

# Non Parametric Models

An Introduction:

Histogram, Parzen Window and *K*-Nearest Neighbor

Dr Muhammad Sarim

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- Density estimation with parametric models assumes that the forms of the underlying density functions are known.
- However, common parametric forms do not always fit the densities actually encountered in practice.
- In addition, most of the classical parametric densities are unimodal, whereas many practical problems involve multimodal densities.
- Non-parametric methods can be used with arbitrary distributions and without the assumption that the forms of the underlying densities are known.

# Non-Parametric Density Estimation

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- The expected value of  $k$  is  $E[k] = nP$  and the MLE for  $P$  is  $\hat{P} = \frac{k}{n}$ .

# Non-Parametric Density Estimation

- If we assume that  $p(\mathbf{x})$  is continuous and  $\mathcal{R}$  is small enough so that  $p(\mathbf{x})$  does not vary significantly in it, we can get the approximation

$$\int_{\mathcal{R}} p(\mathbf{x}') d\mathbf{x}' \simeq p(\mathbf{x})V$$

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- Then, the density estimate becomes

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- If  $p_n(\mathbf{x})$  is to converge to  $p(\mathbf{x})$ , three conditions are required:

$$\lim_{n \rightarrow \infty} V_n = 0$$

$$\lim_{n \rightarrow \infty} k_n = \infty$$

$$\lim_{n \rightarrow \infty} \frac{k_n}{n} = 0$$

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# Histogram Method

- A very simple method is to partition the space into a number of equally-sized cells (**bins**) and compute a **histogram**.

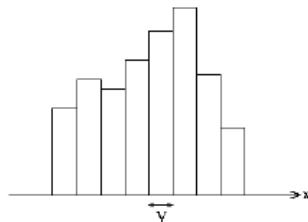


Figure: Histogram in one dimension.

- The estimate of the density at a point  $\mathbf{x}$  becomes

$$p(\mathbf{x}) = \frac{k}{nV}$$

where  $n$  is the total number of samples,  $k$  is the number of samples in the cell that includes  $\mathbf{x}$ , and  $V$  is the volume of that cell.



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  - Dependence trees.

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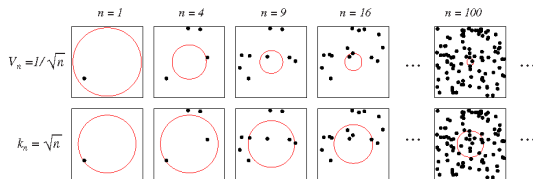
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**Figure:** Two common methods for estimating the density at a point, here at the center of each square.

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# Parzen Windows

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- A density estimate can be obtained as

$$p_n(\mathbf{x}) = \frac{1}{n} \sum_{i=1}^n \frac{1}{V_n} \varphi\left(\frac{\mathbf{x} - \mathbf{x}_i}{h_n}\right)$$

where  $h_n$  is the window width and  $V_n = h_n^d$ .

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- The density estimate can also be written as

$$p_n(\mathbf{x}) = \frac{1}{n} \sum_{i=1}^n \delta_n(\mathbf{x} - \mathbf{x}_i) \quad \text{where} \quad \delta_n(\mathbf{x}) = \frac{1}{V_n} \varphi\left(\frac{\mathbf{x}}{h_n}\right)$$



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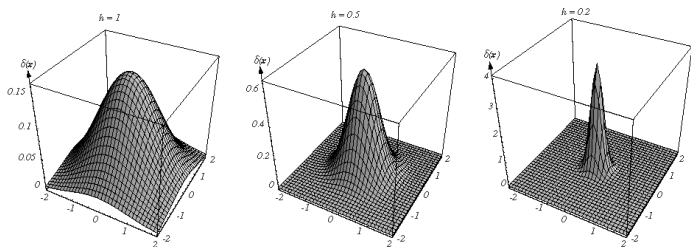
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**Figure:** Examples of two-dimensional circularly symmetric Parzen windows for three different values of  $h_n$ . The value of  $h_n$  affects both the amplitude and the width of  $\delta_n(\mathbf{x})$ .

# Parzen Windows

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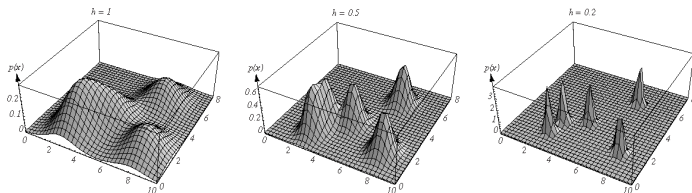
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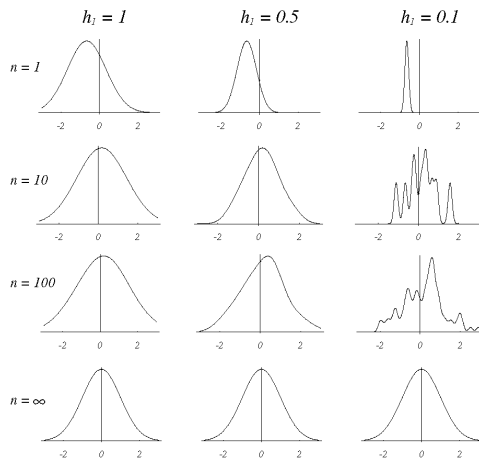
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**Figure:** Parzen window density estimates based on the same set of five samples using the window functions in the previous figure.

