# **Reactive Traversal of Recursive Data Types (?!)**

Francisco Sant'Anna Departamento de Informática — PUC-Rio, Brazil fsantanna@inf.puc-rio.br Hisham Muhammad Departamento de Informática — PUC-Rio, Brazil hisham@inf.puc-rio.br

Johnicholas Hines Affiliation email@domain.com

## **ABSTRACT**

We propose a structured mechanism to traverse recursive data types incrementally, in successive reactions to input events. traverse is an iterator-like anonymous block that can be invoked recursively and suspended at any point, retaining the full state and stack frames alive. traverse is designed for the synchronous language CÉU, inheriting all existing concurrency functionality, such as parallel compositions with orthogonal abortion, static memory management, and bounded memory and reaction time. We present two application scenarios that take advantage of recursive and reactive behavior: incremental computation and control-oriented domain specific languages.

## **Categories and Subject Descriptors**

 $\mathrm{D.3.3}$  [Programming Languages]: Language Constructs and Features

#### **General Terms**

Design, Languages

## **Keywords**

Behavior Trees, Domain Specific Languages, Incremental Computation, Logo, Structured Programming

#### 1. INTRODUCTION

...

 $\dots$  Céu [1, 2]

...

```
input void RESET; // declares an external event
2
     var int v = 0;
                         // variable shared by the trails
     par do
                      // 1st trail
        loop do
           await 1s;
           _{printf("v = %d\n", v);}
       end
9
     with
10
        loop do
                      // 2nd trail
          await RESET;
11
           v = 0;
12
13
     end
14
```

Figure 1: Introductory example in Céu.

# 2. CÉU

CÉU is a concurrent and reactive language in which the lines of execution, known as trails, react all together continuously and in synchronous steps to external stimuli. The introductory example in Figure 1 defines an input event RESET (line 1), a shared variable v (line 2), and starts two trails with the par construct (lines 3-14): the first (lines 4-8) increments variable v on every second and prints its value on screen; the second (lines 10-13) resets v on every external request to RESET. CÉU is tightly integrated with C and can access libraries of the underlying platform directly by prefixing symbols with an underscore (e.g.,  $\_printf(<...>)$ ), in line 7).

In the synchronous model of CÉU, a program reacts to an occurring event completely before handling the next. A reaction represents a logical instant in which all trails awaiting the occurring event awake and execute, one after the other, until they await again or terminate. During a reaction, the environment is invariant and does not interrupt the running trails<sup>1</sup>. If multiple trails react to the same event, the scheduler employs lexical order, i.e., the trail that appears first in the source code executes first. For this reason, programs are deterministic even in the presence of side effects in concurrent lines of execution. To avoid infinite execution for reactions, CÉU ensures that all loops contain await statements [1].

## 2.1 Recursive Data Types

 $<sup>\</sup>overline{\ }^{1}$  The actual implementation enqueues incoming input events to process them in further reactions.

```
data List with
1
2
         tag NIL;
3
      or
         tag CONS with
4
5
             var int head;
             var List* tail;
 6
7
         end
8
      end
9
10
     do
         pool List[1] 1st1;
11
12
          lst1 =new List.CONS(10,
                      List.CONS(20,
13
14
                       List.CONS (30.
                         List.NIL()));
15
          _printf("%d, %d\n", lst1:CONS.head,
16
                           lst1:CONS.tail:NIL);
17
             // prints 10, 1
18
19
      end
20
21
     do
         pool List[] 1st2;
22
         lst2 =new List.CONS(10,
23
24
                      List.CONS(20,
                       List.CONS(30,
26
                        List.NIL());
         lst2:CONS.tail =new List.CONS(50, List.NIL());
_printf("%d\n", lst2:CONS.tail:CONS.head);
27
28
             // prints 50 (20 and 30 have been freed)
29
```

Figure 2: A recursive List data type definition (lines 1–8) and uses (lines 10–18 and 20–28).

The data construct in Céu provides a safer alternative to C's struct, union, and enum definitions. A data entry declares either a non-recursive structure containing a set of mutable fields or a tagged union. A tagged union consists of a set of tag declarations, each of which may be a bare tag or contain mutable fields. If any of the tag declarations refers to the data type being declared, we have a recursive data type. In this case, the first tag of the tagged union must be a bare tag, and it will act as the union's null type: in Céu, every tagged union is an option type.

