- 1 Give examples of Riemannian manifolds having:
- 1.1 positive scalar curvature but not positive Ricci curvature;

Let $M = S_a^n \times S_b^m$, and X, Y, U, V vector fields with X, Y tangent to S^n , and U, V tangent to S^m . Recall (class, or Petersen p.65) that

$$\Re(X \wedge V) = 0$$
 $\Re(X \wedge Y) = aX \wedge Y$ $\Re(U \wedge V) = bU \wedge V$

$$Ric(X) = (n-1)aX$$
 $Ric(V) = (m-1)bV$ $scal = n(n-1)a + m(m-1)b.$

In particular if we put $M = S^1 \times S^2$ (n = 1, m = 2) we have scal = 2b > 0, but Ric(X) = 0.

1.2 positive Ricci curvature but not positive sectional curvature;

As above, but let $M = S^2 \times S^2$ (m = n = 2). Now Ric(X) = aX > 0, Ric(V) = bV > 0, and $\text{sec}(x, v) = \Re(x \wedge v) = 0$.

1.3 positive sectional curvature but not positive curvature operator.

Recall (Petersen p. 86) that \mathbb{CP}^n has eigenvalues of \mathfrak{R} in [0,6], but $\sec \geq 1$.

2 Show that a Riemannian manifold with parallel Ricci tensor has constant scalar curvature. In chapter 3 it will be shown that the converse is not true, and also that a metic with parallel curvature tensor doesn't have to be Einstein.

We have

$$\nabla \operatorname{scal} = \nabla (\operatorname{tr}(\operatorname{Ric})) = \operatorname{tr}(\nabla \operatorname{Ric}) = 0.$$

Therefore, scal is constant as desired.

3 Let G be a Lie group with a bi-invariant metric. Using left-invariant fields establish the following formulas. *Hint:* First go back to the exercises to chapter 1 and take a peek at chapter 3 where some of these things are proved.

(You can assume the following which are proved in Proposition 12 on p. 79. I suggest you read that proof.)

$$\nabla_X Y = \frac{1}{2}[X,Y]; \quad R(X,Y)Z = \frac{1}{4}[Z,[X,Y]]; \quad g(R(X,Y)Z,W) = -\frac{1}{4}(g([X,Y],[Z,W]))$$

3.1 Show that the curvature operator is also nonnegative by showing that:

$$g\left(\Re\left(\sum_{i=1}^k X_i \wedge Y_i\right), \left(\sum_{i=1}^k X_i \wedge Y_i\right)\right) = \frac{1}{4} \left|\sum_{i=1}^k [X_i, Y_i]\right|^2.$$

Compute:

$$g\left(\Re\left(\sum_{i=1}^{k} X_i \wedge Y_i\right), \left(\sum_{i=1}^{k} X_i \wedge Y_i\right)\right) = \sum_{1 \leq i, j \leq k} R(X_i, Y_i, Y_j, X_j)$$

$$= \frac{1}{4} \sum_{1 \leq i, j \leq k} g\left([X_i, Y_i], [X_j, Y_j]\right)$$

$$= \frac{1}{4} \left|\sum_{i=1}^{k} [X_i, Y_i]\right|^2$$

3.2 Show that Ric(X, X) = 0 iff X commutes with all other left-invariant vector fields. Thus G has positive Ricci curvature if the center of G is discrete.

Fixing a basis for T_eM , observe that X commutes with all left-invariant vector fields if and only if $[X, E_i] = 0$ for the left-invariant $E_i(e) = e_i$. However,

$$0 = \text{Ric}(X, X) = \sum_{i=1}^{n} g(R(E_i, X)X, E_i)$$

if and only if

$$0 = g(R(E_i, X)X, E_i) = \frac{1}{4}g([E_i, X], [E_i, X])$$

for all i.

3.3 Consider the linear map $\Lambda^2 \mathfrak{g} \stackrel{p}{\to} [\mathfrak{g}, \mathfrak{g}]$ that sends $X \wedge Y$ to [X,Y]. Show that the sectional curvature is positive iff this map is an isomorphism. Conclude that this can only happen if n=3 and $\mathfrak{g}=\mathfrak{su}(2)$.

