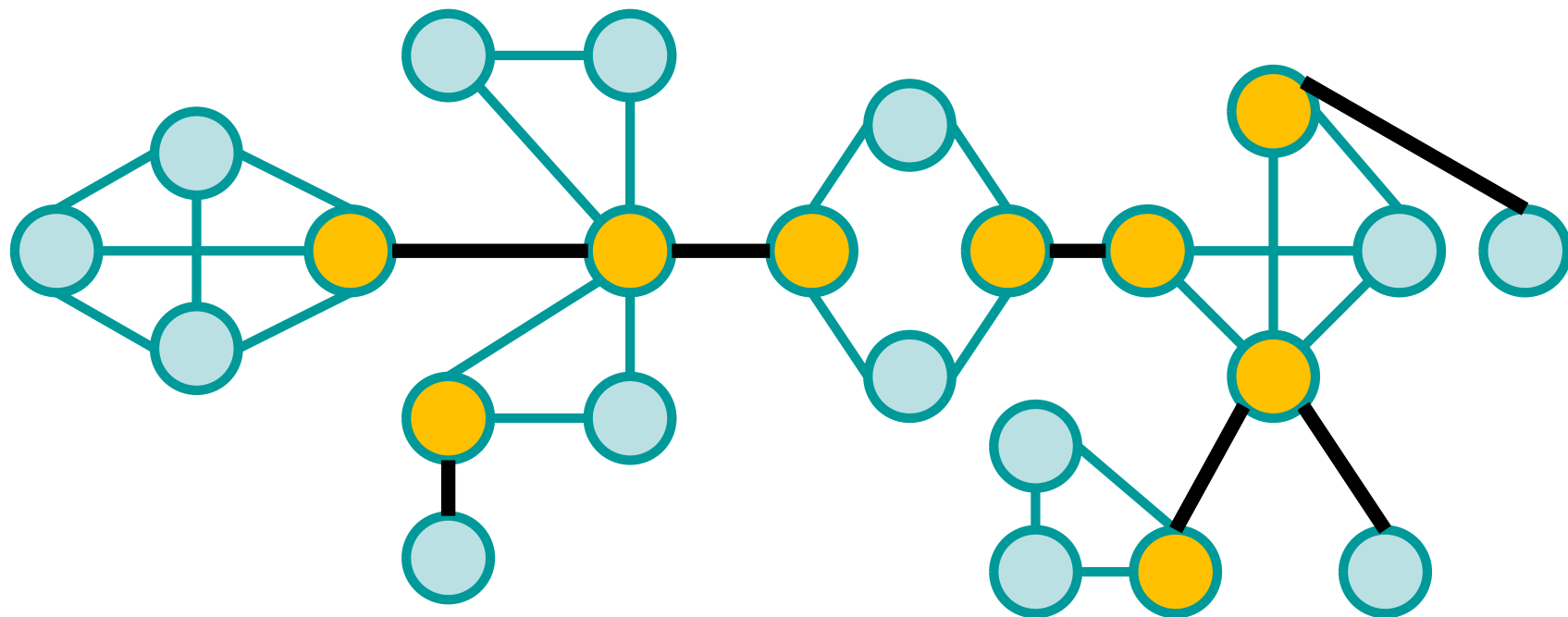
A	B	C	D	E	F	G	H	I	J	K	L	M
0	0	0	0	0	0	0	1	1	2	2	2	2

Bridges

- ❖ Given an undirected and connected graph, find out whether the property of being connected is lost because
 - An edge is removed
- ❖ Bridge
 - Edge whose removal disconnects the graph

Example

Bridges —

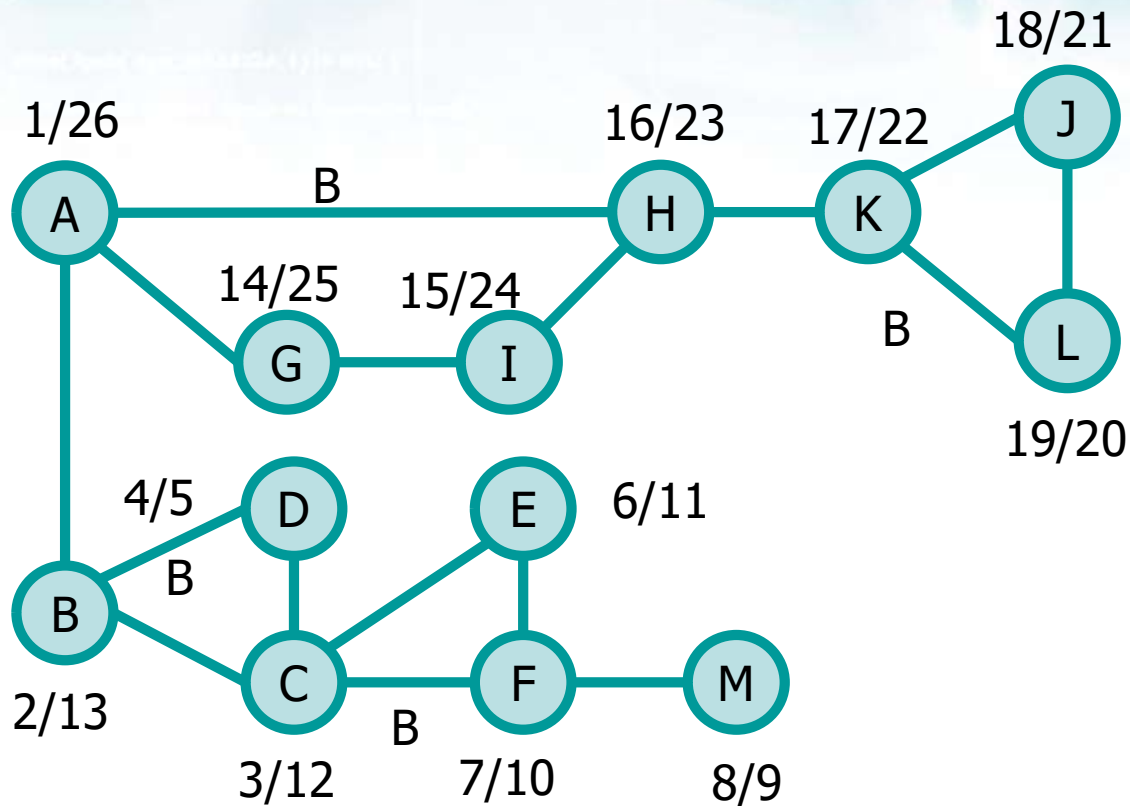


Bridges

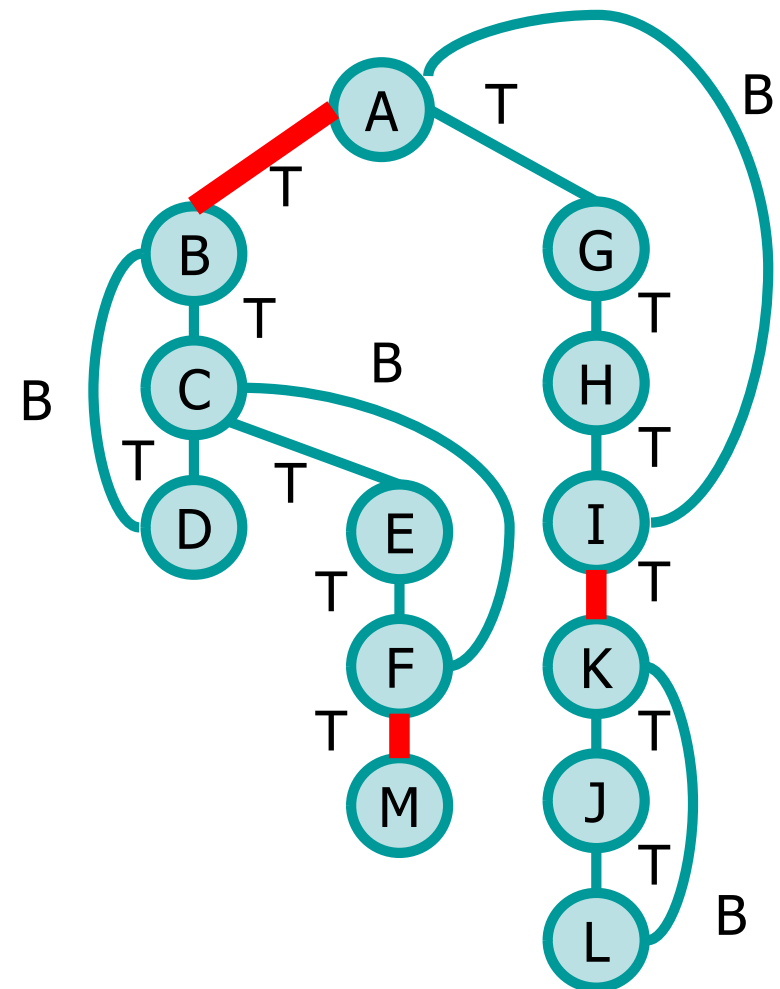
❖ An edge (v,w)

- Labelled Back (B) cannot be a bridge
 - Nodes v and w are also connected by a path in the DFS tree
- Labelled Tree (T) is a bridge if and only if there are no edges labelled Back that connect a descendant of w to an ancestor of v in the DFS tree

