

Formal Modelling of Communicating Systems - Homework 2

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Exercise 3.2

$$CA \stackrel{\text{def}}{=} \overline{\text{coin}}.\text{coffee}.CA$$

$$CTM \stackrel{\text{def}}{=} \text{coin}.\overline{(\text{coffee}.CTM + \overline{\text{tea}}.CTM)}$$

$$CTM' \stackrel{\text{def}}{=} \text{coin}.\overline{\text{coffee}}.CTM' + \text{coin}.\overline{\text{tea}}.CTM'$$

1. No, the first process won't deadlock since it can always synchronize over coffee, hence it's set of completed traces is empty:

$$\text{Traces}((CA|CTM) \setminus \{\text{coin}, \text{coffee}, \text{tea}\}) = \{\}$$

The second process, however can deadlock and has the following set of completed traces:

$$\begin{aligned} \text{Traces}((\{CA|CTM'\} \setminus \{\text{coin}, \text{coffee}, \text{tea}\}) = \{ \\ (\{CA|CTM'\} \setminus \{\text{coin}, \text{coffee}, \text{tea}\}) \rightarrow \\ ((\text{coffee}.CA|\overline{\text{tea}}.CTM') \setminus \{\text{coin}, \text{coffee}, \text{tea}\}) \rightharpoonup \} \end{aligned}$$

2. Yes

Exercise 3.3

$$P \stackrel{\text{def}}{=} a.P_1$$

$$P_1 \stackrel{\text{def}}{=} b.P + c.P$$

$$Q \stackrel{\text{def}}{=} a.Q_1$$

$$Q_1 \stackrel{\text{def}}{=} b.Q_2 + c.Q$$

$$Q_2 \stackrel{\text{def}}{=} a.Q_3$$

$$Q_3 \stackrel{\text{def}}{=} b.Q + c.Q_2$$

To show that $P \sim Q$ we create the following bisimulation:

$$\mathcal{R} = \{(P, Q), (P_1, Q_1), (P, Q_2), (P_1, Q_3)\}$$

- Consider the first pair (P, Q) :
 - transitions from P
 - * $P \xrightarrow{a} P_1$ can be matched by $Q \xrightarrow{a} Q_1$ and $(P_1, Q_1) \in \mathcal{R}$
 - * this is the only transition from P .
 - transitions from Q
 - * $Q \xrightarrow{a} Q_1$ can be matched by $P \xrightarrow{a} P_1$ and $(P_1, Q_1) \in \mathcal{R}$
 - * this is the only transition from Q .
- Consider the next pair (P_1, Q_1) :
 - transitions from P_1
 - * $P_1 \xrightarrow{b} P$ can be matched by $Q_1 \xrightarrow{b} Q_2$ and $(P, Q_2) \in \mathcal{R}$
 - * $P_1 \xrightarrow{c} P$ can be matched by $Q_1 \xrightarrow{c} Q$ and $(P, Q) \in \mathcal{R}$
 - * these are all transitions from P_1 .
 - transitions from Q_1
 - * $Q_1 \xrightarrow{b} Q_2$ can be matched by $P_1 \xrightarrow{b} P$ and $(P, Q_2) \in \mathcal{R}$
 - * $Q_1 \xrightarrow{c} Q$ can be matched by $P_1 \xrightarrow{c} P$ and $(P, Q) \in \mathcal{R}$
 - * these are all transitions from Q_1 .
- Consider the next pair (P, Q_2) :
 - transitions from P
 - * $P \xrightarrow{a} P_1$ can be matched by $Q_2 \xrightarrow{a} Q_3$ and $(P_1, Q_3) \in \mathcal{R}$
 - * this is the only transition from P .
 - transitions from Q_2
 - * $Q_2 \xrightarrow{a} Q_3$ can be matched by $P \xrightarrow{a} P_1$ and $(P_1, Q_3) \in \mathcal{R}$
 - * this is the only transition from Q_2 .
- Consider the final pair (P_1, Q_3) :
 - transitions from P_1
 - * $P_1 \xrightarrow{b} P$ can be matched by $Q_3 \xrightarrow{b} Q$ and $(P, Q) \in \mathcal{R}$
 - * $P_1 \xrightarrow{c} P$ can be matched by $Q_3 \xrightarrow{c} Q_2$ and $(P, Q_2) \in \mathcal{R}$
 - * these are all transitions from P_1 .
 - transitions from Q_3
 - * $Q_3 \xrightarrow{b} Q$ can be matched by $P_1 \xrightarrow{b} P$ and $(P, Q) \in \mathcal{R}$
 - * $Q_3 \xrightarrow{c} Q_2$ can be matched by $P_1 \xrightarrow{c} P$ and $(P, Q_2) \in \mathcal{R}$
 - * these are all transitions from Q_3 .

