SVM: Máquina de Vectores Soporte

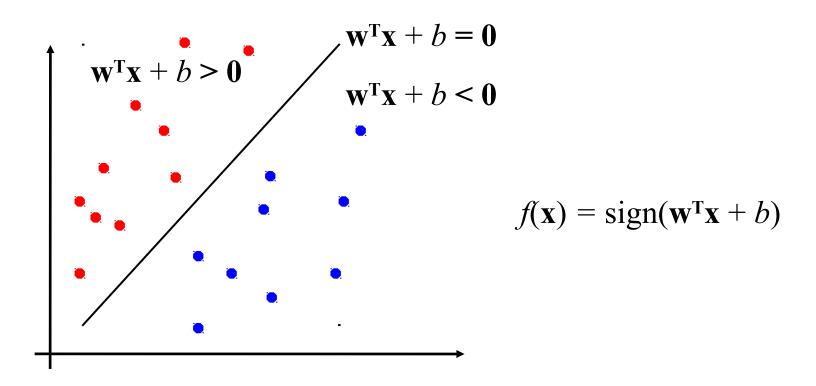
Resumen

- SVM motivación
- SVM formulación
- Kernels

Muchas slides de Ronald Collopert

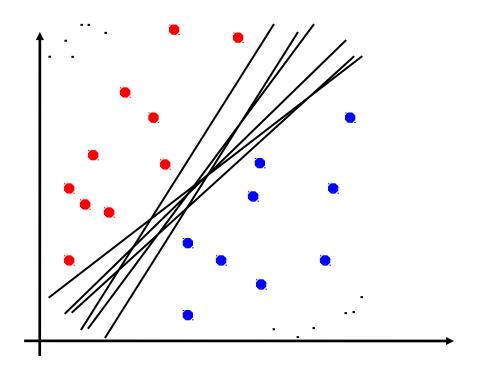
Back to Perceptron

Old method, linear solution



Linear Separators

Which of the linear separators is optimal?



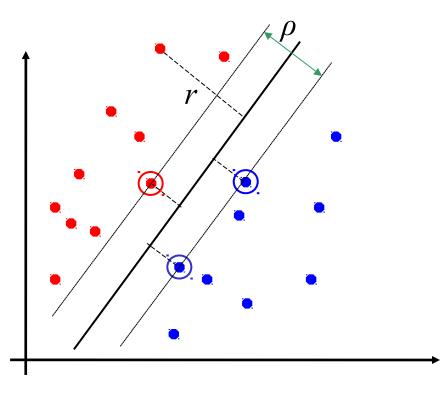
Classification Margin

Distance from example \mathbf{x}_i to the separator is $r = \frac{w^T x_i + b}{\|w\|}$

Examples closest to the hyperplane are support vectors.

Margin ρ of the separator is the distance between support

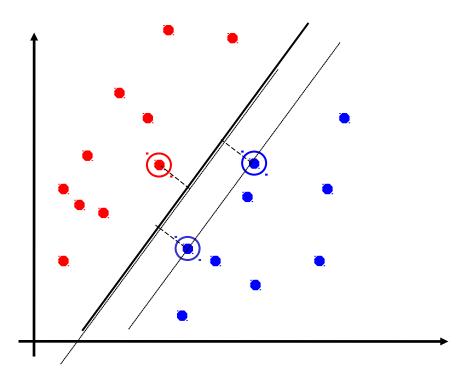
vectors.



Maximum Margin Classification

Maximizing the margin is good according to intuition and learning theory.

Implies that only support vectors matter; other training examples are ignorable.



Vapnik: Et< Ea + $f(VC/\rho)$

where f is a monotonically increasing function and VC is a complexity measure

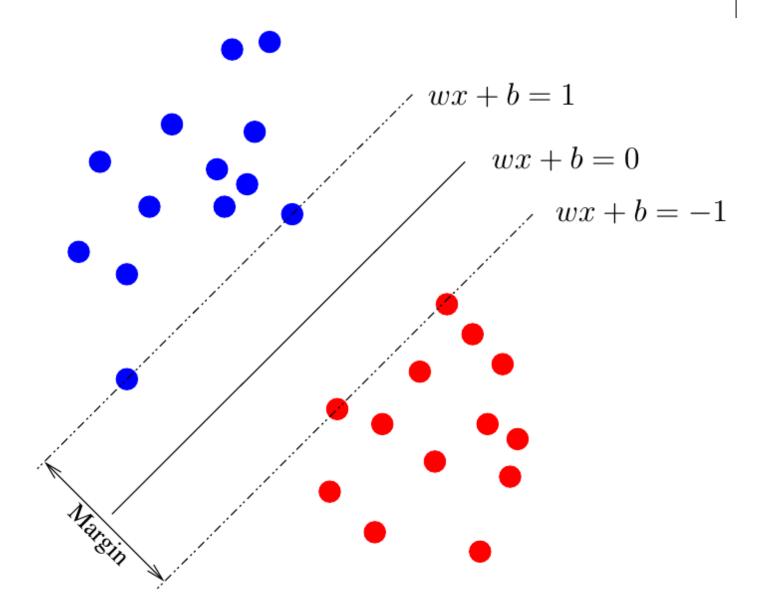
• Training set:

$$(x_t, y_t)_{t=1...T} \in \mathbb{R}^d \times \{-1, 1\}$$

• We would like to find one hyperplane

$$wx + b = 0 \quad (w \in \mathbb{R}^d, \ b \in \mathbb{R})$$

which separates the two classes and maximizes the margin.



