Temporal Graph Motifs

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1 Introduction

In this note, we describe the algorithms to look for temporal $K_{2,h}$ motifs in a graph or network of events. We assume that events are time indexed and grouped under some **root event** which happens first via a tree structure (which could also simply be a linear sequence of events). Many types threaded conversation (e.g. tweets and retweets, Reddit comments, email chains) can be described in this format, which are instances of the W3 paradigm: (i) Who (the actors), (ii) What (the events) and (iii) When (time of the events).

1.1 Data Format

The data consists of k temporal 4- or 5-tuples:

- $\{(event_i, actor_i, t_i, root_i)\}_{i=1}^k$
- $\bullet \ \{(event_i, actor_i, t_i, root_i, parent_i)\}_{i=1}^k$

Where:

- $event_i$: is a unique identifier for each event
- actor_i: is the identifier of the actor/user generating the event
- t_i : is the time of the event, typically in UTC format
- $root_i$: is the identifier of the root event that $event_i$ is part of
- $parent_i$: is the identifier of the parent of this event when events with same $root_i$ have a tree structure

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We assume that:

- $event_i = root_i$ for the **root event**; in this case, $parent_i$ is meaningless
- all events with same $root_i$ can not happen before the root event itself
- if *parent*_i are used, the parent event can not happen before one of its child event

1.2 Temporal $K_{2,h}$ motifs

A $K_{2,h}$ motif is a complete bipartite subgraph with vertices from 2 subsets V_1 and V_2 where $|V_1|=2$ and $|V_2|=h\geq 2$. In our context, nodes in V_1 represent *actors*, such as users in a social network, while nodes in V_2 are *events*, for example a message in a thread, or a re-tweet.

Temporal $K_{2,h}$ motifs are parameterized by 3 values:

- Δt : the reaction time, in seconds;
- ΔT : the repetition time, in seconds;
- h: the number of distinct events forming the motif.

We describe 2 families of motifs next. The pseudo-codes to identify those motifs are detailed in the Appendix.

1.2.1 root-based motifs

A temporal root-based $K_{2,h}$ motifs given $(\Delta t, \Delta T)$ occurs when:

- (1) an actor A submits a root event $root_i$ and a different actor B submits an event under that root event (i.e. with same $root_i$) within Δt seconds (the reaction time), and
- (2) the above scenario happens h times, for h distinct root events, all within ΔT seconds (the *repetition* time).

1.2.2 hop-based motifs

A temporal hop-based $K_{2,h}$ motifs given $(\Delta t, \Delta T)$ occurs when:

(1) an actor A submits an event with identifier $event_i$ (the event needs not be the $root\ event$ but it can be), and a different actor B submits another event with parent identifier $parent_j$ such that $parent_j = event_i$, within Δt seconds (the reaction time), and

(2) the above scenario happens h times, for h distinct root events, all within ΔT seconds (the *repetition* time).

In cases where (1) above happens more than once under the same *root* event, the first instance is retained.

2 The Python Code

Installing the temporal graph mining (tgm) library is straightforward with: pip install tgm. The only dependencies are the igraph python library as well as the standard numpy and pandas libraries.

For both types of temporal motifs, root-based or hop-based, the algorithm to find the motifs is broken up in two steps:

- (a) given the list of event tuples, build a bipartite graph representation of the data, and
- (b) enumerate all *motifs* using this bipartite graph.

The advantage of this decomposition is that if look for motifs multiple times for the same dataset, for example using different parameter values $(\Delta t, \Delta T)$, then step (a) is only run once, which speeds up the process. The pseudocodes are detailed in the appendix, namely:

- Algorithm 1: compute bipartite graph for root-based motifs;
- Algorithm 2: use the bipartite graph from Algorithm 1 to find root-based motifs;
- Algorithm 3: compute bipartite graph for hop-based motifs;
- Algorithm 4: use the bipartite graph from Algorithm 3 to find hop-based motifs.

Examples running the tgm on toy and real datasets are given in the Jupyter notebook which can be found at https://github.com/ftheberge/tgm.

