

# A SKETCHY NOTE OF PDE

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III. FOURIER ANALYSIS AND PDE BAHOURI etc.

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# Ch 1. Sobolev Spaces

## Sec 1.1 Weak derivatives and Sobolev Spaces.

Weak derivative (Uniqueness)



Sobolev Spaces    Sobolev norm    Banach space

[Def 1.1.1] (Weak-derivative) Suppose  $u, v \in L^1_{loc}(U)$  and  $\alpha = (\alpha_1, \dots, \alpha_d)$ .

We say  $v$  is the  $\alpha$ -th weak derivative of  $u$  if

$$\int_U u \partial^\alpha \varphi = (-1)^{|\alpha|} \int_U v \varphi, \quad \forall \varphi \in C_c^\infty(U).$$

and denote it by  $v = \partial^\alpha u$ .

If the  $\alpha$ -th partial weak derivative of  $u$  exists, it's "unique".

[prop 1.1.2] (Uniqueness of weak derivatives) An  $\alpha$ -th weak partial derivative of  $u$ , if exists, is uniquely defined up to a set of measure zero.

The result clearly depends on the lemma below.

[lem 1.1.3] If  $w \in L^1_{loc}(U)$  satisfies  $\int_U w \varphi = 0$  for  $\forall \varphi \in C_c^\infty(U)$ , then  $w=0$  a.e. in  $U$ .

[Rmk 1.1.4] The lemma should be well-known and it clearly says that  $C_c^\infty$  functions are large enough to be test functions. Note that we always consider standard bump functions when it comes to  $C_c^\infty$  functions.

[Def 1.1.5] (Sobolev Spaces of integer dimensions)  $k \in \mathbb{N}$ ,  $p \in [1, \infty]$

$$W^{k,p}(U) := \left\{ f \in L^p(U) : \sum_{|\alpha| \leq k} \| \partial^\alpha f \|_{L^p(U)} < \infty \right\}$$

The  $\partial^\alpha f$  here should refer to the  $\alpha$ -th weak partial derivative of  $f$ .

When  $p=2$ , we denote  $H^k(U) := W^{k,2}(U)$ .

[Def 1.1.6] (norm of  $W^{k,p}$ )  $\|f\|_{W^{k,p}(U)} := \sum_{|\alpha| \leq k} \|\partial^\alpha f\|_{L^p(U)}$  for  $1 \leq p \leq \infty$

[Def 1.1.7] (Convergence) Let  $\{f_m\}, f$  belong to  $W^{k,p}(U)$ . We say  $f_m \rightarrow f$  in  $W^{k,p}(U)$

if  $\|f_m - f\|_{W^{k,p}(U)} \rightarrow 0$  as  $m \rightarrow \infty$ . We say  $f_m \rightarrow f$  in  $W_{loc}^{k,p}(U)$

if  $\|f_m - f\|_{W^{k,p}(U)} \rightarrow 0$  as  $m \rightarrow \infty$  for  $\forall V \subset \subset U$ .

[Def 1.1.8] (Closure) We denote by  $W_0^{k,p}(U)$  the closure of  $C_c^\infty(U)$  in

$W^{k,p}(U)$ . Thus,  $f \in W_0^{k,p}(U)$  iff there exist functions  $f_m \in C_c^\infty(U)$

s.t.  $f_m \rightarrow f$  in  $W^{k,p}(U)$ .

[Rmk 1.1.9] Sobolev spaces equipped with  $W^{k,p}$  norm are Banach spaces.

$f \in W_0^{k,p}(U) \iff f \in W^{k,p}(U) \text{ & } \partial^\alpha f = 0 \text{ on } U \text{ for } |\alpha| \leq k-1$ .

The completeness is not hard to verify:

$\|u_m - u_n\|_{W^{k,p}(U)} \rightarrow 0$  as  $m, n \rightarrow \infty$ ,  $\{u_k\} \subseteq W^{k,p}(U)$

$\Rightarrow \partial^\alpha u_m \rightarrow "u_\alpha"$  in  $\underline{L^p(U)}$

Claim:  $\partial^\alpha u = u_\alpha$

$$\begin{aligned} \int_U u \partial^\alpha \varphi &\stackrel{\text{DCT}}{=} \lim_m \int_U u_m \partial^\alpha \varphi = \lim_m \int_U \partial^\alpha u_m \varphi \\ &\stackrel{\text{DCT}}{=} (-1)^\alpha \int_U u_\alpha \varphi. \end{aligned}$$

□

The second remark is hard to verify right now.

Sec 1.2 Smooth approximation and basic calculus of Sobolev functions.

Local  $\xrightarrow[\text{bounded}]{\text{Pou}}$  Global without boundary  $\xrightarrow[\text{bounded}]{\text{shift}}$  Global with boundary

{ Chain rule  
composition  
Integral by parts.

Now we fix  $k \in \mathbb{N}$ ,  $1 \leq p \leq \infty$  and an open set  $U \subseteq \mathbb{R}^d$ .

For each  $\varepsilon > 0$ , we define  $U_\varepsilon = \{x \in U : \text{dist}(x, \partial U) \geq \varepsilon\} \subseteq U$

Thm 1.2.1 (local) Assume that  $f \in W^{k,p}(U)$  for some  $1 \leq p < \infty$ ,

and set  $f_\varepsilon = \gamma_\varepsilon * f$  in  $U_\varepsilon$ . Then  $f_\varepsilon \in C^\infty(U_\varepsilon)$  for each  $\varepsilon > 0$   
and  $f_\varepsilon \rightarrow f$  in  $W_{loc}^{k,p}(U)$  as  $\varepsilon \rightarrow 0$ .

(1)  $\gamma_\varepsilon$  is the standard mollifier. Bump functions.

$\Rightarrow f_\varepsilon \in C^\infty(U_\varepsilon)$  well-defined

(2)  $\partial^\alpha f_\varepsilon = \partial^\alpha f * \gamma_\varepsilon$ :

$$\begin{aligned} \partial^\alpha f_\varepsilon(x) &= \partial_x^\alpha \int_U \gamma_\varepsilon(x-y) f(y) dy \stackrel{\text{DCT}}{=} \int_U \partial_x^\alpha \gamma_\varepsilon(x-y) f(y) dy \\ &\stackrel{(1)}{=} \int_U \partial_y^\alpha \gamma_\varepsilon(x-y) f(y) dy = \int_U \gamma_\varepsilon(x-y) \partial_y^\alpha f(y) dy \\ &= \int_U \gamma_\varepsilon(x-y) \frac{\partial}{\partial y} f(y) dy = \gamma_\varepsilon * \partial^\alpha f(x). \end{aligned}$$

(3)  $\forall V \subset\subset U$ ,  $\partial^\alpha f_\varepsilon \xrightarrow{L^p} \partial^\alpha f$

□

Thm 1.2.2 (Global without boundary) Assume  $U$  is bounded and  $f \in W^{k,p}(U)$   
for some  $1 \leq p < \infty$ . Then there exist a sequence of functions  $f_m \in C^\infty(U) \cap$   
 $W^{k,p}(U)$  s.t.  $f_m \rightarrow f$  in  $W^{k,p}(U)$

$$U_i := \left\{ x \in U : \text{dist}(x, \partial U) > \frac{1}{i} \right\} \quad \left( \begin{array}{c} i=1 \\ i=2 \\ i=3 \\ \vdots \\ i=n \\ \text{...} \\ \partial U \end{array} \right)$$

$$\begin{aligned} &\xrightarrow{\text{refinement}} V_i = U_{i+1} \setminus \bar{U}_i \\ &V_0 \subset\subset U \\ &\Rightarrow U = \bigcup_{i=0}^{\infty} V_i \quad (\text{locally finite}) \\ &\text{p.s. } \sum_{i=0}^{\infty} \gamma_i \leq 1 \quad \gamma_i \in C_c^\infty(V_i) \\ &\left| \sum_{i=0}^{\infty} \gamma_i \right| = 1 \end{aligned}$$

$$f^i := \gamma_{\varepsilon_i} * (y_i f) \quad \text{supp } f^i \subset V_i = U_{i+1} \setminus \bar{U}_i \quad \varepsilon_i \text{ sufficiently small} \\ \text{s.t. } \|f^i - y_i f\|_{W^{k,p}(U)} \leq \frac{8}{\varepsilon_i}$$

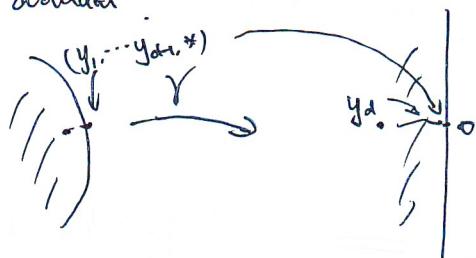
$$F := \sum_{i=0}^{\infty} f^i \quad \Rightarrow \|F - f\|_{W^{k,p}(U)} \leq \sum_i \|f^i - y_i f\|_{W^{k,p}(U)} < 28$$

↑ locally finite summation

$$\Rightarrow \|F - f\|_{W^{k,p}(U)} < 28 \rightarrow 0$$

Def 1.2.3 (Boundary Condition) We say the boundary  $\partial U$  is Lipschitz continuous if for each  $x \in \partial U$ , there exists  $r > 0$  and a Lipschitz continuous mapping  $\gamma: \mathbb{R}^{d-1} \rightarrow \mathbb{R}$  s.t.  $U \cap B(x, r) = \{y : y_d > \gamma(y_1, \dots, y_{d-1})\} \cap B(x, r)$

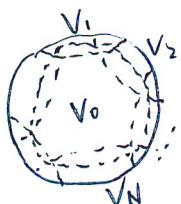
Rmk 1.2.4 The boundary itself is a manifold of  $d-1$  dim. We use  $\gamma$  to transform it into a hyperplane in Euclidean Space and then the value of this map should denote refer to the height the point in the original domain.



This interpretation may not be correct.

Thm 1.2.5 (Global with boundary) Let  $U \subseteq \mathbb{R}^d$  be a bounded open set with a Lipschitz boundary  $\partial U$ . Suppose  $f \in W^{k,p}(U)$  for some  $1 \leq p < \infty$ . Then there exists functions  $f_m \in C^\infty(\bar{U})$  s.t.  $f_m \rightarrow f$  in  $W^{k,p}(U)$ .

It suffices to construct a smooth approximation in each open cover of  $\partial U$ .



$$x^\varepsilon = x + \lambda \varepsilon e_d \quad \lambda \text{ is sufficiently large. } (\lambda \gg l_p(N))$$

$\varepsilon$  small

$$f^\varepsilon(x) := f(x^\varepsilon), F^\varepsilon = f^\varepsilon * \eta_\varepsilon$$

After this shift,  $F$  is smooth in  $\bar{V}$

If we have shown  $F^\varepsilon \rightarrow f$  in  $W^{k,p}(\bar{V})$

$$\Rightarrow \|f_i - f\|_{W^{k,p}(\bar{V}_i)} < \delta \quad f_i \in C^\infty(\bar{V}_i) \quad \begin{matrix} \text{Sub coordinate to} \\ \bar{U} \end{matrix}$$

$$U \subseteq \bigcup_{i=0}^N V_i \quad \|f_i - f\|_{W^{k,p}(V_i)} < \delta \quad F := \sum_{i=0}^N \varphi_i f_i$$

$$\begin{aligned} \Rightarrow \|\partial^d f - \partial^d F\|_{L^p(U)} &\leq \sum_{i=0}^N \|\partial^d (\varphi_i f) - \partial^d (\varphi_i f_i)\|_{L^p(V_i)} \\ &\leq \sum_{i=0}^N \|\varphi_i f - \varphi_i f_i\|_{W^{k,p}(V_i)} < (N+1)\delta \end{aligned}$$

Why do we have  $F^\varepsilon \rightarrow f$  in  $W^{1,p}(V)$ ?

$$\|F^\varepsilon - f\|_{L^p(V)} \leq \|F^\varepsilon - f^\varepsilon\|_{L^p(V)} + \|f^\varepsilon - f\|_{L^p(V)} \xrightarrow{\substack{\text{mollification} \\ \text{translation}}} 0$$

$$\|F^\varepsilon - f^\varepsilon\|_{L^p(V)} = \left\| \|\eta_\varepsilon\|_{L^1_x(B(0,1))} [f(x + \lambda\varepsilon e_i) - f(x + \lambda\varepsilon e_i - \varepsilon e_i)] \right\|_{L^p_x(V)} \xrightarrow{\substack{\text{Minkowski} \\ \text{DCT}}} 0 \quad \square$$

[prop 1.2.6] (Calculus) Assume  $1 \leq p < \infty$

(1) If  $f, g \in W^{1,p}(U) \cap L^\infty(U)$ , then  $fg \in W^{1,p}(U) \cap L^\infty(U)$  and  $\partial_i(fg)$

$= \partial_i f \cdot g + f \partial_i g$  holds a.e. in  $U$  for  $i=1, \dots, d$

(2) If  $f \in W^{1,p}(U)$  and  $F \in C^1(\mathbb{R})$ ,  $F' \in L^\infty(\mathbb{R})$ ,  $F(0) = 0$ , then  $F(f) \in W^{1,p}(U)$  and  $\partial_i(F(f)) = F'(f) \partial_i f$  a.e. in  $U$  for  $i=1, \dots, d$ .

