

# *Transparent Standby for Low-Power, Resource-Constrained Embedded Systems*

*A Programming Language-Based Approach*



*Francisco Sant'Anna*  
**francisco@ime.uerj.br**  
**@\_fsantanna**

# From “Traditional” Internet to “IoT”

# From “Traditional” Internet to “IoT”

- Today: 15 billion devices



# From “Traditional” Internet to “IoT”

- Today: 15 billion devices



# From “Traditional” Internet to “IoT”

- Today: 15 billion devices
- Tomorrow: 50 billion devices (2020)

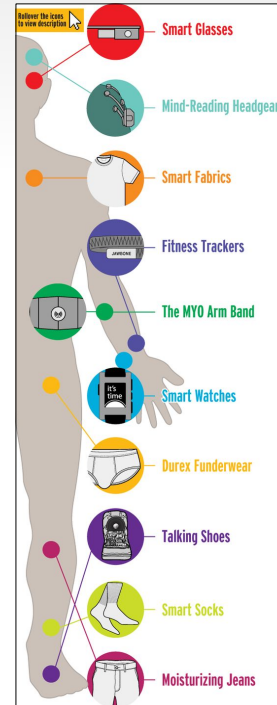


# From “Traditional” Internet to “IoT”

- Today: 15 billion devices



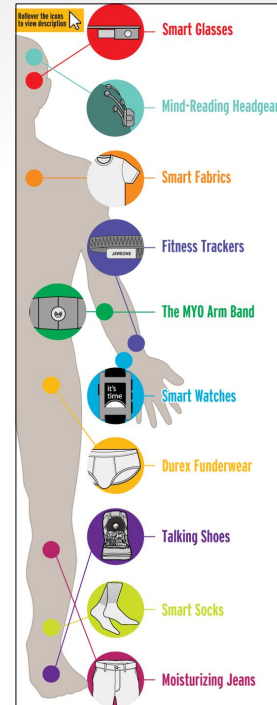
- Tomorrow: 50 billion devices (2020)





# From “Traditional” Internet to “IoT”

- Today: 15 billion devices
- Tomorrow: 50 billion devices (2020)

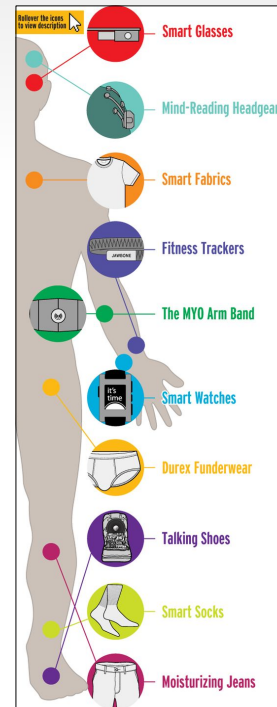
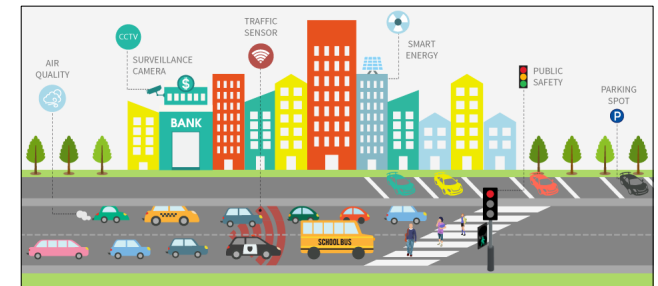


# From “Traditional” Internet to “IoT”

- Today: 15 billion devices



- Tomorrow: 50 billion devices (2020)





# Energy Efficiency for the IoT

# Energy Efficiency for the IoT

- Challenges: Pollution, Autonomy



# Energy Efficiency for the IoT

- Challenges: Pollution, Autonomy



- Opportunity: Effective “standby”



# Energy Efficiency for the IoT

- Challenges: Pollution, Autonomy



- Opportunity: Effective “standby”



**30-50% economy with existing technologies**



All smart devices have software...





All smart devices have software...



# All smart devices have software...

... which is written in a language





# All smart devices have software...



... which is written in a language



Current languages have not been designed  
with energy efficiency in mind!





All smart devices have software...

... which is written in a language



Current languages have not been designed with energy efficiency in mind!







# Our Research Goals

# Our Research Goals

1. Address energy efficiency through rigorous use of **standby**.

# Our Research Goals

1. Address energy efficiency through rigorous use of **standby**.
2. Target **constrained** embedded architectures that form the IoT.

# Our Research Goals

1. Address energy efficiency through rigorous use of **standby**.
2. Target **constrained** embedded architectures that form the IoT.
3. Provide standby mechanisms at the **programming language** level that scale to all applications.

# Our Research Goals

1. Address energy efficiency through rigorous use of **standby**.
2. Target **constrained** embedded architectures that form the IoT.
3. Provide standby mechanisms at the **programming language** level that scale to all applications.
4. Support **transparent**/non-intrusive standby mechanisms that reduce barriers of adoption.



# Research Non-Goals

# Research Non-Goals

- Adaptive Computing
  - QoS (e.g., resolution, frame rate, accuracy)
  - Behavior (e.g., switch UI, disable functionalities)

# Research Non-Goals

- Adaptive Computing
  - QoS (e.g., resolution, frame rate, accuracy)
  - Behavior (e.g., switch UI, disable functionalities)
  - *Don't take advantage of standby modes (goal 1)*

# Research Non-Goals

- Adaptive Computing
  - QoS (e.g., resolution, frame rate, accuracy)
  - Behavior (e.g., switch UI, disable functionalities)
  - *Don't take advantage of standby modes (goal 1)*
- Energy-Aware Network Protocols
  - Low-power listening
  - Small periods of duty cycles

# Research Non-Goals

- Adaptive Computing
  - QoS (e.g., resolution, frame rate, accuracy)
  - Behavior (e.g., switch UI, disable functionalities)
  - *Don't take advantage of standby modes (goal 1)*
- Energy-Aware Network Protocols
  - Low-power listening
  - Small periods of duty cycles
  - *Only for networked parts, not automatic (goals 3 & 4)*

# Research Non-Goals

- Adaptive Computing
  - QoS (e.g., resolution, frame rate, accuracy)
  - Behavior (e.g., switch UI, disable functionalities)
  - *Don't take advantage of standby modes (goal 1)*
- Energy-Aware Network Protocols
  - Low-power listening
  - Small periods of duty cycles
  - *Only for networked parts, not automatic (goals 3 & 4)*
- Complex Hardware Architectures
  - Microprocessors, MMU, OS-based, Smartphones



# Research Non-Goals

- Adaptive Computing
  - QoS (e.g., resolution, frame rate, accuracy)
  - Behavior (e.g., switch UI, disable functionalities)
  - *Don't take advantage of standby modes (goal 1)*
- Energy-Aware Network Protocols
  - Low-power listening
  - Small periods of duty cycles
  - *Only for networked parts, not automatic (goals 3 & 4)*
- Complex Hardware Architectures
  - Microprocessors, MMU, OS-based, Smartphones
  - *Not constrained embedded platforms (goal 2)*

# General Approach

(standby, constrained, programming language, transparent)

# General Approach

(standby, constrained, programming language, transparent)

- Enforce idle states of execution

# General Approach

(standby, constrained, programming language, transparent)

- Enforce idle states of execution
- Infer deepest sleeping mode

# General Approach

(standby, constrained, programming language, transparent)

- Enforce idle states of execution
- Infer deepest sleeping mode
- Put device to sleep

# General Approach

(standby, constrained, programming language, transparent)

- Enforce idle states of execution
- Infer deepest sleeping mode
- Put device to sleep
- Only awake from interrupts