Example



All other edges are tree edges

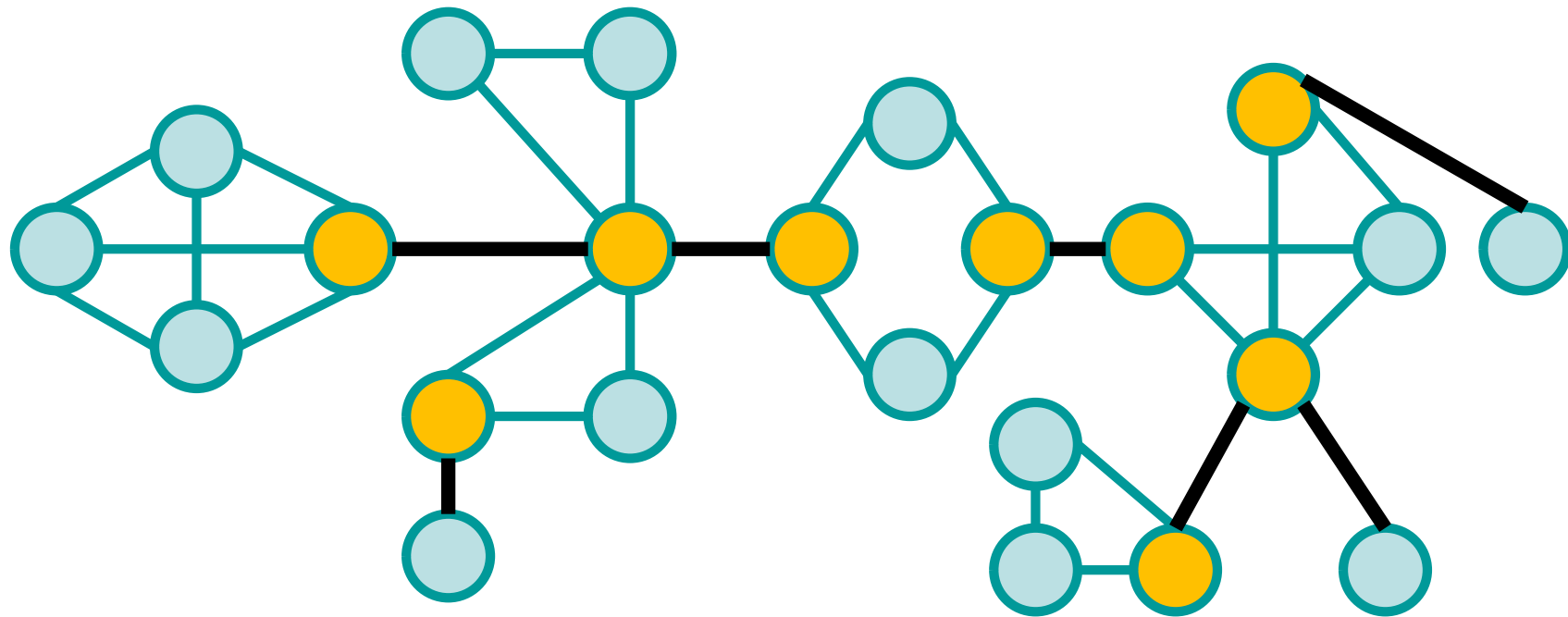


Articulation points

- ❖ Given an undirected and connected graph, find out whether the property of being connected is lost because
 - A node is removed
- ❖ Articulation point
 - Node whose removal disconnects the graph
 - Removing the vertex entails the removal of insisting (incoming and outgoing) edges as well

Example

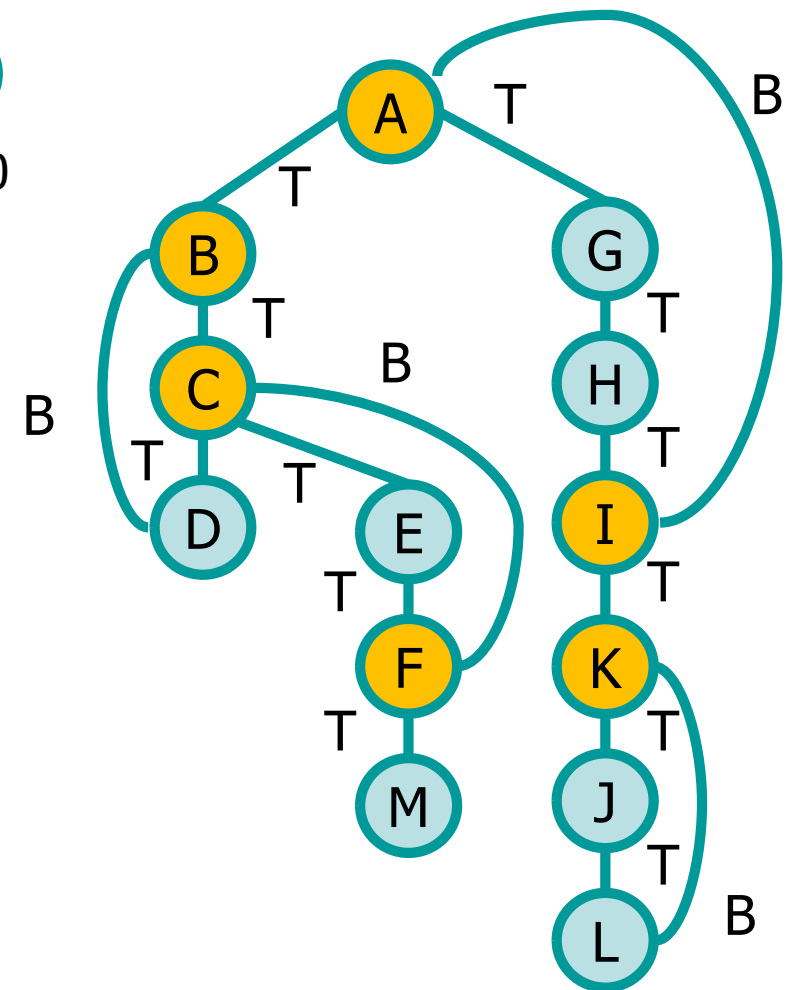
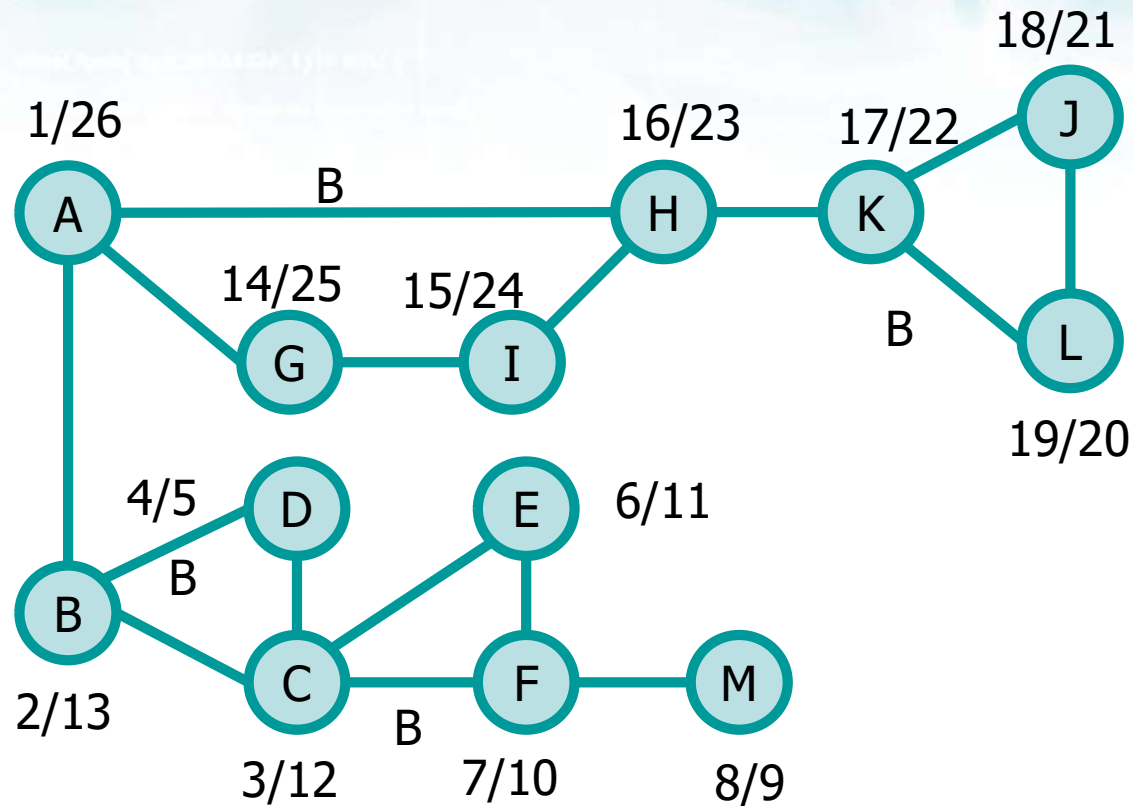
Articulation points 



Articulation points

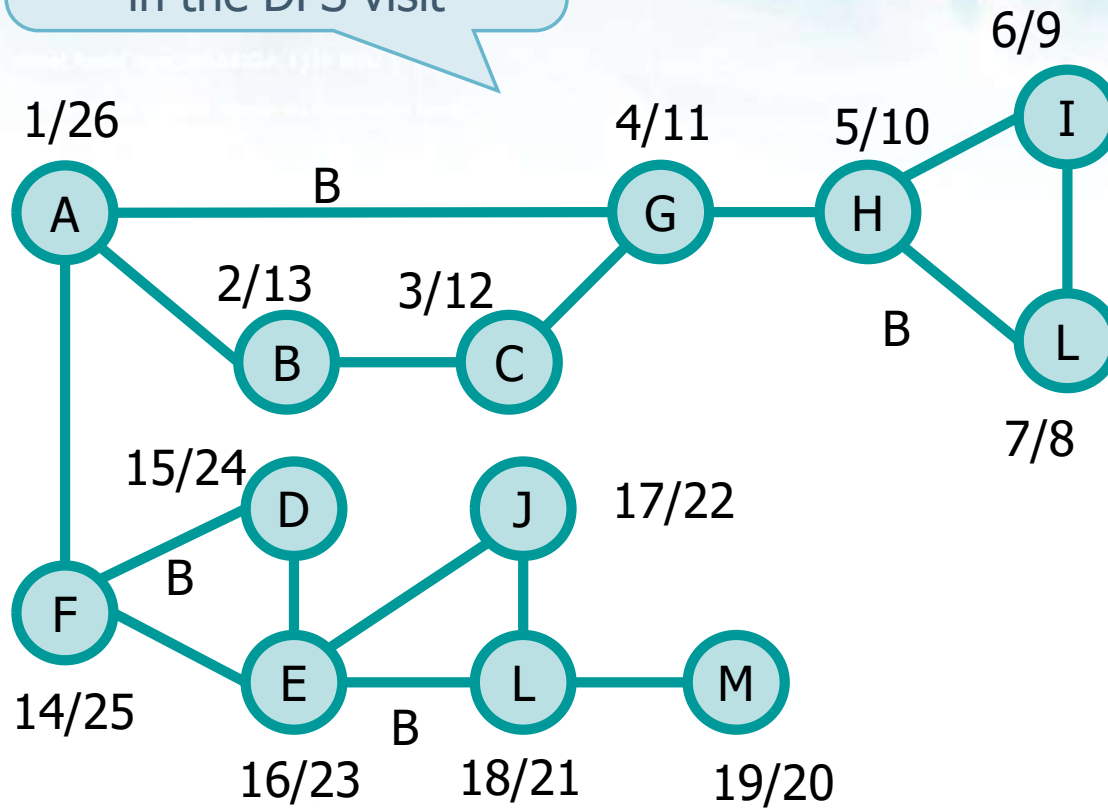
- ❖ Given an undirected graph G , given the DFS tree G_p
 - The root of G_p is an articulation point if and only if it has at least two children
 - Leaves cannot be articulation points
 - Any internal node v is an articulation point of G if and only if v has at least one child s such that there is no edge labelled B from s or from one of its descendants to a proper ancestor of v

