

Energy Efficiency for IoT Software in the Large

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About us...

- Research areas:
 - Programming Languages
 - Concurrent & Distributed Systems
- Programming Language “Céu”
 - Embedded platforms
 - Wireless Sensor Networks (WSNs)
 - Games
 - ~10 years of research

Energy Efficiency for IoT

- 14 billion “traditional” network-connected devices (e.g., mobile phones & smart TVs).
- 50 billion by 2020 with the IoT (e.g., smart bulbs & fitness wearables).
- **Most energy consumed in standby mode.**
- Network standby is one of the six fronts on IEA/G20's Energy Efficiency Action Plan
 - <https://www.iea-4e.org/projects/g20>

Project Goals

1. Address energy efficiency through rigorous use of **standby**.
2. Target **constrained** embedded architectures that form the IoT.
3. Provide standby mechanisms at the **programming language** level that scale to all applications.
4. Support **transparent**/non-intrusive standby mechanisms that reduce barriers of adoption.

Project Non-Goals

- Adaptive Computing
 - QoS (e.g., resolution, frame rate, accuracy)
 - Behavior (e.g., switch UI, disable functionalities)
 - *Don't take advantage of standby modes (goal 1)*
- Energy-Aware Network Protocols
 - Low-power listening
 - Small periods of duty cycles
 - *Only for networked parts, not automatic (goals 3 & 4)*
- Complex Hardware Architectures
 - Microprocessors, MMU, OS-based, Smartphones
 - *Not constrained embedded platforms (goal 2)*

Our Approach

- Enforce idle states of execution
 - Céu enforces a reactive model of execution
- Infer deepest sleeping mode
 - Céu has a semantics amenable to analysis
- Put device to sleep
 - Céu has an energy-aware runtime
- Only awake from interrupts
 - Céu provides interrupt service routines (ISRs)

A Motivating Example

Every second, read sensor value and broadcast it.

- Arduino

```
while (1) {  
    delay(1000);  
    int v = analogRead();  
    radioWrite(v);  
}
```

- Céu

```
loop do  
    await 1s;  
    int v = await AnalogRead();  
    await RadioWrite(v);  
end
```

Let's add concurrency...

Every second, read sensor value and broadcast it.

Stop immediately as soon as a message arrives.

- Arduino

```
uint32_t prv = millis();
while (1) {
    if (radioAvail())
        break;
    uint32_t cur = millis();
    if (cur > prv+1000) {
        prv = cur;
        int v = analogRead();
        radioWrite(v);
    }
}
```

```
while (1) {
    delay(1000);
    int v = analogRead();
    radioWrite(v);
}
```

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    }
}
```

▪ Céu

```
par/or do
    await RadioAvail();
with
    loop do
        await 1s;
        int v = await AnalogRead();
        await RadioWrite(v);
    end
end
```

Standby Considerations

*Every second, read sensor value and broadcast it.
Stop immediately as soon as a message arrives.*

- Arduino

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uint32_t prv = millis();  
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- Céu

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par/or do  
    await RadioAvail();  
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    end  
end
```

Céu in a Nutshell

- Reactive
 - environment in control: *events*
- Imperative
 - sequences, loops, assignments
- Concurrent
 - multiple lines of execution: *trails*
- Synchronous
 - trails synchronize at each external event
 - **trails are always awaiting**
- Deterministic
 - always yields the same outcome for a given timeline

Project In Practice...

- Hardware infrastructure
 - Off-the-shelf Arduinos (ATMega328, Cortex-M0)
- Software infrastructure
 - Implement an energy-aware runtime for Céu
 - Rewrite device drivers in Céu (timers, ADC, Radio)
- Applications
 - Rewrite existing IoT applications in Céu
 - Time to rewrite
 - Coding “aesthetics”
 - Energy consumption

```

par/or do
    await RadioAvail();
with
    loop do
        await 1s;
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    end
end

```

```

output void ADC_REQUEST do
    ADMUX = 0x40|(A0&0x07);
    bitSet(ADCSRA, ADIE);
    bitSet(ADCSRA, ADSC);
end

```

```

input ADC_vect_num do
    bitClear(ADCSRA, ADIE);
    emit ADC_DONE(ADC);
end

```

```

code AnalogRead (void) -> int
do
    PM_SET(PM_ADC, 1);
    do finalize with
        PM_SET(PM_ADC, 0);
    end
    emit ADC_REQUEST;
    int value = await ADC_DONE;
    escape value;
end

```



```

par/or do
    await RadioAvail();
with
    loop do
        await 1s;
        int v = await AnalogRead();
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end

```

```

input ADC_vect_num do
    bitClear(ADCSRA, ADIE);
    emit ADC_DONE(ADC);
end

```

```

void pm_sleep (void) {
    if (PM_GET(PM_TIMER1)) {
        sleep_1(<...>)
    } else if (PM_GET(PM_ADC)) {
        sleep_2(<...>);
    } else {
        sleep_3(<...>);
    }
}

```

```

code AnalogRead (void) -> int
do
    PM_SET(PM_ADC, 1);
    do finalize with
        PM_SET(PM_ADC, 0);
    end
    emit ADC_REQUEST;
    int value = await ADC_DONE;
    escape value;
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Current Status

- SenSys'13, ACM Embedded Networked Sensor Systems
 - *Safe System-level Concurrency on Resource-Constrained Nodes*
- TECS'17, ACM Transactions on Embedded Computing Systems
 - *The Design and Implementation of the Synchronous Language Céu*
- LCTES'18, ACM Conference on Languages, Compilers, and Tools for Embedded Systems
 - *A Memory-Bounded, Deterministic and Terminating Semantics
for the Synchronous Programming Language Céu*
- LCTES'18, ACM Conference on Languages, Compilers, and Tools for Embedded Systems
 - *WIP: Transparent Standby for Low-Power, Resource-Constrained
Embedded Systems*

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(Projeto Serrapilheira)

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