# A Motivating Example



# A Motivating Example

*Every second, read sensor value and broadcast it.*

# A Motivating Example

*Every second, read sensor value and broadcast it.*

- Arduino

# A Motivating Example

*Every second, read sensor value and broadcast it.*

- Arduino

```
while (1) {  
    delay(1000);  
    int v = analogRead();  
    radioWrite(v);  
}
```

# A Motivating Example

*Every second, read sensor value and broadcast it.*

- Arduino

- Céu

```
while (1) {  
    delay(1000);  
    int v = analogRead();  
    radioWrite(v);  
}
```

# A Motivating Example

*Every second, read sensor value and broadcast it.*

- Arduino

```
while (1) {  
    delay(1000);  
    int v = analogRead();  
    radioWrite(v);  
}
```

- Céu

```
loop do  
    await 1s;  
    int v = await AnalogRead();  
    await RadioWrite(v);  
end
```

# A Motivating Example

*Every second, read sensor value and broadcast it.*

- Arduino

```
while (1) {  
    delay(1000);  
    int v = analogRead();  
    radioWrite(v);  
}
```

- Céu

```
loop do  
    await 1s;  
    int v = await AnalogRead();  
    await RadioWrite(v);  
end
```

# A Motivating Example

*Every second, read sensor value and broadcast it.*

- Arduino

```
while (1) {  
    delay(1000);  
    int v = analogRead();  
    radioWrite(v);  
}
```

- Céu

```
loop do  
    await 1s;  
    int v = await AnalogRead();  
    await RadioWrite(v);  
end
```

# Let's add concurrency...

*Every second, read sensor value and broadcast it.*



# Let's add concurrency...

*Every second, read sensor value and broadcast it.*

- Arduino

```
while (1) {  
    delay(1000);  
    int v = analogRead();  
    radioWrite(v);  
}
```

# Let's add concurrency...

*Every second, read sensor value and broadcast it.*

*Stop immediately as soon as a message arrives.*

- Arduino

```
while (1) {  
    delay(1000);  
    int v = analogRead();  
    radioWrite(v);  
}
```

# Let's add concurrency...

*Every second, read sensor value and broadcast it.*

*Stop immediately as soon as a message arrives.*

- Arduino

```
while (1) {  
    delay(1000);  
    int v = analogRead();  
    radioWrite(v);  
}
```

# Let's add concurrency...

*Every second, read sensor value and broadcast it.*

*Stop immediately as soon as a message arrives.*

- Arduino

```
while (1) {  
  delay(1000);  
  int v = analogRead();  
  radioWrite(v);  
}
```

# Let's add concurrency...

*Every second, read sensor value and broadcast it.*

*Stop immediately as soon as a message arrives.*

- Arduino

```
uint32_t lst = millis();
while (1) {
    if (radioAvail())
        break;
    uint32_t cur = millis();
    if (cur > lst+1000) {
        lst = cur;
        int v = analogRead();
        radioWrite(v);
    }
}
```

```
while (1) {
    delay(1000);
    int v = analogRead();
    radioWrite(v);
}
```

# Let's add concurrency...

*Every second, read sensor value and broadcast it.*

*Stop immediately as soon as a message arrives.*

- Arduino

```
uint32_t lst = millis();  
while (1) {  
    if (radioAvail())  
        break;  
    uint32_t cur = millis();  
    if (cur > lst+1000) {  
        lst = cur;  
        int v = analogRead();  
        radioWrite(v);  
    }  
}
```

```
while (1) {  
    delay(1000);  
    int v = analogRead();  
    radioWrite(v);  
}
```

# Let's add concurrency...

*Every second, read sensor value and broadcast it.*

*Stop immediately as soon as a message arrives.*

- Arduino

```
uint32_t lst = millis();  
while (1) {  
    if (radioAvail())  
        break;  
    uint32_t cur = millis();  
    if (cur > lst+1000) {  
        lst = cur;  
        int v = analogRead();  
        radioWrite(v);  
    }  
}
```

```
while (1) {  
    delay(1000);  
    int v = analogRead();  
    radioWrite(v);  
}
```

# Let's add concurrency...

*Every second, read sensor value and broadcast it.*

*Stop immediately as soon as a message arrives.*

- Arduino

```
uint32_t lst = millis();  
while (1) {  
    if (radioAvail())  
        break;  
    uint32_t cur = millis();  
    if (cur > lst+1000) {  
        lst = cur;  
        int v = analogRead();  
        radioWrite(v);  
    }  
}
```

```
while (1) {  
    delay(1000);  
    int v = analogRead();  
    radioWrite(v);  
}
```



# Let's add concurrency...

*Every second, read sensor value and broadcast it.*

*Stop immediately as soon as a message arrives.*

- Arduino

```
uint32_t lst = millis();  
while (1) {  
    if (radioAvail())  
        break;  
    uint32_t cur = millis();  
    if (cur > lst+1000) {  
        lst = cur;  
        int v = analogRead();  
        radioWrite(v);  
    }  
}
```

```
while (1) {  
    delay(1000);  
    int v = analogRead();  
    radioWrite(v);  
}
```

# Let's add concurrency...

*Every second, read sensor value and broadcast it.*

*Stop immediately as soon as a message arrives.*

- Arduino

```
uint32_t lst = millis();
while (1) {
    if (radioAvail())
        break;
    uint32_t cur = millis();
    if (cur > lst+1000) {
        lst = cur;
        int v = analogRead();
        radioWrite(v);
    }
}
```

# Let's add concurrency...

*Every second, read sensor value and broadcast it.*

*Stop immediately as soon as a message arrives.*

- Arduino

- Céu

```
uint32_t lst = millis();
while (1) {
    if (radioAvail())
        break;
    uint32_t cur = millis();
    if (cur > lst+1000) {
        lst = cur;
        int v = analogRead();
        radioWrite(v);
    }
}
```

# Let's add concurrency...

*Every second, read sensor value and broadcast it.*

*Stop immediately as soon as a message arrives.*

- Arduino

```
uint32_t lst = millis();
while (1) {
    if (radioAvail())
        break;
    uint32_t cur = millis();
    if (cur > lst+1000) {
        lst = cur;
        int v = analogRead();
        radioWrite(v);
    }
}
```

- Céu

```
par/or do
    await RadioAvail();
with
    loop do
        await 1s;
        int v = await AnalogRead();
        await RadioWrite(v);
    end
end
```

# Let's add concurrency...

*Every second, read sensor value and broadcast it.*

*Stop immediately as soon as a message arrives.*

- Arduino

```
uint32_t lst = millis();
while (1) {
    if (radioAvail())
        break;
    uint32_t cur = millis();
    if (cur > lst+1000) {
        lst = cur;
        int v = analogRead();
        radioWrite(v);
    }
}
```

- Céu

```
par/or do
    await RadioAvail();
with
    loop do
        await 1s;
        int v = await AnalogRead();
        await RadioWrite(v);
    end
end
```

# Let's add concurrency...

*Every second, read sensor value and broadcast it.*

*Stop immediately as soon as a message arrives.*

- Arduino

```
uint32_t lst = millis();
while (1) {
    if (radioAvail())
        break;
    uint32_t cur = millis();
    if (cur > lst+1000) {
        lst = cur;
        int v = analogRead();
        radioWrite(v);
    }
}
```

- Céu

```
par/or do
    await RadioAvail();
with
    loop do
        await 1s;
        int v = await AnalogRead();
        await RadioWrite(v);
    end
end
```

# Standby Considerations

*Every second, read sensor value and broadcast it.*

*Stop immediately as soon as a message arrives.*

- Arduino

```
uint32_t lst = millis();
while (1) {
    if (radioAvail())
        break;
    uint32_t cur = millis();
    if (cur > lst+1000) {
        lst = cur;
        int v = analogRead();
        radioWrite(v);
    }
}
```

- Céu

```
par/or do
    await RadioAvail();
with
    loop do
        await 1s;
        int v = await AnalogRead();
        await RadioWrite(v);
    end
end
```