\mathcal{R} is a strong bisimulation and $(P, Q) \in \mathcal{R}$, therefore $P \sim Q$.

Exercise 3.5

The LTSs for s and t can be described by the following CCS expressions:

$$\begin{array}{ll}
 s \stackrel{\text{def}}{=} a.s_1 + a.s_2 & t \stackrel{\text{def}}{=} a.t_1 + a.t_3 \\
 s_1 \stackrel{\text{def}}{=} a.s_3 + b.s_4 & t_1 \stackrel{\text{def}}{=} a.t_2 + b.t_2 \\
 s_2 \stackrel{\text{def}}{=} a.s_4 & t_2 \stackrel{\text{def}}{=} a.t \\
 s_3 \stackrel{\text{def}}{=} a.s & t_3 \stackrel{\text{def}}{=} a.t_4 \\
 s_4 \stackrel{\text{def}}{=} a.s & t_4 \stackrel{\text{def}}{=} a.t
 \end{array}$$

We find the following bisimulation:

$$\mathcal{R} = \{(s, t), (s_1, t_1), (s_2, t_3), (s_3, t_2), (s_4, t_2), (s_4, t_4)\}$$

- Consider the first pair (s, t) :
 - transitions from s
 - * $s \xrightarrow{a} s_1$ can be matched by $t \xrightarrow{a} t_1$ and $(s_1, t_1) \in \mathcal{R}$
 - * $s \xrightarrow{a} s_2$ can be matched by $t \xrightarrow{a} t_3$ and $(s_2, t_3) \in \mathcal{R}$
 - * these are all transitions from s .
 - transitions from t
 - * $t \xrightarrow{a} t_1$ can be matched by $s \xrightarrow{a} s_1$ and $(s_1, t_1) \in \mathcal{R}$
 - * $t \xrightarrow{a} t_3$ can be matched by $s \xrightarrow{a} s_2$ and $(s_2, t_3) \in \mathcal{R}$
 - * these are all transitions from t .
- Consider the next pair (s_1, t_1) :
 - transitions from s_1
 - * $s_1 \xrightarrow{a} s_3$ can be matched by $t_1 \xrightarrow{a} t_2$ and $(s_3, t_2) \in \mathcal{R}$
 - * $s_1 \xrightarrow{b} s_4$ can be matched by $t_1 \xrightarrow{b} t_2$ and $(s_4, t_2) \in \mathcal{R}$
 - * this is the only transition from s_1 .
 - transitions from t_1
 - * $t_1 \xrightarrow{a} t_2$ can be matched by $s_1 \xrightarrow{a} s_3$ and $(s_3, t_2) \in \mathcal{R}$
 - * $t_1 \xrightarrow{b} t_2$ can be matched by $s_1 \xrightarrow{b} s_4$ and $(s_4, t_2) \in \mathcal{R}$
 - * these are all transitions from t_1 .
- Consider the next pair (s_2, t_3) :
 - transitions from s_2

