Safe System-level Concurrency on Resource-Constrained Nodes with Céu

Autor:

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Orientadores:

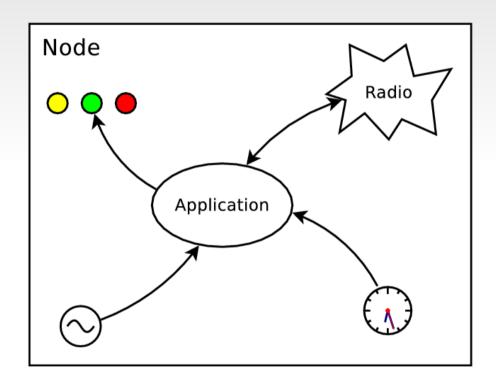
Roberto Ierusalimschy Noemi Rodriguez

Wireless Sensor Networks

- Reactive
 - guided by the environment

- Concurrent
 - safety aspects

- Constrained
 - 32K ROM
 - 4K RAM



Hello world!

Blinking LEDs

- 1. on \leftrightarrow off every 500ms
- 2. stop after 5s
- 3. repeat after 2s

Compositions

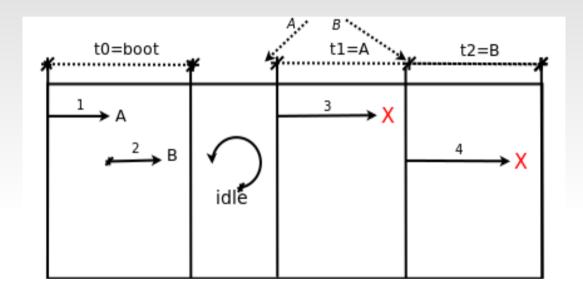
- par, seq, loop
- avoid state vars
- static inference

```
loop do
    par/or do
    loop do
        await 500ms;
        _leds_toggle();
    end
    with
        await 5s;
    end
    await 2s;
end
```

The design of Céu

- 1. Reactive/Synchronous execution
 - based on Esterel
- 2. Shared-memory concurrency
- 3. Internal events
- 4. Integration with C
- 5. Local scopes & Finalization
- 6. First-class timers

1. Synchronous execution



- <...> are trail segments that do not await (e.g. assignments, system calls)
- Reactions to external events never overlap
- The synchronous hypothesis:
- "reactions run infinitely faster in comparison to the rate of events"

2. Shared-memory concurrency

```
var int x=1;
par/and do
    await A;
    x = x + 1;
with
    await B;
    x = x * 2;
end
```

```
var int x=1;
par/and do
    await A;
    x = x + 1;
with
    await A;
    x = x * 2;
end
```

3. Internal events

- Emitted by the program
 - (vs environment)

- Multiple can be active at the same time
 - (vs single)

- Stack-based execution policy
 - (vs queue)

3. Internal events

• Enable advanced control mechanisms (e.g. subroutines, exceptions)

```
event int* inc;
par do
   // define subroutine
   loop do
      var int* p = await inc;
      *p = *p + 1;
   end
with
   // use subroutine
  <...>
  var int v = 1;
   emit inc => &v; // stack this continuation
   assert(v == 2);
end
```

Use bounded memory and execution time

4. Integration with C

Well-marked syntax ("_")

```
native _assert(), _inc(), _I;
_assert(_inc(_I));

native do
    #include <assert.h>
    int I = 0;
    int inc (int i) {
       return I+i;
    }
end
```

- "C hat" (unsafe execution)
- no bounded-execution analysis
- what about side effects in parallel trails?

4. Integration with C

pure and safe annotations

```
pure _inc();
safe _f() with _g();

par do
   _f(_inc(10));
with
   _g();
end
```

5. Local scopes & Finalization

```
loop do
    await 10ms;
    var _message_t msg;
    <...> // prepare msg
    _send_request(&msg);
    await SEND_ACK;
end
```

5. Local scopes & Finalization

```
par/or do
  loop do
    await 10ms;
  var _message_t msg;
  <...> // prepare msg local pointer
  _send_request(&msg);
  await SEND_ACK;
  end
with
  await STOP;
end
var int x = 1;
```

5. Local scopes & Finalization

```
par/or do
   loop do
     await 10ms;
      var message t msg;
      <...> // prepare msg
      finalize
         send request(&msg);
      with
          send cancel(&msg);
      end
      await SEND ACK;
   end
with
   await STOP;
end
var int x = 1;
```

