Comparison of image matching algorithms for rock glacier displacement mapping. A case study for the Laurichard rock glacier, French alps.

Geo 411 - Landschaftsmanagement und Fernerkundung

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1 Introduction

Rock glaciers are distinctive morphological features of high mountain periglacial environments. Their deformation processes are strongly linked to permafrost degradation (Haeberli et al. 2010). Thus, research of deformation velocities of rock glaciers does not only provide insights into periglacial morphology but also in time evolution of permafrost. Several authors have used rock glaciers as proxies for permafrost presence/absence in permafrost distribution models (Boeckli et al. 2012, Marcer et al. (2017)).

In recent years, multi-method approaches have been used in this field of research; Buchli et al. (2018) combine laser scanning, terrestrial radar and in-situ measurements at the Furggwanghorn rock glacier in Switzerland. Remote sensing data, especially radar interferometry (InSAR) (Barboux et al. 2015), optical imagery and laser scanning (L. U. Arenson, Kääb, and O'Sullivan 2016) have become more and more common for rock glacier deformation analysis. With unmanned aerial vehicles (UAVs), high-resolution consumer grade digital cameras and smartphones being more and more widespread, surveys with high to very high resolution in time and space dimensions (Dall'Asta et al. 2017) become affordable in research and natural hazard mitigation contexts. Structure-from-motion (SfM) (M. Smith, Carrivick, and Quincey 2016) and other established photogrammetric techniques allow for the generation of genuine 3D point clouds as well as 2.5D digital surface models (DSMs) and derivates, acquired by abovementioned techniques (Eltner et al. 2016).

From a series of those surface models at different points in time, displacement velocities of mass movement processes as well as surface changes resulting from erosion and denudation can be quantified. Techniques range from simple DEM differencing to 3-dimensional point-cloud comparison (James, Robson, and Smith 2017).

Image matching techniques are well established methods for the quantification of surface changes in geomorphology and glaciology (Paul et al. 2015). They have already been developed for glacier velocity analyses in the mid-1980s (Scambos et al. 1992) and have been developed further since then. They do not necessarily depend on elevation models, except for the quantification of 3-dimensional (i.e. elevation) differences. All image matching algorithms

are based on the comparison of either local image patterns or structures/features, on global image characteristics or a combination thereof. They can be applied to panchromatic or colour images as well as to DEMs and their derivates and image transformations (most commonly used: Fourier transformations, filters and principal component analyses) (T. Heid and Kääb 2012,Dall'Asta et al. (2017)). Besides scope and input data, image matching algorithms can be structured by their similarity measure: The calculation of a normalized cross-correlation coefficient (NCC) on two image parts is the most widespread mesaure (Scambos et al. 1992). More recently, NCC-based similarity measures have been developed further, being based on image derivatives (T. Heid and Kääb 2012) or on global energy functions (Arganda-Carreras et al. 2006).

Image matching techniques have been applied to rock glacier deformation detection and the calculation of velocity fields. Bodin et al. (2018) present one of the most recent examples for the Laurichard rock glacier in the French Alps. Based on their work, we compared the performance of two image matching algorithms for surface displacement detection between 2012 and 2017: 1. The well-established IMCORR algorithm (NSIDC 2018), based on Scambos et al. (1992); and 2. bUnwarpJ, a semi-global algorithm originally developed for image registration in health studies (Arganda-Carreras et al. 2006). For both algorithms we calculated an annual displacement rate of the Laurichard rock glacier, based on high-resolution DEMs from an aerial laser scanning (ALS) campaign in 2012 and from a UAV campaign in 2017. We optimized parameter settings of both approaches and estimated the accuracy of the resulting deformation fields with GPS displacement data from Bodin et al. (2018) and manually mapped surface displacements.

TODO: Structure of the paper?

2 Study Area

The Laurichard rock glacier is situated in the French Alps, with an approximately 800m long and 100-200m wide tounge flowing from south to north-east. Due to its morphological features it can be considered an active rock glacier (Bodin et al. 2018). Especially, hillshades

generated from available digital elevation models (DEMs) exhibit scarps, oriented perpendicular to the flow direction as well as a steep rising frontal lobe.

TODO: Image of study area

Since the beginning of the 1980s, the Laurichard rock glacier has been subject to in-situ and remote sensing photogrammetry research. Refer to Bodin et al. (2018) for the most current research work as well as for an overview over the history of site studies.

3 Data and Methods

3.1 Used Data and Preprocessing

To compare the rock glacier's annual displacement rates we used one DEM, acquired by an ALS survey on 16./17. August 2012 with a vertical accuracy of 2cm and co-registered to a TLS-based DEM from 2005 (Bodin et al. 2018). The second DEM is derived from a UAV survey and processed by Structure-from-Motion techniques (Jason Goetz, personal communication). Both models have been georeferenced and resampled to a 10cm resolution, but have not been co-registered (JG, personal communication). A first inspection with simple DEM differencing (DoD) showed good accordance between the two data sets in supposedly stable areas around the Laurichard rock glacier. Therefore, we decided to omit a co-registration procedure.

From the DEMs we derived common derivats: Slope, Aspect and Hillshade with GIS standard settings as well as a principle component analysis in order to compare algorithm performance based on different input data.

For validation, firstly we

• validation data

- 3.2 IMCORR
- 3.3 ImageJ BUnwrapJ
- 3.4 Comparison
- 4 Results
- 5 Discussion
- 6 Conclusion
- 7 Outlook (or: Conclusion and Outlook?)

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