Graph, Network, and Tree Visualization

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Introduction

- In addition to presenting values associated with data instances, visualization techniques may also represent **relationships**:
 - Part/sub-part, parent/child, or other hierarchical relationship
 - Connectedness, such as cities connected by streets
 - Derivations, such as a sequence of steps or stages
 - Similarities in values/attributes, such as temporal/spatial
- Relationships can be simple or complex
 - Directed/non-directed
 - Weighted/unweighted
 - Certain/uncertain

Relationships may provide more richer information than the contained in the data values.

Visualizing Trees and Hierarchies

- The most basic are the hierarchical relationships
- We can split the techniques for visualizing trees/hierarchies into
 - Space filling methods
 - Non-space filling methods

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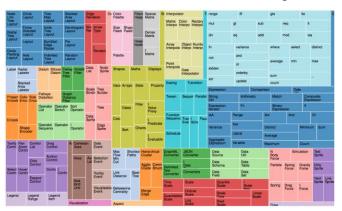
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Space Filling Methods

- Space filling techniques seek to use as much as possible the available visual space
 - Juxtaposition (side-by-side) is used to represent the connection between data objects.
 - As opposed to, for example, using edges to convey relations.
- The most common approaches are:
 - Rectangular, and
 - Radial representations

Space Filling Methods

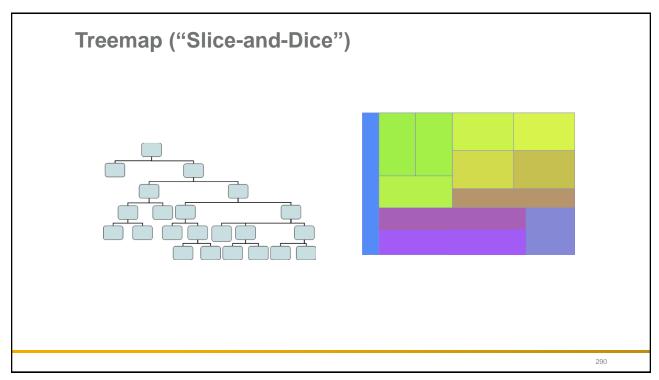
- Treemaps is the most popular rectangular representation
 - A rectangle is recursively divided into pieces, alternating horizontal and vertical cuts, based on the sub-trees size at a given level



https://bl.ocks.org/mbostock/4063582

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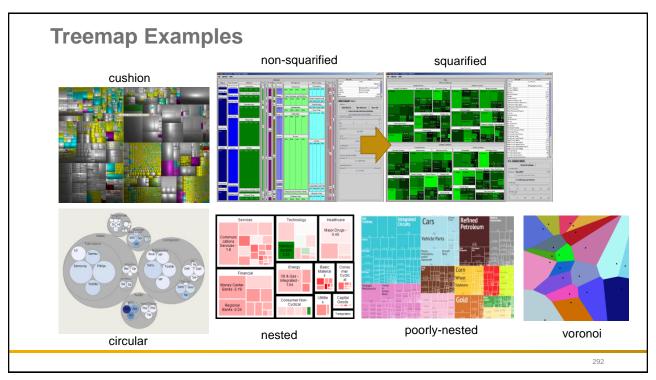


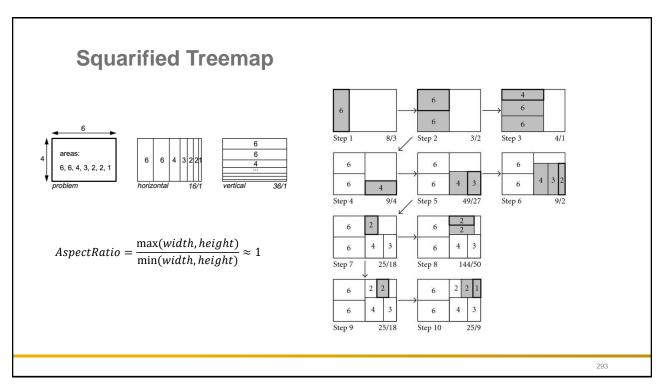
Space-filling Methods

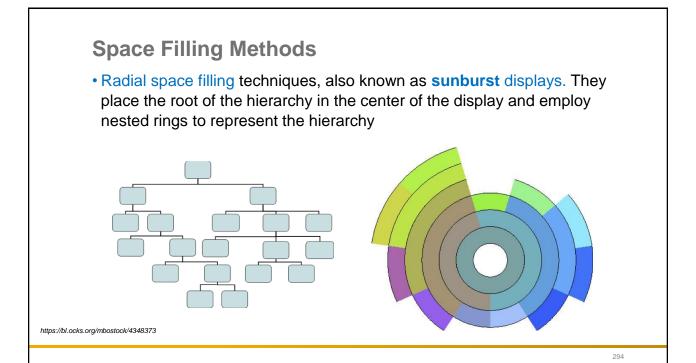
- There are other variations of the basic Treemap method ("slice-and-dice")
 - Cushion treemap uses lighting effect to improve hierarchy identification
 - Squarified treemap reduces long and thin rectangles
 - Nested treemap emphasizes the hierarchical structure
 - Voronoi treemap employs Voronoi diagrams instead of rectangles
 - Circular treemap employs circles within circles
- More Information in
 - http://www.cs.umd.edu/hcil/treemap-history/

