Dynamic Design

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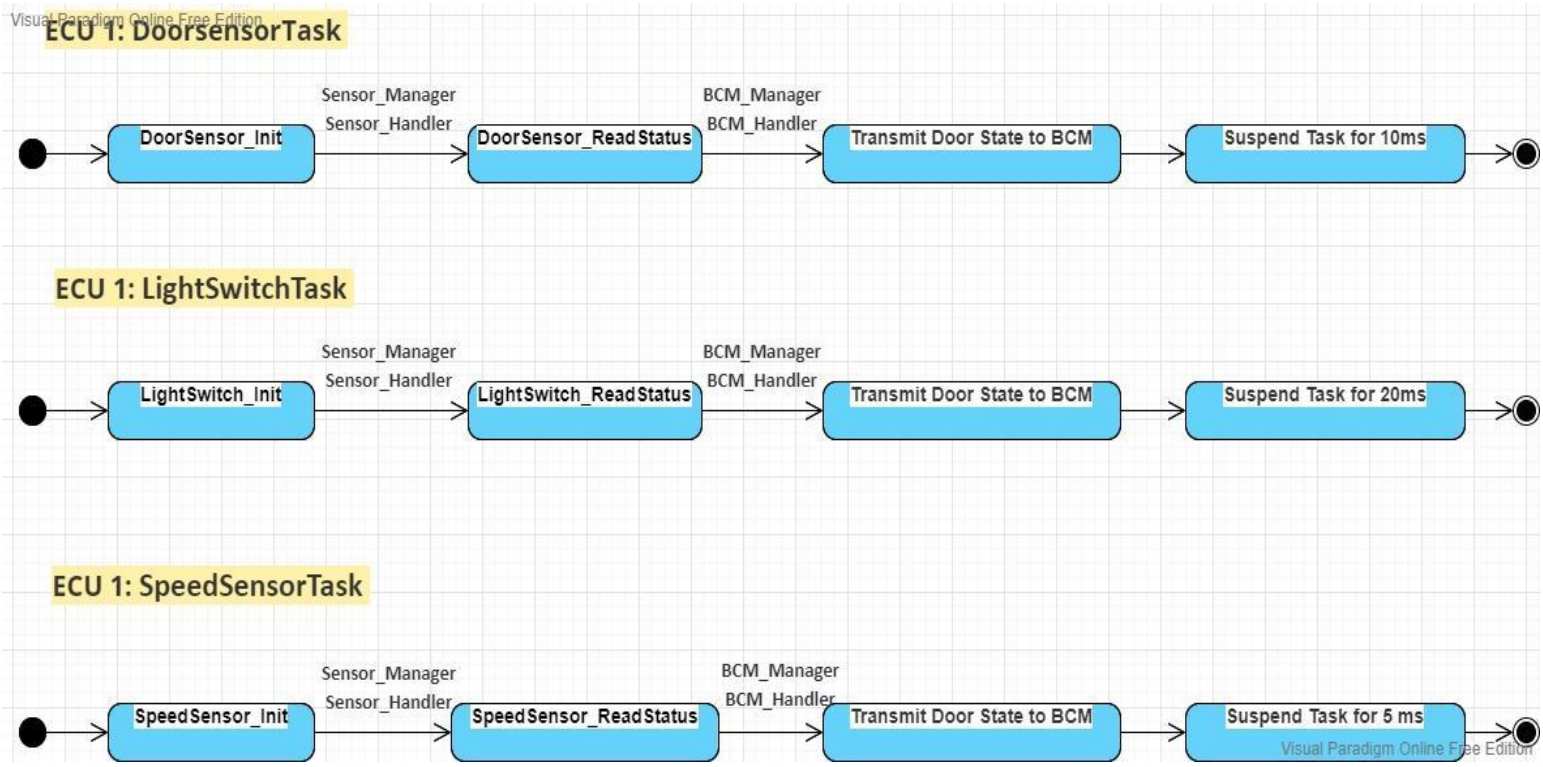
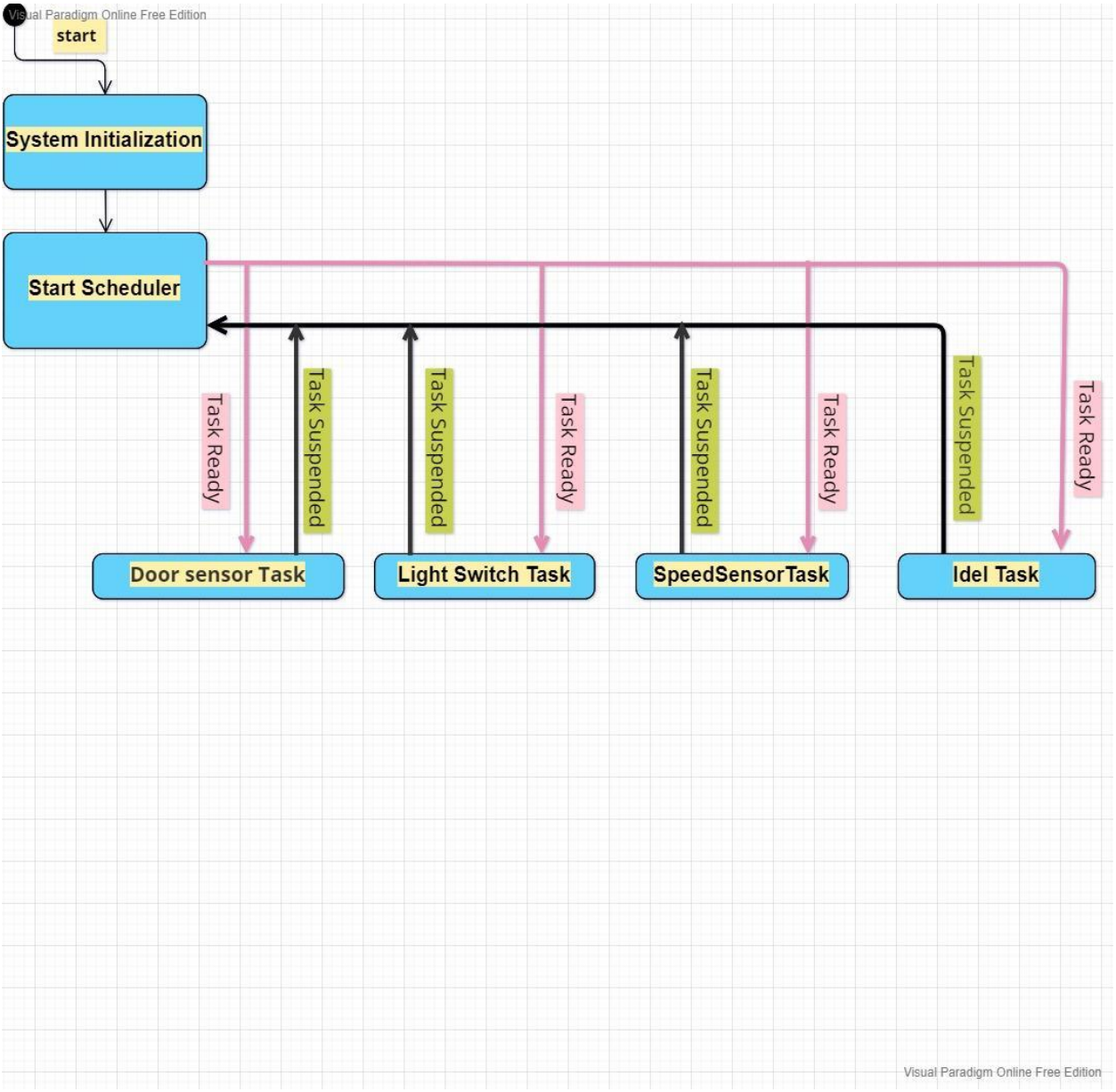
For ECU 1:

