Numerical Analysis Project 3

Writing the Code

-Language: Python

-Input:

• h - the step size, which determines the time intervals at which we find approximate solutions

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- t time points inside the time interval
- initial condition defining y(0) = 0, the starting value for the diff eq.
- Derivative Func defining y'(t) = t + y, the differential equation that represents the slope of the solution curve for approximations
- Exact Solution defining $y(t) = e^t t 1$, so we can calculate the true values at t for comparison with approximations

-Output:

Euler's, Modified Euler's, Heun's, and Midpoint methods compute numerical approximations for y(t) at each time point t, based on the given step size h. The true solution is calculated at each iteration for error analysis. For each method and for each iteration, the percentage error is calculated as: |(Approx - Exact)/ Exact| * 100 which quantifies the difference between the approximations and exact solutions.

The table presents t for each step size, the true solutions, the approximate solutions using each method, and the percentage error. The exact values generate a smooth graph, while the numerical solutions are just a set of points connected by a simple line, this is to visualize the comparison between the true vs approximate graph. Euler's method is quick and simple, but prone to error. Modified Euler's, Heun's, and Midpoint methods use additional computations per step to improve precision and accurately approximate the curve.

Choice of Parameters

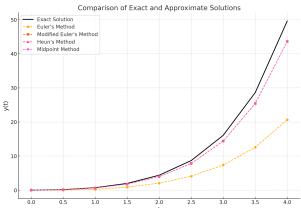
Given h = 0.5, the step size is moderate to limit mesh points, having a balance between accuracy and computational efficiency. A smaller step size would improve accuracy but increase the calculations required.

Given interval: $0 \le t \le 4$, we have 8 mesh points, which is a reasonable amount for evaluation without overstepping computational time. Especially given we want to compute these points for multiple methods.

Results and Analysis

| | | t | Exact | Euler | Modifie | d Euler | Heun | Midpo | oint Eule | r Error (| %) |
|--------------|----|--------|----------|-------|----------|----------|-------|----------|-----------------|-----------|------------|
| | | • | | | | | | | Midpoir | | ` / |
| 0.0 | 0 | 00 | 0000 | | 00000 | 0.00000 | | 0.00000 | • | 000000 | 0.000000 |
| 0.0 | | | | | 0.000000 | | - | | 00000 | | 0.000000 |
| 0.5 0.148721 | | | R721 | | 00000 | 0.12500 | | 0.12500 | | 25000 | 100.000000 |
| 0.5 | 0. | . 1 10 | 5/21 | | 5.950153 | | | | 950153 | 23000 | 100.000000 |
| 1.0 | Λ | 71 | 8282 | | 50000 | 0.64062 | | 0.64062 | | 540625 | 65.194720 |
| 1.0 | U | . / 10 | 0202 | | 0.811471 | | _ | | 3 0.0 811471 | 140023 | 03.134720 |
| 1.5 | 1 | 00 | 1689 | | 75000 | 1.79101 | | 1.79101 | | 91016 | 55.845747 |
| 1.3 | 1 | .90 | 1089 | | | | _ | | | 91010 | 33.843/4/ |
| | | | | | 9.621764 | | | | 21764 | | |
| 2.0 | 4 | .389 | 9056 | 2.06 | 52500 | 3.97290 | 0 | 3.97290 | 0 3.9 | 72900 | 53.008119 |
| | | | 9.481668 | 9.48 | 1668 | 9.4 | 81668 | | | | |
| 2.5 | 8 | .682 | 2494 | 4.09 | 93750 | 7.83096 | 3 | 7.83096 | 3 7.8 | 30963 | 52.850529 |
| | | | | | 9.807445 | 9.80 | 7445 | 9.8 | 07445 | | |
| 3.0 | 16 | .08 | 5537 | 7.39 | 0625 | 14.41281 | 5 | 14.4128 | 15 14. | 412815 | 54.054223 |
| | | | | 1 | 0.398918 | 10.39 | 8918 | 10. | 398918 | | |
| 3.5 | 28 | .61 | 5452 | 12.5 | 85938 | 25.4208 | 25 | 25.42082 | 25 25. | 420825 | 56.016989 |
| | | | | 1 | 1.163994 | 11.16 | 3994 | 11. | 163994 | | |
| 4.0 | 49 | .598 | 8150 | 20.6 | 28906 | 43.6213 | 40 | 43.62134 | 40 43. | 621340 | 58.407912 |
| | | | | 1. | 2.050470 | 12.05 | 0470 | 12. | 050470 | | |
| | | | | | | | | | | | |

