Recorded at time: 24.918 map Broadcaster: /hector_mapping Broadcaster: /hector_mapping Average rate: 40.153 Hz Average rate: 40.153 Hz Most recent transform: 24.900 (0.018 sec old) Most recent transform: 24.900 (0.018 sec old) Buffer length: 3.138 sec Buffer length: 3.138 sec world scanmatcher_frame Broadcaster: /ground_truth_to_tf Average rate: 100.319 Hz Most recent transform: 24.909 (0.009 sec old) Buffer length: 3.130 sec base_footprint Broadcaster: /ground_truth_to_tf Average rate: 100.319 Hz Most recent transform: 24.909 (0.009 sec old) Buffer length: 3.130 sec base_stabilized Broadcaster: /ground_truth_to_tf Average rate: 100.319 Hz Most recent transform: 24.909 (0.009 sec old) Buffer length: 3.130 sec base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (24.918 sec old) Most recent transform: 0.000 (24.918 sec old) Most recent transform: 0.000 (24.918 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec front_cam_link laser0_frame sonar_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (24.918 sec old) Buffer length: 0.000 sec front_cam_optical_frame

view_frames Result