# Standby Considerations

*Every second, read sensor value and broadcast it.*

*Stop immediately as soon as a message arrives.*

- Arduino

```
uint32_t lst = millis();
while (1) {
    if (radioAvail())
        break;
    uint32_t cur = millis();
    if (cur > lst+1000) {
        lst = cur;
        int v = analogRead();
        radioWrite(v);
    }
}
```

- Céu

```
par/or do
    await RadioAvail();
with
    loop do
        await 1s;
        int v = await AnalogRead();
        await RadioWrite(v);
    end
end
```



# Standby Considerations

*Every second, read sensor value and broadcast it.*

*Stop immediately as soon as a message arrives.*

- Arduino

```
uint32_t lst = millis();
while (1) {
    if (radioAvail())
        break;
    uint32_t cur = millis();
    if (cur > lst+1000) {
        lst = cur;
        int v = analogRead();
        radioWrite(v);
    }
}
```

- Céu

```
par/or do
    await RadioAvail();
with
    loop do
        await 1s;
        int v = await AnalogRead();
        await RadioWrite(v);
    end
end
```

# Céu in a Nutshell

# Céu in a Nutshell

- Reactive
  - environment in control: *events*

# Céu in a Nutshell

- Reactive
  - environment in control: *events*
- Imperative
  - sequences, loops, assignments

# Céu in a Nutshell

- Reactive
  - environment in control: *events*
- Imperative
  - sequences, loops, assignments
- Concurrent
  - multiple lines of execution: *trails*

# Céu in a Nutshell

- Reactive
  - environment in control: *events*
- Imperative
  - sequences, loops, assignments
- Concurrent
  - multiple lines of execution: *trails*
- Synchronous (based on Esterel)
  - trails synchronize at each external event

# Céu in a Nutshell

- Reactive
  - environment in control: *events*
- Imperative
  - sequences, loops, assignments
- Concurrent
  - multiple lines of execution: *trails*
- Synchronous (based on Esterel)
  - trails synchronize at each external event
  - **trails are always awaiting**

# Céu in a Nutshell

- Reactive
  - environment in control: *events*
- Imperative
  - sequences, loops, assignments
- Concurrent
  - multiple lines of execution: *trails*
- Synchronous (based on Esterel)
  - trails synchronize at each external event
  - **trails are always awaiting**
- Deterministic
  - always yields the same outcome for a given timeline





# In Practice...

# In Practice...

- Hardware infrastructure

# In Practice...

- Hardware infrastructure
  - Off-the-shelf Arduinos (ATMega328, Cortex-M0)
- Software infrastructure

# In Practice...

- Hardware infrastructure
  - Off-the-shelf Arduinos (ATMega328, Cortex-M0)
- Software infrastructure
  - Implement an energy-aware runtime for Céu

# In Practice...

- Hardware infrastructure
  - Off-the-shelf Arduinos (ATMega328, Cortex-M0)
- Software infrastructure
  - Implement an energy-aware runtime for Céu
  - Rewrite device drivers in Céu (timers, ADC, Radio)
- Applications

# In Practice...

- Hardware infrastructure
  - Off-the-shelf Arduinos (ATMega328, Cortex-M0)
- Software infrastructure
  - Implement an energy-aware runtime for Céu
  - Rewrite device drivers in Céu (timers, ADC, Radio)
- Applications
  - Rewrite existing IoT applications in Céu

# In Practice...

- Hardware infrastructure
  - Off-the-shelf Arduinos (ATMega328, Cortex-M0)
- Software infrastructure
  - Implement an energy-aware runtime for Céu
  - Rewrite device drivers in Céu (timers, ADC, Radio)
- Applications
  - Rewrite existing IoT applications in Céu
    - Time to rewrite, Coding “aesthetics”, Energy consumption



# In Practice...

- Hardware infrastructure
  - Off-the-shelf Arduinos (ATMega328, Cortex-M0)
- Software infrastructure
  - Implement an energy-aware runtime for Céu
  - Rewrite device drivers in Céu (timers, ADC, Radio)
- Applications
  - Rewrite existing IoT applications in Céu
    - Time to rewrite, Coding “aesthetics”, Energy consumption

```
par/or do
  await RadioAvail();
with
  loop do
    await 1s;
    int v = await AnalogRead();
    await RadioWrite(v);
  end
end
```

```
par/or do
  await RadioAvail();
with
  loop do
    await 1s;
    int v = await AnalogRead();
    await RadioWrite(v);
  end
end
```

```
par/or do
  await RadioAvail();
with
  loop do
    await 1s;
    int v = await AnalogRead();
    await RadioWrite(v);
  end
end
```

```
code AnalogRead (void) -> int do
  PM_SET(PM_ADC, 1);
  do finalize with
    PM_SET(PM_ADC, 0);
  end
  emit ADC_REQUEST;
  int value = await ADC_DONE;
  escape value;
end
```

```
par/or do
  await RadioAvail();
with
  loop do
    await 1s;
    int v = await AnalogRead();
    await RadioWrite(v);
  end
end
```

```
code AnalogRead (void) -> int do
  PM_SET(PM_ADC, 1);
  do finalize with
    PM_SET(PM_ADC, 0);
  end
  emit ADC_REQUEST;
  int value = await ADC_DONE;
  escape value;
end
```

```
par/or do  
  await RadioAvail();  
with  
  loop do  
    await 1s;  
    int v = await AnalogRead();  
    await RadioWrite(v);  
  end  
end
```

```
code AnalogRead (void) -> int do  
  PM_SET(PM_ADC, 1);  
  do finalize with  
    PM_SET(PM_ADC, 0);  
  end  
  emit ADC_REQUEST;  
  int value = await ADC_DONE;  
  escape value;  
end
```

```
par/or do
  await RadioAvail();
with
  loop do
    await 1s;
    int v = await AnalogRead();
    await RadioWrite(v);
  end
end
```

```
code AnalogRead (void) -> int do
  PM_SET(PM_ADC, 1);
  do finalize with
    PM_SET(PM_ADC, 0);
  end
  emit ADC_REQUEST;
  int value = await ADC_DONE;
  escape value;
end
```

```
par/or do
  await RadioAvail();
with
  loop do
    await 1s;
    int v = await AnalogRead();
    await RadioWrite(v);
  end
end
```

```
code AnalogRead (void) -> int do
  PM_SET(PM_ADC, 1);
  do finalize with
    PM_SET(PM_ADC, 0);
  end
  emit ADC_REQUEST;
  int value = await ADC_DONE;
  escape value;
end
```



```
par/or do
  await RadioAvail();
with
  loop do
    await 1s;
    int v = await AnalogRead();
    await RadioWrite(v);
  end
end
```

```
code AnalogRead (void) -> int do
  PM_SET(PM_ADC, 1);
  do finalize with
    PM_SET(PM_ADC, 0);
  end
  emit ADC_REQUEST;
  int value = await ADC_DONE;
  escape value;
end
```

```
par/or do
  await RadioAvail();
with
  loop do
    await 1s;
    int v = await AnalogRead();
    await RadioWrite(v);
  end
end
```

```
output void ADC_REQUEST do
  ADMUX = 0x40|(A0&0x07);
  bitSet(ADCSRA, ADIE);
  bitSet(ADCSRA, ADSC);
end
```

```
code AnalogRead (void) -> int do
  PM_SET(PM_ADC, 1);
  do finalize with
    PM_SET(PM_ADC, 0);
  end
  emit ADC_REQUEST;
  int value = await ADC_DONE;
  escape value;
end
```

```
par/or do
  await RadioAvail();
with
  loop do
    await 1s;
    int v = await AnalogRead();
    await RadioWrite(v);
  end
end
```

```
output void ADC_REQUEST do
  ADMUX = 0x40|(A0&0x07);
  bitSet(ADCSRA, ADIE);
  bitSet(ADCSRA, ADSC);
end
```

```
code AnalogRead (void) -> int do
  PM_SET(PM_ADC, 1);
  do finalize with
    PM_SET(PM_ADC, 0);
  end
  emit ADC_REQUEST;
  int value = await ADC_DONE;
  escape value;
end
```

```
par/or do
    await RadioAvail();
with
    loop do
        await 1s;
        int v = await AnalogRead();
        await RadioWrite(v);
    end
end
```

```
output void ADC_REQUEST do
    ADMUX = 0x40|(A0&0x07);
    bitSet(ADCSRA, ADIE);
    bitSet(ADCSRA, ADSC);
end
```

```
code AnalogRead (void) -> int do
    PM_SET(PM_ADC, 1);
    do finalize with
        PM_SET(PM_ADC, 0);
    end
    emit ADC_REQUEST;
    int value = await ADC_DONE;
    escape value;
end
```

```
par/or do
    await RadioAvail();
with
    loop do
        await 1s;
        int v = await AnalogRead();
        await RadioWrite(v);
    end
end
```

```
output void ADC_REQUEST do
    ADMUX = 0x40|(A0&0x07);
    bitSet(ADCSRA, ADIE);
    bitSet(ADCSRA, ADSC);
end
```

```
input ADC_vect_num do
    bitClear(ADCSRA, ADIE);
    emit ADC_DONE(ADC);
end
```

```
code AnalogRead (void) -> int do
    PM_SET(PM_ADC, 1);
    do finalize with
        PM_SET(PM_ADC, 0);
    end
    emit ADC_REQUEST;
    int value = await ADC_DONE;
    escape value;
end
```

```
par/or do
    await RadioAvail();
with
    loop do
        await 1s;
        int v = await AnalogRead();
        await RadioWrite(v);
    end
end
```

```
output void ADC_REQUEST do
    ADMUX = 0x40|(A0&0x07);
    bitSet(ADCSRA, ADIE);
    bitSet(ADCSRA, ADSC);
end
```

```
input ADC_vect_num do
    bitClear(ADCSRA, ADIE);
    emit ADC_DONE(ADC);
end
```

```
code AnalogRead (void) -> int do
    PM_SET(PM_ADC, 1);
    do finalize with
        PM_SET(PM_ADC, 0);
    end
    emit ADC_REQUEST;
    int value = await ADC_DONE;
    escape value;
end
```

```

par/or do
    await RadioAvail();
with
    loop do
        await 1s;
        int v = await AnalogRead();
        await RadioWrite(v);
    end
end