Clearly the given map is onto. It is therefore an isomorphism exactly when it is an injection, i.e. when $[X,Y]=0 \iff X=\alpha Y$. Of course,

$$\sec(v, w) = \frac{g(R(w, v)v, w)}{g(v \land w, v \land w)}$$
$$= \frac{g([v, w], [v, w])}{4g(v \land w, v \land w)}$$

which is positive if and only if |[v, w]| > 0 for all $v \neq \lambda w$.

Now if $\dim \mathfrak{g} = n$ we have $\dim \Lambda^2 \mathfrak{g} = \frac{1}{2}n(n-1)$ and, since the derived Lie algebra is a subalgebra, $\dim [\mathfrak{g}, \mathfrak{g}] \leq \dim \mathfrak{g}$. Therefore for the desired isomorphism to occur we must have

$$\frac{1}{2}n(n-1) \le n \iff 0 \le n \le 3.$$

4 Consider a Riemannian metric (M,g). Now *scale* the metric by multiplying it by a number λ^2 . Then we get a new Riemannian manifold (M,λ^2g) . Show that the new connection and (1,3)-curvature tensor remain the same, but that sec, scal, and \Re all get multiplied by λ^{-2} .

The Levi-Civita connection is given by

$$g(\nabla_X Y, Z) = \frac{1}{2} \{ X(g(Y, Z)) + Y(g(Z, X)) - Z(g(X, Y)) + g([X, Y], Z) - g([Y, Z], X) - g([X, Z], Y) \}$$

which formula is invariant under scaling of the metric. Similarly, the (1,3)-curvature tensor is defined soley in terms of the connection so ∇ remaining unchanged means that R is as well.

Denote the scaled metric g' and compute

 $g'(x \wedge y, v \wedge w) = g'(x, v)g'(y, w) - g'(x, w)g'(y, v) = \lambda^{4}(g(x, v)g(y, w) - g(x, w)g(y, v)) = \lambda^{4}g(x \wedge y, v \wedge w).$

Therefore if \mathfrak{S} denotes the scaled curvature operator we have

$$\begin{split} \lambda^4 g(\mathfrak{S}(X \wedge Y), V \wedge W) &= \\ g'(\mathfrak{S}(X \wedge Y), V \wedge W) &= R'(X \wedge Y, V \wedge W) \\ &= g'(R(X, Y)Z, W) \\ &= \lambda^2 g(R(X, Y)Z, W). \end{split}$$

So, \mathfrak{S} , defined by the relation $g(\mathfrak{S}(X \wedge Y), V \wedge W) = \frac{1}{\lambda^2} g(R(X, Y)Z, W)$ is precisely \mathfrak{R}/λ^2 as desired. Finally compute

$$\sec'(v,w) = \frac{g'(\mathfrak{S}(v \wedge w), v \wedge w)}{g'(v \wedge w, v \wedge w)} = \frac{1}{\lambda^2} \frac{g(\mathfrak{R}(v \wedge w), v \wedge w)}{g(v \wedge w, v \wedge w)} = \frac{1}{\lambda} \sec(v,w)$$

and

$$\operatorname{scal}' = 2 \cdot \operatorname{tr} \mathfrak{S} = \frac{2}{\lambda^2} \operatorname{tr} \mathfrak{R} = \frac{1}{\lambda^2} \operatorname{scal}.$$

Recall that complex manifolds have complex tangent spaces. Thus we can multiply vectors by $\sqrt{-1}$. As a generalization of this we can define an *almost complex* structure. This is a (1,1)-tensor J such that $J^2 = -I$. Show that the *Nijenhuis tensor:*

$$N(X,Y) = [J(X), J(Y)] - J([J(X), Y]) - J([X, J(Y)]) - [X, Y]$$

is indeed a tensor. If J comes from a complex structure then N=0, conversely Newlander & Nirenberg have shown that J comes from a complex structure if N=0.

A *Hermitian structure* on a Riemannian manifold (M, g) is an almost complex structure J such that

$$g(J(X), J(Y)) = g(X, Y).$$

The Kähler form of a Hermitian structure is

$$\omega(X,Y) = g(J(X),Y).$$

Show that ω is a 2-form. Show that $d\omega = 0$ iff $\nabla J = 0$. If the Kähler form is closed, then we call the metric a Kähler metric.

