# Energy Efficiency for IoT Software in the Large

Francisco Sant'Anna francisco@ime.uerj.br







#### About us...

- Research areas:
  - Programming Languages
  - Concurrent & Distributed Systems
- Programming Language "Céu"
  - Embedded platforms
  - IoT & Wireless Sensor Networks
  - Games
  - ~10 years of research

## **Energy Efficiency for IoT**

- 15 billion "traditional" network-connected devices in 2015 (e.g., mobile phones & smart TVs).
- 75 billion by 2025 with the IoT (e.g., smart bulbs & fitness wearables). [2016]
- Most energy consumed in standby mode.
- Network standby is one of the six fronts on IEA/G20's Energy Efficiency Action Plan
  - https://www.iea-4e.org/projects/g20

#### **Our Research Goals**

1. Address energy efficiency through rigorous use of **standby**.

2. Target **constrained** embedded architectures that form the IoT.

3. Provide standby mechanisms at the **programming language** level that scale to all applications.

4. Support **transparent**/non-intrusive standby mechanisms that reduce barriers of adoption.

#### Research Non-Goals

- Adaptive Computing
  - QoS (e.g., resolution, frame rate, accuracy)
  - Behavior (e.g., switch UI, disable functionalities)
  - Don't take advantage of standby modes (goal 1)
- Energy-Aware Network Protocols
  - Low-power listening
  - Small periods of duty cycles
  - Only for networked parts, not automatic (goals 3 & 4)
- Complex Hardware Architectures
  - Microprocessors, MMU, OS-based, Smartphones
  - Not constrained embedded platforms (goal 2)

#### **General Approach**

(standby, constrained, programming language, transparent)

Enforce idle states of execution

Infer deepest sleeping mode

Put device to sleep

Only awake from interrupts

## A Motivating Example

Every second, read sensor value and broadcast it.

Arduino

```
while (1) {
   delay(1000);
   int v = analogRead();
   radioWrite(v);
}
```

Céu

```
loop do
  await   1s;
  int v = await AnalogRead();
  await   RadioWrite(v);
end
```

### Let's add concurrency...

Every second, read sensor value and broadcast it. Stop immediately as soon as a message arrives.

Arduino

```
uint32_t prv = millis();
while (1) {
   if (radioAvail())
      break;
   uint32_t cur = millis();
   if (cur > prv+1000) {
      prv = cur;
      int v = analogRead();
      radioWrite(v);
   }
}
```

```
while (1) {
    delay(1000);
    int v = analogRead();
    radioWrite(v);
}
```

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      prv = cur;
      int v = analogRead();
      radioWrite(v);
   }
}
```

Céu

```
par/or do
   await RadioAvail();
with
   loop do
    await 1s;
   int v = await AnalogRead();
   await RadioWrite(v);
   end
end
```

#### **Standby Considerations**

Every second, read sensor value and broadcast it. Stop immediately as soon as a message arrives.

Arduino

```
uint32_t prv = millis();
while (1) {
   if (radioAvail())
      break;
   uint32_t cur = millis();
   if (cur > prv+1000) {
      prv = cur;
      int v = analogRead();
      radioWrite(v);
   }
}
```

Céu

```
par/or do
    await RadioAvail();
with
    loop do
        await 1s;
    int v = await AnalogRead();
    await RadioWrite(v);
    end
end
```

#### Céu in a Nutshell

- Reactive
  - environment in control: events
- Imperative
  - sequences, loops, assignments
- Concurrent
  - multiple lines of execution: trails
- Synchronous
  - trails synchronize at each external event
  - trails are always awaiting
- Deterministic
  - always yields the same outcome for a given timeline

## **Project In Practice...**

- Hardware infrastructure
  - Off-the-shelf Arduinos (ATMega328, Cortex-M0)
- Software infrastructure
  - Implement an energy-aware runtime for Céu
  - Rewrite device drivers in Céu (timers, ADC, Radio)
- Applications
  - Rewrite existing IoT applications in Céu
    - Time to rewrite
    - Coding "aesthetics"
    - Energy consumption

```
par/or do
   await RadioAvail();
with
   loop do
      await 1s;
   int v = await AnalogRead();
   await RadioWrite(v);
   end
end
```

```
output void ADC_REQUEST do
    ADMUX = 0x40|(A0&0x07);
    bitSet(ADCSRA, ADIE);
    bitSet(ADCSRA, ADSC);
end

input ADC_vect_num do
    bitClear(ADCSRA, ADIE);
    emit ADC_DONE(ADC);
```

end

```
code AnalogRead (void) -> int
do

PM_SET(PM_ADC, 1);
do finalize with
    PM_SET(PM_ADC, 0);
end

emit ADC_REQUEST;
int value = await ADC_DONE;
escape value;
end
```

```
par/or do
   await RadioAvail();
with
   loop do
      await 1s;
   int v = await AnalogRead();
   await RadioWrite(v);
   end
end
```

```
output void ADC_REQUEST do
    ADMUX = 0x40|(A0&0x07);
    bitSet(ADCSRA, ADIE);
    bitSet(ADCSRA, ADSC);
end
```

```
input ADC_vect_num do
  bitClear(ADCSRA, ADIE);
  emit ADC_DONE(ADC);
end
```

```
void pm_sleep (void) {
   if (PM_GET(PM_TIMER1)) {
      sleep_1(<...>)
    } else if (PM_GET(PM_ADC)) {
      sleep_2(<...>);
    } else {
      sleep_3(<...>);
    }
}
```

```
code AnalogRead (void) -> int
do

PM_SET(PM_ADC, 1);
do finalize with
    PM_SET(PM_ADC, 0);
end
emit ADC_REQUEST;
int value = await ADC_DONE;
escape value;
end
```

```
par/or do
   await RadioAvail();
with
   loop do
     await 1s;
   int v = await AnalogRead();
   await RadioWrite(v);
   end
end
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output void ADC_REQUEST do
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input ADC_vect_num do
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```
void pm_sleep (void) {
   if (PM_GET(PM_TIMER1)) {
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    } else if (PM_GET(PM_ADC)) {
      sleep_2(<...>);
    } else {
      sleep_3(<...>);
    }
}
```

```
code AnalogRead (void) -> int
do

PM_SET(PM_ADC, 1);
do finalize with
    PM_SET(PM_ADC, 0);
end
emit ADC_REQUEST;
int value = await ADC_DONE;
escape value;
end
```

#### **General Approach**

(standby, constrained, programming language, transparent)

- Enforce idle states of execution
  - Céu enforces a reactive model of execution
- Infer deepest sleeping mode
  - Céu has a semantics amenable to analysis
- Put device to sleep
  - Céu has an energy-aware runtime
- Only awake from interrupts
  - Céu provides interrupt service routines (ISRs)

```
par/or do
    await RadioAvail();
with
    loop do
    await ls;
    int v = await AnalogRead();
    await RadioWrite(v);
    end
end
```

#### **Publications**

- SenSys'13, ACM Embedded Networked Sensor Systems
  - Safe System-level Concurrency on Resource-Constrained Nodes
- TECS'17, ACM Transactions on Embedded Computing Systems
  - The Design and Implementation of the Synchronous Language Céu

- LCTES'18, ACM Conference on Languages, Compilers, and Tools for Embedded Systems
  - A Memory-Bounded, Deterministic and Terminating Semantics for the Synchronous Programming Language Céu
- LCTES'18, ACM Conference on Languages, Compilers, and Tools for Embedded Systems
  - WIP: Transparent Standby for Low-Power, Resource-Constrained
    Embedded Systems

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