Example

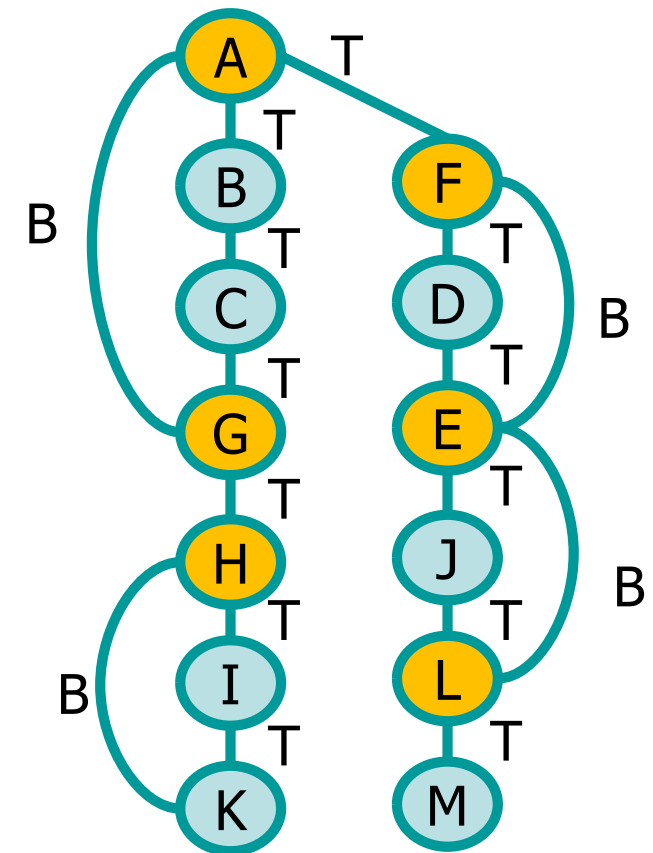


Same example
different ids and order
in the DFS visit

Example



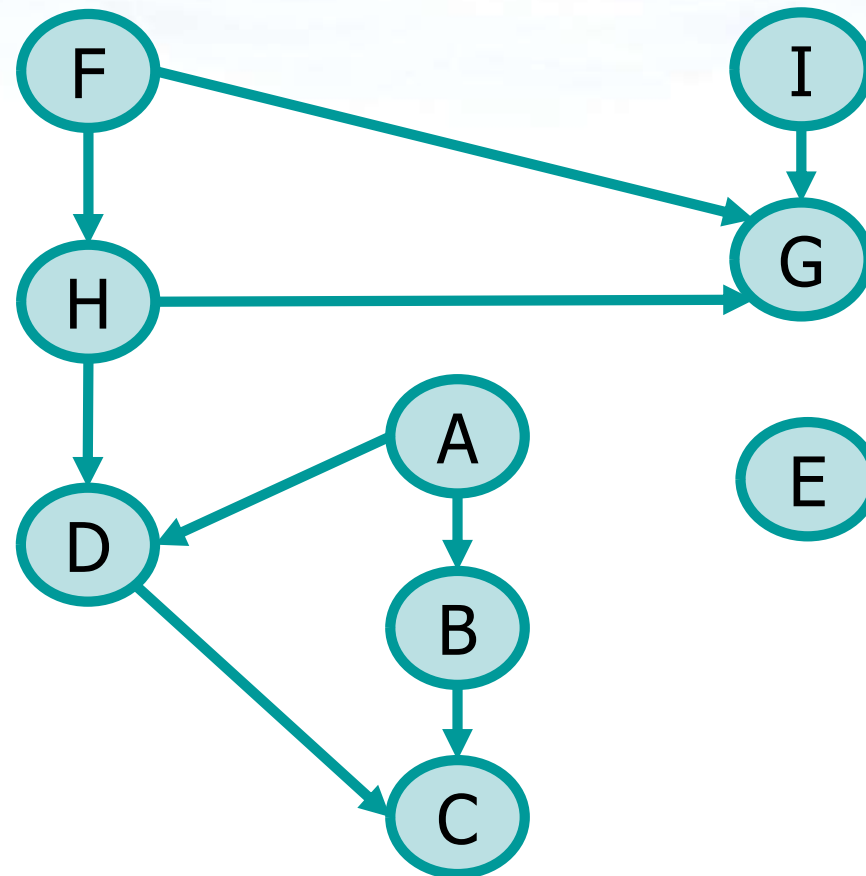
All other
edges are
tree edges



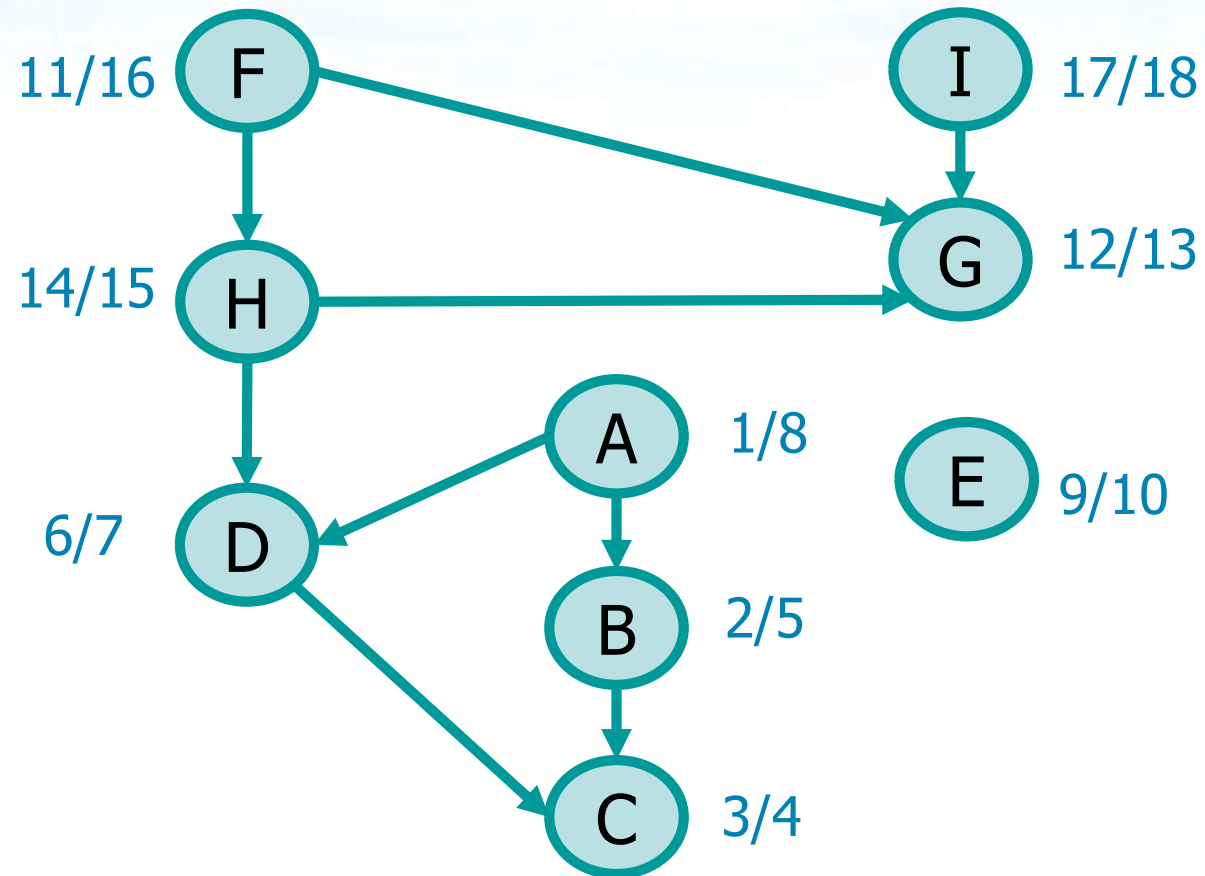
Directed Acyclic Graph (DAG)

- ❖ Topological sort (reverse)
 - Reordering the nodes according to a horizontal line, so that if the (u, v) edge exists, node u appears to the left (right) of node v and all edges go from left (right) to right (left)
- ❖ Algorithm
 - Perform a DFS computing **end-processing** times
 - Order vertices with **descending** end-processing times
- ❖ Alternative algorithm
 - Perform a DFS and when assigning end-processing times insert the vertex into a **LIFO** list

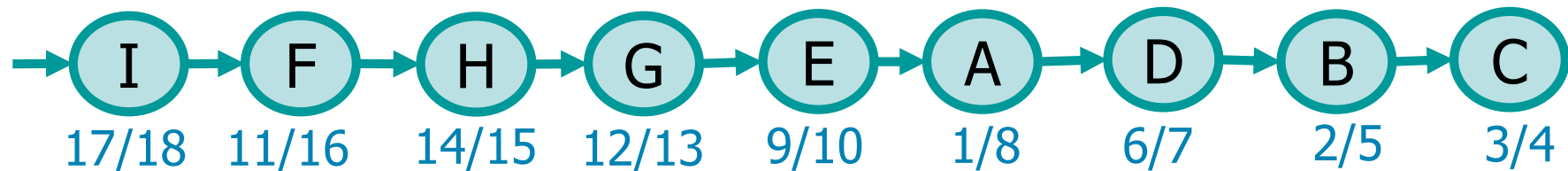
Example



Solution



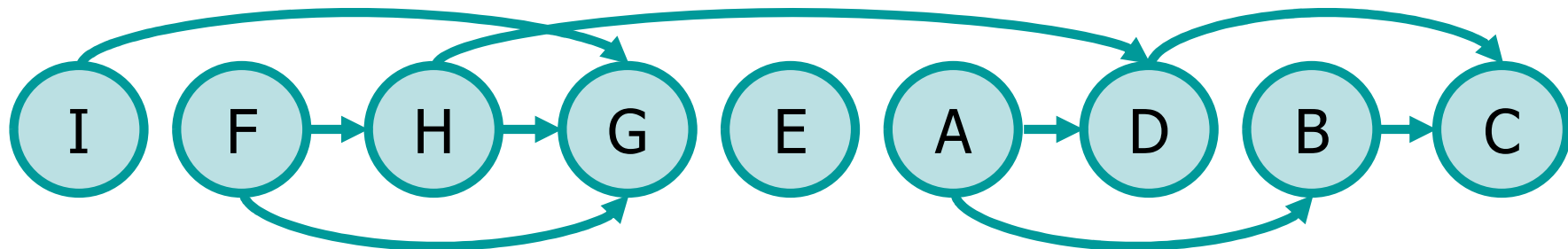
LIFO list



Topological Sort

❖ Topological sort

- With a DAG represented by an adjacency matrix, it is enough to invert references to rows and columns



