PROJECTIVE METRICS

Gabor Riccardi

University of Pavia (UniPv)

with **Hugo Sauerbier Couvée**, Technical University of Munich (TUM)

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You can declare different parts as a parent f sections

PART I: DEMO PRESENTATION PART

PART II: DEMO PRESENTATION PART 2

Part

MOTIVATION

THE PROBLEM

ENERGY TRANSITION

- ► Shift from fossil fuels to renewables
- ► Increasing role of wind and solar energy
- ► Challenges: Variability and storage

THE DUCK

papera

THE SOLUTION

- ▶ Balancing generation and demand
- ► Energy storage as key enabler

NUCLEAR?

- ► Too expensive?
- ▶ Public opposition?
- ► Political challenges?

ENERGY STORAGE

- ► Batteries (short-term)
- ► Hydrogen (long-term)
- ► Pumped hydro

CHALLENGES IN ENERGY MODELING

- ► Huge computational costs in high-resolution models
- ► Need for accurate long-term planning
- ► Trade-off between accuracy and efficiency

EXISTING METHODS

- ► Stochastic programming (computationally expensive)
- ► Robust optimization (conservative approach)
- ► Rolling horizon techniques

PROPOSED APPROACH

- ► Structure-preserving time series aggregation
- ► Iterative refinement process
- ► Heuristic-based selection of time intervals to refine

MATHEMATICAL FORMULATION

- ► Linear programming model
- ► Aggregation reduces problem size
- ► Iterative refinement ensures accuracy

AGGREGATION TECHNIQUES

- ► Rolling horizon validation
- ► Selection heuristics (variance-based, failure-based)

COMPUTATIONAL RESULTS

- ► 5-node network simulation
- ► Comparison of random vs heuristic-based refinement
- ► Faster convergence with structure-preserving methods

CONCLUSION

- ► Time series aggregation reduces computational costs
- ► Preserves structure and accuracy
- ▶ Further work: Adaptive heuristics and dynamic adjustments

PROBLEM DESCRIPTION

We consider a two stage stochastic program consisting of a Capacity Expansion Problem (CEP) and an Economic Dispatch (ED) problem:

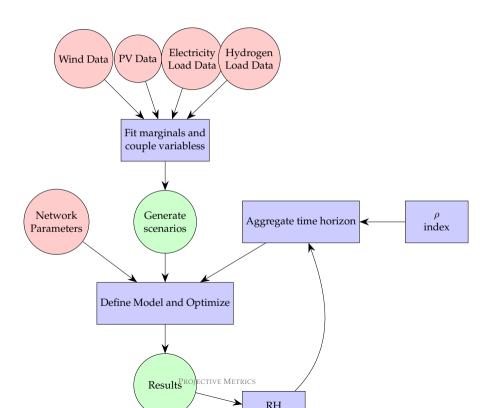
$$\min_{x} c'x + \mathbb{E}_{\omega} [\mathcal{V}(x, \omega)]$$
s.t. $0 \le x \le x^{max}$

- ▶ The first stage determines the optimal capacities *x* for each component of the power grid.
- ▶ The second stage solves the Economic Dispatch for a given time horizon in function of the capacities x and the scenario ω , yielding $\mathcal{V}(x,\omega)$ as solution.

TIME SERIES AGGREGATION METHOD

Give various examples of what has been used

Workflow



GABOR RICCARDI

MODEL - VARIABLES

- ► The grid is modelled as an undirected graph $(\mathcal{N}, \mathcal{E} = \mathcal{E}_P \cup \mathcal{E}_H)$.
- ► CEP variables include:
 - for each node $n \in \mathcal{N}$, number of generators (ns_n, nw_n) and capacities for hydrogen management $(nh_n, mhte_n, meth_n)$;
 - for each edge $l \in \mathcal{E}$, capacity expansion for electricity and hydrogen transmission.
- ▶ ED variables include, for each scenario *j* and time-step *t*:
 - for each node $n \in \mathcal{N}$, stored hydrogen $(H_{j,t,n})$ and hydrogen-electricity conversion $(HtE_{j,t,n}, EtH_{j,t,n})$;
 - for each edge $l \in \mathcal{E}$, electricity and hydrogen transmission.

MODEL - OBJECTIVE FUNCTION

$$\begin{aligned} & & \sum_{n \in \mathcal{N}} (\mathsf{cs}_n \cdot \mathsf{ns}_n + & \mathsf{cw}_n \cdot \mathsf{nw}_n + \mathsf{ch}_n \cdot \mathsf{nh}_n) + \\ & + & \sum_{n \in \mathcal{N}} (\mathsf{cmhte}_n \cdot \mathsf{m} & \mathsf{hte}_n + \mathsf{cmeth}_n \cdot \mathsf{meth}_n) + \\ & + & \sum_{l \in \mathcal{E}_p} (\mathsf{cNTC}_l \cdot \mathsf{ad} & \mathsf{dNTC}_l) + \sum_{l \in \mathcal{E}_H} (\mathsf{cMH}_l \cdot \mathsf{addMH}_l) + \\ & + & \frac{1}{d} \sum_{j=1}^d \sum_{t=1}^T \left(\sum_{n \in \mathcal{N}} (& \mathsf{chte}_n \cdot \mathsf{HtE}_{j,t,n} + \mathsf{ceth}_n \cdot \mathsf{EtH}_{j,t,n}) + \\ & + \sum_{l \in \mathcal{E}_H} (\mathsf{cH_edge}_l \cdot \mathsf{H_edge}_{j,t,l}) \right) \end{aligned}$$