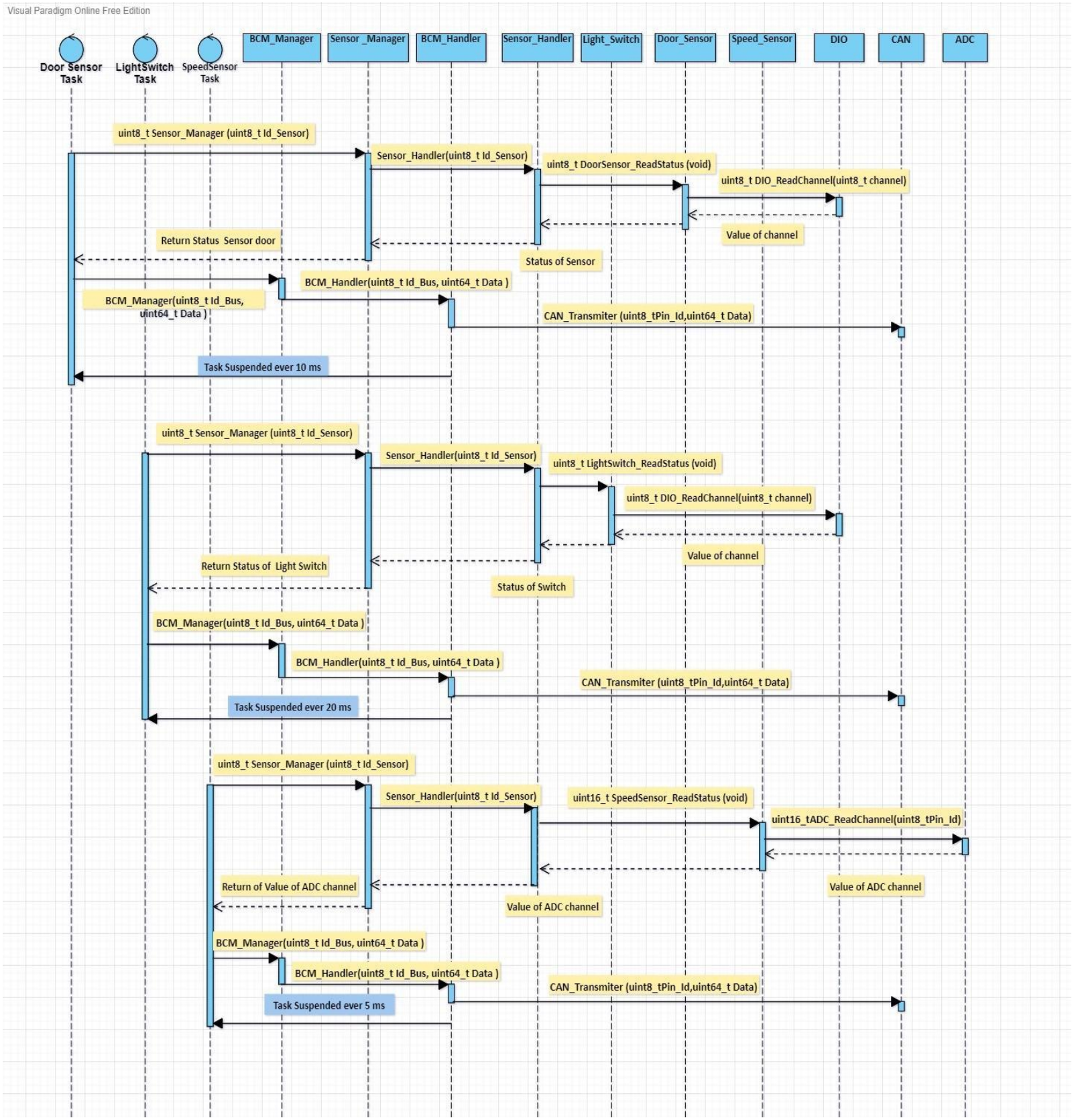
1- state machine diagram for ECU 1 component:



2- state machine diagram for the ECU_1 operation:



3- sequence diagram for the ECU 1 :



4- Calculate CPU load for the ECU 1:

The system contains three tasks assuming the worst case scenario that the execution time of the task is **500 µs.**

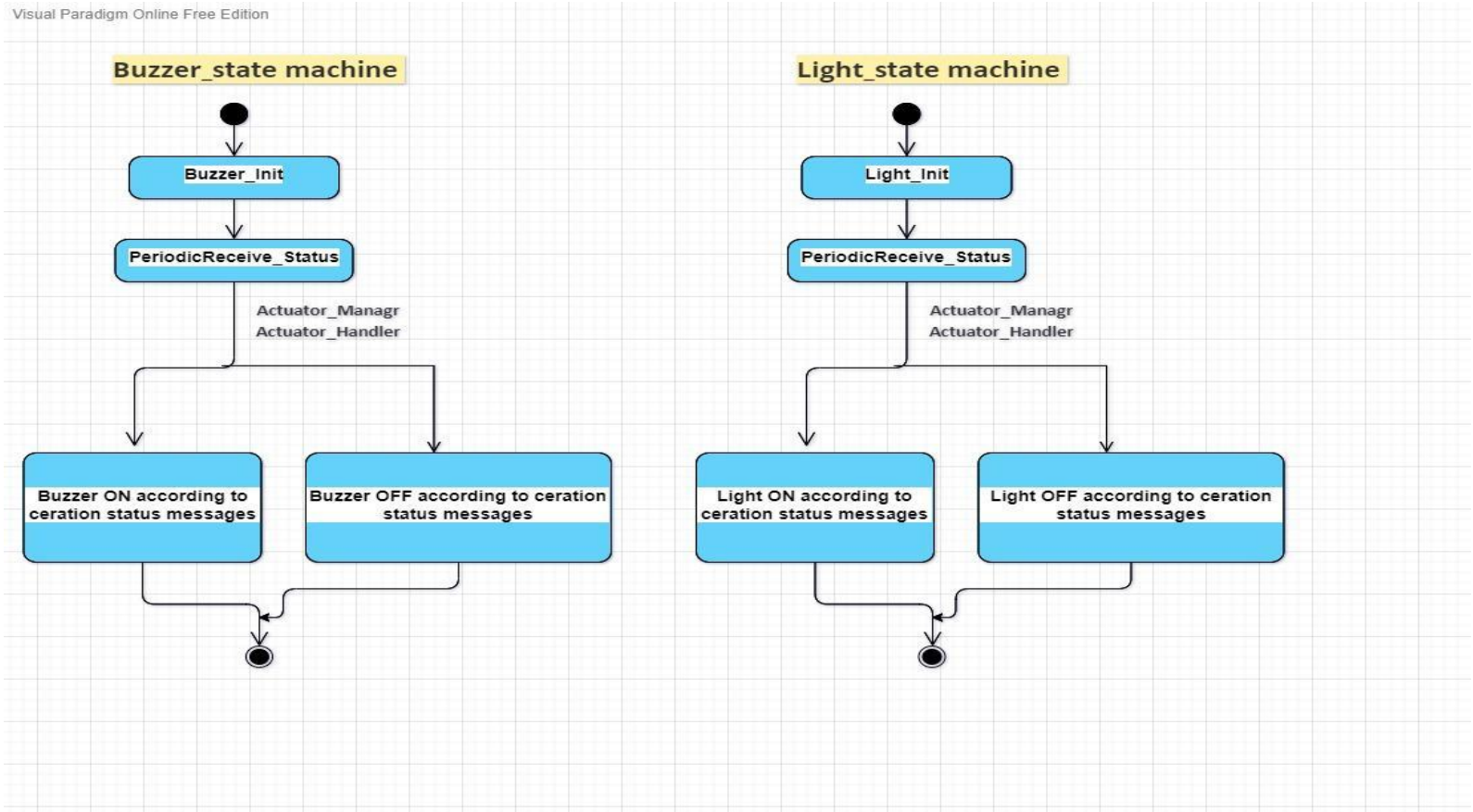
Name Task	Periodicity	Execution Time
Door Sensor Task	**10 ms**	**500 µs**
Light sensor Task	**20 ms**	**500 µs**
Speed Sensor Task	**5 ms**	**500 µs**