- * $s_2 \xrightarrow{a} s_4$ can be matched by $t_3 \xrightarrow{a} t_4$ and $(s_4, t_4) \in \mathcal{R}$
- * this is the only transition from s_2 .
- transitions from t_3
 - * $t_3 \xrightarrow{a} t_4$ can be matched by $s_2 \xrightarrow{a} s_4$ and $(s_4, t_4) \in \mathcal{R}$
 - * this is the only transition from t_3 .
- Consider the next pair (s_3, t_2) :
 - transitions from s_3
 - * $s_3 \xrightarrow{a} s$ can be matched by $t_2 \xrightarrow{a} t$ and $(s, t) \in \mathcal{R}$
 - * this is the only transition from s_3 .
 - transitions from t_2
 - * $t_2 \xrightarrow{a} t$ can be matched by $s_3 \xrightarrow{a} s$ and $(s, t) \in \mathcal{R}$
 - * this is the only transition from t_2 .
- Consider the next pair (s_4, t_2) :
 - transitions from s_4
 - * $s_4 \xrightarrow{a} s$ can be matched by $t_2 \xrightarrow{a} t$ and $(s, t) \in \mathcal{R}$
 - * this is the only transition from s_4 .
 - transitions from t_2
 - * $t_2 \xrightarrow{a} t$ can be matched by $s_4 \xrightarrow{a} s$ and $(s, t) \in \mathcal{R}$
 - * this is the only transition from t_2 .
- Consider the next pair (s_4, t_4) :
 - transitions from s_4
 - * $s_4 \xrightarrow{a} s$ can be matched by $t_4 \xrightarrow{a} t$ and $(s, t) \in \mathcal{R}$
 - * this is the only transition from s_4 .
 - transitions from t_4
 - * $t_4 \xrightarrow{a} t$ can be matched by $s_4 \xrightarrow{a} s$ and $(s, t) \in \mathcal{R}$
 - * this is the only transition from t_4 .

\mathcal{R} is a strong bisimulation and $(s, t) \in \mathcal{R}$, therefore $s \sim t$.

Exercise 3.13

No, given:

$$\begin{array}{ll}
 P \stackrel{\text{def}}{=} a.P & Q \stackrel{\text{def}}{=} a.Q \\
 S \stackrel{\text{def}}{=} (P|Q) \backslash a & T \stackrel{\text{def}}{=} (P \backslash a) | (Q \backslash a)
 \end{array}$$

Process S exhibits an infinite series of τ -actions due to the synchronization over a . However, process T does nothing since a is restricted before P and Q can synchronize. Therefore T cannot match the τ s from S and $S \not\approx T$.

Yes, lets define:

$$S \stackrel{\text{def}}{=} (P|Q)[f] \qquad T \stackrel{\text{def}}{=} (P[f])|(Q[f])$$

Any action outside the domain of f by S can be matched by T , since it would be as if the relabeling never happened on either side. For any action that is relabeled by f by S :

- $(\alpha.P'|Q)[\beta/\alpha] \xrightarrow{\beta} (P'|Q)[\beta/\alpha]$ can be matched by $((\alpha.P')[\beta/\alpha])|(Q[\beta/\alpha]) \xrightarrow{\beta} (P'[\beta/\alpha])|(Q[\beta/\alpha])$
- $(P|\alpha.Q')[\beta/\alpha] \xrightarrow{\beta} (P|Q')[\beta/\alpha]$ can be matched by $(P[\beta/\alpha])|((\alpha.Q')[\beta/\alpha]) \xrightarrow{\beta} (P[\beta/\alpha])|(Q'[\beta/\alpha])$
- $(\bar{\alpha}.P'|\alpha.Q')[\beta/\alpha] \xrightarrow{\tau} (P'|Q')[\beta/\alpha]$ can be matched by $((\bar{\alpha}.P')[\beta/\alpha])|((\alpha.Q')[\beta/\alpha]) \xrightarrow{\tau} (P'[\beta/\alpha])|(Q'[\beta/\alpha])$