MODEL - CONSTRAINTS

For all nodes $n \in \mathcal{N}$, time steps $t \in \{1...T\}$ and scenarios $j \in J$:

Electricity Balance:

$$\operatorname{ns}_{n} \cdot \operatorname{ES}_{j,t,n} + \operatorname{nw}_{n} \cdot \operatorname{EW}_{j,t,n} - \operatorname{EL}_{j,t,n} + \\
+ 0.033 \cdot \operatorname{fhte}_{n} \cdot \operatorname{HtE}_{j,t,n} - \operatorname{EtH}_{j,t,n} + \\
+ \sum_{l \in \operatorname{Out}(n)} \operatorname{P_edge}_{j,t,l} + \sum_{l \in \operatorname{In}(n)} \operatorname{P_edge}_{j,t,l} \ge 0;$$
(1)

Hydrogen Storage:

$$H_{j,t+1,n} = H_{j,t,n} - HL_{j,t,n} + + 30 \cdot feth_n \cdot EtH_{j,t,n} - HtE_{j,t,n} + - \sum_{l \in Out(n)} H_{-}edge_{j,t,l} + \sum_{l \in In(n)} H_{-}edge_{j,t,l}$$
(2)

MODEL - CONSTRAINTS

Variables of the inner ED problem are bound by the respective capacities to be determined in the CEP.

For all time steps $t \in \{1...T\}$, scenarios $j \in J$ and nodes $n \in \mathcal{N}$:

Storage Capacity Limit:
$$H_{i,t,n} \le nh_n$$
; (3)

EtH Conversion Limit:
$$EtH_{j,t,n} \le meth_n;$$
 (4)

HtE Conversion Limit:
$$\text{HtE}_{j,t,n} \leq \text{mhte}_n$$
. (5)

For all time steps $t \in \{1...T\}$, scenarios $j \in J$ and edges $l \in \mathcal{E}_P$ and $l \in \mathcal{E}_H$ respectively:

Net Transfer Capacity:
$$P_{-}edge_{j,l,l}^{\pm} \leq NTC_l + addNTC_l;$$
 (6)

$$H_2$$
 Transfer Capacity: $H_{-}edge_{i,t,l}^{\pm} \le MH_l + addMH_l$. (7)

VALIDATION THROUGH ROLLING HORIZON

Consider a solution \mathbf{x}_{CEP} to the Capacity Expansion Problem solved over train scenarios J_{train} and a test scenario $\hat{\jmath}$.

Rolling Horizon algorithm:

- 1. Initialization: Set $H_{0,n}^{test} = \max_{j \in J_{train}} H_{j,0,n}$.
- 2. **Daily Iteration:** For each day in the time horizon:
 - Optimize the inner Economic Dispatch problem for the given day. If the problem is infeasible, terminate the process.
 - Update the hydrogen storage levels: $H_{0,n}^{day+1} = H_{24,n}^{day}$.

Credit: Glomb et al. 2022

VALIDATION THROUGH ROLLING HORIZON

Definition 4.1

We consider \mathbf{x}_{CEP} to be **RH-feasible** over scenario $\hat{\jmath}$ if the Rolling Horizon optimization algorithm terminates at the end of the year and $H_{\hat{\jmath},T,n} \geq H_{\hat{\jmath},0,n}$ for all nodes $n \in \mathcal{N}$.

Note: the solution $\mathcal{V}_{RH}(\mathbf{x}_{CEP}, \hat{\jmath})$ to the inner ED problem given by the RH is not necessarily optimal, and conversely, solutions \mathbf{x}_{CEP} that are feasible for the perfect foresight ED aren't necessarily RH-feasible.

To incentivize better hydrogen storage management in the RH, we define positive variables $loss_{t,n}$ for each time step t and node n, with positive cost, and add the contraints:

$$loss_{t,n} \geq \frac{1}{d} \left(\sum_{j \in J_{train}} H_{j,t,n} \right) - H_{t,n}^{test}$$
(8)

TIME AGGREGATION

Consider a time aggregation $\{I_0,...,I_n\} \subseteq \mathcal{P}(\{1,...,8760\})$. For all time dependent variables for the inner ED problem, define the aggregated variables as follows:

$$EtH_{j,I,n} = \sum_{i \in I} EtH_{j,i,e}, \qquad HtE_{j,I,e} = \sum_{i \in I} HtE_{j,i,e}.$$

Similarly for $\Delta H_{j,I,e}$, $P_edge^{\pm}_{j,I,e}$ and $H_edge^{\pm}_{j,I,e}$, separately on the two directions. Define the aggregated scenario parameters as:

$$ES_{j,I,n} := \sum_{i \in I} ES_{j,i,n}, \quad EW_{j,I,n} := \sum_{i \in I} EW_{j,i,n}$$

and similarly for $HL_{j,I,n}$ and $HR_{j,I,n}$.

Proposition

The linear problem defined through the above is a relaxation of the unaggregated problem.

TIME AGGREGATION

Algorithm: iterations on time aggregations

- 1. Set up the model environment with enough variables for the iterations to come. Impose the constraints relative to an initial time partition, and solve.
- 2. Select a day using a given selection method.
- 3. Add the constraints relative to each hour of the selected day. Solve the model using a warm start.
- 4. Repeat step 2 and 3 until a given *halting condition* is met.

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