Moreover, if  $U$  has finite Lebesgue measure in  $\mathbb{R}^d$ , then  $F(0) = 0$  is unnecessary.

(3) If  $f \in W^{1,p}(U)$ , then  $f^+, f^-$ ,  $|f| \in W^{1,p}(U)$  and

$$\partial_i f^+ = \begin{cases} \partial_i f & \text{a.e. on } \{f > 0\} \\ 0 & \text{a.e. on } \{f \leq 0\} \end{cases}$$

$$\partial_i f^- = \begin{cases} -\partial_i f & \text{a.e. on } \{f < 0\} \\ 0 & \text{a.e. on } \{f \geq 0\} \end{cases}$$

$$\partial_i |f| = \begin{cases} \partial_i f & \text{a.e. on } \{f > 0\} \\ 0 & \text{a.e. on } \{f = 0\} \\ -\partial_i f & \text{a.e. on } \{f < 0\}. \end{cases}$$

$$\psi \in C_c^\infty(U) : \text{supp } \psi \subseteq V \subset \subset U \quad f_\varepsilon := f * \eta_\varepsilon \quad g_\varepsilon := g * \eta_\varepsilon$$

$$(1) \int fg \, d\psi \xrightarrow[\varepsilon \rightarrow 0]{\text{DCT}} \lim_{\varepsilon \rightarrow 0} \int f_\varepsilon g_\varepsilon \, d\psi \quad \dots$$

$$\left| \int (fg - f_\varepsilon g_\varepsilon) \, d\psi \right| \leq \int |f(g - g_\varepsilon)| \, d\psi + \int |g_\varepsilon(f - f_\varepsilon)| \, d\psi$$

$$\leq \|f\|_{L^\infty} \cdot \|g - g_\varepsilon\|_{L^p} \|\partial_i \psi\|_{L^p} + \dots \xrightarrow{\varepsilon \rightarrow 0} 0$$

(2) See Sol (1, 2, 3)

$$(3) \text{ Let } F_\varepsilon(f) = \begin{cases} \sqrt{r^2 + \varepsilon^2} - \varepsilon & r \geq 0 \\ 0 & r < 0 \end{cases} \quad r \geq 0 \Rightarrow F_\varepsilon(f) \xrightarrow[\text{a.e.}]{\text{DCT}} f^+ \text{ as } \varepsilon \rightarrow 0$$

$$\begin{aligned} \int_U f^+ \varphi \, d\mu &\stackrel{\text{DCT}}{=} \lim_{\varepsilon \rightarrow 0} \int_U F_\varepsilon(f) \varphi \, d\mu = \lim_{\varepsilon \rightarrow 0} \int_U F'_\varepsilon(f) \cdot \varphi \, d\mu \\ &= \lim_{\varepsilon \rightarrow 0} \int_{U \cap \{f \geq 0\}} F'_\varepsilon(f) \varphi \, d\mu \stackrel{W^{1,p}}{\underset{\text{DCT}}{=}} \int_U f \varphi \, d\mu \\ \Rightarrow \varphi f^+ &= \begin{cases} \varphi f & f > 0 \\ 0 & f \leq 0 \end{cases} \quad \square \end{aligned}$$

### Sec 1.3 Trace and extension

Thm 1.3.1 (Trace theorem) Let  $U \subseteq \mathbb{R}^d$  be a bounded open set and  $\partial U$  be Lipschitz continuous. Then :

i) There exists a bounded linear operator  $\text{Tr}: W^{1,p}(U) \rightarrow L^p(\partial U; ds)$  s.t.

$\text{Tr } f = f$  on  $\partial U$  for all  $f \in W^{1,p}(U) \cap C(\bar{U})$  and

$$\|\text{Tr } f\|_{L^p(\partial U)} \leq C \|f\|_{W^{1,p}(U)}$$

$\Leftrightarrow$  for each  $f \in W^{1,p}(U)$  with the constant  $C > 0$  depending only on  $\phi, U$ . Here  $ds = H^{d-1}|_{\partial U}$ .

ii) (Integration by parts) For any  $\phi \in C^1(\mathbb{R}^d \rightarrow \mathbb{R}^d)$  and  $f \in W^{1,p}(U)$ ,

there holds

$$\int_U f \operatorname{div} \phi \, dx = - \int_U \nabla f \cdot \phi \, dx + \int_{\partial U} (\phi \cdot N) \text{Tr } f \, ds$$

where  $N$  denotes the unit outer normal vector to  $\partial U$ .

Rmk 1.3.2  $\text{Tr } f$  almost provides the boundary value of  $f$  on  $\partial U$  and

it actually satisfies that

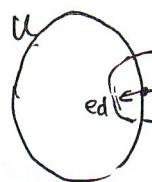
$$\lim_{r \rightarrow 0} \int_{U \cap B(x, r)} |f(y) - \text{Tr } f| \, dy = 0 \quad \text{a.e. } x \in \partial U$$

Rmk Here the conclusion relates to the Rademacher's thm which guarantees the outer normal to  $\partial U$  exists  $H^{d-1}\text{-a.e.}$  and the Divergence thm in weak sense.

Since we have Bounded linear transform theorem (BLT thm), so our idea is ~~obviously~~ clear.

$U$  is bounded, so we can assume  $f \in C^1(\bar{U})$  and  $p=1$ . first.

1.  $f=0$  on  $U \setminus B$  ( $f$  is localized near  $\partial U$ )



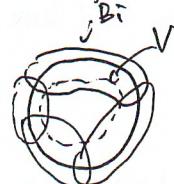
$$-ed \cdot N = \cos \angle(ed, N) = \frac{1}{\sqrt{1 + \tan^2 \angle(ed, N)}} \geq \frac{1}{\sqrt{1 + (\text{Lip } f)^2}} \quad (*)$$

since  $|f|$  is not differentiable everywhere, consider  $\beta_\varepsilon(x) = \frac{1}{\sqrt{x^2 + \varepsilon^2}} - \varepsilon$

so that we have  $\beta_\varepsilon(f) \rightarrow |f|$  a.e.

$$\begin{aligned} \int_{\partial U} \beta_\varepsilon(f) dS_x &\stackrel{(*)}{=} C \int_{\partial U \cap B} \beta_\varepsilon(f) (-ed \cdot N) dS_x \stackrel{\text{d}N}{=} C \int_{U \cap B} \partial_{x_d} (\beta_\varepsilon(f)) dx \\ &\leq C \int_{U \cap B} |\beta'_\varepsilon(f)| |\nabla f| dx \leq C \int_U |\nabla f| dx \end{aligned}$$

2.  $f \neq 0$  on  $U \setminus B$



$$\begin{aligned} \int_{\partial U} \beta_\varepsilon(f) dS_x &\leq C \sum_{i=1}^N \int_{\partial U \cap B_i} \beta_\varepsilon(f) (-ed \cdot N) dS_x \\ &= -C \sum_{i=1}^N \left( \int_{\partial U \cap B_i} \beta'_\varepsilon(f) \partial_{x_d} f dx + \int_{U \cap B_i} (\partial_{x_d} \beta'_\varepsilon(f)) f dx \right) \\ &\leq C \left( \int_U |\beta'_\varepsilon(f)| |\nabla f| dx + \int_U |\beta'_\varepsilon(f)| dx \right) \\ &\stackrel{\text{DCT}}{\rightarrow} C \|f\|_{W^{1,p}(U)} \quad \text{as } \varepsilon \rightarrow 0. \end{aligned}$$

$$\frac{1}{p} - \frac{1}{p'} = 1$$

3. General index  $p$ .

$$\begin{aligned} \int_{\partial U} |f|^p dS_x &\stackrel{\text{def}}{=} C \int_U \underbrace{(|\nabla f| \cdot |f|^{p-1} + |f|^p)}_{\text{Young}} dx \\ &= \frac{|f|^p}{p} + \frac{|f|}{p'} \\ &\leq C \|f\|_{W^{1,p}(U)} \end{aligned}$$



$$\Rightarrow \|f\|_{L^p(\partial U)} \leq C \|f\|_{W^{1,p}(U)} \quad \text{for } f \in C^1(\bar{U})$$

For function  $f \in C^1(\bar{U})$ , we have  $\nabla \cdot (f\phi) = \nabla f \cdot \phi + f \nabla \phi$

$$\begin{aligned} \int_U \nabla \cdot (f\phi) dx &= \int_{\partial U} f\phi n dS_x = \int_{\partial U} \nabla f \cdot \phi n dS_x \\ &= \int_U \nabla f \cdot \phi + \int_U f \nabla \phi \end{aligned}$$

$$\Rightarrow \int_U f \nabla \phi dx = - \int_U \nabla f \cdot \phi dx + \int_{\partial U} f \nabla \phi \cdot n dS_x$$

f. It remains to show the result for  $f \in W^{1,p}(U)$ .

For a given  $f \in W^{1,p}(U)$ , there exists a sequence of smooth functions  $\{f_m\}_{m \in \mathbb{N}}$

s.t.  $f_m \rightarrow f$  in  $W^{1,p}(U)$ , and then we have

$$\|\operatorname{tr} f_m - \operatorname{tr} f\|_{L^p(\partial U)} \leq C_{p,U} \|f_m - f\|_{W^{1,p}(U)}$$

And thus we can define  $\operatorname{tr} f := \lim \operatorname{tr} f_m$  and it's not hard to prove that the limit doesn't depend the choice of  $\{f_m\}$  since we have  $f_m \rightarrow f$  in  $W^{1,p}(U)$  and  $\|\operatorname{tr} f_m\|_{L^p(\partial U)} \leq C_{p,U} \|f\|_{W^{1,p}(U)}$ .

Since  $W^{1,p}(U) \cap C^1(\bar{U}) \stackrel{\text{dense}}{\hookrightarrow} W^{1,p}(U)$ , by BLT theorem (Sobolev), we have defined a bounded linear operator from  $W^{1,p}(U)$  to  $L^p(\partial U)$ .

And the integration by parts formula holds still for  $W^{1,p}(U)$  by Global Smooth approximation.  $\square$

The following several theorems are of rather technique difficulties and here I omit the proof but state the conclusions.

**Thm 1.3.3** (trace-zero) Assume  $U \subseteq \mathbb{R}^d$  is a bounded open set and  $\partial U$  is Lipschitz continuous and  $f \in W^{1,p}(U)$ . Then  $f \in W_0^{1,p}(U)$  if and only if  $\operatorname{tr} f = 0$  on  $\partial U$ .