```

```

void pm_sleep (void) {
    if (PM_GET(PM_TIMER1)) {
        sleep_1(<...>)
    } else if (PM_GET(PM_ADC)) {
        sleep_2(<...>);
    } else {
        sleep_3(<...>);
    }
}

```

```

output void ADC_REQUEST do
    ADMUX = 0x40|(A0&0x07);
    bitSet(ADCSRA, ADIE);
    bitSet(ADCSRA, ADSC);
end

```

```

input ADC_vect_num do
    bitClear(ADCSRA, ADIE);
    emit ADC_DONE(ADC);
end

```

```

code AnalogRead (void) -> int do
    PM_SET(PM_ADC, 1);
    do finalize with
        PM_SET(PM_ADC, 0);
    end
    emit ADC_REQUEST;
    int value = await ADC_DONE;
    escape value;
end

```

```
par/or do
```

```
    await RadioAvail();
```

```
with
```

```
    loop do
```

```
        await 1s;
```

```
        int v = await AnalogRead();
```

```
        await RadioWrite(v);
```

```
    end
```

```
end
```

```
void pm_sleep (void) {
```

```
    if (PM_GET(PM_TIMER1)) {
```

```
        sleep_1(<...>)
```

```
    } else if (PM_GET(PM_ADC)) {
```

```
        sleep_2(<...>);
```

```
    } else {
```

```
        sleep_3(<...>);
```

```
    }
```

```
}
```

```
}
```

```
output void ADC_REQUEST do
```

```
    ADMUX = 0x40|(A0&0x07);
```

```
    bitSet(ADCSRA, ADIE);
```

```
    bitSet(ADCSRA, ADSC);
```

```
end
```

```
input ADC_vect_num do
```

```
    bitClear(ADCSRA, ADIE);
```

```
    emit ADC_DONE(ADC);
```

```
end
```

```
code AnalogRead (void) -> int do
```

```
    PM_SET(PM_ADC, 1);
```

```
    do finalize with
```

```
        PM_SET(PM_ADC, 0);
```

```
    end
```

```
    emit ADC_REQUEST;
```

```
    int value = await ADC_DONE;
```

```
    escape value;
```

```
end
```



## Initial Results

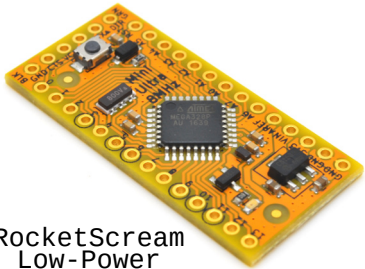
|          | Arduino | Céu   |     | OBS                                 |
|----------|---------|-------|-----|-------------------------------------|
|          |         | M1    | M2  |                                     |
| Empty    | 3.7     | 0.002 |     | No activity.                        |
| Blink    | 6.0     | 3.1   |     | Least efficient mode b/c of TIMER1. |
| Sensor   | 11.4    | 7.7   |     | Most efficient mode b/c of INT2.    |
| Radio    | 19.5    | 15.8  | 3.0 | Alternates INT2 <-> TIMER1.         |
| Protocol | 19.6    | 15.9  |     | Consumption dominated by the Radio. |

*(Consumption in mA)*

## Initial Results

|          | Arduino | Céu   |     | OBS                                 |
|----------|---------|-------|-----|-------------------------------------|
|          |         | M1    | M2  |                                     |
| Empty    | 3.7     | 0.002 |     | No activity.                        |
| Blink    | 6.0     | 3.1   |     | Least efficient mode b/c of TIMER1. |
| Sensor   | 11.4    | 7.7   |     | Most efficient mode b/c of INT2.    |
| Radio    | 19.5    | 15.8  | 3.0 | Alternates INT2 <-> TIMER1.         |
| Protocol | 19.6    | 15.9  |     | Consumption dominated by the Radio. |

*(Consumption in mA)*

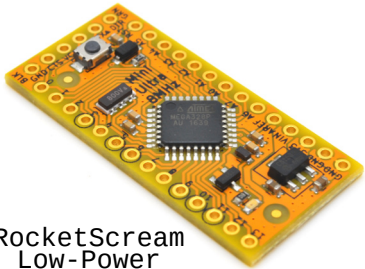


RocketScream  
Low-Power  
Arduino

## Initial Results

|          | Arduino | Céu   |     | OBS                                 |
|----------|---------|-------|-----|-------------------------------------|
|          |         | M1    | M2  |                                     |
| Empty    | 3.7     | 0.002 |     | No activity.                        |
| Blink    | 6.0     | 3.1   |     | Least efficient mode b/c of TIMER1. |
| Sensor   | 11.4    | 7.7   |     | Most efficient mode b/c of INT2.    |
| Radio    | 19.5    | 15.8  | 3.0 | Alternates INT2 <-> TIMER1.         |
| Protocol | 19.6    | 15.9  |     | Consumption dominated by the Radio. |

*(Consumption in mA)*



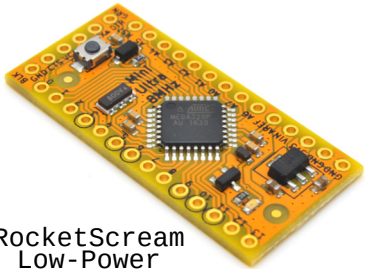
RocketScream  
Low-Power  
Arduino

## Initial Results

|          | Arduino | Céu   |     | OBS                                 |
|----------|---------|-------|-----|-------------------------------------|
|          |         | M1    | M2  |                                     |
| Empty    | 3.7     | 0.002 |     | No activity.                        |
| Blink    | 6.0     | 3.1   |     | Least efficient mode b/c of TIMER1. |
| Sensor   | 11.4    | 7.7   |     | Most efficient mode b/c of INT2.    |
| Radio    | 19.5    | 15.8  | 3.0 | Alternates INT2 <-> TIMER1.         |
| Protocol | 19.6    | 15.9  |     | Consumption dominated by the Radio. |