Exercise 3.21

Definitions from exercise 2.11:

$$\begin{aligned} \text{User} &\stackrel{\text{def}}{=} \bar{p}.\text{enter}.\text{exit}.\bar{v}.\text{User} \\ \text{Sem} &\stackrel{\text{def}}{=} p.v.\text{Sem} \\ \text{Mutex} &\stackrel{\text{def}}{=} (\text{User}|\text{Sem}) \setminus \{p, v\} \\ \text{Mutex}_2 &\stackrel{\text{def}}{=} ((\text{User}|\text{Sem})|\text{User}) \setminus \{p, v\} \\ \text{FUser} &\stackrel{\text{def}}{=} \bar{p}.\text{enter} . (\text{exit}.\bar{v}.\text{FUser} + \text{exit}.\bar{v}.\mathbf{0}) \\ \text{FMutex} &\stackrel{\text{def}}{=} ((\text{User}|\text{Sem})|\text{FUser}) \setminus \{p, v\} \end{aligned}$$

Requested: $\text{Mutex}_2 \approx \text{FMutex}$? First we add the following helper definitions to name the intermediate states:

$$\begin{array}{ll}
\text{User}_1 \stackrel{\text{def}}{=} \text{enter}.\text{exit}.\bar{v}.\text{User} & \text{FUser}_1 \stackrel{\text{def}}{=} \text{enter}.\text{exit}.\bar{v}.\text{FUser} + \text{exit}.\bar{v}.\mathbf{0} \\
\text{User}_2 \stackrel{\text{def}}{=} \text{exit}.\bar{v}.\text{User} & \text{FUser}_2 \stackrel{\text{def}}{=} \text{exit}.\bar{v}.\text{FUser} + \text{exit}.\bar{v}.\mathbf{0} \\
\text{User}_3 \stackrel{\text{def}}{=} \bar{v}.\text{User} & \text{FUser}_3 \stackrel{\text{def}}{=} \bar{v}.\text{FUser} \\
\text{Sem}_1 \stackrel{\text{def}}{=} v.\text{Sem} & \text{FUser}_4 \stackrel{\text{def}}{=} \bar{v}.\mathbf{0} \\
\text{Mutex}_{2,1} \stackrel{\text{def}}{=} ((\text{User}_1|\text{Sem}_1)|\text{User}) \setminus \{p, v\} & \text{FMutex}_1 \stackrel{\text{def}}{=} ((\text{User}_1|\text{Sem}_1)|\text{FUser}) \setminus \{p, v\} \\
\text{Mutex}_{2,2} \stackrel{\text{def}}{=} ((\text{User}_2|\text{Sem}_1)|\text{User}) \setminus \{p, v\} & \text{FMutex}_2 \stackrel{\text{def}}{=} ((\text{User}_2|\text{Sem}_1)|\text{FUser}) \setminus \{p, v\} \\
\text{Mutex}_{2,3} \stackrel{\text{def}}{=} ((\text{User}_3|\text{Sem}_1)|\text{User}) \setminus \{p, v\} & \text{FMutex}_3 \stackrel{\text{def}}{=} ((\text{User}_3|\text{Sem}_1)|\text{FUser}) \setminus \{p, v\} \\
\text{Mutex}_{2,4} \stackrel{\text{def}}{=} ((\text{User}|\text{Sem}_1)|\text{User}_1) \setminus \{p, v\} & \text{FMutex}_4 \stackrel{\text{def}}{=} ((\text{User}|\text{Sem}_1)|\text{FUser}_1) \setminus \{p, v\} \\
\text{Mutex}_{2,5} \stackrel{\text{def}}{=} ((\text{User}|\text{Sem}_1)|\text{User}_2) \setminus \{p, v\} & \text{FMutex}_5 \stackrel{\text{def}}{=} ((\text{User}|\text{Sem}_1)|\text{FUser}_2) \setminus \{p, v\} \\
\text{Mutex}_{2,6} \stackrel{\text{def}}{=} ((\text{User}|\text{Sem}_1)|\text{User}_3) \setminus \{p, v\} & \text{FMutex}_6 \stackrel{\text{def}}{=} ((\text{User}|\text{Sem}_1)|\text{FUser}_3) \setminus \{p, v\} \\
& \text{FMutex}_7 \stackrel{\text{def}}{=} ((\text{User}|\text{Sem}_1)|\text{FUser}_4) \setminus \{p, v\}
\end{array}$$