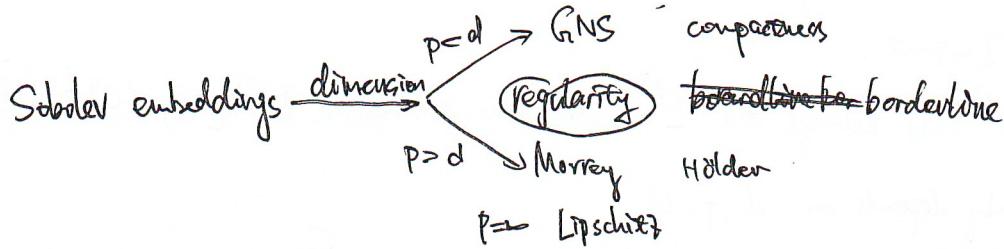
**Thm 1.3.4** (Sobolev extension) Let  $1 \leq p \leq \infty$  and  $U \subseteq \mathbb{R}^d$  be bounded open set with  $\partial U \in C^k$ . Assume  $G \subseteq \mathbb{R}^d$  is open set with  $U \subset \subset G$ . Then there exists a constant  $C > 0$  depending on  $d, k, n, G$  and a bounded linear ~~operator~~ mapping  $E: W^{k,p}(U) \rightarrow W^{k,p}(\mathbb{R}^d)$  s.t. for any  $f \in W^{k,p}(U)$ , it holds

(1)  $Ef = f$  a.e. in  $U$ ;

(2)  $\operatorname{supp} Ef \subset \subset G$ ;

(3)  $\|Ef\|_{W^{k,p}(\mathbb{R}^d)} \leq C \|f\|_{W^{k,p}(U)}$ .

## Sec 1.4 Sobolev embeddings



For scaling invariance, we define Sobolev ~~integr~~ conjugate index

$$p^* = \frac{dp}{d-p} \quad \text{for } 1 \leq p < d \quad \frac{1}{p^*} = \frac{1}{p} - \frac{1}{d} \leq \frac{1}{p}.$$

Thm 1.4.1 (GNS-inequality) Assume  $1 \leq p < d$ , there exists a constant  $C > 0$

only depending on  $p, d$  s.t.

$$\|f\|_{L^{p^*}(\mathbb{R}^d)} \leq C \|\nabla f\|_{L^p(\mathbb{R}^d)} \quad \forall f \in W^{1,p}(\mathbb{R}^d)$$

1. Assume  $f \in C_c^1(\mathbb{R}^d) \Rightarrow |f(x)| \leq \int_{\mathbb{R}} |\nabla f(x_1, \dots, t_i, \dots, x_d)| dt_i$

$$|f(x)|^{\frac{d}{d-1}} = (|f(x)|^d)^{\frac{1}{d-1}} \leq \prod_{i=1}^d \int_{\mathbb{R}} |\nabla f(x_1, \dots, t_i, \dots)| dt_i$$

using Hölder  $d$ -times  $\Rightarrow \left( \int_{\mathbb{R}^d} |f(x)|^{p^*} \right) \leq \left( \int_{\mathbb{R}^d} |\nabla f|^p dx \right)^{\frac{d}{d-1}}$

$$\Rightarrow \|f\|_{L^{p^*}(\mathbb{R}^d)} \leq \|\nabla f\|_{L^p(\mathbb{R}^d)}$$

2.  $1 < p < d \quad g = |f|^r \quad r \geq 1$

$$\Rightarrow \left( \int_{\mathbb{R}^d} |f|^{\frac{rd}{d-1}} \right)^{\frac{d-1}{d}} \leq \int_{\mathbb{R}^d} |f|^{r-1} |\nabla f| dx$$

$$\leq r \left( \int_{\mathbb{R}^d} |f|^{(r-1)p'} \right)^{\frac{1}{p'}} \left( \int_{\mathbb{R}^d} |x \cdot \nabla f|^p \right)^{\frac{1}{p}}$$

Let  $\frac{rd}{d-1} = (r-1)\frac{p}{p-1} \Rightarrow r = \frac{p(d-1)}{d-p} \Rightarrow \frac{r}{d-1} = \frac{p}{p-1} = p^*$

$$\Rightarrow \|f\|_{L^{p^*}(\mathbb{R}^d)} \leq \frac{p(d-1)}{d-p} \|f\|_{L^p(\mathbb{R}^d)} \quad \text{for } f \in \underline{C_c^1(\mathbb{R}^d)}$$

$$\Rightarrow \text{hold for } f \in W^{1,p}(\mathbb{R}^d)$$

□

Thm 1.4.2 (Sobolev embedding) Let  $U \subseteq \mathbb{R}^d$  be a bounded open set with Lipschitz boundary and  $1 \leq p < d$ .

- (1) Any  $f \in W^{1,p}(U)$  belongs to  $L^{p^*}$  with the estimation  $\|f\|_{L^{p^*}(U)} \leq C \|f\|_{W^{1,p}(U)}$  where  $C$  only depends on  $d, p, U$ .
- (2) Any  $f \in W_0^{1,p}(U)$  satisfies the estimation  $\|f\|_{L^q} \leq C \|\nabla f\|_{L^p(U)}$ , for all  $q \in [1, p^*]$  where the constant  $C$  depends on  $d, p, U$ .

Note that we shall avoid zero extension directly since it may break the weak derivative on the boundary.

(1) Since  $\partial U$  Lipschitz, we can extend  $f$  to  $Ef$  s.t.

$$\text{supp } Ef \subset \overset{\text{is compact}}{\cancel{V}} \Rightarrow \|Ef\|_{W^{1,p}(\mathbb{R}^d)} \leq C \|f\|_{W^{1,p}(U)}$$


$Ef$  has compact support  $\Rightarrow u_m \xrightarrow{\substack{\text{in} \\ C_c}} Ef$  in  $W^{1,p}(\mathbb{R}^d)$

$$\Rightarrow \|u_m - Ef\|_{L^{p^*}(\mathbb{R}^d)} = C \|u_m - Ef\|_{L^p(\mathbb{R}^d)} \rightarrow 0$$

$\Rightarrow u_m \rightarrow Ef$  in  $L^{p^*}(\mathbb{R}^d)$

$$\|u_m\|_{L^{p^*}(\mathbb{R}^d)} \leq C \|\nabla u_m\|_{L^p(\mathbb{R}^d)} \Rightarrow \|\nabla Ef\|_{L^p(\mathbb{R}^d)}$$

$$\Rightarrow Ef \in L^{p^*}(\mathbb{R}^d) \quad \|Ef\|_{L^{p^*}(\mathbb{R}^d)} \leq C \|\nabla Ef\|_{L^p(\mathbb{R}^d)} \leq C \|Ef\|_{W^{1,p}(U)}$$

$$\|f\|_{L^{p^*}(U)}.$$

(2) We can use zero extension since  $\operatorname{tr} f = 0$ . Note  $L^p(U) < \infty$ .  $\square$

In the book, there exists a estimation in  $L^p$  sense for  $W_0^{1,p}(U)$  functions, but here the index  $p$  is arbitrary so we do not have a direct proof by the embedding theorem.

By Banach-Alaoglu theorem, boundedness only implies the weak\* convergence (Weak convergence in reflexive space), but we need strong convergence.

(Def 1.4.3) (Compact embedding) Let  $X, Y$  be two Banach spaces satisfying  $X \subseteq Y$ .

We say  $X$  is compactly embedded in  $Y$ , denoted by  $X \hookrightarrow Y$ , if

(1)  $\|f\|_Y \leq C\|f\|_X$  for some constant  $C > 0$ ;

(2) Each bounded sequence in  $X$  is precompact, i.e. any bounded sequence has a convergent subsequence.

(Thm 1.4.4) (Rellich-Kondrachov) Let  $U \subseteq \mathbb{R}^d$  be a bounded open set with a Lipschitz boundary  $\partial U$ . Suppose  $1 \leq p < d$ . Then  $W^{1,p}(U) \hookrightarrow L^q(U)$  for all  $1 \leq q < p^*$ .

Embedding  $\checkmark$  by GNS +  $L^d(U) \hookrightarrow$ .

compactness : Assume  $f_m$  is uniformly bounded in  $W^{1,p}(U)$ .

$$\sup \|f_m\|_{W^{1,p}(U)} = M. \quad \text{[Idea: A-A thm]}$$

equicontinuity  $\Leftarrow$  gradient estimation

1. mollification:  $U \subset V$  extension  $\Rightarrow \begin{cases} f_m \in W^{1,p}(\mathbb{R}^d) \\ \text{supp } f_m \subset \subset V \text{ bounded} \\ \sup_m \|f_m\|_{W^{1,p}(\mathbb{R}^d)} < \infty. \end{cases}$

$$f_m^\varepsilon := f_m * \eta_\varepsilon \stackrel{\text{Claim}}{\Rightarrow} \|f_m^\varepsilon - f_m\|_{L^q(V)} \rightarrow 0 \text{ in } m \text{ as } \varepsilon \rightarrow 0.$$

$$\text{proof of Claim: } |f_m^\varepsilon - f_m| \leq \int_{B(0,\varepsilon)} |\eta_\varepsilon(y)| (f(x+y) - f(x)) dy$$

$$\text{If } f_m \in C^1 \quad = \int_{B(0,\varepsilon)} \eta_\varepsilon(y) \left| \int_0^1 \frac{d}{dt} f(x+ty) dt \right| dy$$

$$\|f_m^\varepsilon - f_m\|_{L^q(V)} \leq \int_0^1 \int_{B(0,\varepsilon)} |\eta_\varepsilon(y)| \|f(x+ty)\|_{L^q(V)} dy dt$$

$$\text{may refer to evans} \quad \leq \varepsilon \|Df\|_{L^1(V)} \leq \varepsilon \|Df\|_{L^1(V)} \|Df\|_{L^p(V)} \leq CM\varepsilon.$$

The estimation holds for  $W^{1,p}(V)$

$$\begin{aligned} \|f_m^\varepsilon - f_m\|_{L^2(V)} &\stackrel{\text{Holder}}{\leq} \|f_m^\varepsilon - f_m\|_{L^1(V)}^0 \|f_m^\varepsilon - f_m\|_{L^{p^*}(V)}^{1-0} \\ &\leq (CM\varepsilon)^0 \left( \|f_m^\varepsilon\|_{L^{p^*}(V)} + \|f_m\|_{L^{p^*}(V)} \right)^{1-0} = C'\varepsilon^0 \end{aligned}$$

2. Uniform bounded in  $M$

$$|f_m^\varepsilon| \stackrel{\text{def}}{=} C\varepsilon^{-d} \|f_m\|_{L^1(V)} \leq C\varepsilon^{-d} \|f_m\|_{L^q(V)} \stackrel{\text{Uniform}}{<}.$$

3. equicontinuity  $\Leftarrow$  gradient

$$|\nabla f_m^\varepsilon| \leq \|\nabla \eta_\varepsilon\|_{L^\infty(V)} \cdot \|f_m\|_{L^1(V)} \leq C\varepsilon^{-1-d} < \infty.$$

$$\xrightarrow{A-A} f_m^\varepsilon \xrightarrow{L^\infty} *$$

$$\left( \limsup_{K,l} \|f_{m_k}^\varepsilon - f_{m_l}^\varepsilon\|_{L^q(V)} \right) \leq \left( \limsup_{K,l} \|f_{m_k}^\varepsilon - f_{m_l}^\varepsilon\|_{L^{\infty}(V)} \right) \|1\|_{L^q(V)} = 0.$$

f. pull back to strong convergence

$$\|f_{m_k} - f_{m_l}\|_{L^q(V)} = \|f_{m_k} - f_{m_l}^\varepsilon\|_{L^q(V)} + \|f_{m_l}^\varepsilon - f_{m_l}^\varepsilon\|_{L^q(V)} + \|f_{m_k}^\varepsilon - f_{m_l}^\varepsilon\|_{L^q(V)} \stackrel{\delta_\varepsilon}{<} \underbrace{\text{uniform in } \varepsilon}_{\text{uniform in } \varepsilon}$$

$$\lim_{K,l} \|f_{m_k} - f_{m_l}\|_{L^q(V)} \leq C(\varepsilon) \rightarrow 0 \quad \text{as } \varepsilon \rightarrow 0.$$

Well, ~~here~~ have I made a mistake since the choice of the subsequence depends on  $\varepsilon$ . Hence we shall use diagonal argument.