To confirm tensoriality we compute:

$$\begin{split} N(X,fY) &= [J(X),fJ(Y)] - J([J(X),fY]) - J([X,fJ(Y)]) - [X,fY] \\ &= J(X)(f)J(Y) + f[J(X),J(Y)] - J(J(X)(f)Y + f[J(X),Y]) \\ &- J(X(f)J(Y) + f[X,J(Y)]) - X(f)Y - f[X,Y] \\ &= f[J(X),J(Y)] - fJ([J(X),Y]) + f[X,J(Y)]) - f[X,Y] \\ &= f \cdot N(X,Y) \end{split}$$

$$N(X, A + B) = [J(X), J(A + B)] - J([J(X), A + B]) - J([X, J(A + B)]) - [X, A + B]$$

= $N(X, A) + N(X, B)$

and similarly in the first place.

Tensoriality of ω is immediate. For antisymmetry compute:

$$\omega(Y,X)=g(J(Y),X)=g(J^2(Y),J(X))=-g(J(X),Y)$$

6 There is a strange curvature quantity we have not yet mentioned. Its definition is somewhat cumbersome and nonintuitive. First, for two symmetric (0,2)-tensors h,k define the *Kulkarni-Nomizu product* as the (0,4)-tensor

$$h \circ k(v_1, v_2, v_3, v_4) = h(v_1, v_4) \cdot k(v_2, v_3) + h(v_2, v_3) \cdot k(v_1, v_4)$$
$$-h(v_1, v_3) \cdot k(v_2, v_4) - h(v_2, v_4) \cdot k(v_1, v_3).$$

Note that (M,g) has constant curvature c iff the (0,4)-curvature tensor satisfies $R=c\cdot(g\circ g)$. If we use the (0,2) form of the Ricci tensor, then we can decompose the (0,4)-curvature tensor as follows in dimensions $n\geq 4$

$$R = \frac{\operatorname{scal}}{2n(n-1)}g \circ g + \frac{1}{n-2}\left(\operatorname{Ric} - \frac{\operatorname{scal}}{n} \cdot g\right) \circ g + W$$

When n = 3 we have instead

$$R = \frac{\operatorname{scal}}{12} g \circ g + \left(\operatorname{Ric} - \frac{\operatorname{scal}}{3} \cdot g \right) \circ g.$$

The (0,4)-tensor W defined for n>3 is called the Weyl tensor.

6.1 Show that these decompositions are orthogonal, in particular:

$$|R|^2 = \left| \frac{\operatorname{scal}}{2n(n-1)} g \circ g \right|^2 + \left| \left(\operatorname{Ric} - \frac{\operatorname{scal}}{n} \cdot g \right) \circ g \right|^2 + |W|^2.$$

- 6.2 Show that if we conformally change the metric $\tilde{g} = f \cdot g$, then $\tilde{W} = f \cdot W$.
- **6.3** If (M, g) has constant curvature, then W = 0.
- 6.4 If (M, g) is locally conformally equivalent to the Euclidean metric, i.e., locally we can always find coordinates where:

$$g = f \cdot \left((dx^1)^2 + \dots + (dx^n)^2 \right),\,$$

then W=0. The converse is also true but much harder to prove.

Assume that we have a Riemannian immersion of an n-manifold into \mathbb{R}^{n+1} . If $n \geq 3$, then show that it can't have negative curvature. If n = 2 give an example where it does have negative curvature.

The sectional curvature is given by $K(X_i, X_j) = k_i k_j$ where the k_i are eigenvalues of the second fundamental form. These cannot all be negative for dim > 2 for purely combinatorial reasons. Suppose $k_1 k_2, k_2 k_3, k_1 k_3$ are all negative. Then exactly one of k_1, k_2 negative. Say WLOG k_1 . Then as $k_1 k_3$ negative, $k_3 > 0$. Thus $k_3 k_2 > 0$ contradiction.

Consider the saddle embedded in \mathbb{R}^3 . This has negative curvature at the saddle point.

8 Let (M,g) be a closed Riemannian n-manifold, and suppose that there is a Riemannian embedding into \mathbb{R}^{n+1} . Show that there must be a point $p \in M$ where the curvature operator $\mathfrak{R}: \Lambda^2 T_p M \to \Lambda^2 T_p M$ is positive. *Hint:* Consider $f(x) = |x|^2$ and restrict it to M, then check what happens at a maximum.