- 1. Classification
 - (a) K-Nearest Neighbor
- 2. Ensemble Algorithms
 - (a) Adaboost

```
Algorithm 1 k-Nearest Neighbor [11]

Input: X: training data, Y:Class labels of X, x: unknown sample

Output: Class with the highest number of occurrence

1: function CLASSIFY(X, Y, x)

2: for i = 1 to m do

3: Compute distance d(X_i, x)

4: end for

5: Compute set I containing indices for the k smallest distances d(X_i, x)

6: Return majority label \{Y_i \text{ where } i \in I\}
```

Algorithm 2 Adaboost [8]

7: end function

Input:

```
Training data \{(x_i, y_i)_{i=1}^N \text{ where } x_i \in \mathbb{R}^k \text{ and } y_i \in \{-1, 1\}\}
Large number of classifiers denoted by f_m(x) \in \{-1, 1\}
0-1 loss function I defined as
```

$$I(f_m(x,y)) = \begin{cases} 0, & \text{if } f_m(x_i) = y_i \\ 1, & \text{if } f_m(x_i) \neq y_i \end{cases}$$
 (1)

```
Output: The final classifier
 1: for i = 1 to N do
        for i = 1 to M do
 2:
 3:
            Fit weak classifier m to minimize the objective function:
            \epsilon_m = \frac{\sum_{i=1}^N w_i^m I(f_m(x_i)) \neq y_i}{x^2 + 2x + 1}
 4:
            where I(f_m(x_i) \neq y_i) = 1 if f_m(x_i) \neq y_i and 0 otherwise
 5:
            \alpha_m = \ln \frac{1}{1}
 6:
        end for
 7:
        8:
 9:
10:
        end for
11: end for
```

References

- [1] M. Bernstein. Random forests @ONLINE, 2016.
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- [7] A. Hertzmann, D.J. Fleet, and M Brubaker. Adaboost @ONLINE, 2015.
- [8] R. Schapire. Machine learning algorithms for classification @ONLINE, 2014.
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- [10] B. Stein. Unit hierarchial cluster analysis @ONLINE, 2016.

```
Algorithm 3 Adaboost [7]
```

```
Input:
     Training data \{(x_i, y_i)_{i=1}^N \text{ where } x_i \in \mathbb{R}^k \text{ and } y_i \in \{-1, 1\}\}
Output: The final classifier
 1: Given Training data \{(x_i, y_i) \text{ where } y_i \in \{-1, 1\}\}
 2: initialize D_1 = uniform distribution on training examples
 3: for t = 1 to T do
          Train weak classifier h_t on D_t
          choose \alpha_t > 0
 5:
          compute new distribution D_{t+1}:
 6:
          for all i do
 7:
               multiply D_t(x) by
 8:
                                                         \begin{cases} e^{-\alpha_t}, & (<1) \text{ if } y_i = h_t(x_i) \\ e^{\alpha_t}, & (>1) \text{ if } y_i \neq h_t(x_i) \end{cases}
                                                                                                                                                     (3)
                                                                                                                                                     (4)
 9:
               renormalize
          end for
10:
          output final classifier H_final(x) = sign(\sum \alpha_t h_t(x))
11:
12: end for
```

Algorithm 4 Random forest [1]

```
Input: S: training set, F:Features and number of trees in forest B
Output: Constructed tree
 1: function RANDOMFOREST(S, F)
       H \leftarrow \emptyset
 2:
       for i \in 1, ....B do
 3:
           S^{(i)} \leftarrow A bootstrap sample from S
 4:
           h_i \leftarrow RANDOMIZEDTREELEARN(S^i, F)
 5:
           H \leftarrow H \bigcup \{h_i\}
 6:
 7:
       end for
       return H
 8:
 9: end function
10: function RANDOMIZEDTREELEARN(S, F)
       At each node:
11:
        f \leftarrow a very small subset of F
12:
       Split on best feature in f
13:
14:
       return The learned tree
15: end function
```