*(Consumption in mA)*

```
await FOREVER;
```



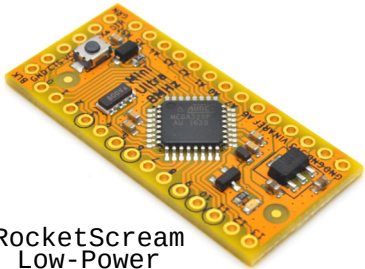
RocketScream  
Low-Power  
Arduino

## Initial Results

|          | Arduino | Céu   |     | OBS                                 |
|----------|---------|-------|-----|-------------------------------------|
|          |         | M1    | M2  |                                     |
| Empty    | 3.7     | 0.002 |     | No activity.                        |
| Blink    | 6.0     | 3.1   |     | Least efficient mode b/c of TIMER1. |
| Sensor   | 11.4    | 7.7   |     | Most efficient mode b/c of INT2.    |
| Radio    | 19.5    | 15.8  | 3.0 | Alternates INT2 <-> TIMER1.         |
| Protocol | 19.6    | 15.9  |     | Consumption dominated by the Radio. |

(Consumption in mA)

await FOREVER;



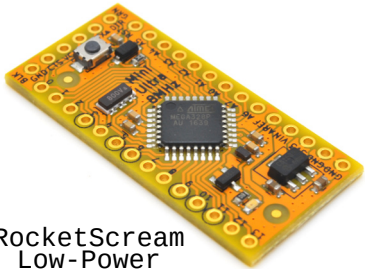
RocketScream  
Low-Power  
Arduino

## Initial Results

|          | Arduino | Céu   |     | OBS                                 |
|----------|---------|-------|-----|-------------------------------------|
|          |         | M1    | M2  |                                     |
| Empty    | 3.7     | 0.002 |     | No activity.                        |
| Blink    | 6.0     | 3.1   |     | Least efficient mode b/c of TIMER1. |
| Sensor   | 11.4    | 7.7   |     | Most efficient mode b/c of INT2.    |
| Radio    | 19.5    | 15.8  | 3.0 | Alternates INT2 <-> TIMER1.         |
| Protocol | 19.6    | 15.9  |     | Consumption dominated by the Radio. |

(Consumption in mA)

await FOREVER;



RocketScream  
Low-Power  
Arduino

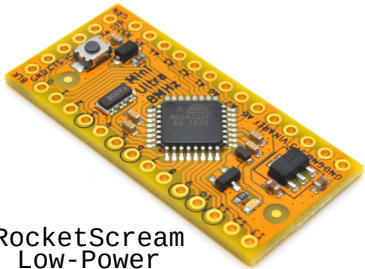
## Initial Results

|          | Arduino | Céu   |     | OBS                                 |
|----------|---------|-------|-----|-------------------------------------|
|          |         | M1    | M2  |                                     |
| Empty    | 3.7     | 0.002 |     | No activity.                        |
| Blink    | 6.0     | 3.1   |     | Least efficient mode b/c of TIMER1. |
| Sensor   | 11.4    | 7.7   |     | Most efficient mode b/c of INT2.    |
| Radio    | 19.5    | 15.8  | 3.0 | Alternates INT2 <-> TIMER1.         |
| Protocol | 19.6    | 15.9  |     | Consumption dominated by the Radio. |

(Consumption in mA)

```
await FOREVER;
```

```
loop do  
  emit PIN(13,high);  
  await 1s;  
  emit PIN(13,low);  
  await 1s;  
end
```



RocketScream  
Low-Power  
Arduino

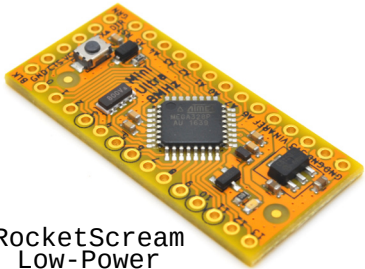
## Initial Results

|          | Arduino | Céu   |     | OBS                                 |
|----------|---------|-------|-----|-------------------------------------|
|          |         | M1    | M2  |                                     |
| Empty    | 3.7     | 0.002 |     | No activity.                        |
| Blink    | 6.0     | 3.1   |     | Least efficient mode b/c of TIMER1. |
| Sensor   | 11.4    | 7.7   |     | Most efficient mode b/c of INT2.    |
| Radio    | 19.5    | 15.8  | 3.0 | Alternates INT2 <-> TIMER1.         |
| Protocol | 19.6    | 15.9  |     | Consumption dominated by the Radio. |

(Consumption in mA)

```
await FOREVER;
```

```
loop do  
  emit PIN(13,high);  
  await 1s;  
  emit PIN(13,low);  
  await 1s;  
end
```



RocketScream  
Low-Power  
Arduino



## Initial Results

|          | Arduino | Céu   |     | OBS                                 |
|----------|---------|-------|-----|-------------------------------------|
|          |         | M1    | M2  |                                     |
| Empty    | 3.7     | 0.002 |     | No activity.                        |
| Blink    | 6.0     | 3.1   |     | Least efficient mode b/c of TIMER1. |
| Sensor   | 11.4    | 7.7   |     | Most efficient mode b/c of INT2.    |
| Radio    | 19.5    | 15.8  | 3.0 | Alternates INT2 <-> TIMER1.         |
| Protocol | 19.6    | 15.9  |     | Consumption dominated by the Radio. |

(Consumption in mA)

```
await FOREVER;
```

```
loop do
```

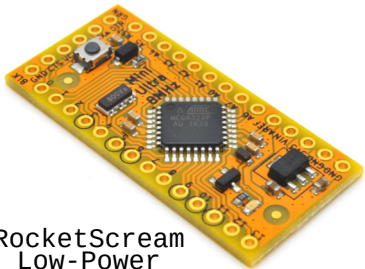
```
  emit PIN(13,high);
```

```
  await 1s;
```

```
  emit PIN(13,low);
```

```
  await 1s;
```

```
end
```



RocketScream  
Low-Power  
Arduino

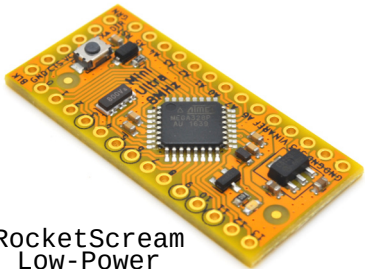
## Initial Results

|          | Arduino | Céu   |     | OBS                                 |
|----------|---------|-------|-----|-------------------------------------|
|          |         | M1    | M2  |                                     |
| Empty    | 3.7     | 0.002 |     | No activity.                        |
| Blink    | 6.0     | 3.1   |     | Least efficient mode b/c of TIMER1. |
| Sensor   | 11.4    | 7.7   |     | Most efficient mode b/c of INT2.    |
| Radio    | 19.5    | 15.8  | 3.0 | Alternates INT2 <-> TIMER1.         |
| Protocol | 19.6    | 15.9  |     | Consumption dominated by the Radio. |

(Consumption in mA)

```
await FOREVER;
```

```
loop do  
  emit PIN(13,high);  
  await 1s;  
  emit PIN(13,low);  
  await 1s;  
end
```



