

## Lecture 19: Monte Carlo Basics

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## 19.1 History

We started with Monte Carlo in the past few lectures. The main method is to use draw samples from a proposal distribution and take sample average to approximate expectations.

$$\begin{aligned}\mathbb{E}_{y \sim p(y|x)}[f(y)] &= \int p(y|x) f(y) dy \\ &\approx \frac{1}{N} \sum_{n=1}^N f(\tilde{y}^{(n)})\end{aligned}$$

where  $\tilde{y}^{(n)} \sim p(y|x)$ . This approach requires the ability to sample  $y \sim p(y|x)$ .

## 19.2 Univariate Case

Let's start at the beginning: We know  $F(x) = p(y \leq x)$  and it is univariate. Assume we can compute  $F^{-1}(u)$ , then

$$p(F^u \leq x) = p(u \leq F(x)) = F(x)u$$

where  $F$  is the CDF of  $u \sim \text{Unif}(0,1)$ . However, this works only for univariate case. What this means is that, if we wish to sample  $y \sim F$  for some known CDF  $F$ , we need only to sample  $U \sim \text{Unif}$  and transform the sample of uniform random variables through  $F^{-1}$  to get a sample of  $y$ . Formally,

$$U \sim \text{Unif} \implies F^{-1}(U) \sim F$$

(This is known as the probability integral transform).

## 19.3 Normal Samples

We pursue the same strategy as in the univariate case. Given Uniform samples, we wish to apply some transform to obtain a sample of multivariate random variables of some distribution we are interested in. We execute this strategy for Normal random variables (this is known as the Box-Muller transformation). The upshot here is that to sample Normal random variables, we need only to sample Uniform random variables, which is much easier to do.

**Box-Muller** Sample  $z_1, z_2 \sim \text{Unif}[-1, 1]$ . Discard the points outside of the unit circle, so our sample of  $\{(z_1, z_2)\}$  is uniform on the unit disk. We would like to transform each  $(z_1, z_2)$  into some  $(x_1, x_2) \sim \mathcal{N}(0, I)$ . We want to find the right transform such that the Jacobian makes the following hold

$$\overbrace{p(x_1, x_2)}^{\text{Normal PDF}} = \overbrace{p(z_1, z_2)}^{\text{Unif disk PDF}} \left| \frac{\partial(z_1, z_2)}{\partial(x_1, x_2)} \right|.$$

We may check that

$$\begin{aligned} x_1 &= z_1 \left( \frac{-2 \log r^2}{r^2} \right)^{1/2} \\ x_2 &= z_2 \left( \frac{-2 \log r^2}{r^2} \right)^{1/2}, \end{aligned}$$

where  $r^2 = z_1^2 + z_2^2$ , is the desired transform.

**Exercise:** Box-Muller shows how to sample from a normal distribution with each component being independent. Suppose now, however, that we are given  $z_1, \dots, z_n \sim \text{Unif}[-1, 1]$  and we wish to sample from  $\mathcal{N}(\mu, \Sigma)$ , which is the general Multivariate Normal distribution with  $n$  components. How can you do this?

**Solution:** First, we can note that we can transform our  $n$  uniform distributions into  $n$  independent standard Normals  $x_1, \dots, x_n$  (through Box-Muller). Then, we can realize that if we can sample from  $\mathcal{N}(0, \Sigma)$ , then we will be able to sample from  $\mathcal{N}(\mu, \Sigma)$  simply by adding  $\mu$  to our sampled vector from the de-meaned distribution.

Thus, the only thing that remains is being able to sample from the de-meaned distribution. First, we argue that because  $\Sigma$  must be positive semi-definite, then there must exist an  $A$  such that  $\Sigma = AA^\top$  (we can find such a square root of  $\Sigma$  for instance through a Cholesky decomposition). Now, we argue that if we denote,

$$x = [x_1 \quad \dots \quad x_n]^\top$$

then

$$Ax \sim \mathcal{N}(0, \Sigma)$$

because

$$\text{Var}(Ax) = E[(Ax)(Ax)^\top] = E[A(xx^\top)A^\top] = AIA^\top = AA^\top = \Sigma,$$

$E[Ax] = 0$ , and  $Ax$  must be distributed as a multivariate Normal because it is the linear combination of Normal random variables, which shows us how to sample from a general Multivariate Normal distribution starting out from uncorrelated uniform random variables.

