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System of Linear Equations

fsjohnhuang

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1 System of Linear Equations

$$\begin{cases} 2x + 3y = 5\\ x + y = 2 \end{cases} \tag{1}$$

We call 2x + 3y = 5 is a linear equation, and the group of linear equations above is called a system of linear equations. x, y and z are variables.

1.1 Definitions of Linear Equation

$$a_1x_1 + a_2x_2 + \dots + a_nx_n = b$$

We call from a_1 , a_2 to a_n as coefficients, from x_1 , x_2 to x_n as variables, and b as constant term.

1.2 Solution of A System of Linear Equations

A solution of a system of linear equations in the variables x_1, x_2, \dots, x_n is a vector $[s_1 \ s_2 \ \dots \ s_n]^T \in \mathbb{R}^n$ such that every equation in the system is satisfied when each x_i is replaced by s_i .

1.3 Solution Set

The set of all solutions of a system of linear equations is called the **solution set**.

Solution
$$Set = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \in \mathbb{R}^n \middle| x_1, x_2, \cdots, x_n \text{ satisfy the system of linear equations} \right\}$$
 (2)

Every system of linear equations has no solution, exactly one solution, or infinitely many solutions.

A system of linear equations is called **consistent** if it has one or more solutions.

A system of linear equations is called **inconsistent** if it has no solutions, denoted as \emptyset or $\{\}$.

1.3.1 Sample

$$R^{2} = \left\{ \begin{bmatrix} x \\ y \end{bmatrix} \middle| x \in R, \ y \in R \right\}$$
 (3)

Subset of R^2 , denoted L_1

$$L_1 = \left\{ \begin{bmatrix} x \\ y \end{bmatrix} \middle| x \in R, \ y \in R, \ x - y = 1 \right\}$$
 (4)

1.4 Equality of System of Linear Equations

Two systems of linear equations are called **equivalent** if they have exactly the same solution set.

1.5 Elementary Row Operations

Simple operations defined on a system of linear equations that do not change the solution set of the system of linear equations.

Used for solving systems of linear equations.

Three types of elementary row operations.

- 1. Interchange
- 2. Scaling
- 3. Row addition

1.6 Augmented Matrix

In general a system of linear equations could be rewritten as

$$A\underline{x} = \underline{b}$$

$$where A = \begin{bmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \cdots & a_{mn} \end{bmatrix}, \ \underline{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}, \ \underline{b} = \begin{bmatrix} b_1 \\ \vdots \\ b_m \end{bmatrix}$$

$$(5)$$

We call A as coefficient matrix, \underline{x} as variable vector and \underline{b} as constant vector.

The matrix of size $m \times (n+1)$

$$[A \mid \underline{b}] = \begin{bmatrix} a_{11} & \cdots & a_{1n} & b_1 \\ \vdots & \ddots & \vdots & \vdots \\ a_{m1} & \cdots & a_{mn} & b_m \end{bmatrix}$$

$$(6)$$

is called the augmented matrix.

1.6.1 Elementary Row Operations

Elementary row operations taken on systems of linear equations as well as on the corresponding augmented matrices.

Three types of elementary row operations.

Interchange interchange any two rows of the matrix.

Scaling multiply every entry of some row of the matrix by the same nonzero scalar.

Row Addition add a multiple of one row of the matrix to another row.

Properties

- 1. Every elementary row operations are reversible.
- 2. $[A \mid \underline{b}] \Leftarrow elementary \ row \ operations \Rightarrow [A' \mid \underline{b'}]$

1.6.2 Row Echelon Form of Matrix

Definition A matrix is said to be in row echelon form if it satisfies the following three conditions:

- 1. Each nonzero row lies above every zero row.
- 2. The leading entry of a nonzero row lies in a column to the right of the column containing the leading entry of and preceding row.
- 3. If a column contains the leading entry of some row, then all entries of the column below the leading entry are 0.

Sample

$$\begin{bmatrix}
2 & * & * & 5 \\
0 & 0 & 1 & 2 \\
0 & 0 & 0 & 0
\end{bmatrix}$$
(7)

1.6.3 Reduced Row Echelon Form of Matrix

Definition A matrix is said to be in reduced row echelon form if it satisfies the following three conditions:

- 1. It's in row echelon form.
- 2. If a column contains the leading entry of some row, then all entries of the column are 0.
- 3. The leading entry of each nonzero row is 1.