~~Let  $\delta_n = \frac{1}{n}$ , we have  $\|f_{m_k} - f_{m_l}^\varepsilon\| \leq \delta_n$  when  $\varepsilon < \varepsilon_n$~~

~~With  $\{f_{m_k}^\varepsilon\} \subseteq \{f_{m_k}\}$~~

~~$\forall \varepsilon < \varepsilon_n \quad \lim_{K,l} \|f_{m_k}^\varepsilon - f_{m_l}^\varepsilon\| = 0 \Rightarrow f_{m_k}^\varepsilon -$~~

~~$\text{Let } \delta_n = \frac{1}{n}, \exists \varepsilon_n, \forall \varepsilon < \varepsilon_n, \lim_{K,l} \|f_{m_k}^\varepsilon - f_{m_l}^\varepsilon\|_{L^q(V)} = 0$~~

~~$\Rightarrow \lim_{K,l} \|f_{m_{k,n}} - f_{m_{l,n}}\|_{L^q(V)} = \frac{1}{n}$~~

~~$\text{Let } g_k = f_{m_{k,n}} \Rightarrow \lim_{K,l} \|g_k - g_l\|_{L^q(V)} \rightarrow 0$~~

□

Punkt 1,4,5 The boundedness assumption is important here.

In Evans's book, he treat an inequality for  $W_0^{1,p}(U)$  as Poincaré inequality by Sobolev embedding's corollary. I do not agree with it.

Thm 1.4.6 (Poincaré inequality for zero trace) Assume  $U$  is a bounded open set with Lipschitz  $\partial U$ . Then we have the estimate

$$\|f\|_{L^p(U)} \leq C \|\nabla f\|_{L^p(U)} \quad \text{for } 1 \leq p \leq \infty, f \in W_0^{1,p}(U)$$

where  $C$  depends on  $p, d, U$ .

If  $d \leq p < \infty$ , we can choose an index  $q$  s.t.

$q^* > p$ . Then by GNS inequality, we have

$$\|f\|_{L^p} \approx \|f\|_{L^{q^*}(U)} \leq \|\nabla f\|_{L^q(U)} \approx \|\nabla f\|_{L^p(U)}$$

here we can take  $q$  relating to  $p$  so the constant still only depends on  $p, U, d$ .

For the case  $p = \infty$ , we can extend  $f$  to zero outside  $U$ .

Then we can assume do have a Lipschitz function  $f$ .

by Morrey embedding which is stated in later section.

And the proof is direct.  $\square$

Thm 1.4.7 (Poincaré inequality) Let  $(f)_u$  denote  $\frac{1}{\int_U f} \int_U f$  if  $\int_U f \neq 0$ .

Let  $U$  be a bounded connected open set with Lipschitz  $\partial U$ . Assume  $1 \leq p \leq \infty$ .

Then there exists a constant  $C > 0$  depending only on  $d, p, U$  s.t.

$$\|f - (f)_u\|_{L^p(U)} \leq C \|\nabla f\|_{L^p(U)} \quad \forall f \in W^{1,p}(U).$$

prove by contradiction.

$$\exists \{f_k\} \text{ s.t. } \|f_k - (f_k)_u\|_{L^p(U)} \geq k \|\nabla f_k\|_{L^p(U)}$$

Renormalization:  $g_k = \frac{f_k - (f_k)_u}{\|f_k - (f_k)_u\|_{L^p(U)}}$

$$\begin{cases} (g_k)_u = 0 \\ \|g_k\|_{L^p(U)} = 1 \end{cases}$$

$$\|\nabla g_k\|_{L^p(U)} < \frac{1}{k}.$$

$$\begin{cases} (g)_u = 0 \\ \|g\|_{L^p(U)} = 1 \\ \|\nabla g\|_{L^p(U)} = 0 \end{cases}$$

By compact embedding (not only  $1 \leq p < d$  but for  $p \in [1, \infty]$ )

Now we're going to deal with the case  $p > d$ . Let  $f^*(x) := \lim_{n \rightarrow \infty} (f(x))_{\text{a.e.}}$ .

Thm 1.4.8 (Morrey's Inequality) Assume  $d < p < \infty$ . Define  $\alpha := 1 - \frac{d}{p}$ . There exists a constant  $C > 0$  depending on  $d, p, \alpha$  s.t.

$$\|f\|_{C^{0,\alpha}(\mathbb{R}^d)} \leq C \|f\|_{W^{1,p}(\mathbb{R}^d)}, \forall f \in C_c^1(\mathbb{R}^d)$$

Remembering:  $\|u\|_{C^{0,\alpha}(\bar{U})} := \sup_{\bar{U}} |u(x)| + \sup_{\bar{U}} \frac{|u(x)-u(y)|}{|x-y|^\alpha} = \|u\|_{C(\bar{U})} + [u]_{C^{0,\alpha}(\bar{U})}$

$$\|u\|_{C^{k,\alpha}(\bar{U})} := \sum_{|\alpha|=k} (\|u\|_{C(\bar{U})} + \sum_{|\alpha|=k} [\partial^\alpha u]_{C^{0,\alpha}(\bar{U})})$$

$C^{k,\alpha}(\bar{U})$  equipped with  $\|\cdot\|_{C^{k,\alpha}(\bar{U})}$  is a Banach space.

For fixed  $x, y$ , let  $r := |x-y|$ .  $W = B(x, r) \cap B(y, r)$

$$|f(x) - f(y)| = \int_W |f(x) - f(z)| dz \leq \int_W |f(x) - f(z)| dz + \int_W |f(z) - f(y)| dz$$

$$\int_W |f(x) - f(z)| dz = \int_0^{xt} \int_W |f(x) - f(x+tz)| dz dt$$

$$\leq C_d \frac{1}{L^d(B(x,r))} \int_{B(x,r)} |f(x) - f(z)| dz = \frac{C_d}{L^d(B(x,r))} \int_{B(x,r)} |f(x) - f(x+tw)| dz$$

$$= \frac{C_d}{L^d(B(x,r))} \int_0^r \int_{\partial B(0,t)} |f(x) - f(x+tw)| ds dt$$

$$= \frac{C_d}{L^d(B(x,r))} \int_0^r \int_{\partial B(0,t)} \left| \int_0^t \frac{ds}{|x-z|} f(x+ws) \right| ds dt$$

$$\leq \frac{C_d}{L^d(B(x,r))} \int_0^r \int_{\partial B(0,t)} \underbrace{\left| \int_0^t \frac{|\nabla f(x+ws)|}{s^{d-1}} ds \right|}_{\leq \frac{1}{s^{d-1}}} \underbrace{dt}_{\int_0^r t^{d-1} dt}$$

$$= \frac{C_d}{L^d(B(x,r))} \int_0^r \int_{B(x,r)} \frac{|\nabla f(z)|}{|x-z|^{d-1}} dz dt$$

$$= \frac{C_d r^d}{d L^d(B(x,r))} \int_{B(x,r)} \frac{|\nabla f(z)|}{|x-z|^{d-1}} dz$$

$$\leq C_d \|\nabla f\|_{L^p(B(x,r))} \cdot \||x-z|^{-1}\|_{L^{p'}(B(x,r))}$$

$$\leq C_d r^{1-\frac{d}{p}} \|\nabla f\|_{L^p(B(x,r))}, \Rightarrow d = 1 - \frac{d}{p} \quad \text{finite} \Leftrightarrow (d-1)(p'-1) < 1 \Leftrightarrow p > d. \checkmark$$

$$|f(x)| \leq \underbrace{\int_{B(x,r)} |f(z)|}_{\|f\|_{L^1(B(x,r))}} + \underbrace{\int_{B(x,r)} |f(x) - f(z)| dz}_{\text{gradient}}$$

(Thm 1.4.9) (Morrey's embedding thm) Let  $U \subseteq \mathbb{R}^d$  be a bounded open set with Lipschitz  $\partial U$ . Assume  $d < p < \infty$  and  $f \in W^{1,p}(U)$ . Then  $f$  coincide with its preare representative  $f^*(x) = \lim_{r \rightarrow 0} (f|_W)_{x,r}$  a.e. in  $U$ . And  $f^* \in C^{0,\alpha}(\bar{U})$  with index  $\alpha = 1 - \frac{1}{p}$ .

By Sobolev extension,  $f_m \xrightarrow[p]{\text{Sob}} f$  in  $W^{1,p}(\mathbb{R}^d)$

$$\text{Using Morrey's inequality } \|f_m\|_{C^{0,\alpha}(\mathbb{R}^d)} \leq C_\alpha \|f\|_{W^{1,p}(\mathbb{R}^d)}$$

$$\Rightarrow \|\bar{f}\|_{C^{0,\alpha}(\mathbb{R}^d)} \leq \|\bar{f}\|_{W^{1,p}(\mathbb{R}^d)} \quad (\bar{f}_m \text{ Cauchy in } C^{0,\alpha}(\mathbb{R}^d)).$$

Note that  $\bar{f} = f$  a.e. (subsequence).  
 $\Rightarrow f^*(x) \xrightarrow[\text{LDT}]{\text{a.e.}} \bar{f} = f$ .

□

Now, we turn to the case  $p = \infty$ .

Thm 1.4.10 (Lipschitz &  $W^{1,\infty}$ ) Let  $U \subseteq \mathbb{R}^d$  be an open set  $f: U \rightarrow \mathbb{R}$  be given. Then  $f$  is locally Lipschitz in  $U$  iff  $f \in W^{1,\infty}_{loc}(U)$ .

Note that "Locally Lipschitz" denotes  $f$  is Lipschitz with restriction to any compact subsets.

⇒ This part is easy.

$$\forall x \in V, D_i^h(f)(x) := \frac{f(x+h) - f(x)}{h}. \text{ Note that } |D_i^h(f)(x)| \leq \text{Lip}(f|_W) < \infty$$

~~Subsequence  $h_j \rightarrow 0$  s.t.  $D_i^{-h_j}(f)(x) \rightarrow v_i$~~

By Banach-Alaoglu theorem,  $D_i^{-h_j}(f) \rightarrow v_i$  weakly in  $L^p_{loc}(W)$  for  $1 < p < \infty$ .

It suffices to show  $v_i \in L^\infty_{loc}(W)$ . Let  $L = \text{Lip}(f|_W)$ .  $A = \{v_i \geq L + \epsilon\}$

$$\int_A D_i^{-h_j}(f) dx = \int_W D_i^{-h_j}(f) \cdot \chi_A dx \xrightarrow{\text{weak}} \int_A v_i dx \geq (L + \epsilon) \int_A^d(A)$$

$$\begin{aligned} L \cdot \int_A^d(A) &\Rightarrow \int_A^d(A) = 0 \Rightarrow v_i \leq L \text{ a.e. similarly, we can prove } v_i \geq -L \\ &\Rightarrow v_i \in L^\infty_{loc}(W) \text{ for all } W \subset \subset U \end{aligned}$$

Now it remains to show  $\psi_i$  is exactly the ~~the~~  $\partial_i$ -weak partial derivation.