Algorithm 5 Iterative Dichotomiser 3

```
Input: D: Training Data, X: Set of Input Attributes
Output: A decision tree
 1: function ID3(D, X)
 2:
       Let T be a new tree
       if all instances in D have the same class c then
 3:
           Label (T) = c; Return T
 4:
       end if
 5:
       if X = \emptyset or no attribute has positive information gain then
 6:
           Label (T) = most common class in D; Return T
 7:
       end if
 8:
       X \leftarrow attribute with highest information gain
 9:
       Label(T) = X
10:
       for each value x of X do
11:
           D_x \leftarrow \text{ instances in } D \text{ with } X = x
12:
13:
           if D_x is empty then
              Let T_x be a new tree
14:
              Label(T_x) = most common class in D
15:
16:
               T_x = ID3(D_x, X - \{x\})
17:
       end if
18.
        Add a branch from T to T_x labeled by x
19:
20: end for
21: return T
and function
```

Algorithm 6 Perceptron [2]

```
Input: ProblemSize, InputPatterns, iterations_max, learn_rate
Output: Weights
 1: for i = 1 to iterations_{max} do
       Pattern_i \leftarrow SelectInputPattern(InputPatterns)
       Activation_i \leftarrow ActivateNetwork(Pattern_i, Weights)
 3:
       Output_i \leftarrow TransferActivation(Activation_i)
       UpdateWeights(Pattern_i, Output_i, learn_{rate})
 6: end for
 7: Return Weights
```

Algorithm 7 Back-propagation [3]

```
Input: ProblemSize, InputPatterns, iterations_max, learn_rate
Output: Network
 1: Network \leftarrow ConstructNetworkLayers()
 2: Network_weights \leftarrow InitializeWeights(Network, ProblemSize)
 3: for i = 1 to iterations_{max} do
       Pattern_i \leftarrow SelectInputPattern(InputPatterns)
       Output_i \leftarrow ForwardPropagate(Pattern_i, Network)
 5:
       BackwardPropagateError(Pattern_i, Output_i, Network)
 6:
       UpdateWeights(Pattern_i, Output_i, Network, learn_{rate})
 7:
 8: end for
 9: Return Network
```

Algorithm 8 Learning Vector Quantization [4]

```
Input: Problem Size, Input Patterns, iterations_{max}, Codebook Vectors_{num}, learn_{rate}
Output: CodebookVectors
 1: CodebookVectors \leftarrow InitializeCodebookVectors(CodebookVectors_{num}, ProblemSize)
 2: for i = 1 to iterations_{max} do
        Pattern_i \leftarrow SelectInputPattern(InputPatterns)
 4:
        Bmu_i \leftarrow SelectBestMatchingUnit(Pattern_i, CodebookVectors)
        for Bmu_i^{attribute} \in Bmu_i do
 5:
            if Bmu_i^{class} \equiv Pattern_i^{class} then
 6:
                 Bmu_i^{attribute} \leftarrow Bmu_i^{attribute} + learn_{rate} \times (Pattern_i^{attribute} - Bmu_i^{attribute})
 7:
 8:
                Bmu_i^{attribute} \leftarrow Bmu_i^{attribute} - learn_{rate} \times (Pattern_i^{attribute} - Bmu_i^{attribute})
 9:
10:
        end if
11: end for
end for
Return CodebookVectors
```

Algorithm 9 Self Organizing Map [5]

```
Input: InputPatterns, iterations_{max}, learn_{rate}, Grid_width, Grid_height
Output: CodebookVectors
 1: CodebookVectors \leftarrow InitializeCodebookVectors(Grid_{width}, Grid_{height}, InputPatterns)
 2: for i = 1 to iterations_{max} do
        Learn_{rate}^{i} \leftarrow CalculateLearningRate(i, learn_{rate}^{init})
 3:
        neighborhood_{size}^{i} \leftarrow CalculateNeighborhoodSize(i, neighborhood_{init}^{size})
 4:
        Pattern_i \leftarrow SelectInputPattern(InputPatterns)
        Bmu_i \leftarrow SelectBestMatchingUnit(Pattern_i, CodebookVectors)
 6:
        Neighborhood \leftarrow Bmu_i
 7:
        Neighborhood \leftarrow SelectNeighbors(Bmu_i, CodebookVectors, neighborhood_{size}^i)
 8:
        for Vector_i \in Neighborhood do
 9:
            for Vector_i^{attribute} \in Vector_i do
10:
                Vector_{i}^{attribute} \leftarrow Vector_{i}^{attribute} + learn_{rate} \times (Pattern_{i}^{attribute} - Vector_{i}^{attribute})
11:
            end for
12:
        end for
14: end for
15: Return CodebookVectors
```