❖ Reverse topological sort



Implementation (with adjacency matrix)

```
void graph_dag (graph_t *g){
    int i, *post, loop=0, timer=0;
    post = (int *)util_malloc(g->nv*sizeof(int));
    for (i=0; i<g->nv; i++) {
        if (g->g[i].color == WHITE) {
            timer = graph_dag_r (g, i, post, timer, &loop);
        }
    }
    if (loop != 0) {
        fprintf (stdout, "Loop detected!\n");
    } else {
        fprintf (stdout, "Topological sort (direct):");
        for (i=g->nv-1; i>=0; i--) {
            fprintf(stdout, " %d", post[i]);
        }
        fprintf (stdout, "\n");
    }
    free (post);
}
```

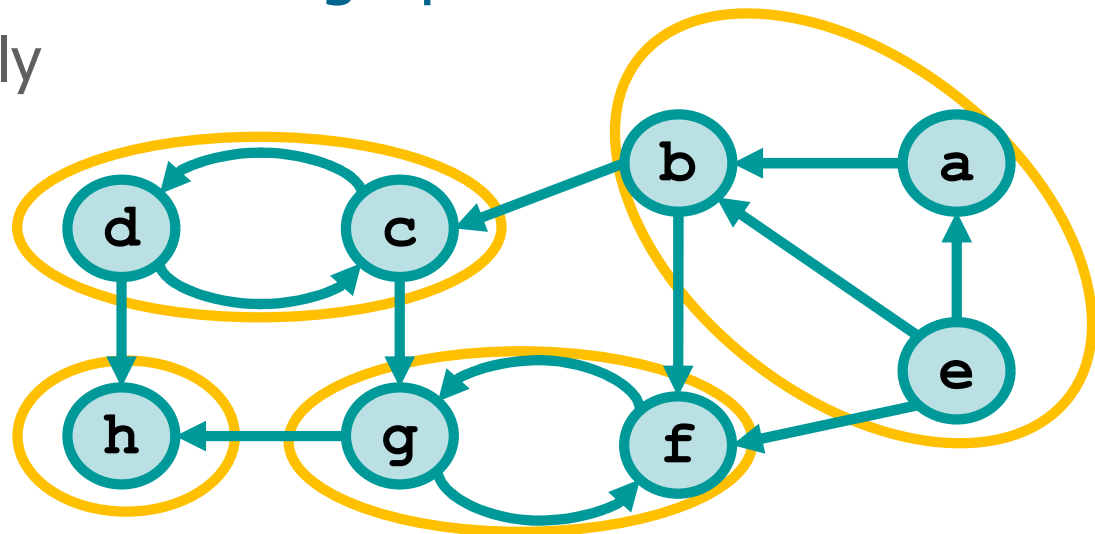
Implementation (with adjacency matrix)

```
int graph_dag_r(graph_t *g, int i, int *post, int t,
               int *loop) {
    int j;
    g->g[i].color = GREY;
    for (j=0; j<g->nv; j++) {
        if (g->g[i].rowAdj[j] != 0) {
            if (g->g[j].color == GREY) {
                *loop = 1;
            }
            if (g->g[j].color == WHITE) {
                t = graph_dag_r(g, j, post, t, loop);
            }
        }
    }
    g->g[i].color = BLACK;
    post[t++] = i;
    return t;
}
```

Connection in directed graphs

- ❖ A directed graph is said to be strongly connected iff
 - $\forall v_i, v_j \in V$ there exists two paths p, p' such that

$$v_i \rightarrow_p v_j \quad \text{and} \quad v_j \rightarrow_{p'} v_i$$
- ❖ In a directed graph
 - Strongly connected component
 - Maximal strongly connected subgraph
 - Strongly connected directed graph
 - Only one strongly connected component

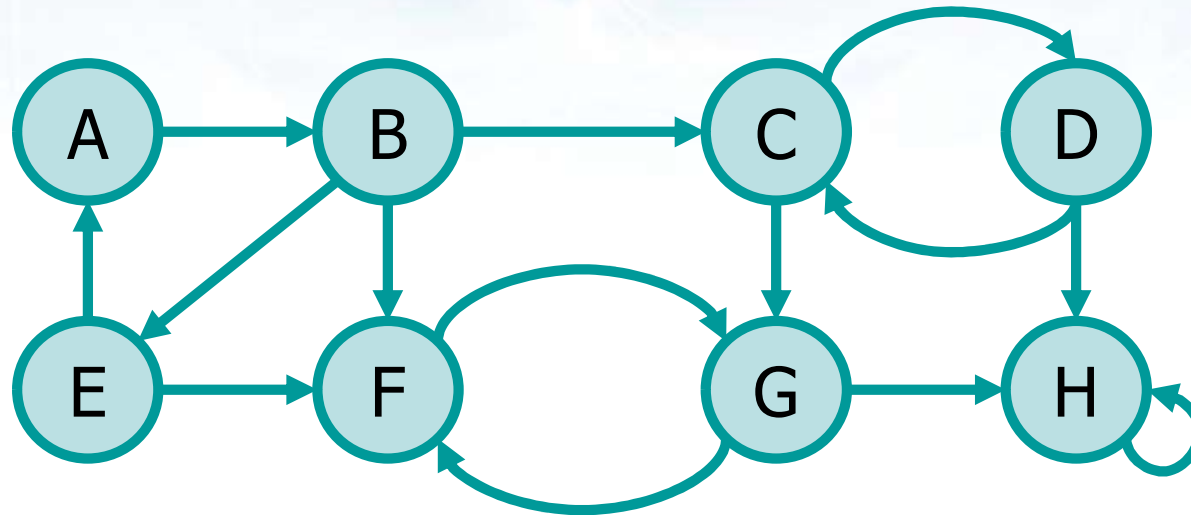


Strongly Connected Component (SCC)

- ❖ Kosaraju's algorithm ('80s)
 - Reverse the graph
 - Execute DFS on the reverse graph, computing discovery and end-processing times
 - Execute DFS on the original graph according to **decreasing** end-processing times
 - The trees of this last DFS are the strongly connected components