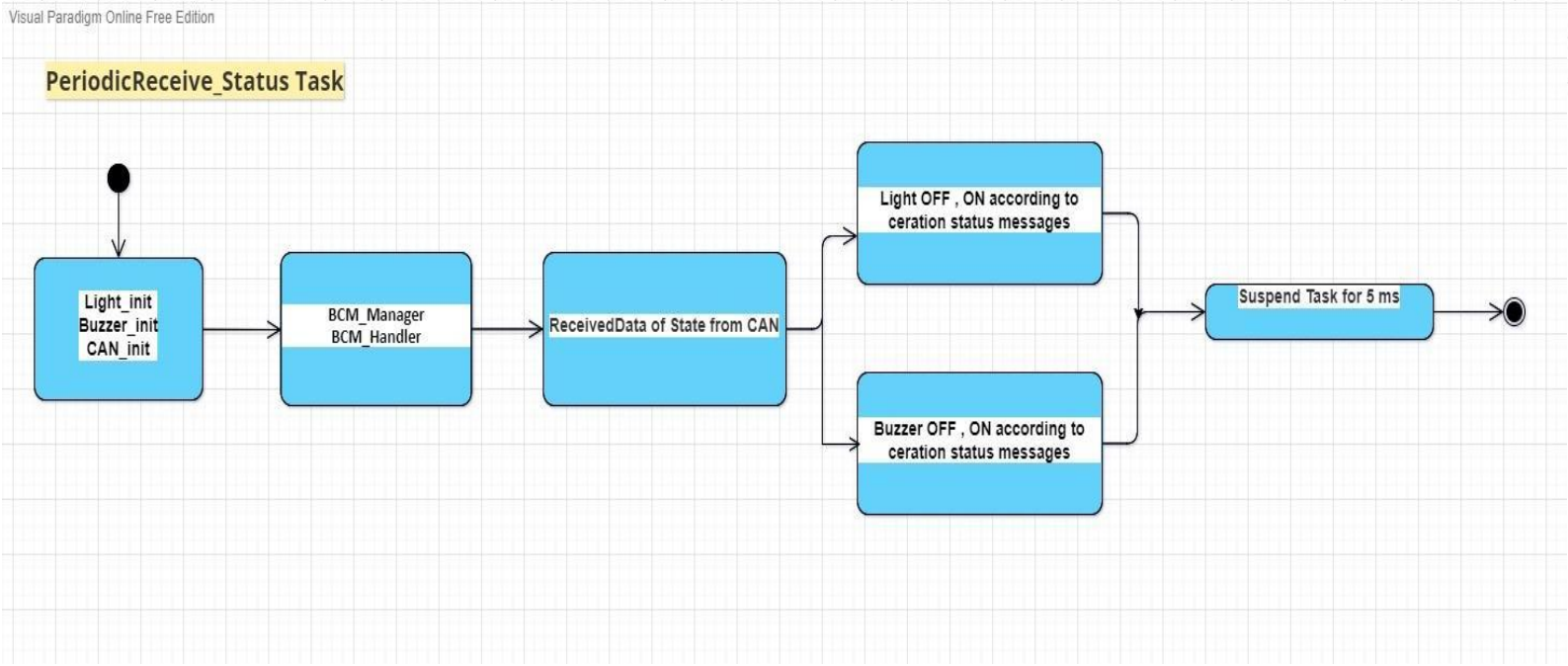
H (Hyper Period) = LCM(Pi) = 20 ms

CPU Load = $\sum$ E / H = (0.5*2 + 0.5*4 + 