

Incremental Object Model Learning from Multimodal Human-Robot Interactions

SUPPLEMENTARY MATERIAL

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1 Additional experimental results

2 This supplementary material includes more detailed results from the experimentation performed to
3 compare the proposed incremental learning approach with different variations and baselines (both
4 incremental and offline), using *Manually cropped patches* (typically clean and less cluttered) in
5 Table 1 and *Automatically segmented patches* in Table 2.

Table 1: Object recognition accuracy (22 Objects), *Manually Cropped* patches

(a) Incremental k-NN									
	# of users processed to build the model								
	1	2	3	4	5	6	7	8	9
20-cluster limit per class									
<i>BoW_{ORB}</i>	7,6	7,2	8,0	8,3	9,0	9,6	10,4	10,3	11,3
<i>HC_{RGB}</i>	10,7	17,9	23,1	26,0	28,0	29,6	30,8	31,1	31,4
SIFT	6,1	5,5	5,2	5,4	6,4	8,5	8,9	7,3	6,8
<i>DenseNet₄</i>	9,92	12,28	13,90	15,16	18,28	20,04	20,78	21,62	21,17
No cluster limit per class (ALL)									
<i>BoW_{ORB}</i>	7,6	7,2	8,0	8,4	9,1	9,7	10,8	11,3	11,8
<i>HC_{RGB}</i>	10,7	17,9	23,1	25,8	27,6	28,4	29,2	30,3	30,2
SIFT	6,1	5,5	5,2	5,5	6,0	6,9	7,2	7,3	7,3
<i>DenseNet₄</i>	9,92	12,28	14,30	15,16	19,00	19,34	20,29	22,82	24,14
(b) Offline baselines									
k-NN+ <i>BoW_{ORB}</i>									11,8
k-NN+ <i>HC_{RGB}</i>									30,2
k-NN+ <i>SIFT</i>									7,3
k-NN+ <i>FC7</i>									2,2
<i>SVM</i> + <i>HC_{RGB}</i> [2]									34,8
<i>Inception-based</i>									59,3

Table 2: Object recognition results using *Automatic Patches* (22 classes, random chance 4.45).

	Accuracy	STD (10-fold cross val.)
Previous Work (offline) [2]:		
$SVM + HC_{RGB}$ (Automatic patches)	7.95	6.6
$SVM + HC_{RGB}$ (Automatic Inspected patches)	11.45	10.53
Other offline baselines:		
Offline k-NN (HC_{RGB})	13.4	6.56
Inception-based	17.5	6.51
Incremental:		
Incremental-50 (HC_{RGB})*	9.0	6.35
Incremental-100 (HC_{RGB})**	13.2	6.30
Incremental-50 ($DenseNet_4$)*	5.55	3.98
Incremental-100 ($DenseNet_4$)**	5.64	3.53

* Performance after 50% of data processed by the incremental system

** Performance after 100% of data processed by the incremental system