• Margin to maximize:

$$dist(wx + b = 1, wx + b = -1) = \frac{2}{\|w\|}$$

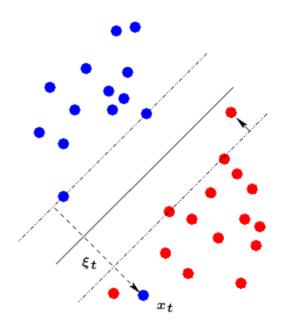
• We would like to minimize:

$$J(w, b) = \frac{\|w\|^2}{2}$$

Under the constraints:

$$y_t(wx_t + b) \ge 1 \quad \forall t$$

This minimization problem does not have any solution if the two classes are not separable.



- Relax the constraints: use a soft margin instead of a hard margin.
- We would like to minimize:

$$J(w, b, \xi) = \frac{\|w\|^2}{2} + C \sum_{t=1}^{T} \xi_t$$

Under the constraints:

$$y_t(wx_t + b) \ge 1 - \xi_t \quad \forall t$$
$$\xi_t \ge 0 \quad \forall t$$

• We want to find u such that:

$$J(u) = \inf_{v \in U} J(v)$$

$$u \in U = \{ v \in \mathbb{R}^n : \varphi_i(v) \le 0 \ \forall i \}$$

• Introduce the Lagrangian:

$$L(v, \mu) = J(v) + \sum_{i} \mu_{i} \varphi_{i}(v) \qquad (\mu_{i} \ge 0)$$

• Theorem: If (u, λ) is a saddle point of the Lagrangian L, then (u, λ) is a solution of the constrained minimization problem.

• (u, λ) is a saddle point of the function L if u is a minimum for the function $v \mapsto L(v, \lambda)$ and λ is a maximum for the function $\mu \mapsto L(u, \mu)$.

• Our Lagrangian:

$$\begin{split} L(w, \, b, \, \xi, \, \frac{\alpha}{\alpha}, \, \mu) &= J(w, \, b, \, \xi) + \sum_{t} \frac{\alpha_{t}}{1 - \xi_{t}} - y_{t}(wx_{t} + b)] - \sum_{t} \frac{\mu_{t}}{\xi_{t}} \\ &= \frac{\|w\|^{2}}{2} + C \sum_{t=1}^{T} \xi_{t} + \sum_{t} \frac{\alpha_{t}}{1 - \xi_{t}} - y_{t}(wx_{t} + b)] - \sum_{t} \frac{\mu_{t}}{\xi_{t}} \\ &\qquad (\alpha_{t} \geq 0 \quad \text{and} \quad \mu_{t} \geq 0) \end{split}$$

• Look for (w, b, ξ) minimum of L:

$$\frac{\partial L}{\partial w} = 0 \iff w = \sum_{t} \alpha_{t} y_{t} x_{t}$$

$$\frac{\partial L}{\partial b} = 0 \iff \sum_{t} \alpha_{t} y_{t} = 0$$

$$\frac{\partial L}{\partial \xi} = 0 \iff C - \alpha_{t} - \mu_{t} = 0$$

• Insert in the Lagrangian:

$$L = \sum_{t} \alpha_{t} - \frac{1}{2} \sum_{s,t} \alpha_{s} \alpha_{t} y_{s} y_{t} x_{s} x_{t}$$

$$0 \le \alpha_{t} \le C$$

$$\sum_{t} \alpha_{t} y_{t} = 0$$

$$w = \sum_{t} \alpha_{t} y_{t} x_{t}$$

• Look for (α, μ) maximum of L:

$$\alpha_t [1 - \xi_t - y_t(wx_t + b)] = 0$$

$$\mu_t \xi_t = 0$$

• Finaly, we "just" have to minimize

$$\alpha \mapsto \frac{1}{2} \alpha^{\mathbf{T}} Q \alpha - \alpha^{\mathbf{T}} 1$$

where

$$Q_{ij} = y_i y_j \, x_i x_j$$

Under the constraints

$$0 \le \alpha_t \le C \text{ and } \sum_t \alpha_t y_t = 0$$

• Then we obtain w and b with

$$w = \sum_{t} \frac{\alpha_t y_t \, x_t}{}$$

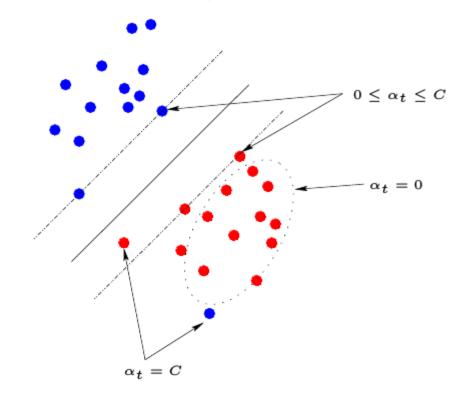
$$\alpha_t[1 - \xi_t - y_t(wx_t + b)] = 0$$