Figure 2 illustrates the recursive List data type, declared as a tagged union. The first tag, NIL (line 2), represents the empty list and is the union's null type. The second tag, CONS, holds a value in its field head and a pointer to the rest of the list in the field tail (lines 4-7).

All memory allocated by Céu constructs is managed by lexically-scoped memory pools. The pool keyword declares a memory pool of a given size and a reference to a root object. In line 11, we declare a pool of List objects of size 1, identified by root reference lst1, scoped by the do block in lines 10–19. The declaration also implicitly initializes the root to the null tag of the associated data type (i.e., List.NIL).

Then, in lines 12–15, we use the =new construct, which performs allocation and assignment: it attempts to dynamically allocate a list of three elements (using three List.CONS constructors in the assignment *r-value*), inferring the destination memory pool based on the assignment's *l-value* (i.e. lst1).

Since the pool has size 1, only the allocation of first element succeeds, with the failed allocations returning the null tag

```
pool List[] l = new List.CONS(1,
2
                           List.CONS(2,
                            List.CONS(3,
3
                             List.NIL()));
     var int sum =
        traverse e in 1 do
8
           if e:NIL then
9
              escape 0;
           else
10
              var int sum_tail = traverse e:CONS.tail;
11
              escape sum_tail + e:CONS.head;
12
           end
13
14
        end:
     printf("sum = %d\n", sum);
15
```

Figure 3: Calculating the sum of a list.

for this type (i.e., List.NIL). The print command (line 16) outputs "10, 1": the head of the first element (the operator ':' is equivalent to C's '->') and a true value for the NIL check of the second element.

In the second block (lines 21–30), we declare the lst2 pool with an unbounded memory limit (i.e., List[] in line 22). Now, the three-element allocation succeeds (lines 23–26). Then, we mutate the tail of the first element to point to a newly allocated element in the same pool, which also succeeds (line 27). The print command (line 28) outputs "50", displaying the head of the new second element. In the moment of the mutation, the old subtree (containing values "20" and "30") is completely removed from memory. Finally, the end of the block (line 30) deallocates the pool along with all of its elements.

Data types in Céu have a number of restrictions. Given that mutations deallocate whole subtrees, data types cannot represent general graphs (in particular, they cannot contain cycles). Elements in different pools cannot be mixed; and pointers to subtrees (i.e., weak references) must be observed via the watching construct, as they can be invalidated at any time (to be discussed in Section 2.2).

#### 2.2 Traversing Data Types

CÉU introduces a structured mechanism to traverse data types. The traverse construct integrates well with the synchronous execution model, supporting nested control compositions, such as await and all par variations. It also preserves explicit lexical scopes with static memory management.

The example in Figure 3 creates a list (lines 1-4) and traverses it to calculate the sum of elements (lines 6-15). The traverse block (line 7) starts with the element e pointing to the root of the list 1. The escape statement (lines 9 and 12) returns a value to be assigned to the sum (line 6). A NIL list has sum=0 (lines 8-9). A CONS list needs to calculate the sum of its tail recursively, invoking traverse again (line 11), which will create a nested instance of the enclosing traverse block (lines 7-14), now with e pointing to the e:CONS.tail. Without nested control mechanisms, traverse is just syntactic sugar for anonymous closures called recursively.

To distinguish traverse from standard recursive functions, Figure 4 extends the body of the previous example with re-

```
1
     pool List[] 1 = <...>; // 1, 2, 3
2
     var int sum :
        traverse e in 1 do
3
           if e:NIL then
              escape 0;
              watching e do
                  printf("me = %d\n", e:CONS.head);
                  await 1s;
9
                  var int sum_tail = traverse e:CONS.tail;
10
                  escape sum_tail + e:CONS.head;
11
              end
12
13
              escape 0;
14
           end
15
        end:
     _printf("sum = %d\n", sum);
16
```

Figure 4: Calculating the sum of a list, one element each second.

active behavior. For each recursive iteration, the traverse prints the current head (line 8) and awaits 1 second before traversing the tail (lines 9–10). In Céu, all accesses to pointers that cross await statements must be protected with watching blocks [2]. This ensures that if side effects occurring in parallel affect the pointed object, no harming code executes because the whole block is aborted. In the example (lines 7–12), if the list is mutated during that 1 second and the specific element is removed from memory, we simply ignore the whole subtree and return 0.