6. First-class timers

- Very common in WSNs
 - sampling, timeouts
- await supports time (i.e. ms, min)
 - it also compensates system delays

```
await 2ms;
v = 1;
await 1ms;
v = 2;
```

- 5ms elapse
- late = 3ms
- late = 2ms

```
par/or do
    await 10ms;
    <...> // no awaits
    await 1ms;
    v = 1;
with
    await 12ms;
    v = 2;
end
```

Formalization

Small-step operational semantics

- Control aspects of the language
 - parallel compositions,stack-based events, finalization
- Mapping: formal → concrete

$$\begin{array}{c} val(id,n) \neq 0 \\ \hline \langle S, (mem(id)?p:q) \rangle \xrightarrow{n} \langle S, p \rangle \\ \hline val(id,n) = 0 \\ \hline \langle S, (mem(id)?p:q) \rangle \xrightarrow{n} \langle S, q \rangle \\ \hline \langle S, p \rangle \xrightarrow{n} \langle S', p' \rangle \\ \hline \langle S, (p;q) \rangle \xrightarrow{n} \langle S', (p';q) \rangle \\ \hline \langle S, (mem(id);q) \rangle \xrightarrow{n} \langle S, q \rangle \\ \hline \langle S, (mem(id);q) \rangle \xrightarrow{n} \langle S, p \rangle \\ \hline \langle S, (mem(id);q) \rangle \xrightarrow{n} \langle S, p \rangle \\ \hline \langle S, (break;q) \rangle \xrightarrow{n} \langle S, break \rangle \\ \hline \langle S, (loop p) \rangle \xrightarrow{n} \langle S, (p@loop p) \rangle \\ \hline \langle S, (p@loop q) \rangle \xrightarrow{n} \langle S', (p'@loop q) \rangle \\ \hline \langle S, (p@loop q) \rangle \xrightarrow{n} \langle S', (p'@loop q) \rangle \\ \hline \langle S, (mem(id)@loop p) \rangle \xrightarrow{n} \langle S, loop p \rangle \\ \hline \langle S, (break@loop p) \rangle \xrightarrow{n} \langle S, nop \rangle \\ \hline \langle S, (p par q) \rangle \xrightarrow{n} \langle S', (p' par q) \rangle \\ \hline \langle S, (p par q) \rangle \xrightarrow{n} \langle S', (p' par q) \rangle \\ \hline \langle S, (break par q) \rangle \xrightarrow{n} \langle S, break \rangle \\ \hline \langle S, (p par break) \rangle \xrightarrow{n} \langle S, break \rangle \\ \hline \langle S, (p par break) \rangle \xrightarrow{n} \langle S, p \rangle \\ \hline \langle S, (p par break) \rangle \xrightarrow{n} \langle S, p \rangle \\ \hline \langle S, (mem(id) and q) \rangle \xrightarrow{n} \langle S, p \rangle \\ \langle S, (mem(id) or q) \rangle \xrightarrow{n} \langle S, nop \rangle \\ \hline \langle S, (mem(id) or q) \rangle \xrightarrow{n} \langle S, nop \rangle \\ \hline (sallocked(n, S, p) \\ \langle S, (mem(id) or q) \rangle \xrightarrow{n} \langle S, nop \rangle \\ \hline (sallocked(n, S, p) \\ \langle S, (mem(id) or q) \rangle \xrightarrow{n} \langle S, nop \rangle \\ \hline (or-nop2) \\ \hline (or-nop2) \\ \hline \end{array}$$

Evaluation

- Source code size
 - number of tokens, data/state variables
- Memory usage
 - ROM, RAM
- Responsiveness
 - time-consuming C calls