We create the following relation:

$$\mathcal{R} = \{(\text{Mutex}_2, \text{FMutex}), (\text{Mutex}_{2,1}, \text{FMutex}_1), (\text{Mutex}_{2,2}, \text{FMutex}_2), \\
(\text{Mutex}_{2,2}, \text{FMutex}_2), (\text{Mutex}_{2,3}, \text{FMutex}_3), (\text{Mutex}_{2,4}, \text{FMutex}_4)\}$$

For $\text{Mutex}_{2,1} \approx \text{FMutex}_1$, $\text{Mutex}_{2,2} \approx \text{FMutex}_2$ and $\text{Mutex}_{2,3} \approx \text{FMutex}_3$ both processes behave like an ordinary Mutex and their bisimilarity is obvious.

Since parallel composition is associative and commutative modulo strong bisimilarity¹, $\text{Mutex}_{2,1} \sim \text{Mutex}_{2,4}$, $\text{Mutex}_{2,2} \sim \text{Mutex}_{2,5}$ and $\text{Mutex}_{2,3} \sim \text{Mutex}_{2,6}$. For symmetry we simulate $\text{Mutex}_{2,1-3}$ with FMutex_{4-7} .

$\text{Mutex}_2 \xrightarrow{\text{enter}} \text{Mutex}_{2,1}$ can be matched by $\text{FMutex}_4 \xrightarrow{\text{enter}} \text{FMutex}_5$

Exercise 3.25

The given LTS can be described with the following equations:

¹Reactive Systems: Modelling, Specification and Verification, Page 53

$$\begin{array}{ll}
s \stackrel{\text{def}}{=} \tau.s_1 + a.s_3 & t \stackrel{\text{def}}{=} \tau.t_1 + a.t_2 + b.t_3 \\
s_1 \stackrel{\text{def}}{=} \tau.s + \tau.s_2 + b.s_4 & t_1 \stackrel{\text{def}}{=} \tau.t \\
s_2 \stackrel{\text{def}}{=} \tau.s_1 + \tau.s_5 & t_2 \stackrel{\text{def}}{=} \mathbf{0} \\
s_3 \stackrel{\text{def}}{=} \mathbf{0} & t_3 \stackrel{\text{def}}{=} \mathbf{0} \\
s_4 \stackrel{\text{def}}{=} \mathbf{0} & \\
s_5 \stackrel{\text{def}}{=} \mathbf{0} &
\end{array}$$

To prove weak bisimilarity we create the following relation:

$$\mathcal{R} = \{(s, t), (s_3, t_2), (s_1, t), (s_5, t_1), (s_4, t_3), (s_2, t)\}$$

- Consider the first pair (s, t) :
 - transitions from s
 - * $s \xrightarrow{a} s_3$ can be matched by $t \xRightarrow{a} t_2$ and $(s_3, t_2) \in \mathcal{R}$
 - * $s \xrightarrow{\tau} s_1$ can be matched by $t \xRightarrow{\tau} t$ and $(s_1, t) \in \mathcal{R}$
 - * these are all transitions from s .
 - transitions from t
 - * $t \xrightarrow{\tau} t_1$ can be matched by $s \xRightarrow{\tau} s_5$ and $(s_5, t_1) \in \mathcal{R}$
 - * $t \xrightarrow{a} t_2$ can be matched by $s \xRightarrow{a} s_3$ and $(s_3, t_2) \in \mathcal{R}$
 - * $t \xrightarrow{b} t_3$ can be matched by $s \xRightarrow{b} s_4$ and $(s_4, t_3) \in \mathcal{R}$
 - * these are all transitions from t .
- Consider the next pair (s_3, t_2) : They are both $\mathbf{0}$.
- Consider the next pair (s_1, t) :
 - transitions from s_1
 - * $s_1 \xrightarrow{b} s_4$ can be matched by $t \xRightarrow{b} t_3$ and $(s_4, t_3) \in \mathcal{R}$
 - * $s_1 \xrightarrow{\tau} s_2$ can be matched by $t \xRightarrow{\tau} t$ and $(s_2, t) \in \mathcal{R}$
 - * these are all transitions from s_2 .
 - transitions from t
 - * $t \xrightarrow{\tau} t_1$ can be matched by $s_1 \xRightarrow{\tau} s_5$ and $(s_5, t_1) \in \mathcal{R}$
 - * $t \xrightarrow{a} t_2$ can be matched by $s_1 \xRightarrow{a} s_3$ and $(s_3, t_2) \in \mathcal{R}$
 - * $t \xrightarrow{b} t_3$ can be matched by $s_1 \xRightarrow{b} s_4$ and $(s_4, t_3) \in \mathcal{R}$
 - * these are all transitions from t .