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Space Filling Methods

- Note:
 - Unlike Treemaps, the sunburst technique employs the visual space to model the intermediate (non-terminal) nodes

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Non-space Filling Methods

- The most common method for displaying hierarchical relationships is the node-link diagram
- In the design of algorithms for drawing diagrams some factors need to be taken into account:
 - Draw conventions straight edges, polygonal lines or curves; position of nodes in a grid; all siblings in the same vertical position, etc.
 - Restrictions positioning a particular node in the center of the drawing, positioning groups of nodes close to each other, etc.
 - Aesthetics several rules that greatly influence the final interpretation (next slide)

Non-space Filling Methods

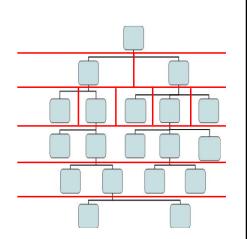
- Aesthetic rules can be:
 - Minimize cross-lines
 - Keep nice aspect ratio
 - · Minimize total drawing area
 - Minimize overall edge size
 - · Minimize the number of distinct angles and curvatures
 - Try to create a symmetric structure

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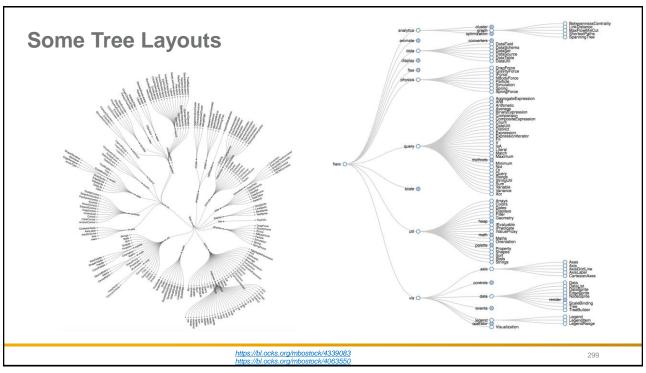
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Non-space Filling Methods

- For trees it is relatively easy to respect these rules
- A simple algorithm could be:
 - 1. Split the drawing area into slices of equal height, considering the height of the tree
 - 2. Divide each slice into rectangles of equal sizes, considering the number of nodes at each level
 - Draw each node in the center of its corresponding rectangle
 - 4. Draw a line between the center-bottom of each node to the center-top of its child nodes



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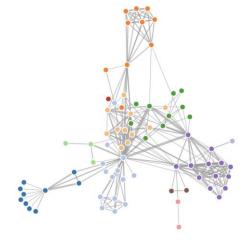
Graphs and Networks

- Trees are a specific type of graphs which are
 - · Connected, unweighted and acyclic
- There are specific techniques for **visualizing** general graphs, two examples are
 - Node-link diagrams
 - Matrix representations

Node-Link Force-based Representations

Example: Les Misérables

What can we say by looking at the graph?



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Node-Link Force-based Representations

- Force-based methods use a spring analogy to represent the edges, with nodes' positions iteratively changed until a stable state is reached
- There are two forces between nodes
 - f_{ii}: spring (attraction/repulsion) force between connected nodes
 - g_{ij} : repulsion force to avoid neighbor nodes to get too close
- The simplest model uses Hook's laws to represent the force of a spring and the inverse square law to represent the repulsion

Node-Link Force-based Representations

• If d(i,j) is the distance between two nodes, s_{ij} is the size of the spring (at rest), and k_{ij} is the spring tension, the *x*-component of the spring force can be calculated as

$$f_{ij}(x) = (k_{ij} \times (d(i,j) - s_{ij})) \times (x_j - x_i) / d(i,j)$$

• If rij is the repulsion tension, the x-component of repulsion force will be

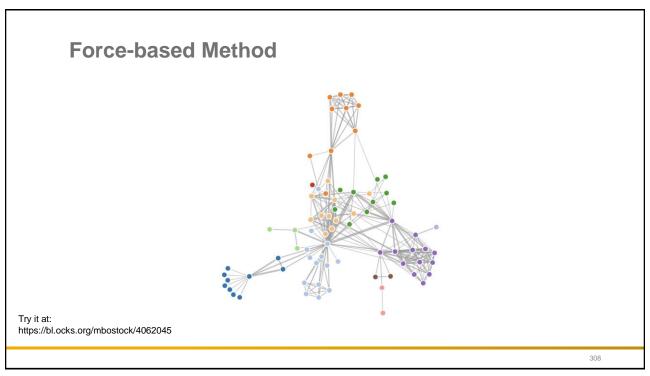
$$g_{ij}(x) = (r_{ij} / d(i,j)^2) \times (x_i - x_j) / d(i,j)$$