- Comparison to nesC
 - WSNs protocols, radio driver

Code size & Memory usage



Memory usage

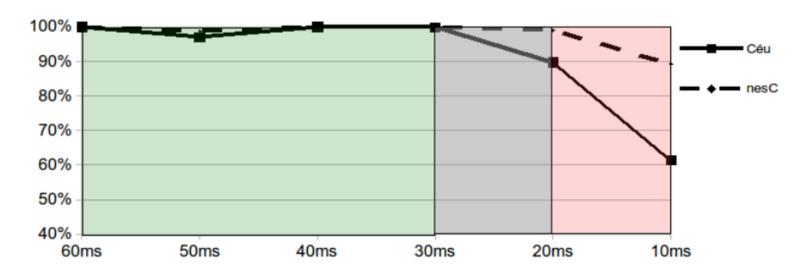
						memory areage			
Application	Language	tokens	Céu vs nesC	glol	oals data	ROM	Céu vs nesC	RAM	Céu vs nesC
СТР	nesC	383	220/	4	5	18896	9%	1295	2%
	Céu	295	-23%	-	2	20542		1319	
SRP	nesC	418	-30%	2	8	12266	5%	1252	-3%
	Céu	291	-30 %	-	4	12836		1215	
DRIP	nesC	342	-25%	2	1	12708	8%	393	4%
	Céu	258	-25%	-	-	13726		407	
CC2420	nesC	519	-27%	1	2	10546	2%	283	3%
	Céu	380	-21 /0	_	-	10782		291	3 /0

no control globals

globals \rightarrow locals

Responsiveness

- 10 sending nodes
 - 20-byte msgs, 600-100ms/msg
- 1 receiving node
 - 60-10ms/msg
 - 8ms operation in sequence w/ every msg



Conclusion

- Main contributions:
 - a comprehensive and resource-efficient design
 - stack-based internal events
 - a set of compile-time guarantees

Safe System-level Concurrency on Resource-Constrained Nodes with Céu

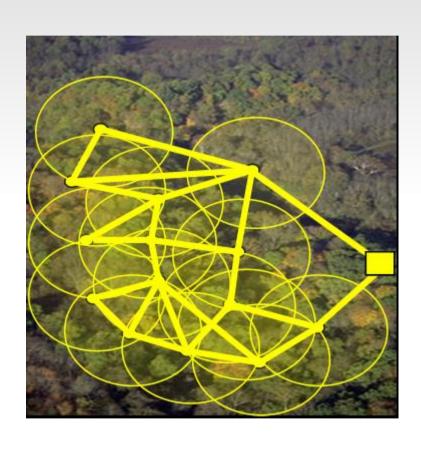
Autor:

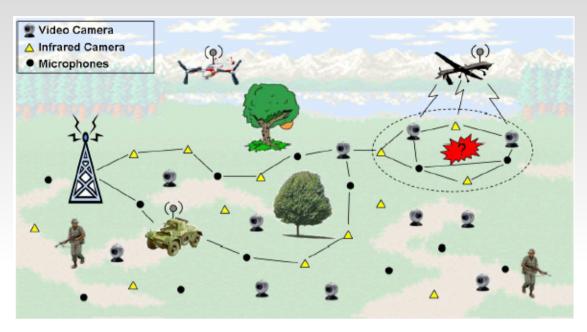
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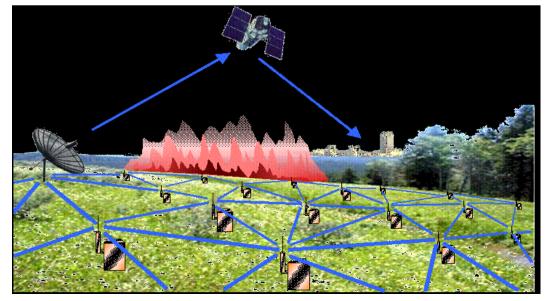
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Wireless Sensor Networks







Programming models in WSNs

- Event-driven programming
 - TinyOS/nesC, Contiki/C

- Multi-threading
 - Protothreads, TinyThreads, OCRAM

- Synchronous languages
 - Sol, OSM, Céu

Programming models in WSNs



- unstructred code
- manual memory
management

- multiple threads
- unrestricted shared
memory

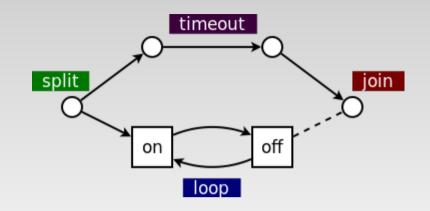
- composable threads
- safety analysis
high
level

Overview of Céu

- Reactive
 - environment in control: events
- Imperative
 - sequences, loops, assignments
- Concurrent
 - multiple lines of execution: *trails*
- Synchronous
 - trails synchronize at each external event
- Deterministic
 - trails execute in a specific order