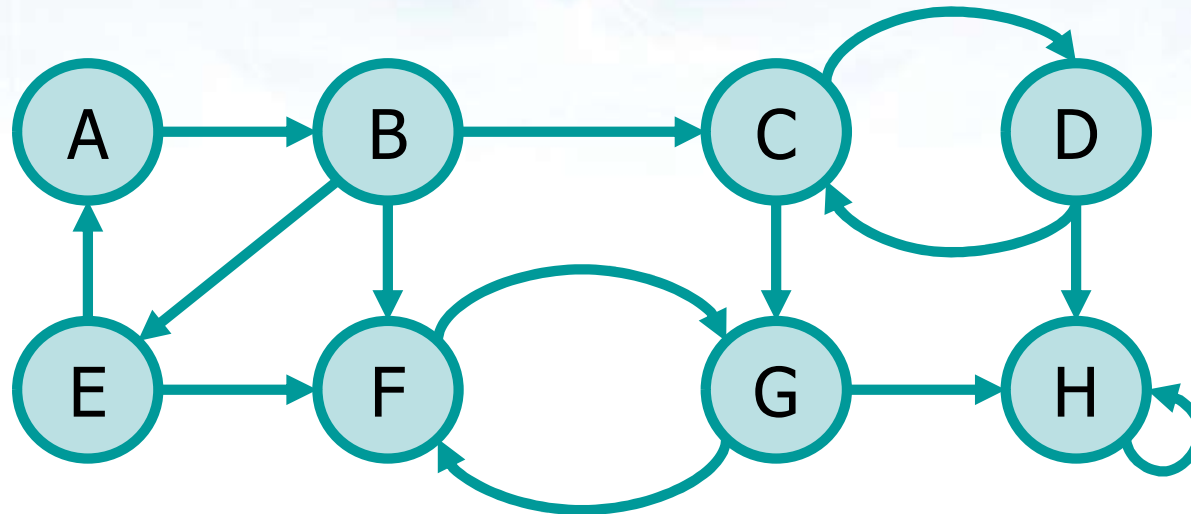
Example

G



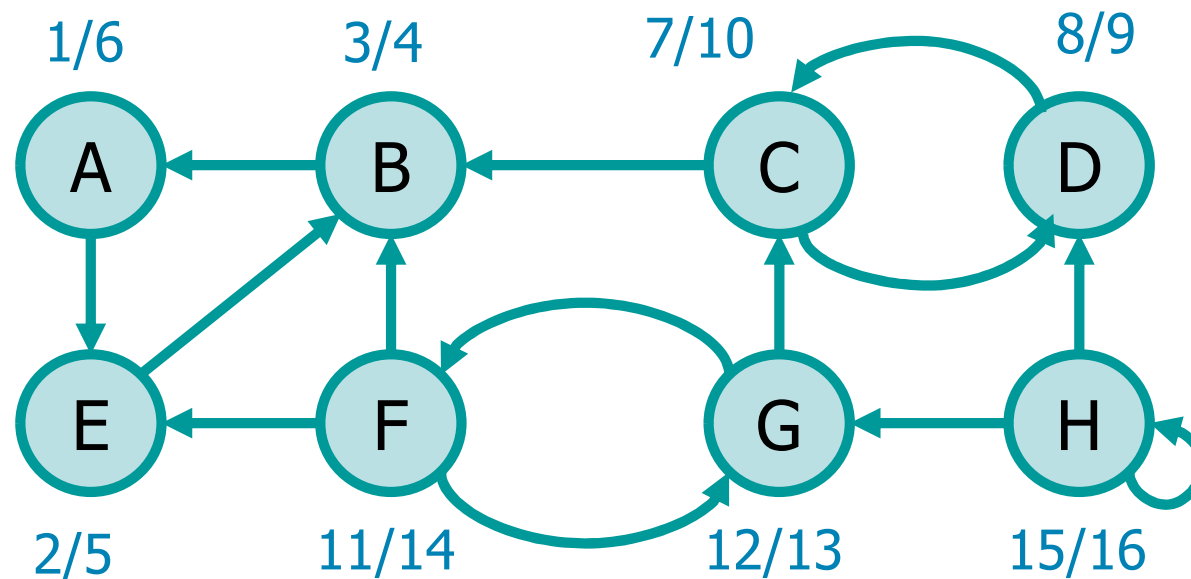
Solution

G



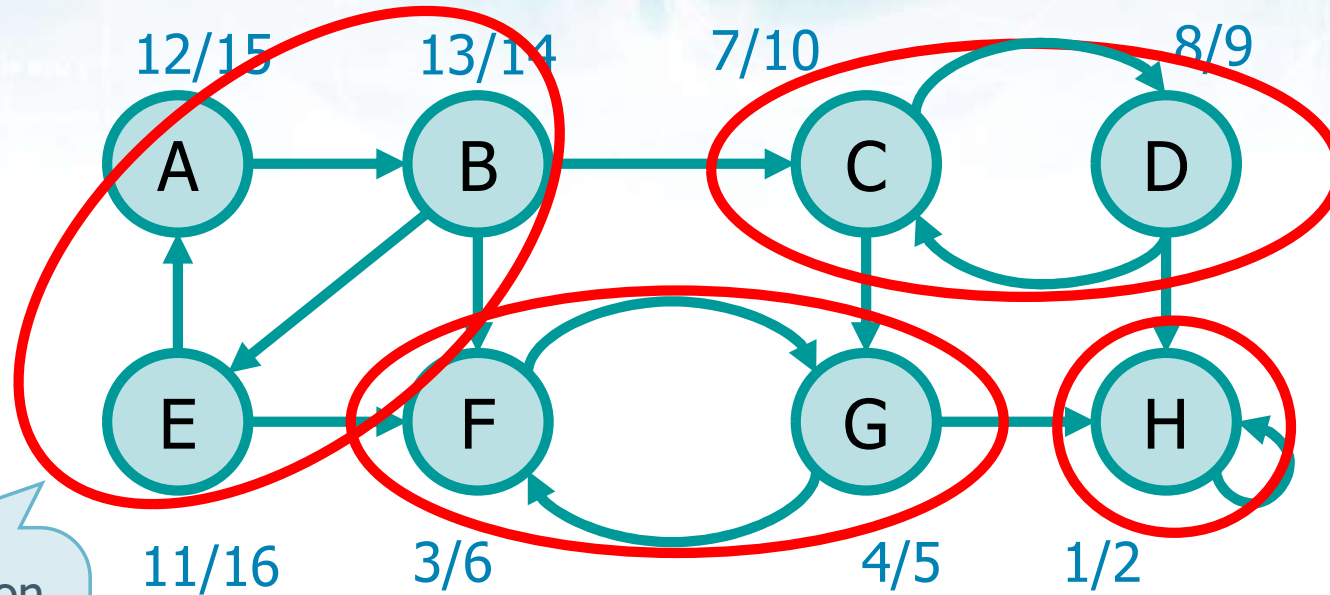
Reverse
the graph
and
perform
DFS on G^T

G^T



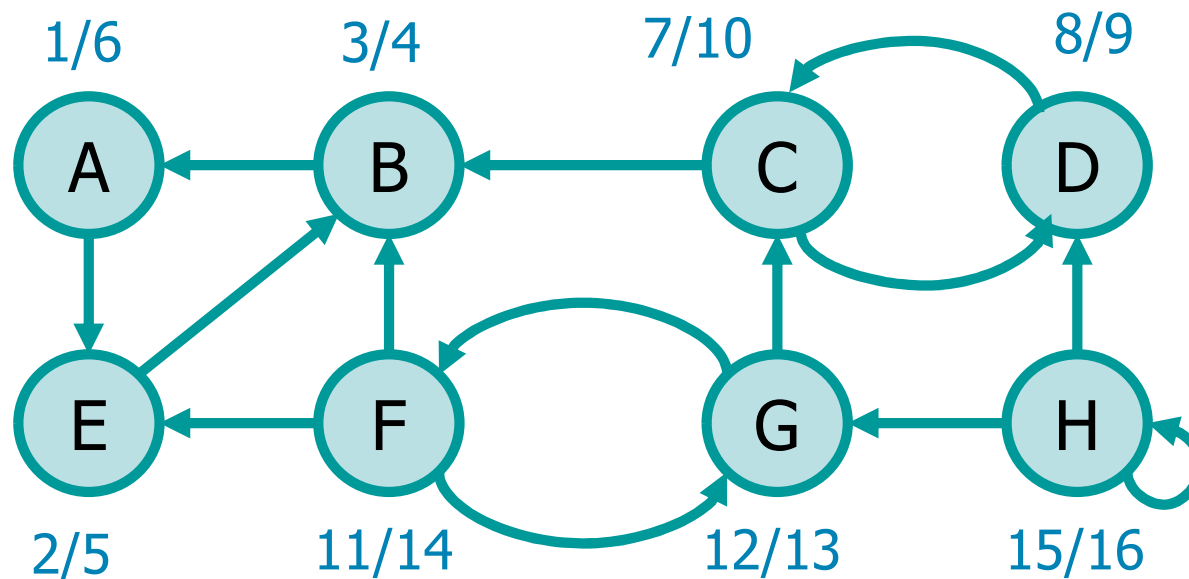
Solution

G



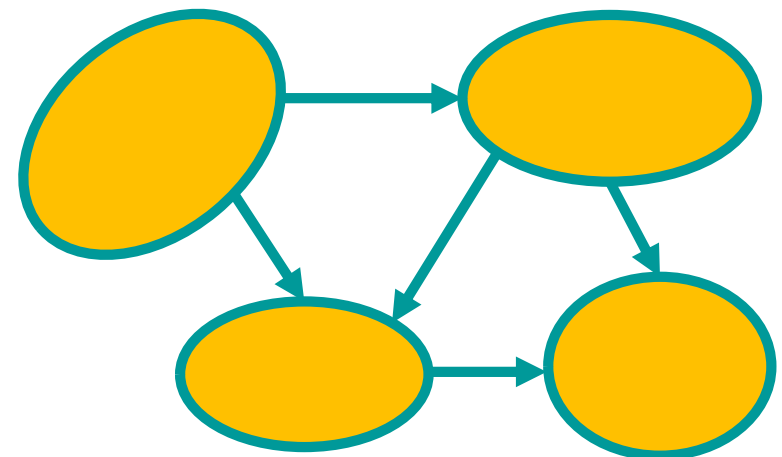
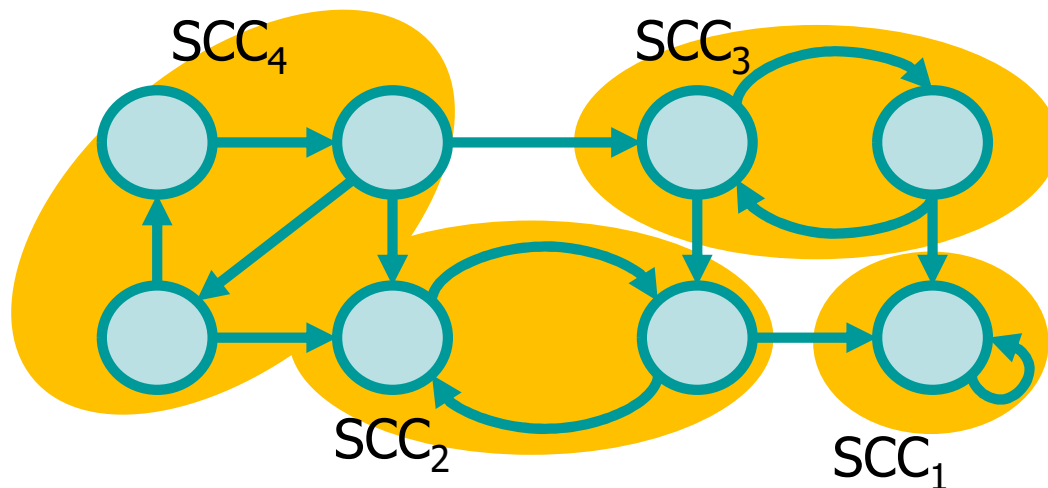
Perform DFS on G by decreasing end-processing times

G^T



Considerations

- ❖ SCCs are equivalence classes with respect to the mutual reachability property
- ❖ We can “extract” a reduced graph G' considering 1 node as representing each equivalence class
- ❖ The reduced graph G' is a DAG



Implementation (with adjacency matrix)

Client
(code extract)

```
g = graph_load (argv[1]);

sccs = graph_scc (g);

fprintf (stdout, "Number of SCCs: %d\n", sccs);
for (j=0; j<sccs; j++) {
    fprintf (stdout, "SCC%d:", j);
    for (i=0; i<g->nv; i++) {
        if (g->g[i].scc == j) {
            fprintf (stdout, " %d", i);
        }
    }
    fprintf (stdout, "\n");
}

graph_dispose (g);
```

Implementation (with adjacency matrix)

```
int graph_scc (graph_t *g) {
    graph_t *h;
    int i, id=0, timer=0;
    int *post, *tmp;

    h = graph_transpose (g);
    post = (int *) util_malloc (g->nv*sizeof(int));
    for (i=0; i<g->nv; i++) {
        if (h->g[i].color == WHITE) {
            timer = graph_scc_r (h, i, post, id, timer);
        }
    }
    graph_dispose (h);
}
```