Graph



As expected, the Euler method being the

simplest method is the most inaccurate with the highest percentage error for every step. The other methods are all the same for this problem. They all have noticeably lower percentage errors (as expected) being higher-order while evaluating a linear function for f(t,y). It is worth noting that the code for the Modified Euler's here uses the Predictor-Corrector steps, but testing the code without including those extra steps for correction, it actually becomes the most inaccurate method.

Code

Method Comparison:

```
import numpy as np
import pandas as pd
# Define the derivative function and exact solution
def dydt(t, y):
      return t + y
def exact solution(t):
      return np.exp(t) - t - 1
# Euler's Method
def euler method(f, t values, y0, h):
     y \text{ values} = [y0]
       for i in range(len(t values) - 1):
                 y_next = y_values[-1] + h * f(t_values[i], y_values[-1])
                 y values.append(y next)
       return y values
# Modified Euler's Method
def modified euler_method(f, t_values, y0, h):
       y \text{ values} = [y0]
       for i in range(len(t values) - 1):
                 # Predictor step
                 y pred = y values[-1] + h * f(t values[i], y values[-1])
                 # Corrector step
                 y = y = y = [-1] + (h / 2) * (f(t values[i], y values[-1]) + f(t values[i + 1], y values[-1]) + f(t values[-1], y values[-1]) + f(t values[-1], y values[-
y pred))
                 y values.append(y next)
       return y values
# Heun's Method (equivalent to Modified Euler for this problem)
def heun method(f, t values, y0, h):
      y \text{ values} = [y0]
       for i in range(len(t values) - 1):
                 y_pred = y_values[-1] + h * f(t_values[i], y_values[-1])
                 y = y = y = [-1] + (h / 2) * (f(t values[i], y values[-1]) + f(t values[i+1],
y pred))
                 y values.append(y next)
       return y values
# Midpoint Method
def midpoint_method(f, t_values, y0, h):
       y \text{ values} = [y0]
       for i in range(len(t values) - 1):
                 y \text{ mid} = y \text{ values}[-1] + (h / 2) * f(t \text{ values}[i], y \text{ values}[-1])
                 y_next = y_values[-1] + h * f(t_values[i] + h / 2, y_mid)
                 y values.append(y next)
       return y values
# Define parameters
h = 0.5 # Step size
t values = np.arange(0, 4.5, h) # Time points
```

```
y0 = 0 # Initial condition
# Compute solutions
exact values = exact solution(t values)
euler values = euler method(dydt, t values, y0, h)
mod euler values = modified euler method(dydt, t values, y0, h)
heun values = heun method(dydt, t values, y0, h)
midpoint values = midpoint method(dydt, t values, y0, h)
# Compute errors
def compute errors(approx values, exact values):
   return [abs((a - e) / e) * 100 if e != 0 else 0 for a, e in zip(approx values,
exact values)]
euler_errors = compute_errors(euler_values, exact_values)
mod euler errors = compute errors(mod euler values, exact values)
heun errors = compute errors(heun values, exact values)
midpoint errors = compute errors(midpoint values, exact values)
# Create a DataFrame for the results
data = {
  "t": t_values,
  "Exact": exact values,
   "Euler": euler values,
   "Modified Euler": mod euler values,
   "Heun": heun values,
   "Midpoint": midpoint values,
   "Euler Error (%)": euler errors,
   "Modified Euler Error (%)": mod euler errors,
   "Heun Error (%)": heun errors,
   "Midpoint Error (%)": midpoint_errors,
df = pd.DataFrame(data)
# Display the results in a simple table
print(df.to_string(index=False))
```