- Consider the next pair (s_5, t_1) :
 - transitions from s_5 : s_5 is **0** and does nothing.
 - transitions from t_1
 - * $t_1 \xrightarrow{\tau} t_1$ can be matched by $s_5 \xRightarrow{\tau} s_5$ (by doing zero τ -actions) and $(s_5, t_1) \in \mathcal{R}$
 - * this is the only transition from t_1 .
- Consider the next pair (s_4, t_3) : They are both **0**.
- Consider the final pair (s_2, t) :
 - transitions from s_2
 - * $s_2 \xrightarrow{\tau} s_1$ can be matched by $t \xRightarrow{b} t$ and $(s_1, t) \in \mathcal{R}$
 - * $s_2 \xrightarrow{\tau} s_5$ can be matched by $t \xRightarrow{\tau} t_1$ and $(s_5, t_1) \in \mathcal{R}$
 - * these are all transitions from s_2 .
 - transitions from t
 - * $t \xrightarrow{\tau} t_1$ can be matched by $s_2 \xRightarrow{\tau} s_5$ and $(s_5, t_1) \in \mathcal{R}$
 - * $t \xrightarrow{a} t_2$ can be matched by $s_2 \xRightarrow{a} s_3$ and $(s_3, t_2) \in \mathcal{R}$
 - * $t \xrightarrow{b} t_3$ can be matched by $s_2 \xRightarrow{b} s_4$ and $(s_4, t_3) \in \mathcal{R}$
 - * these are all transitions from t .

\mathcal{R} is a weak bisimulation containing (s, t) , therefore $s \approx t$.

Exercise 3.27

With $P \xRightarrow{\tau} Q$ and $Q \xRightarrow{\tau} P$, we show that $P \approx Q$. To this end we start a weak bisimulation relation with (P, Q) .

$$\mathcal{R} = \{(P, Q), (P', Q'), \dots\}$$

- Consider the first pair (P, Q) :
 - transitions from P : $P \xRightarrow{\tau} Q$:
 - * P can do nothing and become Q (i.e. $P = Q$). Q matches this by being itself.
 - * P can perform $P \xrightarrow{\tau} P'$, where $P' \xRightarrow{\tau} Q$. Q can either do nothing or perform $Q \xrightarrow{\tau} Q'$, where $Q' \xRightarrow{\tau} P$.
 - transitions from Q
 - * Q can do nothing and become P (i.e. $Q = P$). P matches this by being itself.

* Q can perform $Q \xrightarrow{\tau} Q'$, where $Q' \xrightarrow{\tau} P$. P can either do nothing or perform $P \xrightarrow{\tau} P'$, where $P' \xrightarrow{\tau} Q$.

- Consider the next pair (P', Q') : both have the same transitions as the first pair, with possibly fewer τ -transitions left before P becoming Q and vice versa.

Since both P and Q can only perform τ -actions, or do nothing, the other can always match the action. Eventually, the bisimulation ends up in (P, Q) again and thus $P \approx Q$.