Implementation (with adjacency matrix)

```
id = timer = 0;
tmp = (int *) util_malloc (g->nv * sizeof(int));
for (i=g->nv-1; i>=0; i--) {
    if (g->g[post[i]].color == WHITE) {
        timer=graph_scc_r(g, post[i], tmp, id, timer);
        id++;
    }
}

free (post);
free (tmp);

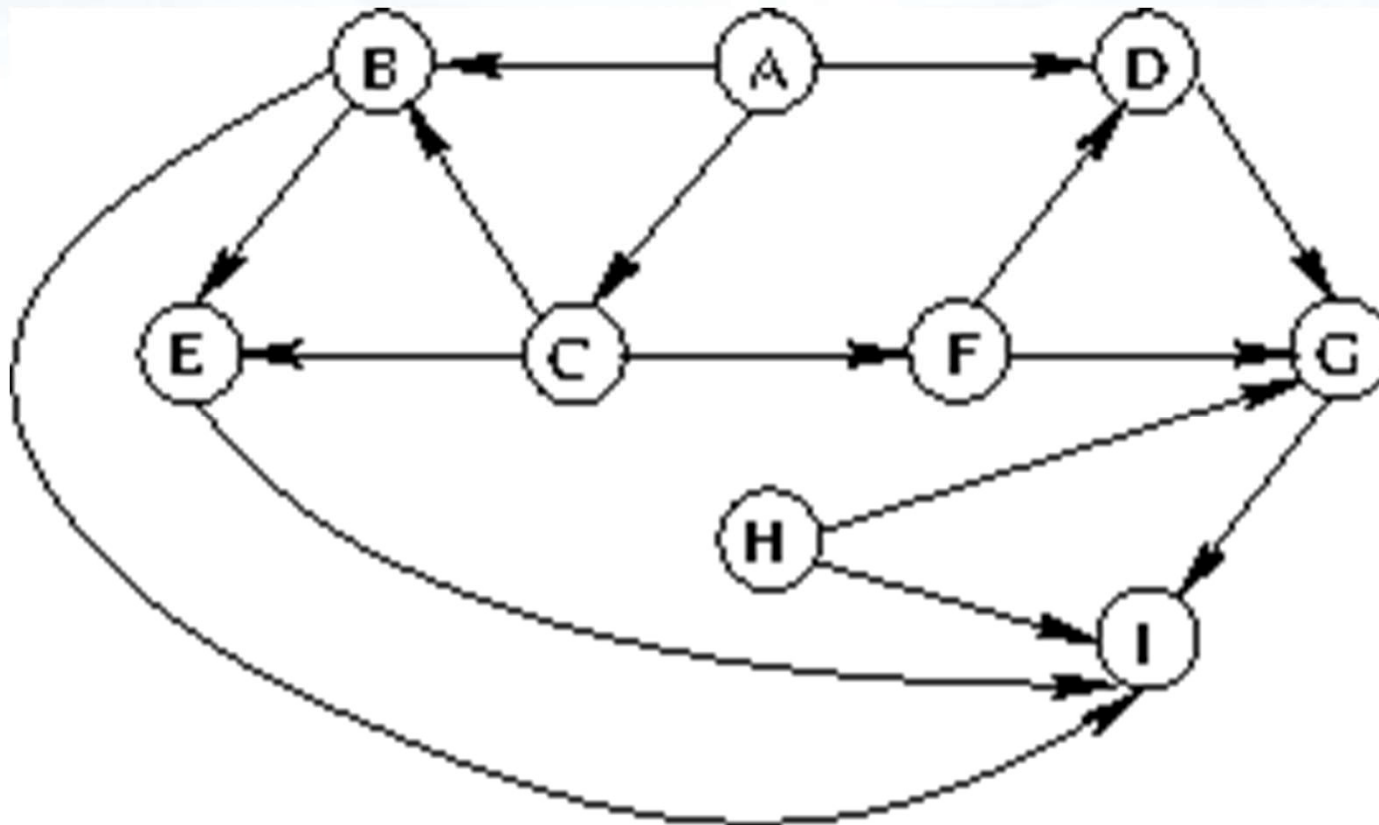
return id;
}
```

Implementation (with adjacency matrix)

```
int graph_scc_r(
    graph_t *g, int i, int *post, int id, int t
) {
    int j;
    g->g[i].color = GREY;
    g->g[i].scc = id;
    for (j=0; j<g->nv; j++) {
        if (g->g[i].rowAdj[j]!=0 &&
            g->g[j].color==WHITE) {
            t = graph_scc_r (g, j, post, id, t);
        }
    }
    g->g[i].color = BLACK;
    post[t++] = i;

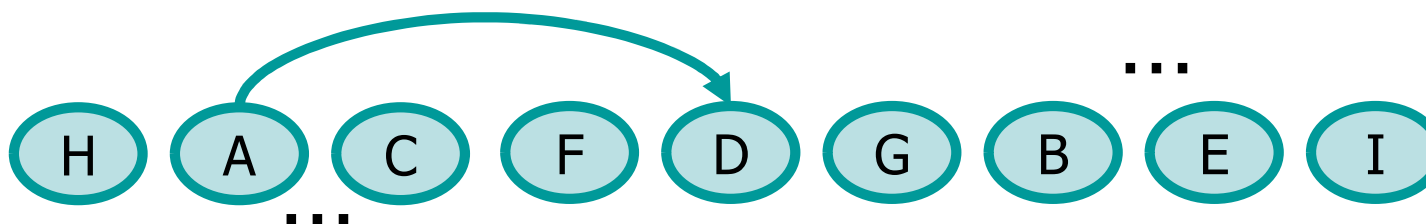
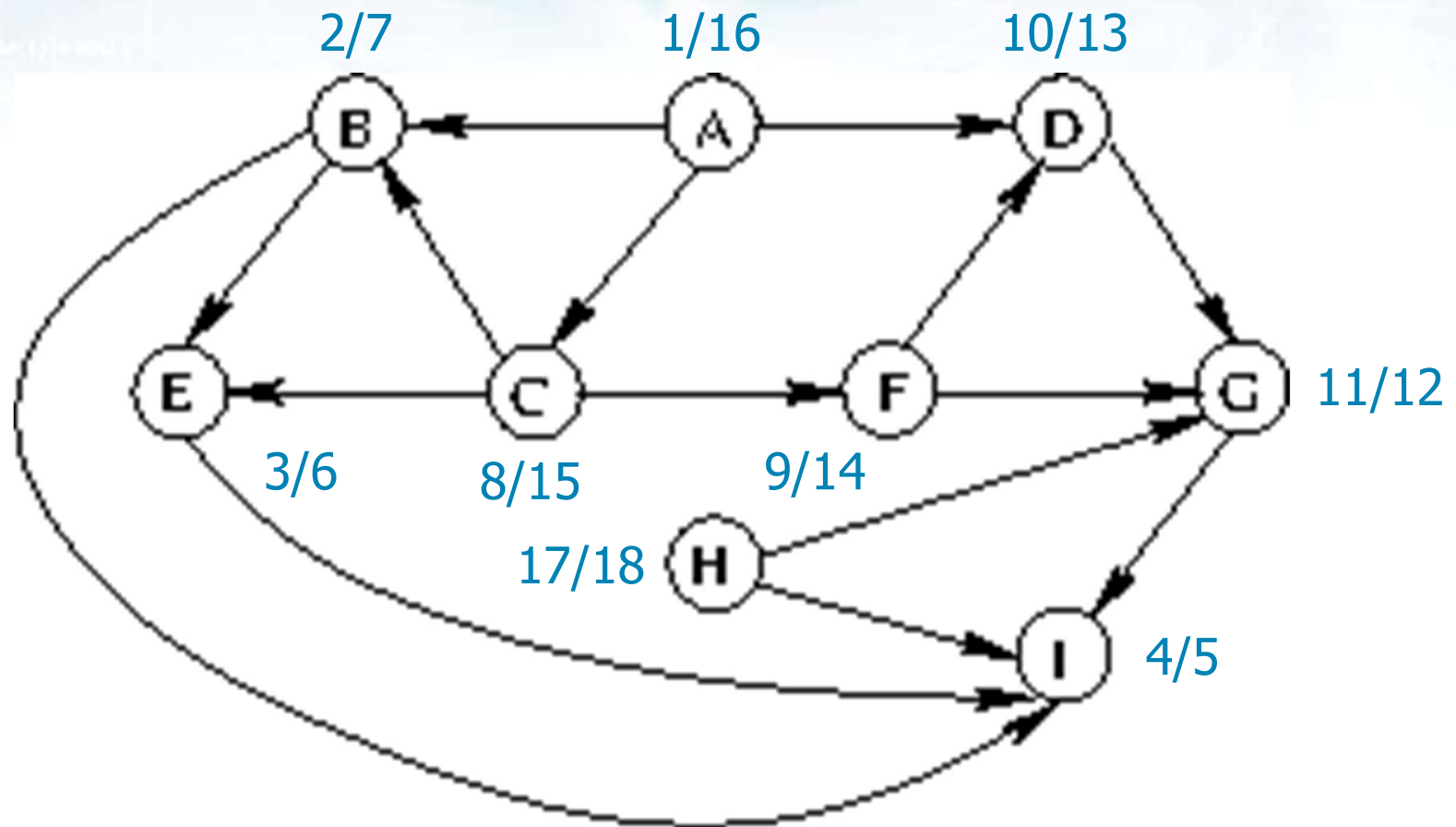
    return t;
}
```