Blinking a LED

- *sequential*: on=2s, off=1s
- *parallel*: 1-minute timeout



```
// nesC: event-driven
event void Boot.booted () {
 call T1.start(0);
 call T2.start(60000);
event void T1.fired() {
  static int on = 0;
  if (on) {
    call Leds.led00ff();
    call T1.start(1000);
  } else {
    call Leds.led00n();
    call T1.start(2000);
  on = !on
event void T2.fired() {
 call T1.cancel();
 call Leds.led00ff();
 <...> // continue
```

```
// Protothreads: multi-threaded
int main() {
  PT INIT(&blink);
  timer set(&timeout,60000);
 while (
    PT SCHEDULE(blink()) &&
    !timer expired(timeout)
  );
  leds off(LEDS RED);
  \langle ... \rangle // continue
PT THREAD blink() {
  while (1) {
    leds on(LEDS RED);
    timer set(&timer,2000);
    PT WAIT(expired(&timer));
    leds off(LEDS RED);
    timer set(&timer, 1000);
    PT WAIT(expired(&timer));
```

```
// Céu: synchronous
par/or do
  loop do
    Leds led00n();
    await 2s;
    Leds led00ff();
    await 1s:
  end
with
  await 1min;
end
Leds led00ff();
<...> // continue
```

Synchronous execution

- 1. Program is idle.
- 2. On any external event, awaiting trails awake.
- 3. Active trails execute, until they await or terminate.
- 4. Goto step 1.

- Reactions to external events never overlap
- The synchronous hypothesis: "reactions run infinitely faster in comparison to the rate of events"

Synchronous execution

Parallel compositions

```
loop do
  par/and do
  <...>
  with
   await 100ms;
  end
end
```

```
loop do
    par/or do
    <...>
    with
     await 100ms;
    end
end
```

Sampling and Timeout patterns

Synchronous execution

Céu enforces bounded execution

```
loop do
  if <cond> then
    break;
  end
end
```

```
loop do
  if <cond> then
    break;
  else
    await A;
  end
end
```

• Limitation: time-consuming operations

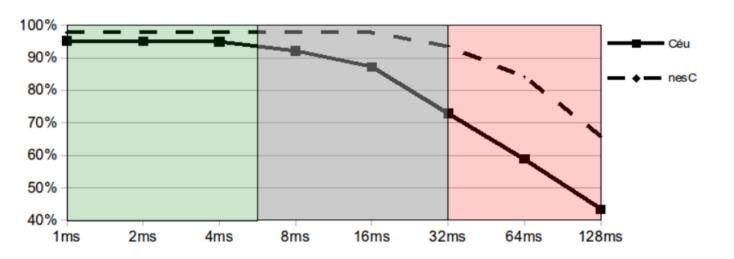
Local scopes

```
par/and do
  var int a;
  <...>
with
  var int b;
  <...>
end
var int c;
<...>
```

- blocks in parallel: sum memory
- blocks in sequence: reusue memory

Responsiveness

- 10 sending nodes
 - 20-bytes msgs, 200ms/msg
- 1 receiving node
 - 50msg/s
 - 1-128ms operation (every 150ms)



Operation	Duration
Block cypher [26, 18]	1ms
MD5 hash [18]	$3 \mathrm{ms}$
Wavelet decomposition [41]	6ms
SHA-1 hash [18]	8ms
RLE compression [38]	70ms
BWT compression [38]	300ms
Image processing [37]	50-1000ms

Safety

- Time-bounded reactions
- No concurrency in variables
- No concurrency in C calls
- Finalization for blocks going out of scope
- Auto-adjustment for timers in sequence
- Synchronization for timers in parallel

Related work

Language			Comp	olexity		Safety			
name	year	1: sequential execution	2: local variables	3: parallel compositions	4: internal events	5: deterministic execution	6: bounded execution	7: safe shared memory	8: finalization blocks
Preemptive	many	•	1		1		rt		
nesC	2003					•	async	1	
OSM	2005		1	1	1				
Protothreads	2006	1				1			
TinyThreads	2006	1	1			/			
Sol	2007	1	1	1		1	1		
FlowTalk	2011	1	1						
Ocram	2013	1	1			1			
Céu		1	1	1	1	•	1	1	1

- Demo applications
 - explore the programming style of Céu

- Semantics of Céu
 - control aspects
 - determinism, stacked internal events

- Implementation of Céu
 - parsing, temporal analysis, code generation

Safe System-level Concurrency on Resource-Constrained Nodes

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