Note that for bounded pools (e.g., List[3] 1), we can infer at compile time the maximum number of "stack frames" required for traverse. In addition, we can also enforce bounded execution time by asserting that the structure of the recursive steps converge to the base cases. This is an important requirement for constrained and real-time embedded systems, which is the original application domain of CÉU [1].

## 3. APPLICATIONS

incremental computation, behavior trees, control-dominated  $\operatorname{DSLs}$ 

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#### 3.1 Incremental Computation

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• gray binary generation?

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## 3.2 Domain Specific Languages

#### 3.2.1 Behavior Trees

The term "Behavior Trees" denotes a family of DSLs used for Game AI. The term is loose, because different games use different languages, but generally it indicates an interpreted domain-specific language for creature behavior that includes at least sequence and selection combinators, and which are "ticked" periodically.

The semantics of the sequence combinator can be understood as short-circuit evaluation of a conjunction; the Seq

```
data Command with
2
         tag NOTHING;
3
     or
          tag ROTATE with
              var int angle;
6
7
     or
         tag MOVE with
8
              var int pixels;
9
10
11
     or
12
         tag AWAIT with
13
              var int ms;
14
          end
15
     or
         tag SEQUENCE with
16
              var Command* one;
17
              var Command* two;
19
          end
20
     or
         tag REPEAT with
21
              var int
                            times;
22
23
              var Command* command:
24
25
         tag PAROR with
26
27
              var Command* one;
              var Command* two;
28
29
```

Figure 5: DSL for a LOGO turtle.

node ticks its left subtree until it finishes, and if it finishes successfully, ticks its right subtree until it finishes. The semantics of the selection combinator can be understood as short-circuit evaluation of an alternation; the Sel node ticks its left subtree until it finishes, and if it did not finish successfully, ticks its right subtree until it finishes.

This skeleton, augmented with leaves that test properties, set properties, perform animations and sounds, and other custom combinators, can be preferable to finite state machines (hierarchical, augmented, or otherwise) for authoring Game AI.

Ceu's parallel features make implementing a parallel combinator for behavior trees much easier.

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## 3.2.2 Logo Turtle

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## 4. RELATED WORK

...

# 5. CONCLUSION

#### 6. REFERENCES

- F. Sant'Anna et al. Safe System-level Concurrency on Resource-Constrained Nodes. In *Proceedings of SenSys'13*. ACM, 2013.
- [2] F. Sant'Anna et al. Structured Synchronous Reactive Programming with Céu. In *Proceedings of Modularity'15*, 2015. to appear.

```
class Interpreter with
1
            pool Command[]& cmds;
3
            var Turtle&
            traverse cmd in cmds do
    watching cmd do
    if cmd:AWAIT then
 5
6
7
                             await (cmd:AWAIT.ms) ms;
 8
10
                        else/if cmd:ROTATE then
                             do TurtleRotate with
   this.turtle = turtle;
   this.angle = cmd:ROTATE.angle;
11
12
13
                              end;
14
15
                        \verb"else/if" cmd: \verb"MOVE" then"
17
                             \textbf{do} \ \texttt{TurtleMove} \ \textbf{with}
                                   this.turtle = turtle;
this.pixels = cmd:MOVE.pixels;
18
19
                              end;
20
22
                        else/if cmd:PAROR then
23
                              par/or do
                              traverse cmd:PAROR.one; with
24
25
                                  traverse cmd:PAROR.two;
26
27
29
                        \verb"else/if" cmd: SEQUENCE" then"
                             traverse cmd:SEQUENCE.one;
traverse cmd:SEQUENCE.two;
30
31
32
                        else/if cmd:REPEAT then
33
                             loop i in cmd:REPEAT.times do
    traverse cmd:REPEAT.command;
34
35
                             end
36
                 end
end
37
38
            end
39
      end
```

Figure 6: The turtle interpreter.