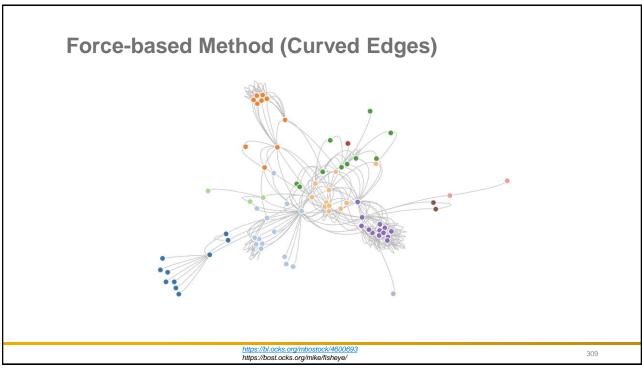
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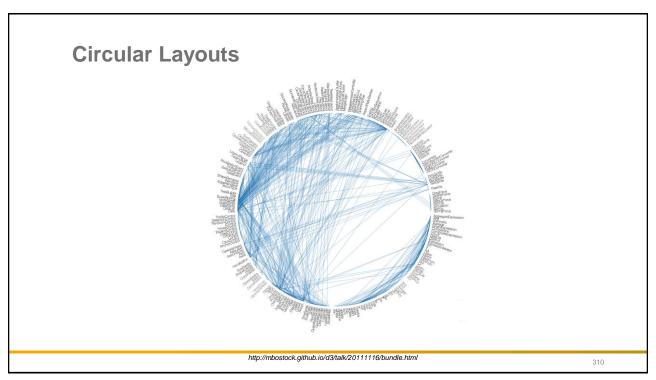
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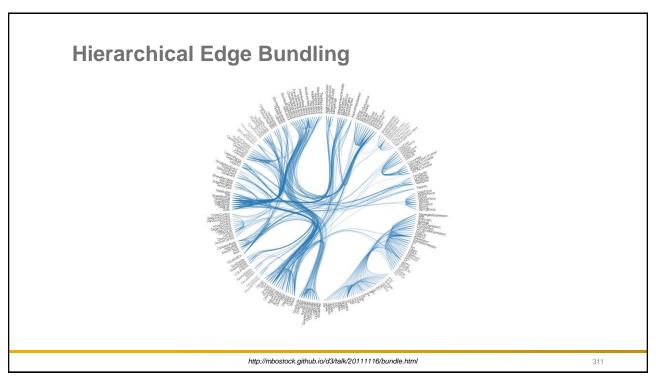
Node-Link Force-based Representations

- Start position can be random
- In each iteration the forces on each node are calculated and their positions are updated
- To avoid oscillations the forces should decrease over time
 - The result can converge to a local minimum

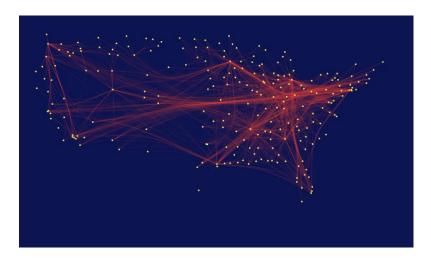








Force-based Edge Bundling



http://bl.ocks.org/upphiminn/6515478

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Matrix Representation

- An alternative representation is the adjacency matrices
 - A grid $n \times n$ where the positions (i,j) represent the existence (or not) of edges between nodes i and j
- This method overcomes the edge-crossing problem, but has issues with scalability (with thousands of nodes)
- Research began to seek for reordering's that could depict structures in the data

Matrix Representation

• There are specific strategies for reordering, from user-centric to automatic (it is a NP-complete problem)

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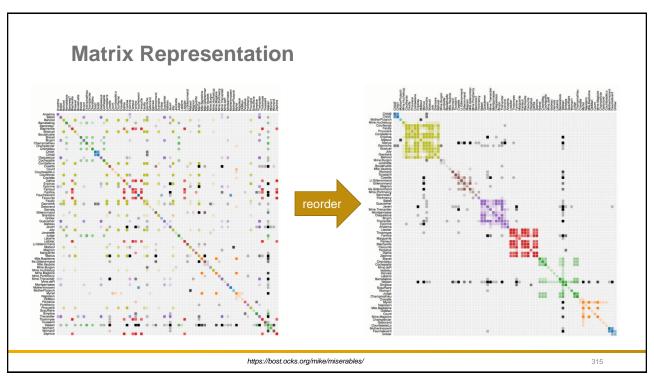
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Reference

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