RocketScream  
Low-Power  
Arduino

## Initial Results

|          | Arduino | Céu   |     | OBS                                 |
|----------|---------|-------|-----|-------------------------------------|
|          |         | M1    | M2  |                                     |
| Empty    | 3.7     | 0.002 |     | No activity.                        |
| Blink    | 6.0     | 3.1   |     | Least efficient mode b/c of TIMER1. |
| Sensor   | 11.4    | 7.7   |     | Most efficient mode b/c of INT2.    |
| Radio    | 19.5    | 15.8  | 3.0 | Alternates INT2 <-> TIMER1.         |
| Protocol | 19.6    | 15.9  |     | Consumption dominated by the Radio. |

(Consumption in mA)

await FOREVER;

loop do

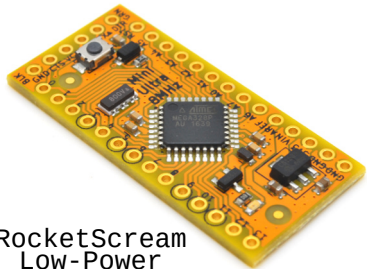
emit PIN(13,high);

await 1s;

emit PIN(13,low);

await 1s;

end



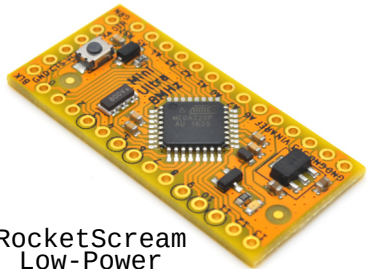
RocketScream  
Low-Power  
Arduino



## Initial Results

|          | Arduino | Céu   |     | OBS                                 |
|----------|---------|-------|-----|-------------------------------------|
|          |         | M1    | M2  |                                     |
| Empty    | 3.7     | 0.002 |     | No activity.                        |
| Blink    | 6.0     | 3.1   |     | Least efficient mode b/c of TIMER1. |
| Sensor   | 11.4    | 7.7   |     | Most efficient mode b/c of INT2.    |
| Radio    | 19.5    | 15.8  | 3.0 | Alternates INT2 <-> TIMER1.         |
| Protocol | 19.6    | 15.9  |     | Consumption dominated by the Radio. |

(Consumption in mA)



RocketScream  
Low-Power  
Arduino



await FOREVER;

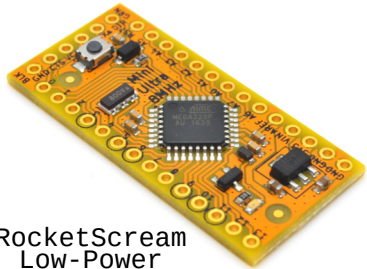
```
loop do
  emit PIN(13,high);
  await 1s;
  emit PIN(13,low);
  await 1s;
end
```

```
emit PIN(13, _digitalRead(2));
loop do
  var bool v = await Pin(2);
  emit PIN(13, v);
end
```

## Initial Results

|          | Arduino | Céu   |     | OBS                                 |
|----------|---------|-------|-----|-------------------------------------|
|          |         | M1    | M2  |                                     |
| Empty    | 3.7     | 0.002 |     | No activity.                        |
| Blink    | 6.0     | 3.1   |     | Least efficient mode b/c of TIMER1. |
| Sensor   | 11.4    | 7.7   |     | Most efficient mode b/c of INT2.    |
| Radio    | 19.5    | 15.8  | 3.0 | Alternates INT2 <-> TIMER1.         |
| Protocol | 19.6    | 15.9  |     | Consumption dominated by the Radio. |

(Consumption in mA)



RocketScream  
Low-Power  
Arduino



```
await FOREVER;
```

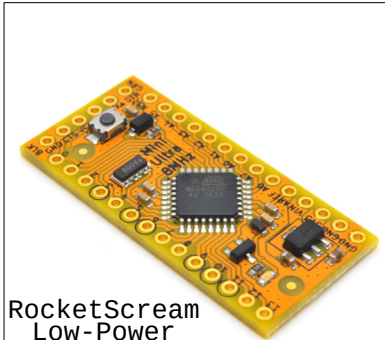
```
loop do
  emit PIN(13,high);
  await 1s;
  emit PIN(13,low);
  await 1s;
end
```

```
emit PIN(13, _digitalRead(2));
loop do
  var bool v = await Pin(2);
  emit PIN(13, v);
end
```

## Initial Results

|          | Arduino | Céu   |     | OBS                                 |
|----------|---------|-------|-----|-------------------------------------|
|          |         | M1    | M2  |                                     |
| Empty    | 3.7     | 0.002 |     | No activity.                        |
| Blink    | 6.0     | 3.1   |     | Least efficient mode b/c of TIMER1. |
| Sensor   | 11.4    | 7.7   |     | Most efficient mode b/c of INT2.    |
| Radio    | 19.5    | 15.8  | 3.0 | Alternates INT2 <-> TIMER1.         |
| Protocol | 19.6    | 15.9  |     | Consumption dominated by the Radio. |

(Consumption in mA)



RocketScream  
Low-Power  
Arduino



```
await FOREVER;
```

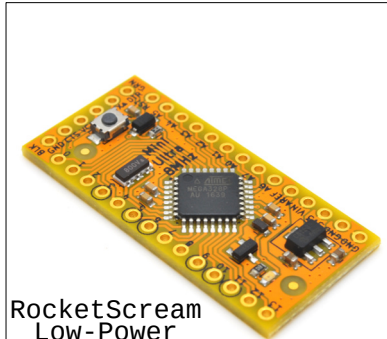
```
loop do
  emit PIN(13,high);
  await 1s;
  emit PIN(13,low);
  await 1s;
end
```

```
emit PIN(13, _digitalRead(2));
loop do
  var bool v = await Pin(2);
  emit PIN(13, v);
end
```

## Initial Results

|          | Arduino | Céu   |     | OBS                                 |
|----------|---------|-------|-----|-------------------------------------|
|          |         | M1    | M2  |                                     |
| Empty    | 3.7     | 0.002 |     | No activity.                        |
| Blink    | 6.0     | 3.1   |     | Least efficient mode b/c of TIMER1. |
| Sensor   | 11.4    | 7.7   |     | Most efficient mode b/c of INT2.    |
| Radio    | 19.5    | 15.8  | 3.0 | Alternates INT2 <-> TIMER1.         |
| Protocol | 19.6    | 15.9  |     | Consumption dominated by the Radio. |

(Consumption in mA)



RocketScream  
Low-Power  
Arduino



```
await FOREVER;
```

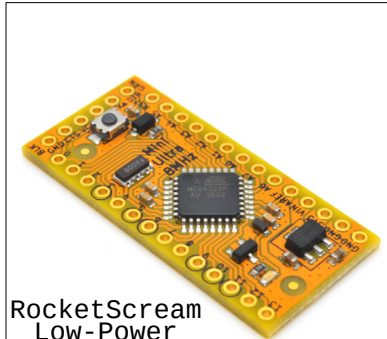
```
loop do
  emit PIN(13,high);
  await 1s;
  emit PIN(13,low);
  await 1s;
end
```

```
emit PIN(13, _digitalRead(2));
loop do
  var bool v = await Pin(2);
  emit PIN(13, v);
end
```

## Initial Results

|          | Arduino | Céu   |     | OBS                                 |
|----------|---------|-------|-----|-------------------------------------|
|          |         | M1    | M2  |                                     |
| Empty    | 3.7     | 0.002 |     | No activity.                        |
| Blink    | 6.0     | 3.1   |     | Least efficient mode b/c of TIMER1. |
| Sensor   | 11.4    | 7.7   |     | Most efficient mode b/c of INT2.    |
| Radio    | 19.5    | 15.8  | 3.0 | Alternates INT2 <-> TIMER1.         |
| Protocol | 19.6    | 15.9  |     | Consumption dominated by the Radio. |

(Consumption in mA)



RocketScream  
Low-Power  
Arduino



await FOREVER;

```
loop do
  emit PIN(13,high);
  await 1s;
  emit PIN(13,low);
  await 1s;
end
```