Sample

$$\begin{bmatrix}
2 & * & 0 & 0 \\
0 & 0 & 1 & 0 \\
0 & 0 & 0 & 1
\end{bmatrix}$$
(8)

Solution Set There is a augmented matrix below:

$$\begin{bmatrix}
1 & -3 & 0 & 2 & 0 & 7 \\
0 & 0 & 1 & 6 & 0 & 9 \\
0 & 0 & 0 & 0 & 1 & 2 \\
0 & 0 & 0 & 0 & 0 & 0
\end{bmatrix}$$
(9)

We call the coressponding variable as **basic variable** if the column contains the leading entry of some row. Otherwise we call the coressponding variable as **free variable**. Free variable could be any real value. And basic variable is according to free variable.

In this case, x_1 , x_3 and x_5 are basic variable; x_2 and x_4 are free variable.

$$x_{1} = 7 + 3x_{2} - 2x_{4}$$
 $x_{2} \ free$
 $x_{3} = 9 - 6x_{4}$
 $x_{4} \ free$
 $x_{5} = 2$
(10)

General Solution:

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 7 \\ 0 \\ 9 \\ 0 \\ 2 \end{bmatrix} + \begin{bmatrix} 3 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} \underline{x_2} + \begin{bmatrix} -2 \\ 0 \\ -6 \\ 1 \\ 0 \end{bmatrix} \underline{x_4}$$
 (11)

Unique Solution No free variables.

Infinitely Many Solutions Has free variables.

No Solution Whenever an agumented matrix contains a row in which the only nonzero entry lies in the last column, the corresponding system of linear equations has no solution.

Theorem Every matrix can be transformed into **one and only one** in reduced row echelon form by means of a sequence of elementary row operations.

1.6.4 Ganssian Elimination

Ganssian elimination is an algorithm for finding a (actually "the") reduced row echelon form of a matrix. There are 6 steps:

1. Determine the **leftmost nonzero column**. This is a **pivot column**, and the **topmost position**($1^s t$ row) in this column is a **pivot position**.

$$[A \mid \underline{b}] = \begin{bmatrix} 0 & 0 & 2 & 5 \\ 0 & 1 & -1 & -1 \\ 0 & 6 & 0 & 7 \end{bmatrix}$$
 (12)

 $[\ 0\ 1\ 6\]^T$ is pivot column, and the topmost entry 0 is pivot position.

- 2. In the pivot column, choose any nonzero entry in a row that is not ignored, and perform the approriate **row interchange** to bring this entry into the pivot position.
- 3. Add an appropriate multiple of the row containing the pivot position to each lower row in order to change each entry below to pivot position into zero.
- 4. Ignore the row that contains the pivot position. If there is a nonzero row that is not ignored, repeat steps 1-4 on the submatrix that remains.
- 5. If the leading entry of the row is not 1, perform appropriate scaling operation to make it 1. Then add an appropriate multiple of this row to every preceding row to change each entry above the pivot position into zero.
- 6. If step 5 was performed using the first row, stop. Otherwise, repeat step 5 on the preceding row.

steps 1-4 is forward pass which would transform a matrix from original form to row echelon form; steps 5-6 is backward pass which would transform a matrix from row echelon form to reduced row echelon form.

1.6.5 Rank and Nullity

Definite

- 1. The **rank** of an $m \times n$ matrix A, denoted by rank A, is defined to be the number of nonzero rows in the reduced row echelon form of A.
- 2. The **nullity** of A, denoted by *nullity* A, is defined to be n rank A (n is column count).

Interpretations

- 1. The **rank** of $[A \underline{b}]$ is the number of "useful" equations in the system of linear equations $A\underline{x} = \underline{b}$.
- 2. The **rank** of A represents the number of **basic variables** while the **nullity** of A is the number of **free** variables.

Cautions: rank A is not as same as $rank [A \mid b]$ all the time.

1.6.6 Theorem

Let $A \in M_{m \times n}$ and $\underline{b} \in \mathbb{R}^m$. Then the following conditions are equivalent:

- 1. The matrix equation $A\underline{x} = \underline{b}$ is consistent.
- 2. The vector \underline{b} is a linear combination of the columns of A.
- 3. The reduced row echelon form of the augmented matrix [$A \ \underline{b}$] has no row of the form [$0 \ 0 \ \cdots \ d$] where $d \neq 0$.
- 4. The rank of the coefficient matrix is equal to the rank of the augumented matrix, i.e., $rank\ A = rank\ [A\ \underline{b}\]$.