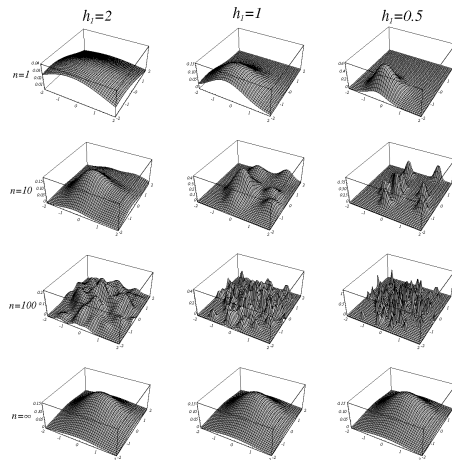
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**Figure:** Parzen window estimates of a univariate Gaussian density using different window widths and numbers of samples where  $\varphi(u) = N(0, 1)$  and  $h_n = h_1/\sqrt{n}$ .

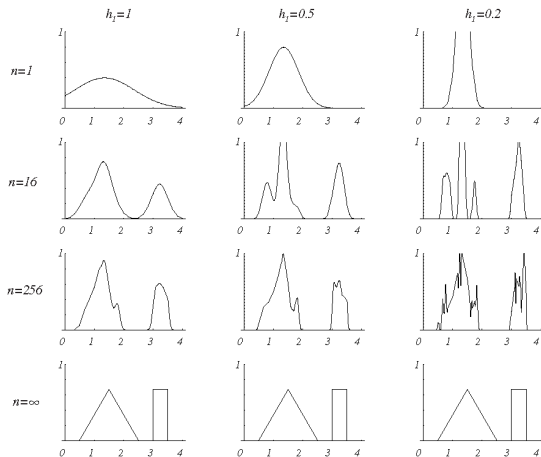


# Parzen Windows



**Figure:** Parzen window estimates of a bivariate Gaussian density using different window widths and numbers of samples where  $\varphi(\mathbf{u}) = N(\mathbf{0}, \mathbf{I})$  and  $h_n = h_1/\sqrt{n}$ .

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**Figure:** Estimates of a mixture of a uniform and a triangle density using different window widths and numbers of samples where  $\varphi(\mathbf{u}) = N(\mathbf{0}, \mathbf{I})$  and  $h_n = h_1/\sqrt{n}$ .

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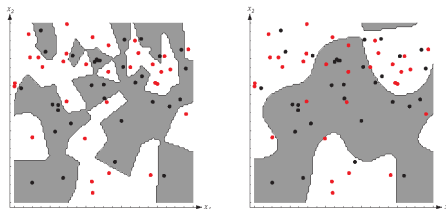
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**Figure:** Decision boundaries in 2-D. The left figure uses a small window width and the right figure uses a larger window width.

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# K-Nearest Neighbors

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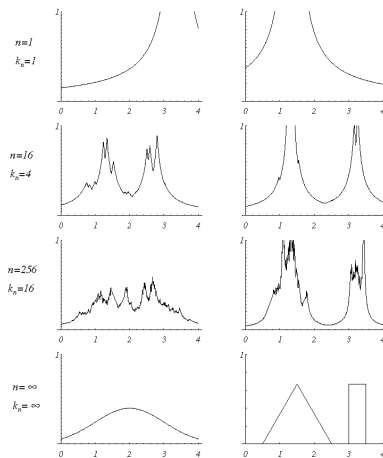
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- These samples are called the  $k$ -nearest neighbors of  $\mathbf{x}$ .
- If the density is high near  $\mathbf{x}$ , the volume will be relatively small. If the density is low, the volume will grow large.

# K-Nearest Neighbors



**Figure:**  $k$ -nearest neighbor estimates of two 1-D densities: a Gaussian and a bimodal distribution.

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- Suppose that a volume  $V$  around  $\mathbf{x}$  includes  $k$  samples,  $k_i$  of which are labeled as belonging to class  $w_i$ .
- As estimate for the joint probability  $p(\mathbf{x}, w_i)$  becomes