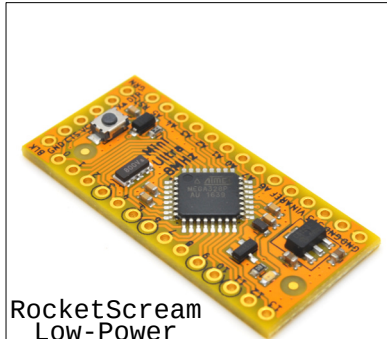
```
emit PIN(13, _digitalRead(2));
loop do
  var bool v = await Pin(2);
  emit PIN(13, v);
end
```



## Initial Results

|          | Arduino | Céu   |     | OBS                                 |
|----------|---------|-------|-----|-------------------------------------|
|          |         | M1    | M2  |                                     |
| Empty    | 3.7     | 0.002 |     | No activity.                        |
| Blink    | 6.0     | 3.1   |     | Least efficient mode b/c of TIMER1. |
| Sensor   | 11.4    | 7.7   |     | Most efficient mode b/c of INT2.    |
| Radio    | 19.5    | 15.8  | 3.0 | Alternates INT2 <-> TIMER1.         |
| Protocol | 19.6    | 15.9  |     | Consumption dominated by the Radio. |

(Consumption in mA)



RocketScream  
Low-Power  
Arduino



await FOREVER;

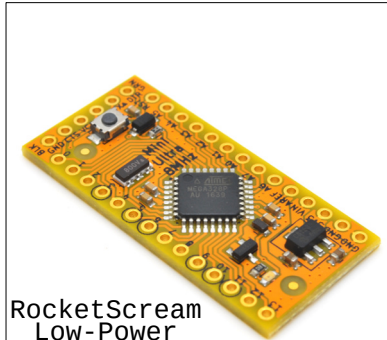
```
loop do
  emit PIN(13,high);
  await 1s;
  emit PIN(13,low);
  await 1s;
end
```

```
emit PIN(13, _digitalRead(2));
loop do
  var bool v = await Pin(2);
  emit PIN(13, v);
end
```

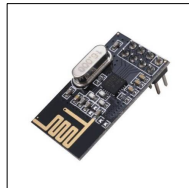
## Initial Results

|          | Arduino | Céu   |     | OBS                                 |
|----------|---------|-------|-----|-------------------------------------|
|          |         | M1    | M2  |                                     |
| Empty    | 3.7     | 0.002 |     | No activity.                        |
| Blink    | 6.0     | 3.1   |     | Least efficient mode b/c of TIMER1. |
| Sensor   | 11.4    | 7.7   |     | Most efficient mode b/c of INT2.    |
| Radio    | 19.5    | 15.8  | 3.0 | Alternates INT2 <-> TIMER1.         |
| Protocol | 19.6    | 15.9  |     | Consumption dominated by the Radio. |

(Consumption in mA)



RocketScream  
Low-Power  
Arduino



```
await FOREVER;
```

```
loop do
  emit PIN(13,high);
  await 1s;
  emit PIN(13,low);
  await 1s;
end
```

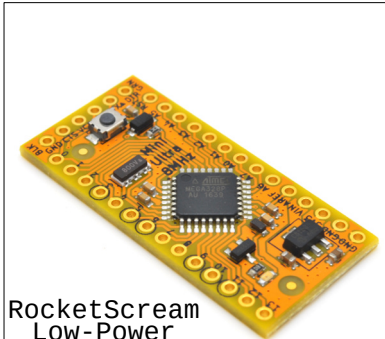
```
emit PIN(13, _digitalRead(2));
loop do
  var bool v = await Pin(2);
  emit PIN(13, v);
end
```

```
loop do
  await 5s;
  <...>
  await Nrf24l01_TX(...);
  <...>
  await Nrf24l01_RX(...);
  <...>
end
```

## Initial Results

|          | Arduino | Céu   |     | OBS                                 |
|----------|---------|-------|-----|-------------------------------------|
|          |         | M1    | M2  |                                     |
| Empty    | 3.7     | 0.002 |     | No activity.                        |
| Blink    | 6.0     | 3.1   |     | Least efficient mode b/c of TIMER1. |
| Sensor   | 11.4    | 7.7   |     | Most efficient mode b/c of INT2.    |
| Radio    | 19.5    | 15.8  | 3.0 | Alternates INT2 <-> TIMER1.         |
| Protocol | 19.6    | 15.9  |     | Consumption dominated by the Radio. |

(Consumption in mA)



RocketScream  
Low-Power  
Arduino



```
await FOREVER;
```

```
loop do
  emit PIN(13,high);
  await 1s;
  emit PIN(13,low);
  await 1s;
end
```

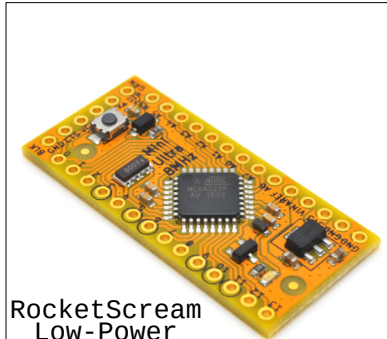
```
emit PIN(13, _digitalRead(2));
loop do
  var bool v = await Pin(2);
  emit PIN(13, v);
end
```

```
loop do
  await 5s;
  <...>
  await Nrf24l01_TX(...);
  <...>
  await Nrf24l01_RX(...);
  <...>
end
```

## Initial Results

|          | Arduino | Céu   |     | OBS                                 |
|----------|---------|-------|-----|-------------------------------------|
|          |         | M1    | M2  |                                     |
| Empty    | 3.7     | 0.002 |     | No activity.                        |
| Blink    | 6.0     | 3.1   |     | Least efficient mode b/c of TIMER1. |
| Sensor   | 11.4    | 7.7   |     | Most efficient mode b/c of INT2.    |
| Radio    | 19.5    | 15.8  | 3.0 | Alternates INT2 <-> TIMER1.         |
| Protocol | 19.6    | 15.9  |     | Consumption dominated by the Radio. |

(Consumption in mA)



RocketScream  
Low-Power  
Arduino



```
await FOREVER;
```

```
loop do
  emit PIN(13,high);
  await 1s;
  emit PIN(13,low);
  await 1s;
end
```

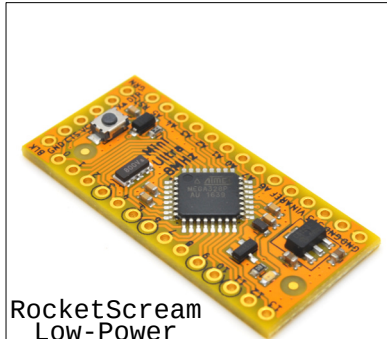
```
emit PIN(13, _digitalRead(2));
loop do
  var bool v = await Pin(2);
  emit PIN(13, v);
end
```

```
loop do
  await 5s;
  <...>
  await Nrf24l01_TX(...);
  <...>
  await Nrf24l01_RX(...);
  <...>
end
```

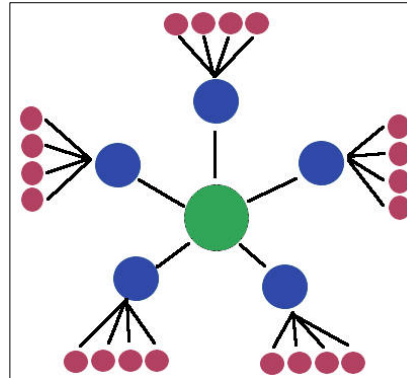
## Initial Results

|          | Arduino | Céu   |     | OBS                                 |
|----------|---------|-------|-----|-------------------------------------|
|          |         | M1    | M2  |                                     |
| Empty    | 3.7     | 0.002 |     | No activity.                        |
| Blink    | 6.0     | 3.1   |     | Least efficient mode b/c of TIMER1. |
| Sensor   | 11.4    | 7.7   |     | Most efficient mode b/c of INT2.    |
| Radio    | 19.5    | 15.8  | 3.0 | Alternates INT2 <-> TIMER1.         |
| Protocol | 19.6    | 15.9  |     | Consumption dominated by the Radio. |