$\forall \varphi \in C_c(V)$ ,

$$\int_U f(x) \frac{\varphi(x+h\epsilon_i) - \varphi(x)}{h} = - \int_U D_i^\epsilon(f)(x) \varphi(x)$$

$$h=h_j \rightarrow 0$$

$$\int_U f(x) d_i \varphi(x) = - \int_U \psi \varphi$$

$\Leftarrow f \in W_{loc}^{1,\infty}(U) \quad \text{dist}(W, \partial U), \text{dist}(V, \partial W) < \varepsilon_0$



$$f_\varepsilon := f * \eta_\varepsilon \quad \underline{\varepsilon \leq \varepsilon_0} \quad (f_\varepsilon \rightarrow f)$$

Claim: 1.  $f_\varepsilon \Rightarrow F$  in  $V$  as  $\varepsilon \rightarrow 0$

2.  $F$  Lipschitz in  $V$

3.  $F = f$  a.e. in  $\forall U \subset V$

$$\begin{aligned} |f_\varepsilon(x) - f_\varepsilon(y)| &= \left| \int_{B(0,1)} \eta(y) [f(x-\varepsilon y) - f(x-\varepsilon y)] dy \right| \\ &\leq \int_{B(0,1)} \eta(y) |f(x-\varepsilon y) - f(x-\varepsilon y)| dy \end{aligned}$$

$$f \in W^{1,\infty}(U) \subseteq W^{1,p}(W) \stackrel{1 < p < \infty}{\Rightarrow} f = f^* \in C^{\alpha}(W) \text{ a.e. in } W$$

$$\lim_{\varepsilon \rightarrow 0} |f_\varepsilon - f| \stackrel{\text{DCT}}{\rightarrow} 0$$

$\Rightarrow f_\varepsilon \Rightarrow F$  in  $V$ ,  $F \in C(V)$

$$|F(x) - F(y)| \leq \underbrace{|F(x) - f_\varepsilon(x)|}_{\text{S}} + \underbrace{|f_\varepsilon(x) - f_\varepsilon(y)|}_{\text{S}} + \underbrace{|f_\varepsilon(y) - F(y)|}_{\text{S}}$$

$$|f_\varepsilon(x) - f_\varepsilon(y)| = \left| \int_0^1 \tau^2 f(tx + (1-\tau)y) \cdot (x-y) d\tau \right| \stackrel{W^{1,\infty}(V)}{\leq} \|f\|_{L^\infty(U)} |x-y|.$$

$\Rightarrow F$  is Lipschitz in  $V$  so  $f$  is Lipschitz in  $V$ .  $\square$

For convenience, we only introduce a special case of general Sobolev inequality which implies  $H^k(\Omega) \subseteq L^\infty(\Omega)$  where  $\Omega$  is bounded and has Lipschitz boundary with the estimate

$$\|f\|_{L^\infty(\Omega)} \leq \|f\|_{H^k(\Omega)}$$

The proof will be revisited in the later ch.

## Ch 2. Linear Elliptic PDEs

### 1. Divergence form

$$Lu = -\partial_j(a^{ij}\partial_i u) + b^i(x)\partial_i u + c(x)u$$

### 2. Non-divergence form

$$Lu = -a^{ij}\partial_i \partial_j u + b^i \partial_i u + c(x)u$$

where  $a^{ij} = a^{ji}$

$L$  is (uniformly) elliptic if  $\exists$  a constant  $\Theta > 0$  s.t

$$a^{ij}\xi_i \xi_j \geq \Theta |\xi|^2$$

An extra condition in this ch is  
 $u=0$  on  $\partial\Omega$ .

#### 2.1 Weak solution $\in H^{-1}$

Def 2.1.1 (Weak solution)  $B[\cdot, \cdot]$  associated with the elliptic operator in the divergence form is

$$B[u, v] := \int_U a^{ij}\partial_i u \partial_j v + b^i \partial_i u v + c u v \quad \forall u, v \in H_0^1(U)$$

We say that  $u \in H_0^1(U)$  is a weak solution if

$$B[u, v] = (f, v)_{L^2(U)} \quad \text{for } \forall v \in H_0^1(U)$$

Def 2.1.2 ( $H^{-1}$ ) We define  $H^{-1}(U)$  to be the dual space of  $H_0^1(U)$ .

$$\|f\|_{H^{-1}(U)} := \sup \left\{ \langle f, u \rangle : u \in H_0^1(U), \|u\|_{H_0^1(U)} \leq 1 \right\}$$

Rmk 2.1.3  $H_0^1(U) \subseteq L^2(U) \subseteq H^{-1}(U)$

Thm 2.1.4 (Characterization of  $H^{-1}$ )  $f \in H^{-1}(U) \iff \exists f^\circ, \dots, f^\alpha \in L^2(U)$  s.t

$$\langle f, v \rangle = \int_U f^\circ v + f^i \partial_i v \, dx \quad \forall v \in H_0^1(U)$$

If the formula holds, we have  $f = f^0 - \sum \alpha_i f^i$

$$\|f\|_{H^{-1}(u)} = \inf \left\{ \beta \left( \sum_{i=0}^d \|f^i\|^2 \right)^{\frac{1}{2}} \right\}$$

$\Rightarrow (v, u)_{L^2(u)} = \langle v, u \rangle$  for  $v \in H_0^1(u)$  if we identify  $v \in L^2(u)$  as an element in  $H^{-1}(u)$ .

$$\begin{aligned} \text{Riesz: } & \Rightarrow \langle f, v \rangle = \int_u^H (u, v) \quad \forall v \in H_0^1 \\ & = \int_u^H uv + \nabla u \cdot \nabla v \end{aligned}$$

$$\Rightarrow f^0 = u \quad f^i = \partial_i u$$

$$\Rightarrow \langle f, v \rangle = \int_u^H f^0 v + f^i \partial_i v$$

$$\Rightarrow \int_u^H |f^i|^2 \leq \|f\|_{H^{-1}(u)} = \left( \int_u^H |f^i|^2 \right)^{\frac{1}{2}}$$

on the other hand, setting  $v = \frac{u}{\|u\|_{H_0^1}}$

## 2.2. Existence theorem I: Lax-Milgram theorem

Thm 2.2.1 (L-M) Bilinear map  $B: H \times H \rightarrow \mathbb{R}$  satisfies

- (1) Boundedness  $|B[u, v]| \leq \alpha \|u\| \|v\|$  for  $u, v \in H$  where  $H$  is
- (2) Coercivity  $|B[u, u]| \geq \beta \|u\|^2$

a Hilbert space. Let  $f: H \rightarrow \mathbb{R}$  be a bounded linear functional on  $H$ . Then there exists a unique  $u \in H$  s.t.  $B[u, v] = \langle f, v \rangle$  for  $v \in H$ .

$$\boxed{\begin{array}{l} \langle f, v \rangle = (w, v) \\ \|B[u, v]\| = (Au, v) \end{array} \quad \boxed{u = A^{-1}w}}$$

$$\text{I. } B[u, v] = (w, v) \quad (\text{by riez}) \quad \forall v \in H$$

$$\begin{cases} A: H \rightarrow H \\ u \mapsto w \end{cases} \quad \begin{cases} & (Au, v) \\ & \end{cases}$$

$$\text{II. } A \text{ is bounded linear trivial}$$

$$\|Au\|^2 = (Au, Au) = B(u, Au) \leq \alpha \|u\| \|Au\|$$

III. Inv & sur

$$\beta \|u\|^2 \leq |B[u, u]| = |(Au, u)| \leq \|Au\| \|u\| \Rightarrow \text{Inv}$$

$$\forall w \in R(A) \quad \begin{cases} \# \\ \# \\ \# \\ \# \\ \# \\ \# \end{cases} \quad \beta \|w\|^2 = |(Aw, w)| = 0 \Rightarrow \text{Sur}$$

IV. Existence  $\langle f, v \rangle = \underbrace{\langle w, v \rangle}_{\substack{H \\ B}} = \underbrace{(Au, v)}_{\substack{! \\ u=A^{-1}w}} = B[u, v]$

□

Uniqueness is implied.

Thm 2.2.2 (energy estimate) For the associated case Def 2.1.1, we have

$$|(B[u, v])| \leq \alpha \|u\|_{H_0^1(u)} \|v\|_{H_0^1(v)}$$

$$\text{or } \beta \|u\|_{H_0^1}^2 \leq B[u, u] + \gamma \|u\|_{L^2(u)}$$

$$\begin{aligned} \text{(1)} B[u, v] &= \int (\alpha^{ij} \partial_i u \partial_j v + b^i \partial_i u v + c u v) \\ &\leq \|\alpha^{ij}\|_{L^\infty(u)} \|\partial_i u\|_{L^2(u)} \|\partial_j v\|_{L^2(u)} + \|b^i\|_{L^\infty(u)} \|\partial_i u\|_{L^2(u)} \|v\|_{L^2(u)} \\ &\quad + \|c\|_{L^\infty(u)} \|u\|_{L^2(u)} \|v\|_{L^2(u)} \\ &\leq \# \|u\|_{H_0^1(u)} \|v\|_{H_0^1(u)} \end{aligned}$$

$$\begin{aligned} \text{(2)} B[u, u] &= \int \underbrace{\alpha^{ij} \partial_i u \partial_j u + b^i \partial_i u u + c u^2}_{\text{elliptic}} \\ &\geq \theta \|\nabla u\|_{L^2(u)}^2 + \|b^i\|_{L^\infty(u)} \|\partial_i u\|_{L^2(u)} \|u\|_{L^2(u)} + \|c\|_{L^\infty(u)} \|u\|_{L^2(u)}^2 \\ &\stackrel{\text{Young}}{\geq} \theta \|\nabla u\|_{L^2(u)}^2 - \underbrace{\varepsilon \|\nabla u\|_{L^2(u)}^2}_{\text{co}} - \left(\frac{C_1}{\varepsilon} + C_2\right) \|u\|_{L^2(u)}^2 \\ &= \beta \|u\|_{H_0^1(u)}^2 - \gamma \|u\|_{L^2(u)}^2. \end{aligned}$$

□

Then, for equation  $\begin{cases} Lu + cu = f \\ u=0 \end{cases} \quad u \text{ where } \underline{c \geq \gamma}$

There exists a unique weak solution.

## 2.3 Existence theorem II. Fredholm alternative

A linear bounded operator  $K: X \rightarrow Y$  is called compact operator if  $K$  maps bounded set to precompact set.  $K \in C(X, Y)$

Let  $X, Y, Z$  be Banach spaces, then

(1) If  $K \in C(X, Y)$  &  $x_n \rightarrow x$ , then  $Kx_n \rightarrow Kx$

(2)  $K_1: X \rightarrow Y, K_2: Y \rightarrow Z \Rightarrow K_2 \circ K_1 \in C(X, Z)$

(3)  $K \in C(X, Y) \Rightarrow K^* \in C(Y^*, X^*)$

Fredholm Alternative:  $X$  Banach,  $K \in C(X)^*$

(1)  $\dim N(I-K) < \infty$

(2)  $R(I-K)$  is closed

(3)  $R(I-K) = R N(I-K^*)^\perp \quad R(I-K^*)^\perp = N(I-K)^\perp$

(4)  $N(I-K) = \{0\} \Leftrightarrow R(I-K) = X$

(5)  $\dim N(I-K) = \dim N(I-K^*)$

$\sigma(A) = A$ 's spectrum

Riesz-Schauder  $X$  = Banach space  $K \in C(X)$

(1)  $0 \in \sigma(K)$  unless  $\dim X = \infty$

(2)  $\sigma(K) \setminus \{0\} = \sigma_p(K) \setminus \{0\}$

(3) The accumulation point of  $\sigma_p(K)$ , if exists, must be  $\{0\}$ .

$$L = -a^{ij} \partial_j u + b^i \partial_i u + cu + f \in C^1(\bar{\Omega})$$

$$L^*v = -\partial_i(a^{ij}\partial_j v) - b^i \partial_i v + (c - \partial_i b^i)v$$

[Thm 2.3.1] (Second existence theorem)