0.5*1) /20 * 100 = 17.5 %

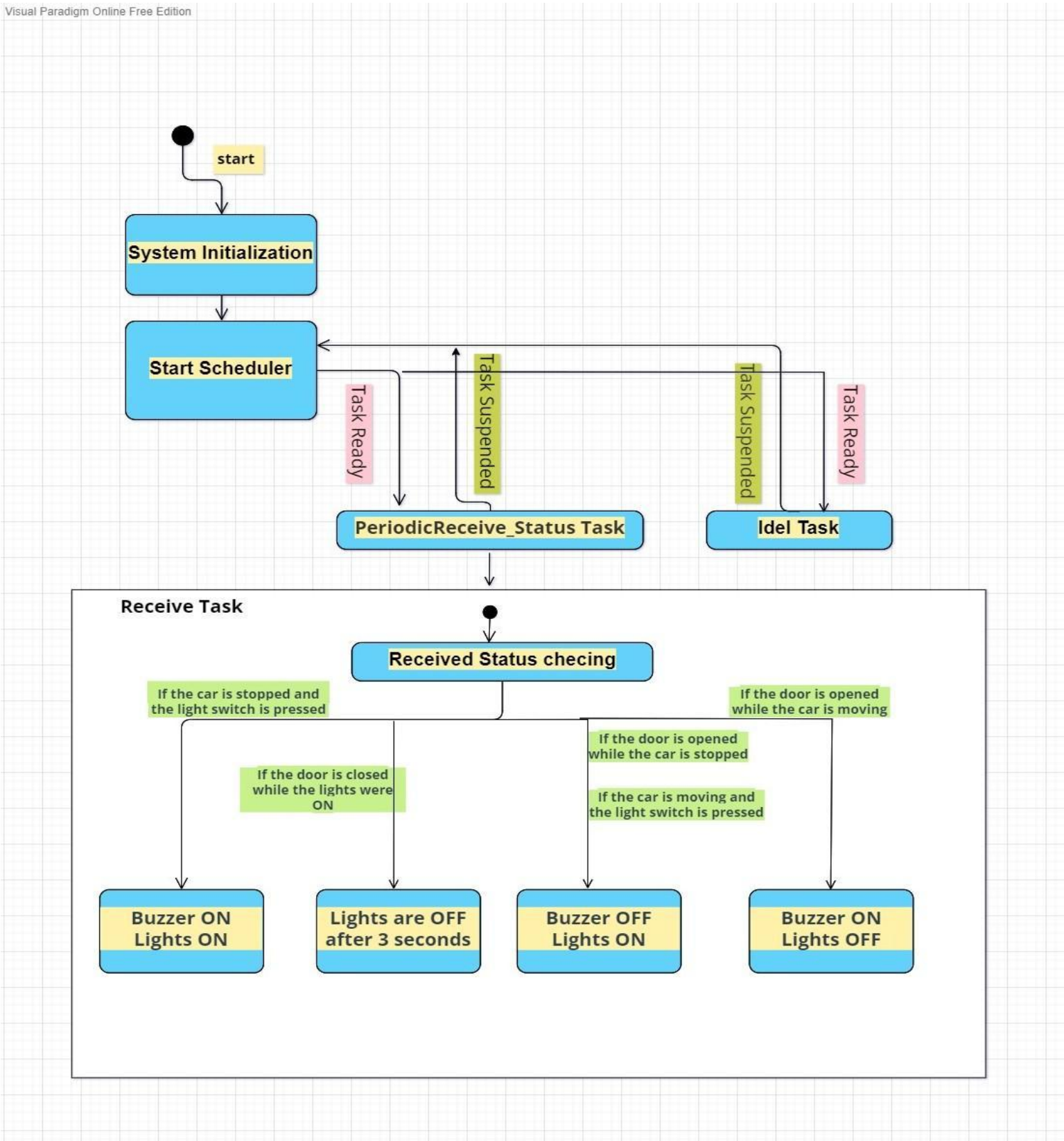
For ECU 2:

1- state machine diagram for ECU 2 component:

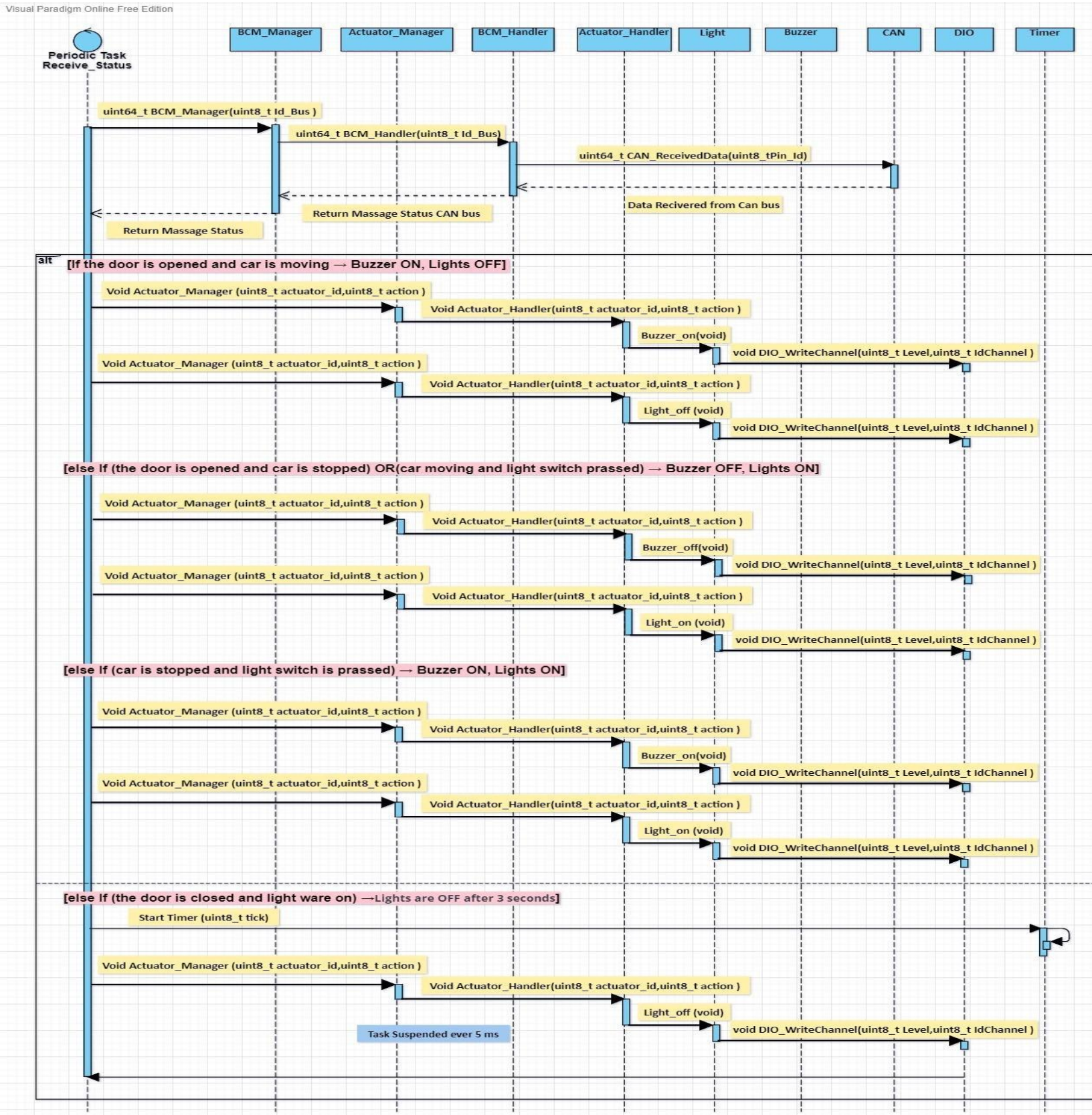




2- state machine diagram for the ECU_2 operations:



3- sequence diagram for the ECU 2 :



4- Calculate CPU load for the ECU 2:

The system contains one task assuming the worst case scenario that the execution time of task is 1 ms.

Name Task	Periodicity	Execution Time
Periodic Task Receive Status	**5 ms**	**1 ms**

H (Hyper Period) = LCM(Pi) = 5 ms
CPU Load = $\sum$ E / H = (1*1) /5 * 100 = 20%

Calculate bus load in your system:

Notes: With what percentage of system bus was busy per 1 second

CAN Bus Load in System: time the CAN bus loaded with data
1 CAN frame contains approximately 125 bits.
assume we are using a 500 Kbit/s bit rate.
bit time = 1 / bit rate = 1 / (500 * 1000) s = 2 µs
Approximate time to transfer 1 frame = (2 µs/bit * 125 bit) = 250 µs.
We have multiple sending intervals on the bus:
1 frame every 5 ms 200 frames every 1000 ms
1 frame every 10 ms 100 frames every 1000 ms
1 frame every 20 ms 50 frames every 1000 ms
This is in total = 350 frames every 1000 ms
Total time on bus = (total number of frames) * (time of 1 frame)
Total time on bus = 350 * 250 =87500 µs
Bus load = {((87500 µs *1000)\ 1000)* 100 %} = 8.75 %