(Consumption in mA)



RocketScream  
Low-Power  
Arduino



await FOREVER;

```
loop do
  emit PIN(13,high);
  await 1s;
  emit PIN(13,low);
  await 1s;
end
```

```
emit PIN(13, _digitalRead(2));
loop do
  var bool v = await Pin(2);
  emit PIN(13, v);
end
```

```
loop do
  await 5s;
  <...>
  await Nrf24l01_TX(...);
  <...>
  await Nrf24l01_RX(...);
  <...>
end
```

# General Approach

(standby, constrained, programming language, transparent)

```
par/or do
  await RadioAval();
with
  loop do
    await 1s;
    int v = await AnalogRead();
    await RadioWrite(v);
  end
end
```

# General Approach

(standby, constrained, programming language, transparent)

- Enforce idle states of execution

```
par/or do
  await RadioAval();
with
  loop do
    await 1s;
    int v = await AnalogRead();
    await RadioWrite(v);
  end
end
```

# General Approach

(standby, constrained, programming language, transparent)

- Enforce idle states of execution
  - Céu enforces a reactive model of execution
- Infer deepest sleeping mode

```
par/or do
  await RadioAvail();
with
  loop do
    await 1s;
    int v = await AnalogRead();
    await RadioWrite(v);
  end
end
```



# General Approach

(standby, constrained, programming language, transparent)

- Enforce idle states of execution
  - Céu enforces a reactive model of execution
- Infer deepest sleeping mode

```
par/or do
  await RadioAvail();
with
  loop do
    await 1s;
    int v = await AnalogRead();
    await RadioWrite(v);
  end
end
```

# General Approach

(standby, constrained, programming language, transparent)

- Enforce idle states of execution
  - Céu enforces a reactive model of execution
- Infer deepest sleeping mode
  - Céu has a semantics amenable to analysis
- Put device to sleep

```
par/or do
  await RadioAval();
with
  loop do
    await 1s;
    int v = await AnalogRead();
    await RadioWrite(v);
  end
end
```

# General Approach

(standby, constrained, programming language, transparent)

- Enforce idle states of execution
  - Céu enforces a reactive model of execution
- Infer deepest sleeping mode
  - Céu has a semantics amenable to analysis
- Put device to sleep

```
par/or do
  await RadioAvail();
with
  loop do
    await 1s;
    int v = await AnalogRead();
    await RadioWrite(v);
  end
end
```

# General Approach

(standby, constrained, programming language, transparent)

- Enforce idle states of execution
  - Céu enforces a reactive model of execution
- Infer deepest sleeping mode
  - Céu has a semantics amenable to analysis
- Put device to sleep
  - Céu has an energy-aware runtime
- Only awake from interrupts

```
par/or do
  await RadioAvail();
with
  loop do
    await 1s;
    int v = await AnalogRead();
    await RadioWrite(v);
  end
end
```

# General Approach

(standby, constrained, programming language, transparent)

- Enforce idle states of execution
  - Céu enforces a reactive model of execution
- Infer deepest sleeping mode
  - Céu has a semantics amenable to analysis
- Put device to sleep
  - Céu has an energy-aware runtime
- Only awake from interrupts
  - Céu provides interrupt service routines (ISRs)

```
par/or do
  await RadioAvail();
with
  loop do
    await 1s;
    int v = await AnalogRead();
    await RadioWrite(v);
  end
end
```

# *Transparent Standby for Low-Power, Resource-Constrained Embedded Systems*

*A Programming Language-Based Approach*



*Francisco Sant'Anna*  
**francisco@ime.uerj.br**  
**@\_fsantanna**



# Standby Efficiency for IoT



# Standby Efficiency for IoT

- 15 billion “traditional” network-connected devices in 2015 (e.g., mobile phones & smart TVs).

# Standby Efficiency for IoT

- 15 billion “traditional” network-connected devices in 2015 (e.g., mobile phones & smart TVs).
- 75 billion by 2025 with the IoT (e.g., smart bulbs & fitness wearables). [2016]

# Standby Efficiency for IoT

- 15 billion “traditional” network-connected devices in 2015 (e.g., mobile phones & smart TVs).
- 75 billion by 2025 with the IoT (e.g., smart bulbs & fitness wearables). [2016]
- **Most energy consumed in standby mode.**

# Standby Efficiency for IoT

- 15 billion “traditional” network-connected devices in 2015 (e.g., mobile phones & smart TVs).
- 75 billion by 2025 with the IoT (e.g., smart bulbs & fitness wearables). [2016]
- **Most energy consumed in standby mode.**
- Network standby is one of the six fronts on IEA/G20's Energy Efficiency Action Plan
  - <https://www.iea-4e.org/projects/g20>

# Related Publications

# Related Publications

- SenSys'13, ACM Embedded Networked Sensor Systems
  - *Safe System-level Concurrency on Resource-Constrained Nodes*

# Related Publications

- SenSys'13, ACM Embedded Networked Sensor Systems
  - *Safe System-level Concurrency on Resource-Constrained Nodes*
- TECS'17, ACM Transactions on Embedded Computing Systems
  - *The Design and Implementation of the Synchronous Language Céu*

# Related Publications

- SenSys'13, ACM Embedded Networked Sensor Systems
  - *Safe System-level Concurrency on Resource-Constrained Nodes*
- TECS'17, ACM Transactions on Embedded Computing Systems
  - *The Design and Implementation of the Synchronous Language Céu*
- LCTES'18, ACM Conference on Languages, Compilers, and Tools for Embedded Systems
  - *A Memory-Bounded, Deterministic and Terminating Semantics  
for the Synchronous Programming Language Céu*



# Related Publications

- SenSys'13, ACM Embedded Networked Sensor Systems
  - *Safe System-level Concurrency on Resource-Constrained Nodes*
- TECS'17, ACM Transactions on Embedded Computing Systems
  - *The Design and Implementation of the Synchronous Language Céu*
- LCTES'18, ACM Conference on Languages, Compilers, and Tools for Embedded Systems
  - *A Memory-Bounded, Deterministic and Terminating Semantics  
for the Synchronous Programming Language Céu*
- LCTES'18, ACM Conference on Languages, Compilers, and Tools for Embedded Systems
  - *WIP: Transparent Standby for Low-Power, Resource-Constrained*

# Related Publications

- SenSys'13, ACM Embedded Networked Sensor Systems
  - *Safe System-level Concurrency on Resource-Constrained Nodes*
- TECS'17, ACM Transactions on Embedded Computing Systems
  - *The Design and Implementation of the Synchronous Language Céu*
- LCTES'18, ACM Conference on Languages, Compilers, and Tools for Embedded Systems
  - *A Memory-Bounded, Deterministic and Terminating Semantics  
for the Synchronous Programming Language Céu*
- LCTES'18, ACM Conference on Languages, Compilers, and Tools for Embedded Systems
  - *WIP: Transparent Standby for Low-Power, Resource-Constrained*

# Cooperation Opportunities

- Hardware infrastructure
  - Off-the-shelf Arduinos (ATMega328, Cortex-M0)
- Software infrastructure
  - Implement an energy-aware runtime for Céu
  - Rewrite device drivers in Céu (timers, ADC, Radio)
- Applications
  - Rewrite existing IoT applications in Céu
    - Time to rewrite

# Cooperation Opportunities

- Hardware infrastructure
  - Off-the-shelf Arduinos (ATMega328, Cortex-M0)
- Software infrastructure
  - Implement an energy-aware runtime for Céu
    - Rewrite device drivers in Céu (timers, ADC, Radio)
- Applications
  - Rewrite existing IoT applications in Céu
    - Time to rewrite