(1) For any  $f \in L^2(\Omega)$ , divergence form elliptic equations

$$\begin{cases} Lu = f & \text{in } \Omega \\ u = 0 & \text{on } \partial\Omega \end{cases}$$

admits a unique weak solution  $u \in H_0^1(\Omega)$

(2) The homogeneous equation  $\begin{cases} Lu = 0 \\ u = 0 \text{ on } \partial\Omega \end{cases}$  admits non-zero solution  $u \in H_0^1(\Omega)$

Furthermore, if should hold, the solution space  $N$  is finite dimensional subspace of  $H_0^1(\Omega)$  &  $\dim N = \dim N^*$  where  $N^*$  denotes the solution space of  $\begin{cases} L^*v = 0 \\ v = 0 \text{ on } \partial\Omega \end{cases}$

Finally,  $(*)$  has a weak solution  $\Leftrightarrow (f, v) = 0 \quad \forall v \in N^*$

$$\begin{aligned} \text{I. } Lu = f &\Rightarrow L_\gamma u = \gamma u + f \text{ solvable} \\ &\Rightarrow u = L_\gamma^{-1}(ru + f) \Rightarrow (I - rL_\gamma^{-1})u = L_\gamma^{-1}f \\ &\Rightarrow k = rL_\gamma^{-1} \quad h = L_\gamma^{-1}f \\ &\Rightarrow (I - k)u = h \end{aligned}$$

II. Verify  $K$  is a compact operator on  $\underline{\underline{L^2(U)}}$

We know  $B_{\gamma^{-1}}[g, \varphi] = (g, \varphi)$  holds for each  $g \in L^2(U) \otimes \varphi \in H_0^1(U)$

$$\Rightarrow \beta \|v\|_{H_0^1(U)}^2 \leq |B_{\gamma^{-1}}(v, v)| = \|(g, v)_{L^2(U)}\| \leq \|g\|_{L^2(U)} \|v\|_{H_0^1(U)}$$

$$\Rightarrow \|Kg\|_{H_0^1(U)} \lesssim \|g\|_{L^2(U)}$$

$$\Rightarrow K: L^2(U) \rightarrow H_0^1(U) \quad (\hookrightarrow L^2(U)) \Rightarrow K \text{ is compact.}$$

III. Fredholm Alternative  $X = L^2(U)$

Case I.  $N(I - K) = \{0\}$   $\Rightarrow$  unique solution for  $v \in L^2(U)$

Case II.  $N(I - K) \neq \{0\}$   $\Rightarrow \gamma \neq 0$

homogeneous equation  $u - Ku = 0$  has non-zero solutions in  $L^2(U)$ .

$$\dim N(I - K) = \dim N(I - K^*)$$

IV. Verify the further argument (existence of solutions  $\Leftrightarrow (f, v) = 0$ )

The adjoint equation of  $Lu = 0$  ( $\Leftrightarrow (I - k)u = 0$ )  $\beta$

$$L^*v = 0 \quad (\Leftrightarrow (I - K^*)v = 0)$$

$v$  is a weak solution of  $(I - K^*)v = 0$

$$(h, v) = \gamma^{-1}(Kf, v) = \gamma^{-1}(f, K^*v) = \gamma^{-1}(f, v)$$

but we have known that  $(I - K)u = h$  has a solution  $\Leftrightarrow (h, v)_{L^2(U)} = 0$

$\Leftrightarrow (f, v) = 0$  where  $v \in \ker(I - K^*)$ .  $\square$

I was confused that we just prove  $u \in L^2(U)$ , how can we claim  $u \in H_0^1$  initially.

But I found that  $L_\gamma: H_0^1 \rightarrow H^1$  is an isomorphism

$$\Rightarrow L_\gamma^{-1}: H^1 \rightarrow H_0^1$$

$$u = \underbrace{ku}_{\in H_0^1} + \underbrace{h}_{\in H_0^1} \quad \text{Done!}$$

**Thm 2.3.2** There exists an at most countable set  $\Sigma \subseteq \mathbb{R}$  s.t the boundary-value problem  $\begin{cases} Lu = \lambda u + f & \text{in } U \\ u = 0 & \text{on } \partial U \end{cases}$  has a unique solution for  $\forall f \in L^2(U)$  weak

if & only if  $\lambda \notin \Sigma$ . Moreover, if  $\Sigma$  is an infinite set, then  $\Sigma = \{\lambda_k\}$ , then values of a non-decreasing sequence with  $\lambda_k \rightarrow \infty$ .

We call  $\Sigma$  the spectrum of the operator  $L$   
Note in particular that the boundary value problem

$$\begin{cases} Lu = \lambda u & \text{in } U \\ u = 0 & \text{on } \partial U \end{cases}$$

has a non-trivial solution  $u \neq 0$  if and only if  $\lambda \in \Sigma$ . in which case  $\lambda$  is called an eigenvalue of  $L$ ,  $u$  a corresponding eigenfunction.

WLOG, let  $\lambda > -r$ ,  $r > 0$ . By Fredholm theory,  $Lu = \lambda u + f$  admits a unique solution if & only if the homogeneous equation

$Lu = \lambda u$  has only zero solution.  
 $\Leftrightarrow u = \frac{r+\lambda}{r} \not\in Ku$  where  $k = r/r$  only has the solution  $u=0$ .

that is to say  $\frac{r}{r+\lambda}$  is not an eigenvalue of  $K$ .

Then we can use Riesz-Shauder thm. □

2.4 The eigenvalue problem of linear elliptic operators

$$\begin{cases} Lu = \lambda u & \text{in } U \\ u = 0 & \text{on } \partial U \end{cases}$$

where  $U$  is a bounded domain with smooth boundary.

Here we consider  $L = -\partial_j(a^{ij}\partial_i)$   $a^{ij} = a^{ji}$   $a^{ij} \in C^0(\bar{U})$

A preliminary acknowledgement which was not mentioned for most textbook is

Courant-Fisher minmax principle. It states that  $A \in \mathcal{E}(H)$  is symmetric and have eigenvalues  $\lambda_1^+ \geq \lambda_2^+ \geq \dots \geq 0 \geq \lambda_{-1}^- \geq \lambda_2^- \geq \lambda_1^-$ . Then

$$\lambda_n^+ = \inf_{E_{n+1}} \sup_{E_n} \frac{(Ax, x)}{\|x\|}, \quad \lambda_n^- = \sup_{E_{n+1}} \inf_{E_n} \frac{(Ax, x)}{\|x\|}$$

Its idea is kind of direct and proof depends on Rayleigh quotient.

Thm 2.4.1 (Eigenvalues of symmetric elliptic operators) Each eigenvalue of L is a real num.

Furthermore, if we repeat each eigenvalue according to its multiplicity. We have

$$\Sigma = \{ \lambda_k \} \text{ where } 0 \leq \lambda_1 \leq \dots \quad \lim_{k \rightarrow \infty} \lambda_k = +\infty.$$

Finally, there exists an orthonormal basis  $\{w_k\}$  of  $L^2(U)$ , where  $w_k \in H_0^1(U)$  in U.

$$\text{s.t. } Lw_k = \lambda_k w_k \quad w_k = 0 \text{ on } \partial U$$

By regularity theory,  $a^{ij} \in C^1(\bar{U})$  implies that  $w_k \in C^1(U)$   
and " $\partial U$  is smooth" implies  $w_k \in C^1(\bar{U})$ .

I. By Lax-Milgram theorem, L is invertible. Let  $S = L^{-1}: L^2(U)$

$\rightarrow H_0^1(U) \hookrightarrow L^2(U)$ . That is to say S is a compact operator.

II.  $u = Sf$ ,  $v = Sg$  where  $f, g \in L^2(U)$ .

$$(Sf, g)_{L^2(U)} = (u, g)_{L^2(U)} = B[v, u] \xrightarrow[\text{sym}]{} B[u, v] = (f, g)_{L^2(U)}$$

$\Rightarrow S$  is symmetric. Since  $B[u, v] = \int_U a^{ij} \frac{\partial u}{\partial x^i} \frac{\partial v}{\partial x^j} d\Omega$ ,  $B$  is strictly positive defined by Poincaré inequality  
 $(Sf, f) = B[u, u] \geq 0$  for  $\forall f \in L^2(U) \Rightarrow$  All the eigenvalues of S is positive real numbers.

$$\text{III. } Sw = \gamma w \text{ for some } w \in H_0^1(U) \Rightarrow Lw = \lambda w \text{ where } \lambda = \gamma^{-1}$$

IV. Riesz-Schauder.

Thm 2.4.2 (Variation principle of principal eigenvalue)

Let  $\lambda_1 > 0$  be the principal eigenvalue of elliptic operator L with vanishing boundary condition where  $[u] = -\partial_j(a^{ij})\partial_i u$  with  $a^{ij} = a^{ji}$ .

$$(1) \text{ We have } \lambda_1 = \min \left\{ B[u, u] : \|u\|_{L^2(U)} = 1 \right\}$$

(2) The minimum is attained for a smooth function  $w_1$  that doesn't change sign within U. Also,  $\begin{cases} Lw_1 = \lambda_1 w_1 \text{ in } U \\ w_1 = 0 \text{ on } \partial U. \end{cases}$

(3) Finally, if  $u \in H_0^1(U)$  is any solution to  $\begin{cases} Lu = \lambda_1 u \text{ in } U \\ u = 0 \text{ on } \partial U \end{cases}$

the  $u$  is a multiple of  $w_1$ . This implies that  $\lambda_1$  must be simple.  
( $0 < \lambda_1 < \lambda_2 \leq \dots$ )

(1) the eigenfunctions  $\{w_k\}$  of  $L$  form an orthonormal basis of  $L^2(u)$

$$(\cdot, \cdot)_{H_0^1(u)} := B[\cdot, \cdot]$$

Consider  $\left\{ \frac{w_k}{\sqrt{\lambda_k}} \right\} \Rightarrow \left\{ \frac{w_k}{\sqrt{\lambda_k}} \right\}$  is orthogonal

Suppose  $u = \sum_k d_k w_k$   
 $H_0^1 \subseteq L^2$

$$B[w_k, u] = \sum_j d_j B[w_k, w_j] = \sum_k d_k \underbrace{\lambda_k}_{\neq 0} (w_k, w_k) \Rightarrow d_k = 0.$$

$$\Rightarrow u = \sum_k d_k \sqrt{\lambda_k} \frac{w_k}{\sqrt{\lambda_k}} \quad (\text{Here we assume } \sum d_k^2 = 1)$$

$$B[u, u] = \sum d_k^2 \lambda_k \geq \lambda_1 \sum d_k^2 = \lambda_1$$

The equality holds when  $u = w_1$ .

