Final Review Quiz:

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1) What are the two types of turns?

2) Which type of turn do you use in tight places?

3) Where do you go on your brick to get sensor readings such as “what color the robot sees” and “how many degrees the robot moved”?

4) What block do you use to repeat an action?

5) What block would you use to select between two different actions based on a sensor reading?

6) To program using a sensor and perform an action UNTIL a sensor is activated (black line seen, touch pressed), what block do you use?

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