# Learning Discriminative Representations to Interpret Image Recognition Models Thèse de Doctorat

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- Opti-CAM: Optimizing saliency maps for interpretability
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- A learning paradigm for interpretable gradients
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Low Stakes

My go to exercise is running, but...

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#### My go to exercise is running, but...

I think my running shoes are getting worn



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I want a replacement, but I know about machines, not shoes!



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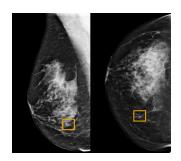
Nike Free RN Distance 2



How could my phone identify that model?

Raising the stakes

Raising the stakes



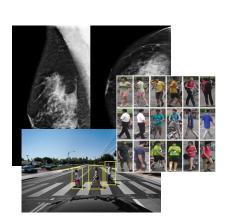
Raising the stakes



Raising the stakes

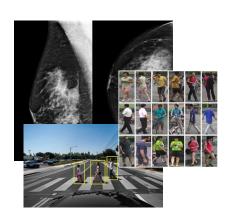


# Motivation Straight to the point



• How do we know how a system works? Introduction Background Opti-CAM CA-Stream Gradient References

# Motivation Straight to the point



- How do we know how a system works?
- How do we know how safe a system is?

Straight to the point



- How do we know how a system works?
- How do we know how safe a system is?
- If a system fails, who is accountable?

We must **understand** the behaviour of these models.

### Step by step

Computation,
Computer
Vision and Al

→ Explainable AI

Thesis objectives

troduction Background Opti-CAM CA-Stream Gradient References

### Computation, Computer Vision and AI

#### Computation



Alan Turing forefather of current computer science.

Better known as *Computer Science*.

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### Computation, Computer Vision and AI

#### Computation



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#### Study of:

- Algorithms.
- Data structures.
- Design of hardware and software.

Computer Vision

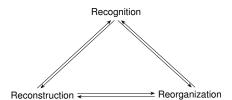
Replication of human vision capabilities.

Computer Vision

Replication of human vision capabilities.

Three fundamental tasks[1]:

- Recognition.
- Reconstruction.
- Reorganization.



Artificial Intelligence

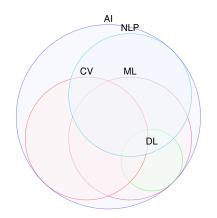
Systems capable of performing tasks requiring human intelligence [2].

Artificial Intelligence

Systems capable of performing tasks requiring human intelligence [2].

#### Subfields:

- Machine Learning (ML) & Deep Learning (DL).
- Computer Vision(CV).
- Natural Language Processing (NLP).
- Robotics.



### Explainable Al

We are interested in understanding models, behaving like a black box model:



### Explainable Al

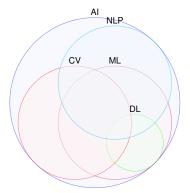
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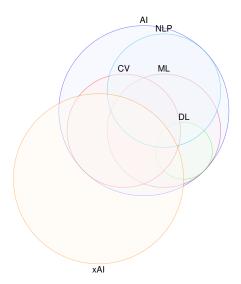
We want to *know why*  $f(x) \rightarrow y$ 



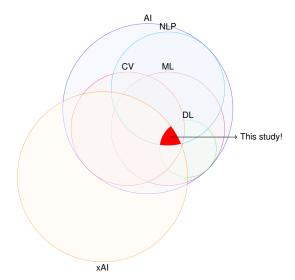
### Fitting it all together



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### Fitting it all together



Improvement of recognition and interpratable properties of model predictions.

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#### In particular:

 Development of low cost/complexity explainability approaches.

# Improvement of recognition and interpratable properties of model predictions.

#### In particular:

- Development of low cost/complexity explainability approaches.
- Establishment of a fixed evaluation protocol.

## Improvement of recognition and interpratable properties of model predictions.

#### In particular:

- Development of low cost/complexity explainability approaches.
- Establishment of a fixed evaluation protocol.
- Differenciation of human based and machine explanations.

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### Background

To familiarize with this work, we split it into three points:

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#### **Preliminaries**

- Approaching Vision.
- David Marr's approach.
- CV currently.
- Desiredata of Interpretability Study.

#### **Image Recognition Models**

- Traditional Models.
- Convolutional Neural Networks (CNN).
- Hybrid Architectures.

#### Interpretability

- Transparency.
- Post-Hoc Interpretability.
  - Class Activation Methods.
- Evaluating Interpretability.

### Preliminaries

Approaching Vision

#### David Marr's approach



# Addressing vision on three levels:

- Algorithmic.
- Implementation.
- Computational.
  - Three fundamental tasks. [1]

#### David Marr's approach



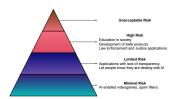
# Addressing vision on three levels:

- Algorithmic.
- Implementation.
- Computational.
  - Three fundamental tasks. [1]

Computer Vision focuses on the last level.

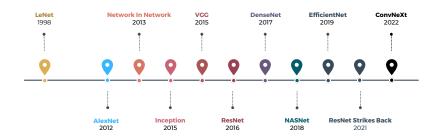
**CV** Currently

#### Desiredata of Interpretability Study



Classic Models

#### Convolutional Neural Networks



Self Attention Architectures

Hybrid Architectures

Transparency

Post-Hoc Interpretability

Class Activation Methods

Evaluating Interpretability

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#### References I



J. Malik, P. Arbeláez, J. Carreira, K. Fragkiadaki, R. Girshick, G. Gkioxari, S. Gupta, B. Hariharan, A. Kar, and S. Tulsiani, "The three r's of computer vision: Recognition, reconstruction and reorganization," *Pattern Recognition Letters*, vol. 72, pp. 4–14, 2016.



J. McCarthy et al., "What is artificial intelligence," 2007.