Notations

We use the following Hamiltonian with aperiodic boundary condition (ABC):

$$\hat{H}_K = -\sum_{x=1}^{L} \left(\hat{c}_x^{\dagger} \hat{c}_{x+1} + \delta \hat{c}_x^{\dagger} c_{x+1}^{\dagger} + \text{h.c.} \right) - \mu \sum_{j=1}^{L} \hat{c}_x^{\dagger} \hat{c}_x ;$$
(1)

where we consider $\hat{c}_{L+1} = -\hat{c}_1$.

In the scaling functions of this model, we fix these scaling variables:

$$\Upsilon = \tau_s L^{-(y_\mu + z)} , \qquad (2)$$

$$\kappa = w_i \tau_s^{y_\mu/(y_\mu + z)} , \qquad (3)$$

$$\Omega = w(t)\tau_s^{y_{\mu}/(y_{\mu}+z)} , \qquad (4)$$

(5)

with $w(t) = \mu(t) - \mu_c$ and $w(t) = t/\tau_s$.

Moreover, to analyze the system behavior, we introduce a set of observables:

• the time-dependent correlations functions:

$$C_x = \langle \psi(t) | \hat{c}_y^{\dagger} \hat{c}_{y+x} + \text{h.c.} | \psi(t) \rangle ,$$
 (6)

$$P_x = \langle \psi(t) | \hat{c}_{\nu}^{\dagger} \hat{c}_{\nu+x}^{\dagger} + \text{h.c.} | \psi(t) \rangle ; \qquad (7)$$

(8)

• the equilibrium correlations functions:

$$C_x^o = \langle GS(t)|\hat{c}_y^{\dagger}\hat{c}_{y+x} + \text{h.c.}|GS(t)\rangle$$
, (9)

$$P_x^o = \langle GS(t)|\hat{c}_y^{\dagger}\hat{c}_{y+x}^{\dagger} + \text{h.c.}|GS(t)\rangle ; \qquad (10)$$

(11)

• the adiabacity:

$$A = -\ln|\langle GS(t)|\psi(t)\rangle| ; \qquad (12)$$

• the energy difference:

$$E - E_o = \langle \psi(t) | \hat{H}(t) | \psi(t) \rangle - \langle GS(t) | \hat{H}(t) | GS(t) \rangle ; (13)$$

• the particle density:

$$\delta\rho(t) = \rho - \rho_c = \frac{\mathbf{N} - \mathbf{N}_c}{\mathbf{L}} \ . \tag{14}$$