1 Let G be a compact Lie group. Show that G admits a bi-invariant metric, i.e., both right and left translations are isometries. *Hint:* Fix a left invariant metric g_L and a volume form $\omega = \sigma^1 \wedge \cdots \wedge \sigma^n$ where σ^i are left invariant 1-forms. Then define g as the average over right translations:

$$g(v, w) = \frac{1}{\int \omega} \int g_L(DR_x(v), DR_x(w))\omega.$$

Let g_L be a left invariant metric on G, i.e. $g_L(v, w) = g_L(DL_x(v), DL_x(w))$ for all $x \in G$. Suppose also $\omega = \sigma^1 \wedge \cdots \wedge \sigma^n$ for σ^i left invariant 1-forms, and define as in the hint

$$g(v, w) = \frac{1}{\int \omega} \int g_L(DR_x(v), DR_x(w))\omega.$$

First compute

$$\begin{split} g(DL_y(v),DL_y(w)) &= \frac{1}{\int \omega} \int g_L(DR_x(DL_y(v)),DR_x(DL_y(w)))\omega \\ &= \frac{1}{\int \omega} \int g_L(DL_y(DR_x(v)),DL_y(DR_x(w)))\omega \\ &= \frac{1}{\int \omega} \int g_L(DR_x(v),DR_x(w)) \\ &= g(v,w) \end{split}$$

so g left invariant.

From the right we have

$$g(DR_y(v), DR_y(w)) = \frac{1}{\int \omega} \int g_L(DR_x(DR_y(v)), DR_x(DR_y(w)))\omega$$
$$= \frac{1}{\int \omega} \int g_L(DR_{x \cdot y}(v), DR_{x \cdot y}(w))\omega$$
$$= g(v, w)$$

2 Consider the upper-half plane

$$\mathbb{R}^2_+ = \{(x, y) \in \mathbb{R}^2 \mid y > 0\}$$

with the hyperbolic metric

$$\frac{dx^2 + dy^2}{y^2}.$$

Show that the vertical line segment between (0,1) and (0,2) is the shortest path between these points.

Let $\gamma(t) = \langle \gamma_x(t), \gamma_y(t) \rangle$ be a path $\gamma : [0, a] \to \mathbb{R}^2_+$ with $\gamma(0) = (0, 1)$ and $\gamma(a) = (0, 2)$. Assume without loss of generality that γ is parameterized by (Euclidean) arclength. We can compute

$$|\gamma| = \int_0^a \frac{1}{\gamma_y(t)} \left[\left(\frac{\gamma_x'(t)}{1/\gamma_y(t) \left(\gamma_y'(t)^2 + \gamma_x'(t)^2 \right)} \right)^2 + \left(\frac{\gamma_y'(t)}{1/\gamma_y(t) \left(\gamma_y'(t)^2 + \gamma_x'(t)^2 \right)} \right)^2 \right] dt$$

since we assumed γ arclength parameterized this reduces to

$$|\gamma| = \int_0^a \gamma_y(t)dt.$$

By assumption, $\gamma_y'(t) \in [-1, 1]$. In particular $\gamma_y' \le 1 \Rightarrow \gamma_y(a-t) \ge 2-t$. Notice $a \ge 1$ since γ is arclength parameterized and the Euclidean distance between its endpoints is 1. Now compute:

$$|\gamma| = \int_0^a \gamma_y(t)dt$$

$$\geq \underbrace{\int_0^{a-1} \gamma_y(t)dt}_{(*)} + \int_1^0 (2-t)dt$$

Of course the contribution of (*) is strictly positive if a > 1 since γ_y is restricted to take only positive values. Thus, our bound is tight if and only if a = 1 and $\gamma_y(a - t) = 2 - t$, to wit, when

$$\gamma(t) = \langle 0, 1 + t \rangle$$

as desired.

3 Consider \mathbb{R}^2_+ with the hyperbolic metric as above. Let $v_0 = (0,1)$ be a tangent vector at the point (0,1) of \mathbb{R}^2_+ . Let v(t) be the parallel transport of v_0 along the curve $x=t,\ y=1$. Show that v(t) makes an angle t with the direction of the y-axis, measured in the clockwise sense.

First note that the nonzero components of the metric and respectively inverse metric are just

$$g^{xx} = g^{yy} = y^2$$
 and $g_{xx} = g_{yy} = \frac{1}{y^2}$.

We can therefore reduce the expression for Christoffel symbols

$$\Gamma^m_{ij} = \frac{1}{2} \sum_k \left(\frac{\partial}{\partial x_i} g_{jk} + \frac{\partial}{\partial x_j} g_{ki} - \frac{\partial}{\partial x_k} g_{ij} \right) g^{km} = \frac{y^2}{2} \left(\frac{\partial}{\partial x_i} g_{jm} + \frac{\partial}{\partial x_j} g_{mi} - \frac{\partial}{\partial x_m} g_{ij} \right)$$

Clearly this can only be nonzero if at least one of i, j, m is y and the others coincide. Thus compute:

$$\Gamma^y_{yy} = \Gamma^x_{xy} = \Gamma^x_{yx} = -\frac{1}{y}; \quad \Gamma^y_{xx} = \frac{1}{y}; \quad \Gamma^m_{ij} = 0 \text{ otherwise.}$$

Now let

$$v(t) = \langle \sin t, \cos t \rangle$$
 $x(t) = \langle t, 1 \rangle$ $\dot{x}(t) = \langle 1, 0 \rangle$

and check

$$\frac{dv^x}{dt} + \sum_{i,j} \Gamma^x_{ij} v^j \frac{dx_i}{dt} = \cos t - \frac{1}{y} \cos t = 0 \quad \text{and} \quad \frac{dv^y}{dt} + \sum_{i,j} \Gamma^y_{ij} v^j \frac{dx_i}{dt} = -\sin t + \frac{1}{y} \sin t.$$

- 4 For any $p \in (M, g)$ and orthonormal basis e_1, \ldots, e_n for T_pM , show that there is an orthonormal frame E_1, \ldots, E_n in a neighborhood of p such that $E_i = e_i$ and $(\nabla E_i)|_p = 0$. Hint: Fix an orthonormal frame \overline{E}_i near $p \in M$ with $\overline{E}_i(p) = e_i$. If we define $E_i = \alpha_i^j \overline{E}_j$, where $[\alpha_i^j(x)] \in SO(n)$ and $\alpha_i^j(p) = \delta_i^j$, then this will yield the desired frame provided that the $D_{e_k}\alpha_i^j$ are appropriately prescribed.
- 5 For any point p in a Riemannian manifold (M,g), show that there exist coordinates x^1, \ldots, x^n near p such that $\partial_i = e_i$ and $\nabla \partial_i = 0$ at p.
- 6 Let (M,g) be oriented and define the Riemannian volume form dvol as follows:

$$d\mathbf{vol}(v_1,\ldots,v_n) = \det(g(v_i,e_j)),$$

where e_1, \ldots, e_n is a positively oriented orthonormal basis for T_pM .

- 7 Petersen, Chapter 2, Exercise 11 on p. 58
- 8 Petersen, Chapter 2, Exercise 13 on p. 58