(2) Claim :  $B[u, u] = \lambda_1 \Leftrightarrow [u = \lambda_1 u]$  where  $\|u\|_{L^2(u)} = 1$

( $\Leftarrow$ ) trivial

$$(\Rightarrow) \quad u = \sum d_k w_k \quad \text{with } \sum d_k^2 = 1$$

$$\lambda_1 = B[u, u] = \sum \lambda_k d_k^2 \Rightarrow d_k = 0 \text{ if } \lambda_k > \lambda_1$$

$$\lambda_1 \sum d_k^2$$

The multiplicity of  $\lambda_1$  is finite (Fredholm)  $\checkmark$

$$\text{Now } [u = \lambda_1 u] \quad \alpha = P(u^+)^2 \quad \beta = P(u^-)^2 \Rightarrow u^+, u^- \in H_0^1(u)$$

$$\lambda_1 = B[u, u] = B[u^+, u^+] + B[u^-, u^-] \stackrel{H_0^1}{\geq} \lambda_1 \alpha + \lambda_1 \beta = \lambda_1$$

$\Rightarrow$  Since the equality holds,  $u^+, u^-$  are also eigenfunctions corresponding to

$$\lambda_1,$$

Using interior regularity,  $u^+, u^- \in C^\infty(u)$

Using Strong maximum principle  $\begin{cases} u^+ > 0 & \text{or} \\ u^- < 0 & \end{cases} \Rightarrow \begin{cases} u > 0 \\ u < 0 \end{cases} \Rightarrow u = 0$

(3)  $u, \tilde{u}$  are both nonzero weak solution to  $Lu = \lambda_1 u$ .

$$\Rightarrow \exists c \text{ s.t. } \underbrace{\int u - c \tilde{u}}_0 = 0 \quad \text{also eigenfunction} \Rightarrow u = c \tilde{u}$$

$\square$

Rank 2.4.3

$$\lambda_1 = \min_{\substack{u \in H_0^1(u) \\ \neq 0}} \frac{B[u, u]}{\|u\|_{L^2(u)}^2}$$

## 2.5 Elliptic regularity

$$\left\{ \begin{array}{l} f \in L^2(\Omega) \Rightarrow u \in H^2(\Omega) \\ f \in C(\bar{\Omega}) \not\Rightarrow u \in C^2(\bar{\Omega}) \\ \alpha \in (0,1) \quad f \in C^{0,\alpha}(\bar{\Omega}) \Rightarrow u \in C^{2,\alpha}(\bar{\Omega}) \end{array} \right. \quad \begin{array}{l} Lu = f \\ \int \end{array} \quad \text{sufficiently regular?}$$

$$D_i^h f(x) = \frac{f(x + e_i h) - f(x)}{h} \quad \text{where } x \in V \subset \Omega \quad 0 < h < \text{dist}(V, \partial\Omega)$$

and  $f$  is locally integrable.

(prop 2.5.1) (Difference Quotients & weak derivatives)

$$\text{i) } 1 \leq p < \infty \quad f \in W^{1,p}(\Omega), \quad V \subset \Omega$$

$$\|D^h f\|_{L^p(V)} \leq C \|\nabla f\|_{L^p(\Omega)} \quad \text{where } |e_i h| < \frac{1}{2} \text{dist}(V, \partial\Omega)$$

$$\text{ii) } 1 \leq p < \infty \quad f \in L^p(\Omega) \quad \left. \begin{array}{l} \\ \|D^h f\|_{L^p(V)} \leq c \end{array} \right\} \text{Condition}$$

Then In particular, if  $f \in W^{1,p}(\Omega) \Rightarrow \|\nabla f\|_{L^p(\Omega)} \leq C$ .

iii) WLOG, we can assume  $f$  is smooth enough.  $\Rightarrow p \in [1, \infty)$

$$|f(x + e_i h) - f(x)| \leq |h| \int_0^1 |\nabla f(x + t e_i h)| dt$$

$$\int_V |D^h f|^p dx \approx \sum_i \int_V \int_0^1 |\nabla f(x + t e_i h)|^p dt$$

$$\Rightarrow \frac{1}{h} \sum_i \int_0^1 |\nabla f(x + t e_i h)|^p dt \lesssim \|\nabla f\|_{L^p(\Omega)}^p.$$

$$\text{iv) } \int_V D_i^h u \varphi = - \int_V \varphi u \underbrace{D_i^{-h} \varphi}_{\text{if } f \in C_c^\infty(\Omega)}$$

$$\sup_h \|D_i^h u\|_{L^p(V)} \Leftrightarrow \xrightarrow{B-A} D_i^h u \rightarrow v \text{ in } L^p$$

$$\Rightarrow \limsup \int u \varphi = \liminf u D_i^h \varphi = \liminf D_i^{-h} u \varphi$$

$$= - \int_V \varphi$$

(Thm 2.5.2) (Interior regularity)  $a) \forall \varphi \in C_c^\infty(\Omega) \quad b) \exists c \in L^\infty(\Omega), \quad f \in L^2(\Omega)$

$u$  is a weak solution  $Lu = f$  in  $\Omega$ . Then  $u \in H^2_{loc}(\Omega)$  & for  $V \subset \subset \Omega$

$$\|u\|_{H^2(V)} = C (\|f\|_{L^2(\Omega)} + \|u\|_{L^2(\Omega)}) \quad C = C(V, \Omega, L).$$

We shall note that " $a^{ij}, b^i, c \in C^{m+1}(U)$ " + " $f \in H^m(U) \Rightarrow u \in H^{m+2}(U)$ "  
 by " $\|u\|_{H^{m+2}(V)} \leq c (\|f\|_{H^m(U)} + \|a^{ij}\|_{L^2(U)})$  with  $c = C(m, v, u, L)$ "  
 We can prove it by iteration and we shall believe its correctness.

proof of original theorem:

Since we already have the weak solution of the divergence form equation,  
 WLOG, we can treat  $-\partial_j(a^{ij} \operatorname{div} u) = f$  for convenience.

$$\Rightarrow \int_U \cancel{a^{ij} \partial_i u \partial_j v} = \int_U f v$$

$\left\{ \begin{array}{l} \text{weak derivative or difference quotient} \\ \text{localization} \end{array} \right.$

$D(v)$

$v \in C_c^{\infty}(U)$   
 truncate  $\begin{cases} \xi=1 & \text{in } V \\ \xi=0 & \text{in } \mathbb{R}^N \end{cases}$

A choice of  $v$  is from the classical book:  $v = D_k^{-h}(\xi^2 D_k^h u)$

$$\text{LHS} = - \int_U a^{ij} \partial_i u \partial_j (D_k^{-h} \xi^2 D_k^h u) \xrightarrow{\text{exchange}} - \int_U a^{ij} \partial_i u D_k^{-h} \partial_j (\xi^2 D_k^h u)$$

$$= \int_U D_k^{-h} (a^{ij}) \partial_i u \partial_j (\xi^2 D_k^h u)$$

$$\text{four terms} = \int_U \underbrace{D_k^{-h} (a^{ij}) \partial_i u \partial_j (\xi^2)}_{A_1} \cancel{\xi^2 (D_k^h u)} + \underbrace{a^{ij} D_k^{-h} \partial_i u \partial_j (\xi^2) D_k^h u}_{A_2}$$

$$+ \int_U \underbrace{a^{ij} D_k^{-h} (\partial_i u) \xi^2 \partial_j (D_k^h u)}_{A_3} + \underbrace{D_k^{-h} (a^{ij}) \partial_i u \xi^2 \partial_j (D_k^h u)}_{\text{otherwise } A_4}.$$

$$= A_1 + A_2$$

$$A_1 = \int_U a^{ij} D_k^{-h} (\partial_i u) \xi^2 \partial_j (D_k^h u) = \int_U a^{ij} \cancel{\partial_i (D_k^{-h} u)} D_k^{-h} (\partial_i u) D_k^h (\partial_j u) \xi^2$$

$$\stackrel{\text{Elliptic}}{\geq} 0 \int_U |D_k^{-h} (\partial_i u)|^2 \xi^2 \quad L^2 \text{ form of } D_k^{-h} (\partial_i u) \cdot \xi$$

$$(A_2) \approx \int_U |D_k^{-h} (a^{ij}) \partial_i u D_k^h u|^2 \xi^2 + |a^{ij} D_k^{-h} \partial_i u D_k^h u|^2 \xi^2 + |D_k^{-h} a^{ij} \partial_i u D_k^h u|^2 \xi^2$$

$$\begin{aligned} a^{ij} \in C^1(U) \\ \text{truncate} \end{aligned} \leq c \|a^{ij}\|_{C^1(U)} \int_U |D_k^{-h} (a^{ij}) \partial_i u D_k^h u|^2 \xi^2 + |D_k^{-h} (a^{ij}) \partial_i u D_k^h u|^2 \xi^2 + |D_k^{-h} a^{ij} \partial_i u D_k^h u|^2 \xi^2$$

$$+ \frac{c}{h} \|a^{ij}\|_{C^1(U)}^2 \left( \xi^2 |D_k^{-h} u|^2 + \sum_{i,j} |D_k^{-h} a^{ij}|^2 \right) + \frac{c}{h} \|D_k^{-h} u\|_{L^2(U)}^2 + \frac{c}{h} \|D_k^{-h} a^{ij}\|_{L^2(U)}^2$$

Using prop 2.5.1, we can obtain

$$|A_2| \leq \varepsilon \|D_K^h \nabla u\|_{L^2(U)}^2 + \frac{C}{\varepsilon} \|\nabla u\|_{L^2(U)}^2 \quad \text{Let } \varepsilon = \frac{\theta}{2}$$

$$\Rightarrow A = A_1 + A_2 \geq \frac{\theta}{2} \|D_K^h \nabla u\|_{L^2(U)}^2 - \frac{C}{\varepsilon} \|\nabla u\|_{L^2(U)}^2$$

$$B = \int_U f \underbrace{\gamma^2 D_K^h u}_{\nabla}$$

$$\begin{aligned} \|D_K^{-h}(\gamma^2 D_K^h u)\|_{L^2(U)}^2 &= \|\gamma(D_K^h u)\|_{L^2(U)}^2 = \|\nabla(\gamma^2 D_K^h u)\|_{L^2(U)}^2 + \|\gamma^2 \nabla D_K^h u\|_{L^2(U)}^2 \\ &= \|\nabla(\gamma^2 D_K^h u)\|_{L^2(U)}^2 + \|\gamma^2 D_K^h \nabla u\|_{L^2(U)}^2 \end{aligned}$$

$$\begin{aligned} B &\leq \varepsilon \left( \|\nabla(\gamma^2) D_K^h u\|_{L^2(U)}^2 + \|\gamma^2 D_K^h \nabla u\|_{L^2(U)}^2 \right) + \frac{C}{\varepsilon} \|f\|_{L^2(U)}^2 \\ &\leq \frac{\theta}{4} \|\gamma D_K^h \nabla u\|_{L^2(U)}^2 + C \left( \|f\|_{L^2(U)}^2 + \|\nabla u\|_{L^2(U)}^2 \right) \end{aligned}$$

$$\Rightarrow \frac{\theta}{4} \|\gamma D_K^h \nabla u\|_{L^2(U)}^2 \leq C \left( \|f\|_{L^2(U)}^2 + \|\nabla u\|_{L^2(U)}^2 \right)$$

$$\Rightarrow \cancel{\|\gamma D_K^h \nabla u\|_{L^2(U)}^2} \|u\|_{H^2(V)} \leq C (\|f\|_{L^2(U)} + \|u\|_{H^1(W)})$$

Since  $V \subset\subset W \subset\subset U$

$$\Rightarrow \text{refine: } \|u\|_{H^2(V)} \leq C (\|f\|_{L^2(U)} + \|u\|_{H^1(W)})$$

$$\text{likewise: } \|u\|_{H^1(W)} \leq C (\|f\|_{L^2(U)} + \|u\|_{L^2(U)})$$

$$\Rightarrow \|u\|_{H^2(V)} \leq C (\|f\|_{L^2(U)} + \|u\|_{L^2(U)}) \Rightarrow u \in H_{loc}^2(U) \quad \square$$

[Thm 2.5.3] (Boundary regularity) If bounded open  $\partial U$  is  $C^2$   
 $a_{ij} \in C^1(\bar{U})$ ,  $b_i, c \in L^\infty(U)$ ,  $f \in L^2(U)$ ,  $u \in H_0^1(U)$  is the weak solution

$$\text{to } \begin{cases} Lu = f & \text{in } U \\ u = 0 & \text{on } \partial U \end{cases} \Rightarrow u \in H^2(U) \text{ with } \|u\|_{H^2(U)} \leq C (\|f\|_{L^2(U)} + \|u\|_{L^2(U)})$$

$$C = C(U, L).$$

By intuition, we shall see

$$\begin{cases} \exists u \in C^{m+2} \\ a^j, b^j, c \in C^m(\bar{U}) \\ f \in H^m \end{cases} \Rightarrow u \in H^{m+2} \quad " \|u\|_{H^{m+2}} \leq C \left( \|f\|_{H^m(U)} + \|u\|_{L^2(U)} \right)$$