**Exercise:** From the probability inverse transform, we see that we can sample from any distribution using a uniform random variable. How can we generate a uniform random variable from an infinite stream of Bernoulli random variables (with parameter  $p = .5$ ).

**Solution:** Let our infinite stream be  $B_1, \dots$ , and then take,

$$U = \sum_{i=1}^{\infty} \frac{B_i}{2^i}$$

which we claim is distributed as a uniform random variable. We can show this by showing that the probability that this quantity is less than some quantity  $x$  is  $x$  (and thus that the CDF is  $F(x) = x$ ). In particular, write  $x$  in binary such that  $x = 0.b_1b_2\dots$ . Then, the event that  $U$  is less than  $x$  is equal to the event that

$$b_m = 1 \text{ where } m = \arg\min_i b_i \neq B_i.$$

Thus, the probability that  $m = i$  is given by  $2^{-i}$ , and using the law of total probability, we get,

$$F(x) = \sum_{i=1}^{\infty} \frac{b_i}{2^i} = x$$

by construction of the binary expansion, as desired. Thus, given sufficient random coin tosses, we can sample from a uniform distribution to arbitrary precision.

## 19.4 Rejection Sampling

Assume that we have access to the PDF  $p(x)$  or the unnormalized PDF  $\tilde{p}(x)$ . The idea is to pick a **guide function** (valid PDF)  $q(x)$  that is similar to  $p$  and easy to compute. We also pick a **scale**  $M$ . We require that

$$Mq(x) > p(x)$$

for all  $x$  and that we have access to  $p(x)$  or  $\tilde{p}(x)$ . The algorithm is as follows:

1. Sample  $x_n \sim q(x)$
2. Draw  $u \sim \text{Unif}[0, 1]$
3. If  $u < \frac{p(x_n)}{Mq(x_n)}$ , then keep  $x_n$ ; otherwise, rerun from 1.

The interpretation is simple. The algorithm “graphs”  $p(x)$  and the bounding  $Mq(x)$  on a board, then proceeds to throw darts at the board and accepting those darts that hit below  $p(x)$ . The same algorithm works even if  $\tilde{p}$  is unnormalized, since we have the degree of freedom to choose  $M$  and thus absorb the normalizing constant.

This method works with  $\frac{\tilde{p}(x)}{Z} = p(x)$ . But why should it work?

**ANS** This works because for whatever guide function we pick, we can write that guide function to be:

$$\tilde{M} = ZM$$

### 19.4.1 Proof of Rejection Sampling

$$\begin{aligned} p(x \leq x_0 | \text{is accepted}) &= \frac{\int_{-\infty}^{x_0} \int_0^1 q(x) 1(u \leq \frac{\tilde{p}(x)}{Mq(x)}) du dx}{\int_{-\infty}^{\infty} \int_0^1 q(x) 1(u \leq \frac{\tilde{p}(x)}{Mq(x)}) du dx} \\ &= \frac{\frac{1}{M} \int_{-\infty}^{x_0} \tilde{p}(x) dx}{\frac{1}{M} \int_{-\infty}^{\infty} \tilde{p}(x) dx} \quad \text{the denominator is probability the acceptance} \\ &= \int_{-\infty}^{x_0} p(x) dx \\ &= p(x \leq x_0) \end{aligned}$$