A Pseudo-code

Algorithm 1 Directed Bipartite Graph for Root-based Motifs

```
Require: Events (event_i, actor_i, t_i, root_i) in dataframe D

Initialize empty directed bipartite graph B_r

for each event (event_i, actor_i, t_i, root_i) in D do

if event_i = root_i then

add edge actor_i \rightarrow root_i to B_r with attribute (time = t_i, isRoot = True)

else

add edge actor_i \rightarrow root_i to B_r with attribute (time = t_i, isRoot = False)

end if
end for
return B_r
```

Algorithm 2 Root-based Temporal $K_{2,h}$ Motifs

```
Require: B_r from Algorithm 1 and parameters (h, \Delta t, \Delta T)
  initialize empty list E
  for each vertex root in B_r with in-degree (root) > 1 (i.e. at least 2 events)
  do
     if there is an edge actor \rightarrow root with attributes (time = t, isRoot =
     True) for some t then
       t_{min} = t (time of the root event)
       rootActor = actor (actor of the root event)
       for each actor_i such that there is at least one edge actor_i \to root \mathbf{do}
          let t_i be the minimum of all time attributes from all edges actor_i \rightarrow
          if t_i - t_{min} \leq \Delta t and actor_i \neq rootActor then
            append 4-tuple (root, actor_i, t_{min}, rootActor) to E
          end if
       end for
     end if
  end for
  let |E| = k, re-label E = (root_i, actor_i, t_i, rootActor_i) for 1 \le i \le k
  initialize empty graph G
  for 1 \le i \le k do
     if there is already an edge actor_i \rightarrow rootActor_i in G then
       append event (root_i, t_i) as edge attribute
     else
       add edge actor_i \rightarrow rootActor_i to G with event (root_i, t_i) as edge
       attribute
     end if
  end for
  for all edges in G do
     order edge attributes (root_i, t_i) with respect to time
     count the number of h-consecutive events happening within \Delta T, store
     as edge weight (or drop edge if weight = 0)
  end for
  return weighted graph G where each edge represents an actor \rightarrow
  rootActor pair and edge weight is the number of temporal K_{2,h} motifs
  for this pair.
```

```
Algorithm 3 Directed Bipartite Graph for Hop-based Motifs
```

```
Require: Events (event_i, actor_i, t_i, root_i, parent_i) in dataframe D
  for each (event_i, actor_i, t_i, root_i, parent_i) in D do
     if there exists j such that event_j = parent_i and actor_j \neq actor_i then
        (i) parent\_actor_i = actor_j
        (ii) parent_{-}t_{i} = t_{j}
        (iii) \Delta t_i = t_i - parent_{-}t_i
        (iv) add parent\_actor_i, parent\_t_i, \Delta t_i to D
     else
        drop this event in D
     end if
  end for
  prune D keeping only the earliest instance with respect to t for every
  unique triple (actor, root, parent_actor)
  initialize empty directed bipartite graph B_h
  for each (event_i, actor_i, t_i, root_i, parent\_actor_i, parent\_t_i, \Delta t_i) in D do
     add edge actor_i \rightarrow parent\_actor_i to B_h with attribute (root =
     root_i, time = parent_t, \Delta t = \Delta t_i
  end for
  return B_h
```

Algorithm 4 Hop-based Temporal $K_{2,h}$ Motifs

```
Require: B_h from Algorithm 3 and (h, \Delta t, \Delta T)
  initialize empty graph {\cal G}
                                \rightarrow parent_actor<sub>i</sub> in B_h with attributes
  for each edge actor_i
  (root_i, parent_-t_i, \Delta t_i) do
     if \Delta t_i \leq \Delta t then
       if there is already an edge actor_i \rightarrow parent\_actor_i in G then
          append event (root_i, parent_{-}t_i) as edge attribute
       else
          add edge actor_i \rightarrow parent\_actor_i to G with event (root_i, parent\_t_i)
          as edge attribute
        end if
     end if
  end for
  for all edges in G do
     order edge attributes (root_i, parent_t_i) with respect to time
     count the number of h-consecutive events happening within \Delta T, store
     as edge weight (or drop edge if weight = 0)
  end for
            weighted graph G where each edge represents an actor \rightarrow
  parent_actor pair and edge weight is the number of temporal K_{2,h} motifs
  for this pair.
```