Exercise

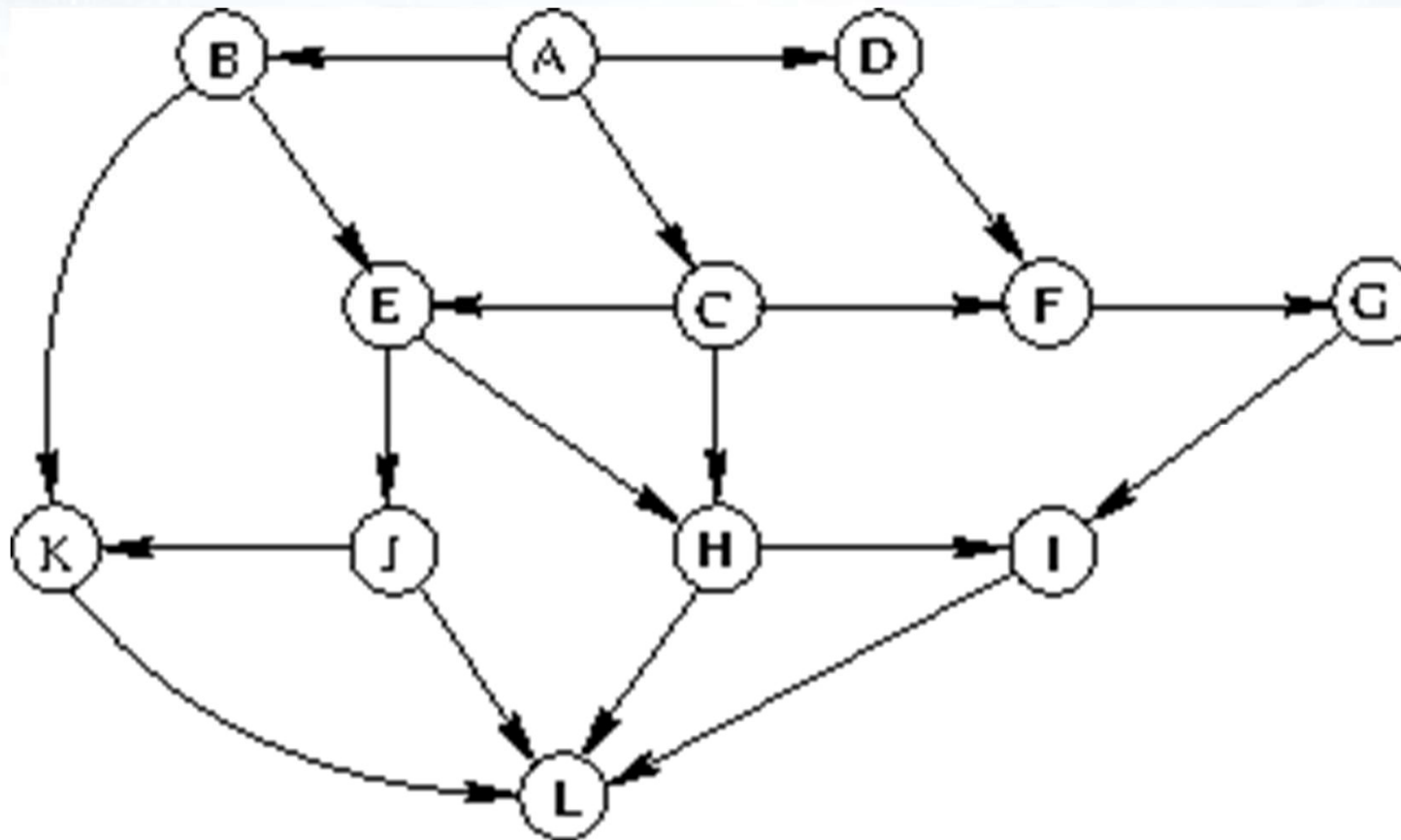


- ❖ Given the previous DAG find the topological order of all vertices

Solution

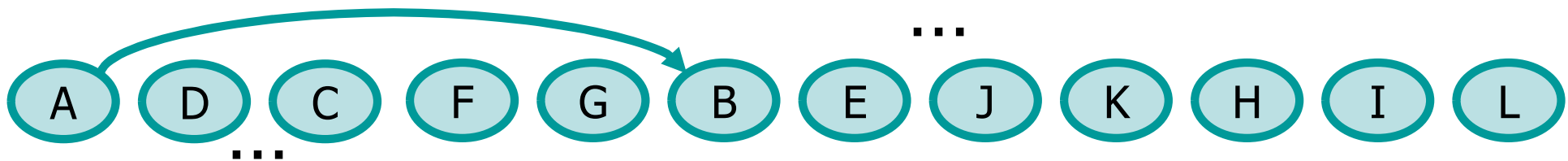
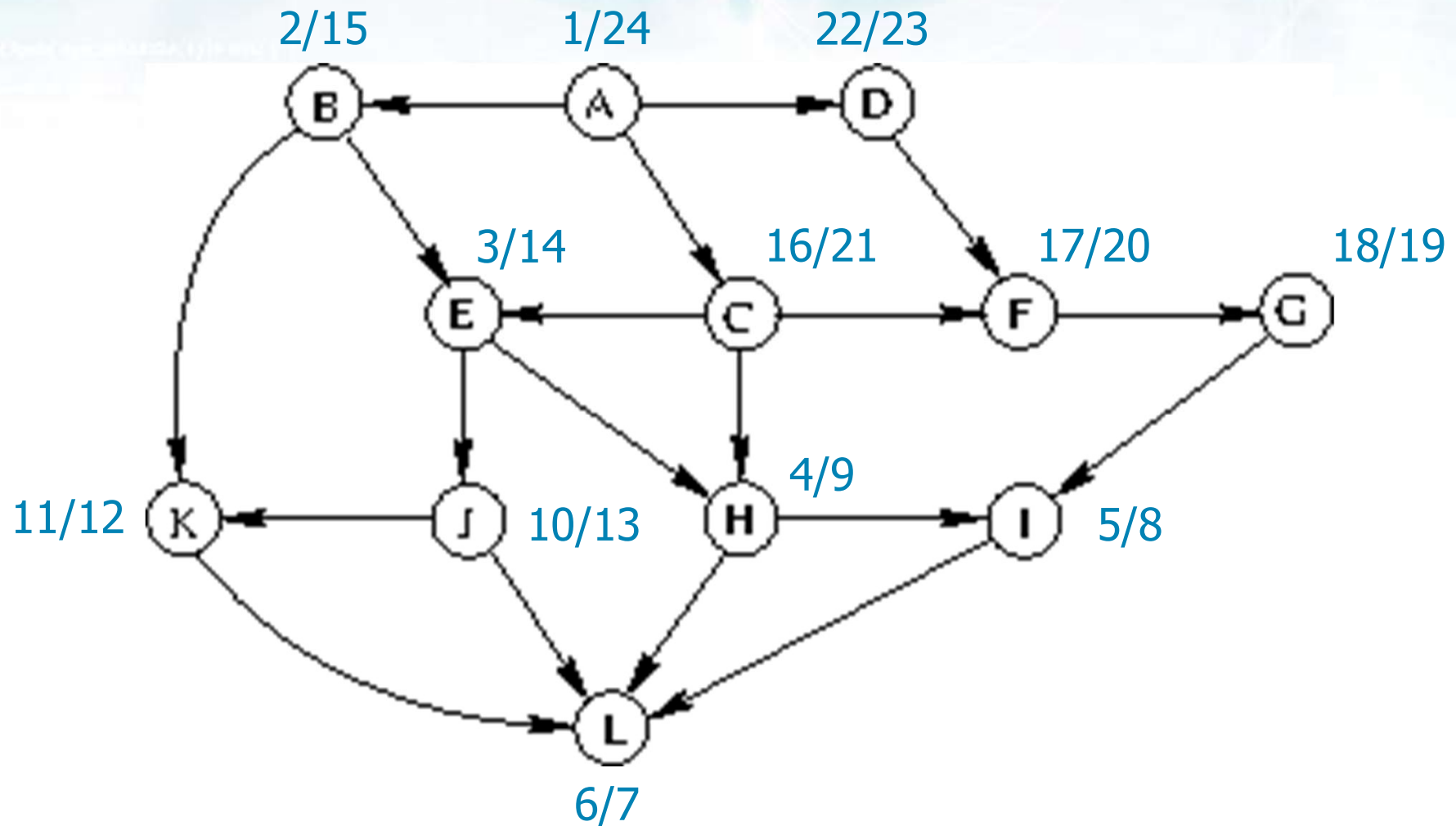