## 19.5 Examples for Rejection Sampling

1. In Bayesian statistics, we often encounter the following problem. We are given  $p(\theta)$ ,  $p(x|\theta)$ , and we wish to sample from the posterior  $p(\theta|x)$ . We can compute the unnormalized posterior  $\tilde{p}(\theta|x) = p(x|\theta)p(\theta)$ . Set  $q(\theta) = p(\theta)$ . Choose  $M = p(x|\hat{\theta})$ , where  $\hat{\theta}$  is the maximum likelihood estimator. Then  $Mq \geq p$ . Thus, rejection sampling says the following. Sample from the prior  $q(\theta) = p(\theta)$ , roll a uniform  $u$ , and keep those  $\theta \sim p(\theta)$  with

$$u \leq \frac{p}{Mq} = \frac{p(x|\theta)}{p(x|\hat{\theta})} \leq 1.$$

2. Let  $p \sim \mathcal{N}(0, \sigma_p^2 I)$  and  $q \sim \mathcal{N}(0, \sigma_q^2 I)$  where  $\sigma_q^2 > \sigma_p^2$ . Pick

$$M = (\sigma_q / \sigma_p)^D,$$

where  $D$  is the dimension of the Multivariate Normal. Note that  $M$  becomes very large when  $D$  becomes large, and so rejection sampling may be inefficient when  $D$  is large. If we imagine  $M$  as the metric of which to boost the Gaussians to make random sampling work, due to the known geometry of Gaussian distributions we can imagine as  $D$  increase there will be more and more "space" between  $p$  and  $q$  to fill, thus making Random Sampling quite difficult.

## 19.6 Importance Sampling

We want to approximate the expectation

$$\mathbb{E}_{x \sim p}(f(x)) = \int f(x)p(x) dx.$$

So far, we can sample a bunch of points—via, say, rejection sampling—from  $p$  and calculate a sample mean to approximate the true expectation. If the structure of  $p$  and the structure of  $f$  are very different, so Monte Carlo methods so far might be inefficient, since it samples from high density areas in  $p$ , which may have very low values of  $f$ , and the Monte Carlo may miss areas with high values of  $f$  but low probability of happening.

Consider the integral

$$\int q(x) \frac{p(x)}{q(x)} f(x) dx = \mathbb{E}_q \left( f(x) \frac{p(x)}{q(x)} \right) = \mathbb{E}_p(f(x)).$$

We may now apply the same Monte Carlo trick to sample from  $q$  and take the sample mean of  $f(x)p(x)/q(x)$ .

What is the benefit of using  $q$ ? Since we can choose  $q$  to be closer to  $f$ , then more of the sample we choose would be around high values of  $f$ . Here we don't need to wait for some low-probability tail event in  $p$  to happen in order to get reliable estimates of  $\mathbb{E}_p(f(x))$ . Instead, we can directly look at the tail events via  $q$  and weight the data appropriately using  $p/q$  to still maintain asymptotic convergence.

How exactly do we choose  $q$ ? We want to minimize the variance of  $f(x)p(x)/q(x)$  when  $x \sim q$ , since this allows for faster convergence. Then

$$\begin{aligned} \text{Var} \left( \frac{f(x)p(x)}{q(x)} \right) &= \mathbb{E} \left[ \left( \frac{f(x)p(x)}{q(x)} \right)^2 \right] - \underbrace{\left( \mathbb{E} \left( \frac{f(x)p(x)}{q(x)} \right) \right)^2}_{\text{constant eventually}} \\ \mathbb{E} \left( \frac{f(x)p(x)}{q(x)} \right)^2 &\geq \left( \mathbb{E}_q \left( \frac{p(x)|f(x)|}{q(x)} \right) \right)^2 && \text{(Jensen's inequality)} \\ &= \left( \int p(x)|f(x)| dx \right)^2 \end{aligned}$$

We minimize the lower bound via Jensen's inequality (similar to what we did in variational inference). The optimal  $q$  is chosen via

$$q^* = \frac{|f(x)|p(x)}{\int |f(x)|p(x) dx}.$$

It may be difficult to normalize  $q^*$  in practice, however.

$$\begin{aligned} \mathbb{E}_p[f(x)] &= \int p(x)f(x)dx \\ &\approx \frac{1}{N} \sum_{n=1}^N f(\tilde{x}^{(n)}) \end{aligned}$$

where  $\tilde{x}^{(n)} \sim p(x)$

**Exercise:** Approximate  $\int_0^\pi x \sin(x) dx$  using importance sampling.

**Solution:** See `importancesampling.ipynb` in the same directory.