(Rmk 2.5.4) After proving regularity theorem,  $Lu = f$  ae holds not only for weak sense

Before longish proof, we shall see two basic calculus formula.

$$1. \quad \Phi: \Omega_x \longrightarrow \Omega_y \quad \psi(y) = \varphi(x)$$

$$x \mapsto y = \Phi(x)$$

$$\Rightarrow " \nabla_y \psi(y) = D(\Phi^{-1})(y)^T \nabla_x \varphi(x) "$$

$$\text{Since } \nabla_y \psi(y) = \left( \sum_j \frac{\partial \psi}{\partial x^j} \frac{\partial x^j}{\partial y^i} \right)_i = \left( \frac{\partial x^j}{\partial y^i} \right) \left( \frac{\partial \varphi}{\partial x^j} \right) = D(\Phi^{-1})(y)^T \nabla_x \varphi(x)$$

$$2. \quad F = \begin{pmatrix} F_1 \\ \vdots \\ F_m \end{pmatrix}, \forall \varphi \in C_c^\infty(\cdot) \quad |J(y)| = |\det D(\Phi^{-1})(y)|$$

$$\int_{\Omega_x} \nabla_x \cdot F(x) \varphi(x) dx = - \int_{\Omega_x} F(x) \cdot \nabla_x \varphi(x) dx$$

$$\xrightarrow{\text{to } \Psi} \int_{\Omega_y} (\nabla_x \cdot F)(\Phi^{-1}(y)) \Psi(\Phi^{-1}(y)) \frac{dy}{|J(y)|} = - \int_{\Omega_y} F(\Phi^{-1}(y)) \cdot (\nabla_x \varphi)(\Phi^{-1}(y)) \frac{dy}{|J(y)|}$$

$$\text{RHS} = - \int_{\Omega_y} F(\Phi^{-1}(y)) \cdot (\nabla_x \varphi)(\Phi^{-1}(y)) |J(y)| dy$$

$$= - \int_{\Omega_y} F(\Phi^{-1}(y)) \cdot [D(\Phi^{-1})(y)]^T \nabla_y \varphi(\Phi^{-1}(y)) |J(y)| dy$$

$$= - \int_{\Omega_y} \underbrace{\left( |J(y)| D(\Phi^{-1})(y) \right)^{-1} F(\Phi^{-1}(y))}_{G(y)} \nabla_y \varphi(\Phi^{-1}(y)) dy$$

Piola transform

$$\Rightarrow (\nabla_x \cdot F)(\Phi^{-1}(y)) = \frac{1}{|J(y)|} \nabla_y \cdot G(y)$$

$$\Rightarrow (\nabla_x \cdot F)(\Phi^{-1}(y)) = \frac{1}{|D(\Phi^{-1})(y)|} \nabla_y \cdot \underbrace{\left( \frac{1}{|J(y)|} D(\Phi^{-1})(y) \right)^{-1} F(\Phi^{-1}(y))}_{D(\Phi^{-1})}$$

Proof of [Thm 2.5.3]

The special case of " $\Delta$ " is quite easy.

We immediately obtain

$$\|\partial_i \partial_j u\|_{L^2(V)}^2 \leq C(\|\ell\|_{L^2(U)}^2 + \|u\|_{H^1(U)}^2) \text{ for } i, j < 2d.$$

for  $d=dd$ ; since  $L_n = f$  a.e.

$$\Rightarrow a_{\partial_i^2 u}^{dd} = \sum_{i+j \leq 2d} -\partial_j(a^i \partial_i u) + b \partial_i u + c u - f - \partial_d a^{\partial d} \partial_d u$$

Elliptic  $\Rightarrow a^{dd} \geq 0$

$$\Rightarrow \|\partial_d^2 u\|_{L^2(V)}^2 \leq C(\|\ell\|_{L^2(U)}^2 + \|u\|_{H^1(U)}^2)$$

Mimicing the previous proof we can get the wanted estimate.

But, How ~~do~~ we treat the general case?

In Evans's book, he showed longish calculation without motivation. Here I'm

going to explain it clearly.

$$\text{In } \Omega_x, \text{ we have } -\partial_j(a^i \partial_i u) = -\nabla_x \cdot (A(x) \nabla_x u(x))$$

$$\text{Using previous two formula, we have } -\nabla_y \cdot (\tilde{A}(y) \nabla_y \tilde{u}(y))$$

$$\text{where } \tilde{u}(y) = u(\Phi^{-1}(y)) \text{ and } \tilde{A}(y) = D\Phi(\Phi^{-1}(y)) A(\Phi^{-1}(y)) D\Phi(\Phi^{-1}(y))^T.$$

We shall always use the notation  $\sim$  to represent the pull up map.

$$\text{The formula of } \tilde{A}(y) \text{ implies the formula } \tilde{a}^{kl} = \sum a^{rs} \Phi_r^k \Phi_s^l$$

which agrees with Evans's book.

$$\text{likewise. } \tilde{b}^{jkl} u(x) = b(y) \nabla_x u(x) = b(y) D\Phi(\Phi^{-1}(y))^T \nabla_y \tilde{u}(y)$$

$$\Rightarrow \tilde{b}^{jk} = \sum b^r \Phi_r^k$$

Since  $|D\Phi| = 1 \Rightarrow \tilde{\Gamma}$  is still uniformly elliptic

Now, it's clear that  $\tilde{u}(y)$  is the weak solution of  $\tilde{\Gamma} \tilde{u} = \tilde{f}$

since the only thing we do is to change variable.  $\square$

## 2.6 Maximum principle

(non-divergence form with continuous coefficients)

Energy estimate  $\rightarrow$  Pointwise estimate: maximum principle

$$\nabla u(x_0) = 0 \quad \Delta^2 u \text{ is nonpositive definite}$$



Theorem 2.6.1 (Weak maximum principle)  $u \in C^1(\bar{\Omega}) \cap C(\bar{\Omega})$ ,  $c=0$  in  $\Omega$

1)  $\Delta u \leq 0$  in  $\Omega \Rightarrow \max_{\bar{\Omega}} u = \max_{\partial\Omega} u$   $u$  is called a subsolution

2)  $\Delta u \geq 0$  in  $\Omega \Rightarrow \min_{\bar{\Omega}} u = \min_{\partial\Omega} u$   $u$  is called a supersolution.

The most important trick in proving these principles, in my opinion,  
is the perturbation trick.

" $\Delta u \leq 0 \Rightarrow \Delta u^\varepsilon < 0 \Rightarrow u^\varepsilon$  satisfies the conclusion"

$\Rightarrow \varepsilon \rightarrow 0^+$ ,  $u$  does so.

$$\begin{aligned} L(\varepsilon e^{\lambda x_i}) &= \cancel{\varepsilon} \sum a^{ij} \varepsilon e^{\lambda x_i} (-a^{ii}\lambda_i^2 + b^i\lambda) < 0 \quad \text{for } \lambda \text{ sufficient large} \\ &\leq \varepsilon e^{\lambda x_i} (-\delta \lambda^2 + \|b\|_{L^2(\Omega)} \lambda) \end{aligned}$$

Now, it remains to show the case  $\Delta u < 0$ . We shall see that a  
non-divergence form elliptic operator is very similar to Laplacian. " $-\Delta$ ".

Suppose  $\Omega A \Omega^T = \Lambda = \text{diag}(\lambda_1, \dots, \lambda_d) \quad \lambda_i > 0$

$$y = x_0 + O(x - x_0)$$

$$\Rightarrow \partial_{x_i} u = \sum_k \partial_{y^k} u \frac{\partial y^k}{\partial x_i} = \sum_k \partial_{y^k} u \partial_{x_i}$$

$$\partial_{x_i} \partial_{x_j} u = \sum_{k,l} \partial_{x_i} \partial_{y^k} u \partial_{x_j}$$

$$\begin{aligned} \text{Then } -a^{ij} \partial_{x_i} u \partial_{x_j} u &= \sum_{i,j} -a^{ij} \sum_{k,l} \partial_{x_i} \partial_{y^k} u \partial_{x_j} \\ &= - \sum_{k,l} \left( \sum_{i,j} \partial_{x_i} a^{ij} \partial_{x_j} \right) \partial_{y^k} u = - \sum_{k,l} \delta_{kl} \lambda_k \partial_{y^k} u \end{aligned}$$

if it's an interior point,

$$= \sum_k -\lambda_k \partial_{y^k}^2 u$$

$$\downarrow L_u(x_0) = -a^{ij} \partial_{x_i} \partial_{x_j} u = \sum_k -\lambda_k^2 \partial_{y^k}^2 u < 0$$

contradiction!



From the previous proof, it's not hard to see the claim below.

Thm 2.6.2 (Weak maximum principle for  $C \geq 0$ ) The same conditions as the last claim except  $C \geq 0$  in  $U$ . We have

$$Lu \leq 0 \Rightarrow \max_{\bar{U}} u = \max_{\partial U} u^+$$

Now, we want to have a certain expression ~~at~~ when we can obtain the maximal value. We need a "geometric lemma" to state it precisely.

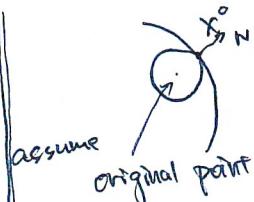
Lem 2.6.3 (Höpfer's lemma)  $u \in C^2(\bar{U}) \cap C(\bar{U})$ ,  $C \geq 0$  in  $U$ .

If

$$\begin{cases} \text{(1)} & Lu \leq 0 \\ \text{(2)} & \exists x_0 \in \partial U \text{ s.t. } u(x_0) > u(x) \text{ for all } x \in U \\ \text{(3)} & \text{"Interior ball condition" at } x_0, \exists B \subseteq U \text{ with } x_0 \in \partial B \end{cases}$$

$$\Rightarrow \frac{\partial u}{\partial N}(x_0) > 0 \quad \text{where } N \text{ is the outer normal unit vector to } \partial B \text{ at } x_0. \text{ If } C > 0, \text{ the same conclusion holds if } u(x_0) \geq 0$$

Our idea is that  $u(x_0) > u(x)$  implies we can make a perturbation and after the perturbation we still have  $\frac{\partial u}{\partial N} \geq 0$  which it's trivial, but  $\frac{\partial v}{\partial N} < 0$ .



And here our choice is  $u + \varepsilon v = u(x) + \varepsilon (e^{-\lambda|x|} - e^{-\lambda r^2})$

(To obtain  $Lu + \varepsilon Lv \leq 0$ , we may consider the annulus  $B(0, r) \setminus B(0, \frac{r}{2})$ )  $\square$

Thm 2.6.4 (Strong maximum principle)  $U \subseteq \mathbb{R}^d$  is a bounded domain,  $u \in C^2(\bar{U}) \cap C(\bar{U})$ ,  $C \geq 0$  in  $U$ . If  $Lu \leq 0$  +  $u$  attains its maximum over  $\bar{U}$  at  $x^* \in U$

$\Rightarrow u$  is a constant in  $U$ .

If  $C > 0$ ,  $Lu \leq 0$  &  $u$  attains its nonnegative maximum over  $\bar{U}$  at  $x^* \in U$

$\Rightarrow u$  is a constant in  $U$ .

$$Lu \leq 0, M = \max_{\bar{U}} u, C := \{x \in U \mid u(x) = M\}, V = \{x \in U \mid u(x) < M\}$$

$\neq \emptyset$   
open  
(not a constant)



set  $y \in V$ ,  $\text{dist}(y, c) < \text{dist}(y, \partial B)$

$B$  is the largest ball centered at  $y$  s.t.  $B \subseteq V$  &  $\exists x_0 \in \partial B \Rightarrow \frac{\partial u}{\partial N}(x_0) > 0$

$$(u(x_0) = M)$$

$\square$