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Chapter 1 Basic Concepts on Matrices and Vectors

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1 Matrix

1.1 Definitions

A matrix is a rectangular array of scalars.

If the matrix has m rows and n columns, we say the **size** of matrix is **m by n**, written $m \times n$. The matrix is called square if m = n.

The scalar in ith row and jth column is called (i, j)-entry of the matrix.

1.2 Notation

$$A = \begin{bmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \cdots & a_{mn} \end{bmatrix} = [a_{ij}] \in M_{m \times n}$$

$$\tag{1}$$

 $M_{m\times n}$ denotes the set that contains all matrices whose size is $m\times n$.

1.3 Equality of matrices

1.3.1 Definitions

We say two matrices A and B are equal if

- 1. they have the same size.
- 2. they have equal corresponding entries.

Let $A, B \in M_{m \times n}$

Then
$$A = B \iff a_{ij} = b_{ij}, \forall i = 1, \dots, m, j = 1, \dots, n$$

1.4 Submatrices

1.4.1 Definitions

A submatrix is obtained by deleting from a matrix entire rows and/or columns.

1.4.2 Sample

$$\begin{bmatrix} 1 & 2 & 3 \\ 2 & 1 & 4 \end{bmatrix} is a submatrix of \begin{bmatrix} 1 & 2 & 3 \\ 2 & 1 & 4 \\ 1 & 3 & 2 \end{bmatrix}$$
 (2)

1.5 Matrix addition

1.5.1 Definitions

Let A and B be in matrix $m \times n$. We define the sum of A and B, denoted A + B, to be a $m \times n$ matrix obtained by adding the corresponding entries of A and B; that is the $m \times n$ matrix whose (i, j) - entry is $a_{ij} + bij$.

1.5.2 Notation

Let
$$A, B \in M_{m \times n}$$

Then $A + B = [a_{ij} + b_{ij}], \forall i = 1, ..., m, j = 1, ..., n$

1.5.3 Theorem

Commutative A + B = B + A

Associative (A + B) + C = A + (B + C)

1.6 Scalar Multiplication

1.6.1 Definitions

Let A be an $m \times n$ matrix and c be a scalar. The scalar multiple cA of matrix A is defined to be the $m \times n$ matrix whose (i, j) - entries is $c \times a_{ij}$.

1.6.2 Notation

Let
$$A \in M_{m \times n}$$
 and $c \in R$
Then $cA = [c \times a_{ij}], \forall i = 1, ..., m, j = 1, ..., n$

1.6.3 Theorem

Associative (st)A = s(tA), $(s, t \in R)$

Distributive s(A+B) = sA + sB or (s+t)A = sA + tA, $(s \in R)$

1.7 Zero Matrices

1.7.1 Definitions

A zero matrix with all zero entries, denoted by O(any size) or $O_{m \times n}$.

1.7.2 Properties

1.
$$A = O + A, \forall A \in M_{m \times n}$$

2.
$$0 \cdot A = O, \forall A \in M_{m \times n}$$

1.8 Matrix Substraction

1.8.1 Definitions

We define the matrix -A to be -1(A). The matrix substraction of the two matrix A and B is define to be as

$$A - B = A + (-B)$$

1.8.2 Theorem

1.
$$A - A = O, \forall A \in M_{m \times n}$$

1.9 Matrix Transpose

1.9.1 Definitions

The transpose of a $m \times n$ matrix A is the $n \times m$ matrix A^T whose (i, j) - enrty is the (j, i) - enrty of A.

1.9.2 Properties

$$A \in M_{m \times n} \Rightarrow A^T \in M_{n \times m}$$

1.9.3 Theorem

associative $(sA)^T = s(A^T)$, $\forall s \in R$

Distributive $(A+B)^T = A^T + B^T$

$$(A^T)^T = A$$

2 Vector

2.1 Definitions

Vector can refer to either a **row vector** or a **column vector**. Row vector is a matrix with **one** row.

$$\underline{v} = [a_1, \cdots, a_n]$$

Column vector is a matrix with **one** column.

$$\underline{v} = \begin{bmatrix} a_1 \\ \vdots \\ a_m \end{bmatrix} \text{ or } \underline{v}^T = [a_1, \cdots, a_m]$$
(3)

So row vector can transpose to column vector, vice versa.

2.2 Notation

$$\underline{v} = \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} = [a_i] \in R^n, \forall i = 1, \dots, n$$

$$\tag{4}$$

We denote the set of all column vectors with n components by \mathbb{R}^n . That is $\mathbb{R}^n = M_{n \times 1}$.

2.3 Vector Addition/Substraction, Scalar Multiplication and Zero Vector

Follow those for matrices.