$$p_n(\mathbf{x}, w_i) = \frac{k_i/n}{V}$$

and gives an estimate for the posterior probability

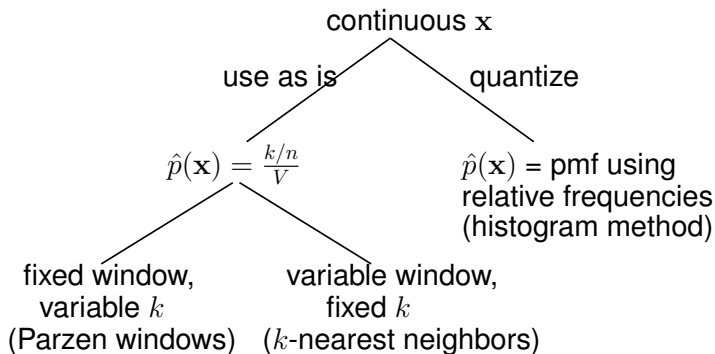
$$P_n(w_i|\mathbf{x}) = \frac{p_n(\mathbf{x}, w_i)}{\sum_{j=1}^c p_n(\mathbf{x}, w_j)} = \frac{k_i}{k}$$



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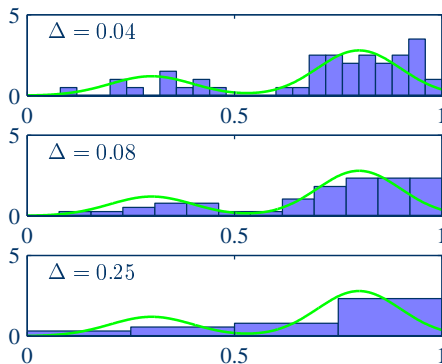
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  - There may be severe requirements for computation time and storage.

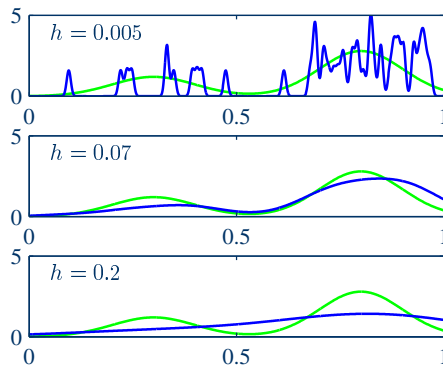


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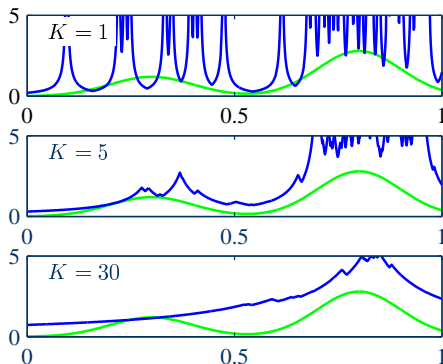
**Figure 10:** An illustration of the histogram approach to density estimation, in which a data set of 50 points is generated from the distribution shown by the green curve. Histogram density estimates are shown for various values of the cell volume ( $\Delta$ ).

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**Figure 11:** Illustration of the Parzen density model. The window width ( $h$ ) acts as a smoothing parameter. If it is set too small (top), the result is a very noisy density model. If it is set too large (bottom), the bimodal nature of the underlying distribution is washed out. An intermediate value (middle) gives a good estimate.

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**Figure 12:** Illustration of the  $k$ -nearest neighbor density model. The parameter  $k$  governs the degree of smoothing. A small value of  $k$  (top) leads to a very noisy density model. A large value (bottom) smooths out the bimodal nature of the true distribution.

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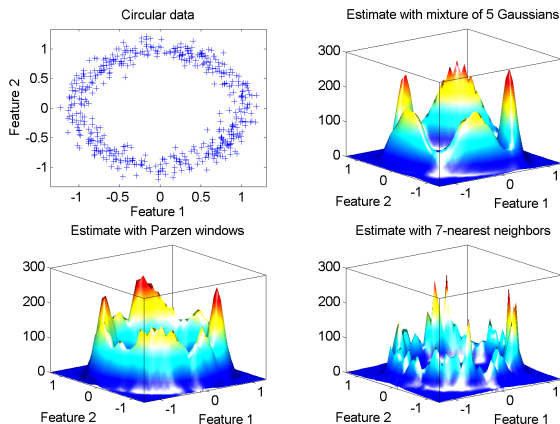


Figure 13: Density estimation examples for 2-D circular data.

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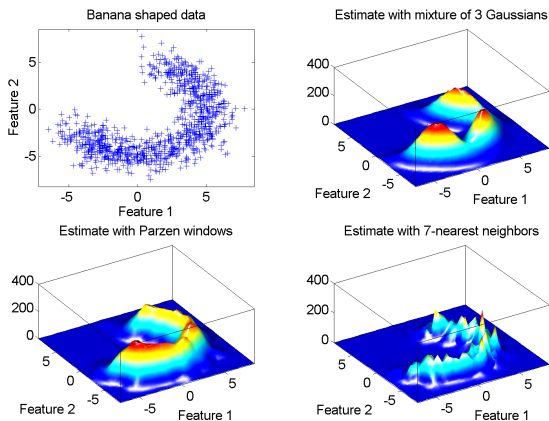


Figure 14: Density estimation examples for 2-D banana shaped data