Exercise

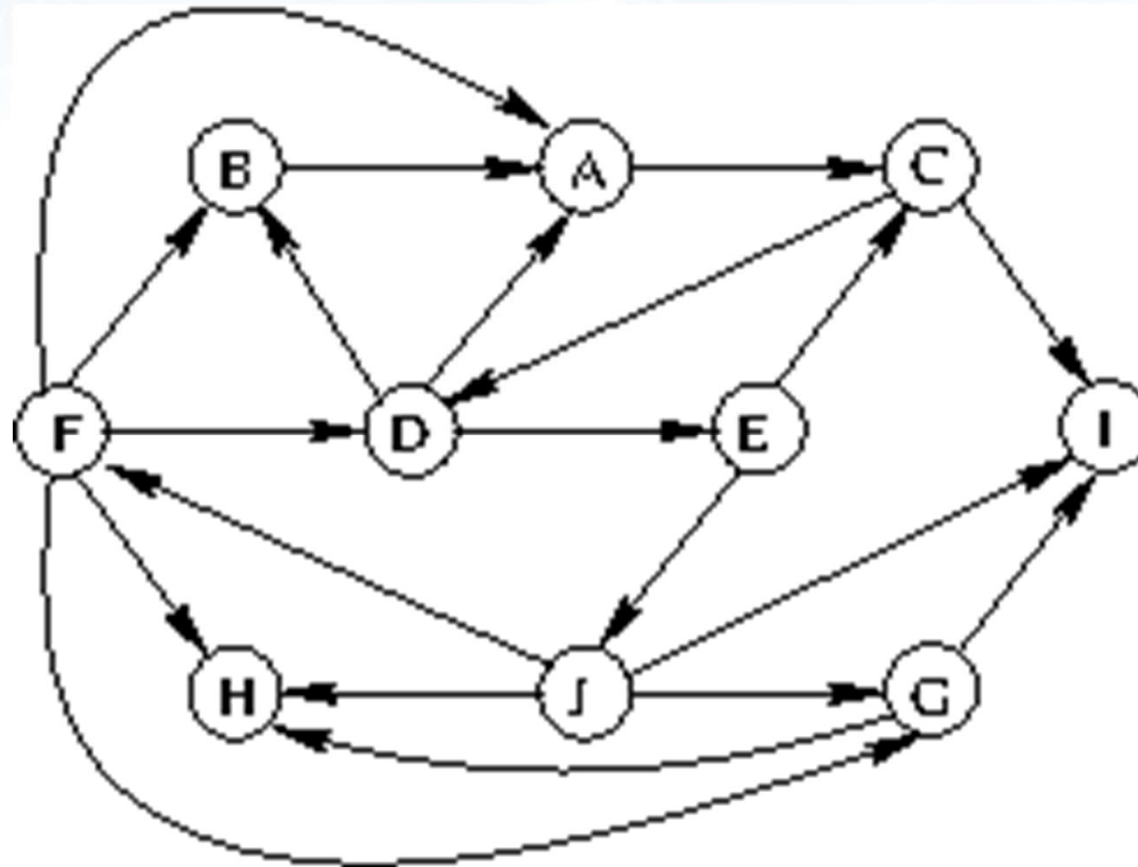


- ❖ Given the previous DAG find the topological order of all vertices

Solution

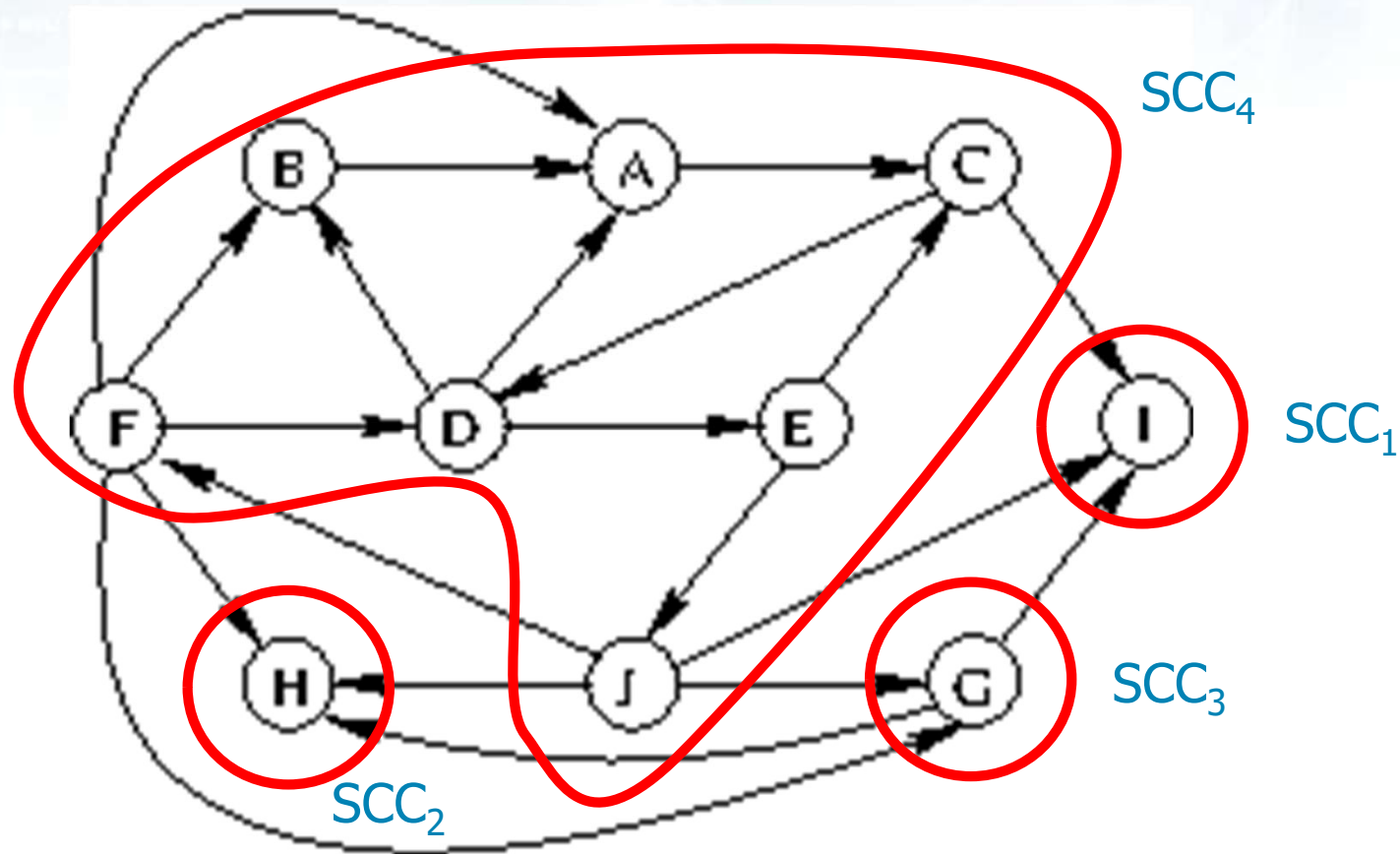


Exercise



- ❖ Given the previous graph, find its SCC

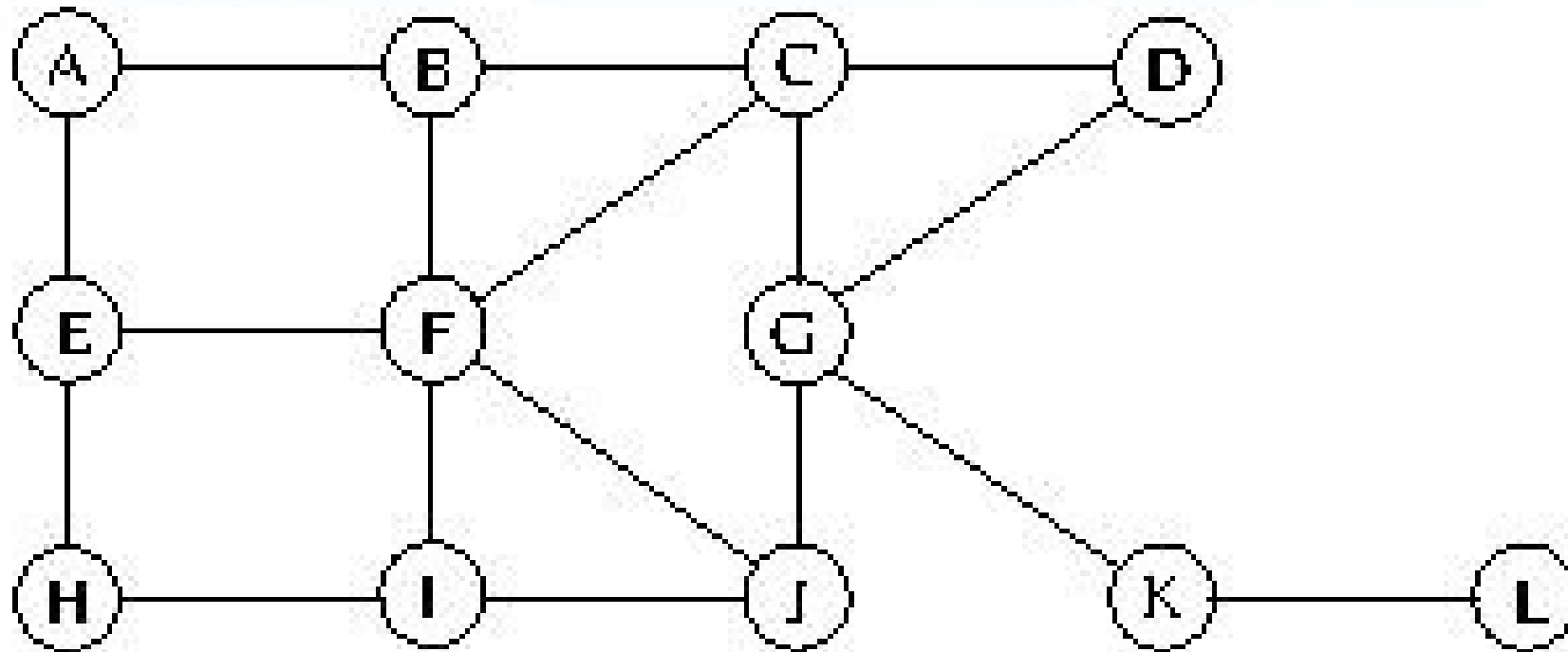
Solution



❖ SCCs

- {I}, {H}, {G}, {A, B, C, D, E, F, J}

Exercise

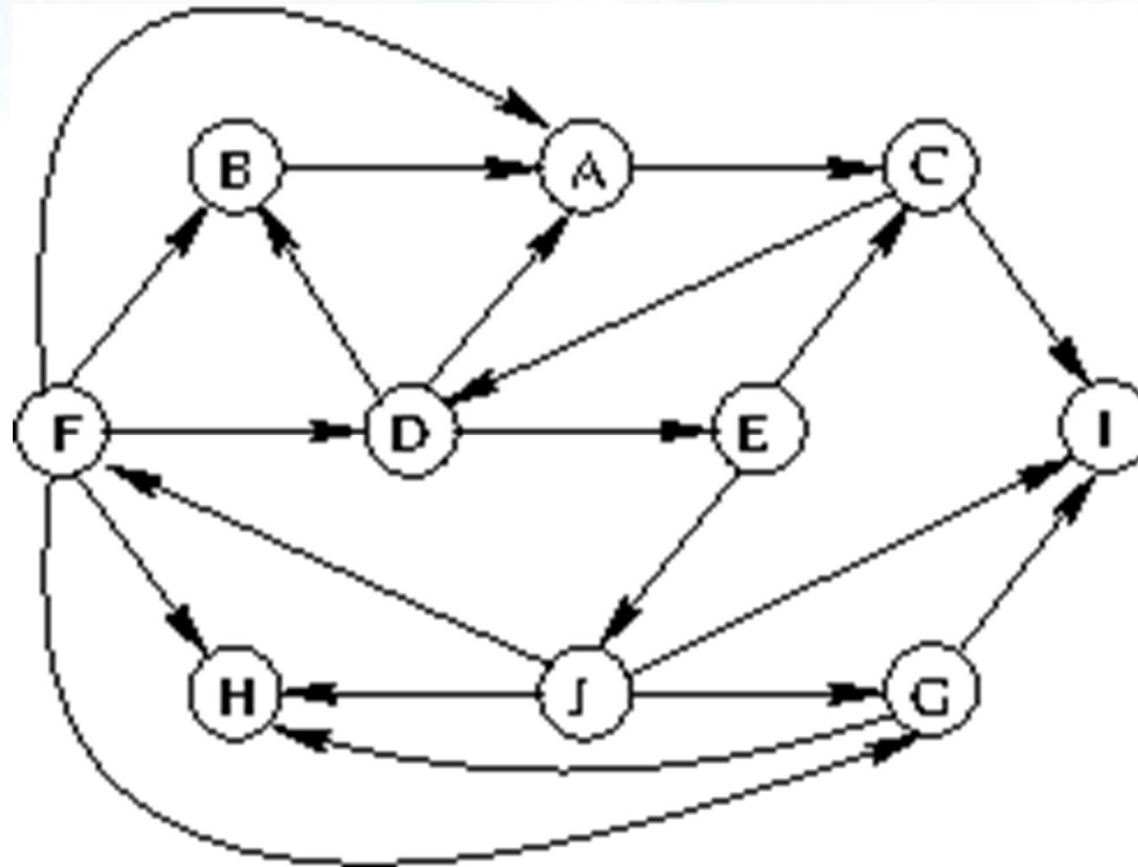


❖ Given the previous graph find articulation points

Solution

- ❖ Articulation points
 - G and K

Exercise



- ❖ Given the previous graph, transform it into an undirected graph and find articulation points, bridges, and connected components

Solution

- ❖ Articulation points
 - None
- ❖ Bridges
 - None
- ❖ Connected Components
 - One with all vertices, $\{A, B, C, D, E, F, G, H, I, J\}$