Algorithm 10 Hierarchial Agglomerative Algorithm [9]

```
Input:
     \langle V, E, w \rangle. Weighted graph
     d_c. Distance measure for two clusters
Output: \langle V_T, E_T \rangle. Cluster hierarchy or dendogram
 1: C = \{\{v \mid v \in V\}\}
                                                                                                                   ▶ Initial Clustering
 2: V_t = \{v_C \mid C \in C\}, E_T = \emptyset
                                                                                                                  ▷ Initial Dendogram
 3: while |C| > 1 do
         update\_distance\_matrix(C, G, d_c)
 4:
                           argmin
         \{C, C'\} =
                                         d_c(C_i, C_j)
 5:
                     \{C_i, C_j\} \in C: C_i \neq C_j
         C = (C \setminus \{C, C'\}) \cup \{C \cup C'\}
 6:
                                                                                                                               ▶ Merging
         V_T = V_T \cup \{v_{C,C'}\}, E_T = E_T \cup \{\{v_{C,C'}, v_C\}, \{v_{C,C'}, v_C\}\}\
                                                                                                                          ▶ Dendogram
 8: end while
 9: Return T
```

Algorithm 11 Hierarchial Divisive Algorithm [10]

```
Input:
     \langle V, E, w \rangle. Weighted graph
     d_c. Distance measure for two clusters
Output: \langle V_T, E_T \rangle. Cluster hierarchy or dendogram
 1: C = \{V\}
                                                                                                                              ▶ Initial Clustering
 2: V_t = \{v_C \mid C \in C\}, E_T = \emptyset
                                                                                                                            \triangleright Initial Dendogram
 3: while \exists C_x : (C_x \in C \land |C| > 1) do
          update\_distance\_matrix(C, G, d_c)
                        \underset{\{C_i,C_j\}:C_i\cup C_j=C_x\wedge\ C_i\cap C_j=\emptyset}{argmax}d_c(C_i,C_j)
 5:
          C = (C \setminus \{C, C'\}) \cup \{C \cup C'\}
                                                                                                                                          ▶ Merging
 6:
          V_T = V_T \cup \{v_{C,C'}\}, E_T = E_T \cup \{\{v_{C,C'}, v_C\}, \{v_{C,C'}, v_C\}\}\
                                                                                                                                     ▶ Dendogram
 8: end while
 9: Return T
```

Algorithm 12 C4.5 [6]

```
Input:
    T: Training dataset
    S: Attributes
Output: decision tree Tree
 1: function C4.5(T)
        if T is NULL then
            return failure
 3:
        end if
 4:
        if S is NULL then
 5:
 6:
            return Tree as a single node with most frequent class label in T
        end if
 7:
        if |S| = 1 then
 8:
            return Tree as a single node S
 9:
        end if
10:
        set Tree = \{\}
11:
        for a \in S do
12:
            set Info(a,T) = 0 and SplitInfo(a,T) = 0
13:
            compute Entropy(a)
14:
            for v \in values(a, T) do
15:
                set T_{a,v} as the subset of T with attribute a=v
16:
                Info(a,T) + = \frac{|T_{a,v}|}{|T_a|} Entropy(a)
SplitInfo(a,T) + = -\frac{|T_{a,v}|}{|T_a|} \log \frac{|T_{a,v}|}{|T_a|}
17:
18:
            end for
19:
            Gain(a,T) = Entropy(a) - Info(a,T) \\
20:
            GainRatio(a,T) = \frac{Gain(a,T)}{SplitInfo(a,T)}
21:
22:
        end for
        set \ a_{best} = argmax\{GainRatio(a,T)\}
23:
        a_{best}into Tree
24:
        for v \in values(a_{best}, T) do call C4.5(T_{a,v})
25:
        end for
26:
        return Tree
27:
28: end function
```