

o

Krug treba biti pritisnut na joysticku jednom da raspberry pocne izvorsavati naredbe.

<http://floortest.dbtouch.com/test/getNextCommand>

Raspberry je polla da dobije naredbu

<http://floortest.dbtouch.com/test/resetCommands>

Poništi sve komande u queue za robota.

<http://floortest.dbtouch.com/test/go?command=followmillimeter&description=mainline&value=1000>

<http://floortest.dbtouch.com/test/go?command=turn&description=left&value=180>

<http://floortest.dbtouch.com/test/go?command=followmarker&description=mainline&value=1>

<http://floortest.dbtouch.com/test/go?command=followmarker&description=mainline&value=-1>

<http://floortest.dbtouch.com/test/go?command=followmillimeter&description=mainline&value=2000&restartpos=1>

Prosljeđujem parameter restartpos=1 da se kalibrira i nakon toga izvrsi naredbu.

Robot treba biti postavljen uz crvenu i zutu.

Pritisni o. (ako je vec pritisnut o, pritisni opet, postavi robota, dodaj naredbu i pritisni opet.)

<http://192.168.1.4/>

Slika s kamere, što robot vidi