Zero Vector is denoted **0**

A matrix is often regarded as a stack of row vectors or a cross list of column vectors. Let $C \in M_{m \times n}$

$$C = [\underline{c_1}, \dots, \underline{c_j}, \dots, \underline{c_n}]$$

$$\underline{c_j} = \begin{bmatrix} c_{1j} \\ \vdots \\ c_{mj} \end{bmatrix} = [c_i] \in R^m, \forall i = 1, \dots, m$$
(5)

3 Linear Combinations

3.1 Definitions

A linear combination of vectors $\underline{u_1}, \cdots, \underline{u_n}$ is a vector of the form

$$\underline{u} = c_1 u_1 + \dots + c_n u_n$$

Where c_1, \dots, c_n are scalars which called **coefficients** of the linear combination.

3.2 Samples

3.2.1 Given coefficients, computes linear combination

Let
$$\underline{u_1}^T = [-1, -3, 4], \ \underline{u_2}^T = [-4, 1, 2], \ c_1 = 3 \text{ and } c_2 = 2$$

Then
$$c_1 \underline{u_1}^T + c_2 \underline{u_2}^T = \begin{bmatrix} -3 & -9 & 12 \end{bmatrix} + \begin{bmatrix} -12 & 3 & 6 \end{bmatrix} = \begin{bmatrix} -15 & -6 & 18 \end{bmatrix}$$
 (6)

$$\therefore c_1 \underline{u_1}^T + c_2 \underline{u_2}^T = (c_1 \underline{u_1} + c_2 \underline{u_2})^T$$
 (7)

$$\therefore c_1 \underline{u_1} + c_2 \underline{u_2} = \begin{bmatrix} -15 \\ -6 \\ 18 \end{bmatrix}$$
 (8)

3.2.2 Given linear combination, computes coefficients

Which could be transform to solve a system of linear equations. But there are three solution.

Unique solution when sc_1 and c_2 are not collinear vectors.

Infinitely many solutions when $s\underline{c_1}$, $\underline{c_2}$ are **collinear vectors** and $\underline{c} = s\underline{c_1}$, \underline{c} is linear combination

No solutions when $s\underline{c_1}, \ \underline{c_2}$ are **collinear vectors** and $\underline{c} \neq s\underline{c_1}, \ \underline{c}$ is linear combination

3.3 Parallel/Collinear Vectors

Let \underline{a} and \underline{b} not be in zero vector. We define \underline{a} is parallel with \underline{b} when $s\underline{a} = \underline{b}$, $s \in R$.

3.3.1 Notations

Let $\forall \underline{a}, \underline{b} \notin \mathbb{R}^n$

Then $\underline{a} \parallel \underline{b} \Rightarrow s\underline{a} = \underline{b}$, $s \in R$

 $\underline{a} \parallel \underline{b}$ denotes the vectors $\underline{a}, \underline{b}$ are the parallel or collinear vector

4 Standard Vectors

4.1 Definitions

The standard vectors of \mathbb{R}^n are defined as

$$\underline{e_1} = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \underline{e_2} = \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix} \cdots \underline{e_n} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{bmatrix}$$
(9)

4.2 Properties

Every vector in \mathbb{R}^n may be uniquely linearly combined by standard vectors.

5 Matrix-Vector Product

5.1 Definitions

Let A be an $m \times n$ matrix and \underline{v} be an $n \times 1$ vector. We define the **matrix-vector product** of A and \underline{v} , denoted by $A\underline{v}$, to be the linear combination of the columns of A whose coefficients are the corresponding components of \underline{v} . That is

$$A\underline{v} = v_1\underline{a_1} + v_2\underline{a_2} + \dots + v_n\underline{a_n}$$

5.2 Cautions

- 1. the size of \underline{v} must be equal to the count of columns of A.
- 2. the solution of matrix-vector product is a new vector whose size is same with the count of rows of A.

5.3 Theorems

Distributive
$$A(\underline{u} + \underline{v}) = A\underline{u} + A\underline{v}$$
 and $(A + B)\underline{u} = A\underline{u} + B\underline{u}$
Associative $A(c\underline{u}) = c(A\underline{u}) = (cA)\underline{u}$, $\forall c \in R$
 $A\underline{0} = \underline{0}$ and $O\underline{v} = \underline{0}$, $\forall A \in M_{m \times n}$ and $\underline{v} \in R^n$
 $A\underline{e_j} = \underline{a_j}$, $A = [\underline{a_1} \cdots \underline{a_m}]$
 $B\underline{w} = A\underline{w} \Rightarrow A = B$, $\forall B, A \in M_{m \times n}$ and $\forall \underline{w} \in R^n$.

6 Identity Matrix

6.1 Definitions

For each positive integer n, the $n \times n$ identity matrix I_n is the $n \times n$ matrix whose respective columns are the standard vectors $\underline{e_1}$, $\underline{e_2}$, \cdots , $\underline{e_n}$ in R^n Sometime I_n is simply written as \overline{I} .

6.2 Sample

$$I_4 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \tag{10}$$

6.3 Properties

$$I_n v = v$$
, $\forall v \in \mathbb{R}^n$

7 Stochastic Matrix

7.1 Definitions

An matrix $A \in M_{m \times n}$ is called a stochastic matrix if all entries of A is nonnegative and the sum of all entries in each columns is unity.