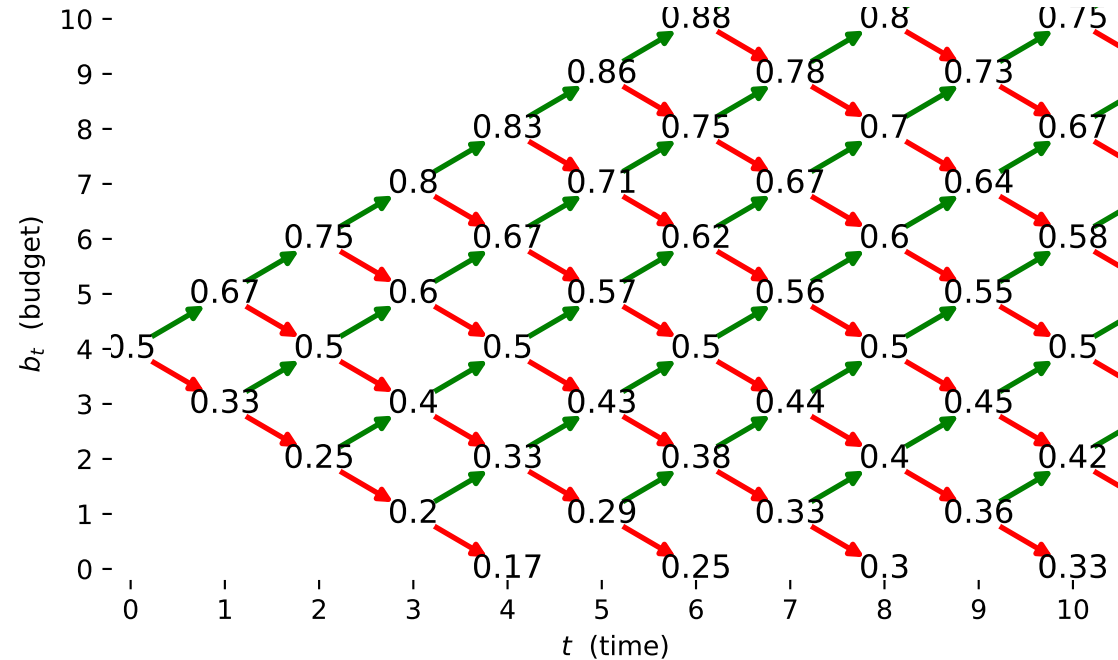


Bayesian estimation of  $p$ 

Naive Policy