Exercise 3.37

The LTS can be described with the following equations:

$$\begin{array}{llll}
s \stackrel{\text{def}}{=} a.s_1 & t \stackrel{\text{def}}{=} a.t_1 & u \stackrel{\text{def}}{=} a.u_1 & v \stackrel{\text{def}}{=} a.v_1 \\
s_1 \stackrel{\text{def}}{=} b.s_2 & t_1 \stackrel{\text{def}}{=} b.t_1 + b.t_2 & u_1 \stackrel{\text{def}}{=} b.u_2 & v_1 \stackrel{\text{def}}{=} b.v_2 + b.v_3 \\
s_2 \stackrel{\text{def}}{=} a.s + b.s_2 & t_2 \stackrel{\text{def}}{=} a.t & u_2 \stackrel{\text{def}}{=} a.u + b.u_2 & v_2 \stackrel{\text{def}}{=} a.v \\
& & u_3 \stackrel{\text{def}}{=} a.u + b.u_2 & v_3 \stackrel{\text{def}}{=} b.v_2 + b.v_3
\end{array}$$

To show $s \approx t$, we give a universal winning strategy for the attacker:

- The start configuration is (s, t) . The attacker plays $s \xrightarrow{a} s_1$ on the left, the defender responds with $t \xrightarrow{a} t_1$ on the right.
- The new configuration is (s_1, t_1) . The attacker plays $t_1 \xrightarrow{b} t_1$ on the right (sabotage the defender for the next round). The defender plays $s_1 \xrightarrow{b} s_2$ on the left.
- The final configuration is (s_2, t_1) . The attacker plays $s_2 \xrightarrow{a} s$ on the left. The defender cannot respond and loses.

To show $s \sim u$, we give a universal winning strategy for the defender:
The start configuration is (s, u) .

- The attacker can play:
 - $s \xrightarrow{a} s_1$. The defender can only respond with $u \xrightarrow{a} u_1$.
 - $u \xrightarrow{a} u_1$. The defender can only respond with $s \xrightarrow{a} s_1$.

Either way, the next configuration is (s_1, u_1) .

- The attacker can play:

- $s_1 \xrightarrow{b} s_2$. The defender can only respond with $u_1 \xrightarrow{b} u_3$.
- $u_1 \xrightarrow{b} u_3$. The defender can only respond with $s_1 \xrightarrow{b} s_2$.

Either way, the next configuration is (s_2, u_3) .

- The attacker can play:
 - $s_2 \xrightarrow{a} s$. The defender can only respond with $u_3 \xrightarrow{a} u$.
 - $u_3 \xrightarrow{a} u$. The defender can only respond with $s_2 \xrightarrow{a} s$.

In both cases, the next configuration is (s, u) : a cycle, so the defender wins. Alternatively, the attacker could play:

- $s_2 \xrightarrow{b} s_2$. The defender can only respond with $u_3 \xrightarrow{b} u_2$.
- $u_3 \xrightarrow{b} u_2$. The defender can only respond with $s_2 \xrightarrow{b} s_2$.

In these cases the next configuration is (s_2, u_2) .

- The attacker can play:
 - $s_2 \xrightarrow{a} s$. The defender can only respond with $u_3 \xrightarrow{a} u$.
 - $u_3 \xrightarrow{a} u$. The defender can only respond with $s_2 \xrightarrow{a} s$.

In both cases, the next configuration is (s, u) : a cycle, so the defender wins. Alternatively, the attacker could play:

- $s_2 \xrightarrow{b} s_2$. The defender can only respond with $u_3 \xrightarrow{b} u_2$.
- $u_3 \xrightarrow{b} u_2$. The defender can only respond with $s_2 \xrightarrow{b} s_2$.

In these cases the next configuration is (s_2, u_2) : another cycle, so the defender wins.

In all cases, the defender wins. The relation is

$$\mathcal{R} = \{(s, u), (s_1, u_1), (s_2, u_3), (s_2, u_2)\}$$

Finally, we show that $s \approx v$ with a universal winning strategy for the attacker:

- The start configuration is (s, v) . The attacker plays $s \xrightarrow{a} s_1$ on the left. The defender can only respond with $v \xrightarrow{v} v_1$ on the right. (Attacking on the other side has the same result).
- The next configuration is (s_1, v_1) . The attacker plays $v_1 \xrightarrow{b} v_2$ on the right. The defender can only respond with $s_1 \xrightarrow{b} s_2$ on the left.
- The final configuration is (s_2, v_2) . The attacker plays $s_2 \xrightarrow{b} s_2$. The defender cannot respond and loses.