SVM formulation - end

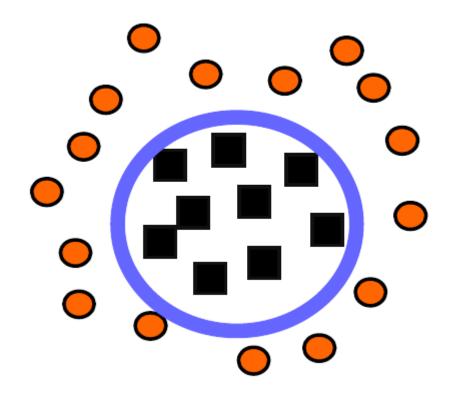
• Note that the decision function could be rewritten as:

$$x \mapsto \sum_{t} \alpha_t y_t x_t x + b$$

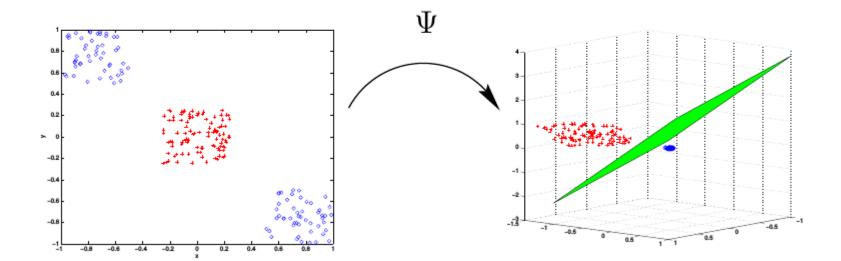
• Training examples x_t with $\alpha_t \neq 0$ are support vectors.



What about this problem?



- Project the data into a higher dimensional space: it should be easier to separate the two classes.
- Given a function $\Psi : \mathbb{R}^d \to F$, work with $\Psi(x_t)$ instead of working with x_t .



- Note that we have only dot products $\Psi(x_s)\Psi(x_t)$ to compute.
- Unfortunately, it could be expensive in a high dimensional space.
- Use instead a kernel: a function $(x, z) \mapsto k(x, z)$ which represents a dot product in a "hidden" feature space.

$$k(x, z) = \Psi(x)\Psi(z)$$

• Example: instead of

$$\Psi(x) = \begin{pmatrix} x_1^2 \\ \sqrt{2}x_1x_2 \\ x_2^2 \end{pmatrix}$$

use

$$k(x, z) = (xz)^2$$

Polynomial:

$$k(x, z) = (u xz + v)^p \quad (u \in \mathbb{R}, v \in \mathbb{R}, p \in \mathbb{N}_+^*)$$

• Gaussian:

$$k(x, z) = \exp\left(-\frac{\|x - z\|^2}{2\sigma^2}\right) \quad (\sigma \in \mathbb{R}_+^*)$$

•
The function

$$k(x, z) = \tanh(u xz + v)$$

is not a kernel!

 Any symmetric positive-definite kernel f(u,v) is a dot product in some space. Not matter what is the space.

 Kernel algebra → linear combinations of kernels are kernels

Open door: kernels for non-vectorial objects

Using SVMs

- Choose a kernel k().
- Minimize

$$\alpha \mapsto \frac{1}{2} \alpha^{\mathbf{T}} Q \alpha - \alpha^{\mathbf{T}} 1$$

where

$$Q_{ij} = y_i y_j \, k(x_i, \, x_j)$$

Under the constraints

$$0 \le \alpha_t \le C \text{ and } \sum_t \alpha_t y_t = 0$$

• For $0 < \alpha_t < C$, compute b using

$$1 - y_t \left[\sum_s \alpha_s y_s \, k(x_s, \, x_t) + b \right] = 0$$

Using SVMs

• The decision function will be

$$x \mapsto \operatorname{sign}\left(\sum_{t} \alpha_{t} y_{t} k(x_{t}, x) + b\right)$$

In practice

- Parameter C controls the solution. Must be carefully selected using validation or K-folds
- When using a kernel, the same should be done for its parameters (all combinations!)

Other methods

 Any Machine Learning method that only depends on inner products of the data can use kernels

 Lots of methods: kernel-pca, kernel regression, kernel-...

Summary

- SVMs maximize the margin (in the feature space)
- Use the soft margin trick
- Project the data into a higher dimensional space for non-linear relations
- Kernels simplify the computation
- A Lagrangian method leads to a "nice" quadratic minimization problem under constraints.