

## 33B: Notes

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## **Format**

Generally I'll spend the first part (at most  $1/2$ ) of class on exposition, recapping the material from class. The rest of class will be spent on working examples similar to those on your homework.

# 1 Introduction

Differential equations are just equations involving the derivatives of functions. There are partial differential equations - differential equations involving partial derivatives of functions, and ordinary differential equations - differential equations which just involve ordinary derivatives.

We can also classify differential equations by the order of the derivatives they involve:

**Definition 1** (Order). *The order of a differential equation is just the order of the highest order derivative that it involves.*

Differential equations don't specify just one solution, but rather a family of solutions. For instance consider  $x' = 3$ . This equation is solved by  $x = 3t$  and  $x = 3t + 5$ . In general solutions are exactly those equations of the form  $x = 3t + C$ . We call this the *general solution*.

**Definition 2** (General Solution). *The general solution to an ordinary differential equation of order  $n$  is an equation containing  $n$  constants which describes all possible solutions to the equation.*

Often we're interested in one particular solution to a differential equation which satisfies constraints of the form  $y^{(n)}(t) = y_0$ . We call these constraints *initial conditions*. This sort of problem is called an *initial value problem*. It takes  $n$  conditions to fully specify a particular solution to a differential equation of order  $n$ .

Suppose in our example above that in addition to the differential equation  $x' = 3$  we had specified that  $x(5) = 4$ , then we could find a particular solution by first finding the general solution  $x = 3t + C$ , and then plugging in the initial condition:  $x(5) = 3 \cdot 5 + C = 4 \Rightarrow C = -1$ . Our solution is then just  $x(t) = 3t - 1$ .

## Examples

Give some examples of PDE / ODEs of different orders...

Differential equations come up all the time in practical applications. Here's a really simple example problem.

**Example 1.** *A ball is dropped from a height of 100m. It's position as a function of time satisfies the (second order linear) differential equation*

$$\frac{d^2x}{dt^2} = -10m/s^2$$

*When does it hit the ground?*

We should be able to solve this without any new techniques. Just integrate.

$$\frac{d^2x}{dt^2} = -10m/s^2 \Rightarrow \frac{dx}{dt} = -10t + C \Rightarrow x(t) = -5t^2 + Ct + D$$

Of course, this doesn't really specify the location of our ball. We need to use our initial conditions. Since we dropped ball, initial acceleration is  $x'(0) = 0$ , also we are given  $x(0) = 100$ . Substituting these into general solution we have:

$$x'(0) = -10t + C = C = 0$$

and

$$x(0) = -5t^2 + Ct + D = D = 100.$$

Thus, solve

$$0 = x(t) = -5t^2 + 100 \Rightarrow t = \pm\sqrt{20}.$$

Clearly our solution must be positive, so the answer is  $2\sqrt{5}$  seconds.

Of course this is a sort of silly example since we can solve it by integration. We'll solve harder problems later using more sophisticated techniques.

## 2 Chapter 2

### 2.1 Section 1

If we have a purported solution  $y(t)$  to some differential equation, we can check that it's actually valid by differentiating and checking to see that the derivatives satisfy whatever equation they are supposed to satisfy.

**Definition 3** (Interval of Existence). *The interval of existence for an initial value problem is the largest interval on which a solution exists and satisfies the differential equation.*

For instance, the interval of existence for  $x' = 3; x(0) = 0$  is  $(-\infty, \infty)$  since the solution  $x = 3t$  exists, and satisfies the given differential equation for all time.

**Definition 4** (Normal form). *A differential equation is said to be in normal form if it is of the form  $y' = f(y, t)$ .*

Given a first order ODE in normal form  $y' = f(y, t)$  we can draw a vector field describing solutions by drawing small lines of slope  $f(y, t)$  at some collection of points  $(y, t)$ .

### Examples

*Check*

**Example 2** (Exercise 2.1.3). *Check that  $y' = -ty$  is solved by  $y = Ce^{-(1/2)t^2}$*

Just differentiate and compare:

$$y' = -tCe^{-(1/2)t^2} = -ty$$

so it is a solution to the differential equation.

*Interval of Existence*

**Example 3** (Exercise 2.1.13). Find the interval of existence for the differential equation  $y' = \frac{2}{3}t - \frac{5}{3t^2}$  satisfying initial condition  $y(1) = 2$

We can solve by integration:

$$\begin{aligned}\frac{dy}{dt} &= \frac{2}{3}t - \frac{5}{3t^2} \\ dy &= \left( \frac{2}{3}t - \frac{5}{3t^2} \right) dt \\ y &= \frac{1}{3}t^2 + \frac{5}{3t} + C\end{aligned}$$

This is the general solution. If we further demand  $y(1) = 2$

$$y(1) = \frac{1}{3} + \frac{5}{3} + C = 2 \Rightarrow C = 0$$

Therefore

$$y(t) = \frac{1}{3}t^2 + \frac{5}{3t}$$

is the particular solution we're after.

Now that we have the solution it's easy to determine interval of existence. There's an asymptote at  $t = 0$ , so that is the lower end of the interval. The function is continuous as  $t \rightarrow \infty$ , so there is no upper limit. Interval of existence is therefore  $(0, \infty)$ .

*Normal Form*

**Example 4** (Exercise 2.1.1). Put  $\phi(t, y, y') = t^2y' + (1 + t)y = 0$  in normal form.

Just solve for  $y'$ :

$$y' = -\frac{y(1+t)}{t^2}$$

*Vector Field*

**Example 5** (Exercise 2.1.17). Draw vector field for  $y' = y + t$ .

