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Session 4: Loop Tiling, MPI

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Discussion:

DGEMM Optimization







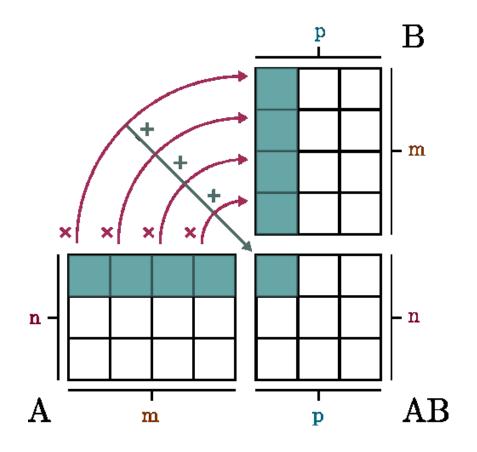


Recap: Matrix Product

$$(AB)_{ij} = \sum_{k=1}^{m} A_{ik} B_{kj}$$

Notation in summation convention:

$$(AB)_{ij} = A_{ik}B_{kj}$$





Matrix Product



Matrix Product - Naïve Implementation

```
for (index i = 0; i < n; i++) {
    for (index j = 0; j < p; j++) {
        double sum = 0.0;
        for (index k = 0; k < m; k++) {
            sum += A[i][k] * B[k][j];
        }
        C[i][j] = sum;
    }
}</pre>
```

How about loop unrolling?





Did you make yourselves familiar with blocking / tiling?

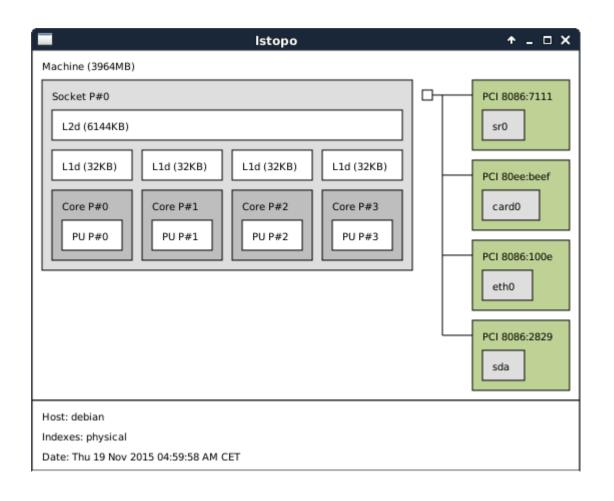
Principle idea:

Find out the CPU cache size.













Did you make yourselves familiar with blocking / tiling?

Principle idea:

- Find out the CPU cache size.
- Resolve maximum matrix extents $b \times b$ so sub-matrices in A, B, C fit into cache, i.e. solve:

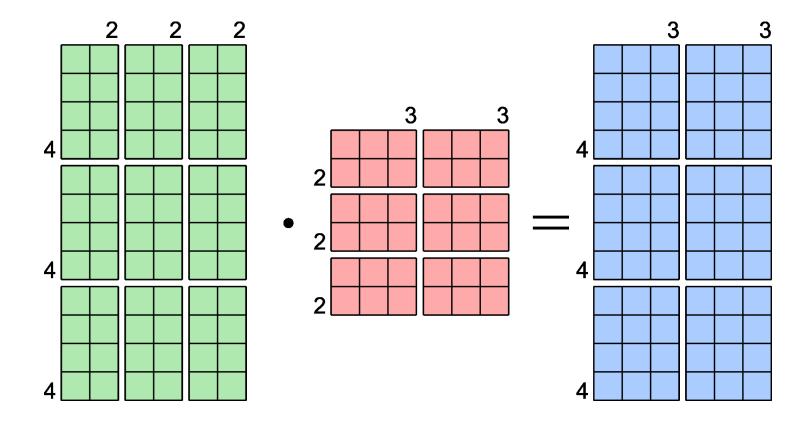
$$3(b^2) \cdot E = M$$
 for cache size M and element size E

 Partition nested for-loops into partial sub-matrix product solutions.





Block matrix multiplication:









```
// Outer loops: Iterate in b x b block steps
for (i0 = 0; i0 < n; i0 += b):
    for (j0 = 0; j0 < n; j0 += b):
        for (k0 = 0; k0 < n; k0 += b):
            // Inner loop: Matrix product of single block
            // -> 2b^3 operations on 3b^2 elements
            for (i = i0; i < min(i0+b, n); i++):
                for (j = j0; j < min(j0+b, n); j++):
                    double sum = C[i][j];
                    for (k = k0; k < min(k0+b, n); k++):
                        sum += A[i][k] * B[k][j];
                    C[i][i] = sum;
```

- Same number of operations, identical result, same round-off errors
- Cache misses: n^3 / (m · b) before: n^3 (m · b is significantly large)







Strassen's algorithm (Volker Strassen, 1969)

- Divide-and-Conquer algorithm
- Multiplying two 2 × 2-matrices using 7 multiplications (instead of 8) with additional add and sub operations
 - → Sub-cubic complexity
- Cache-oblivious
- But: numeric stability is inferior to sequential algorithm
- Used in OpenBLAS in some cases (e.g. finite fields)
- Complex implementation! (See me after this session if you want to go for it)



Recap: Common MPI Functions



Further Reading



The one MPI tutorial you all want to read:

Basics: https://cvw.cac.cornell.edu/MPI/

P2P: https://cvw.cac.cornell.edu/MPIP2P/

RMA: https://cvw.cac.cornell.edu/MPIoneSided/

Advanced: https://cvw.cac.cornell.edu/MPIAdvTopics/

Official MPI 3.1 documentation (Index):

http://www.mpi-forum.org/docs/mpi-3.1/mpi31-report/mpi31-report.htm#Node0

Again, a collection of documented MPI examples:

http://www.mcs.anl.gov/~thakur/sc14-mpi-tutorial/



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MPI Recap



```
#include <mpi.h>
#include <stdio.h>
int main(int argc, char * argv[]) {
    int rank, size;
   MPI_Init(&argc, &argv);
    MPI_Comm_rank(MPI_COMM_WORLD, &rank);
    MPI_Comm_size(MPI_COMM_WORLD, &size);
    printf("I am %d of %d\n", rank, size );
   MPI_Finalize();
    return 0;
```





Point-to-Point vs. Collective

Collective operations are called by all processes in a communicator.

Point-to-point operations are called at sender and receiver process.







Point-to-Point Operations

Blocking Nonblocking Somewhat-blocking

MPI_Send MPI_Isend MPI Ssend

MPI_Recv MPI_Irecv MPI Bsend

MPI_Sendrecv

- Transfer of a message from one specific process to another specific process in the communicator.
- Requires action from both the sending and receiving processes.







MPI Send / MPI Recv (P2P)

```
MPI_Send(buffer, count, dtype, dst_rank, tag, comm)
MPI_Recv(buffer, count, dtype, src_rank, tag, comm, status)
Send from process with rank src_rank to process with rank dst_rank.
At send process:
   // buffer out initialized with values before call
   MPI_Send(&out, 1, MPI_CHAR, dst_rnk, tag, MPI_COMM_WORLD);
At receive processes:
   MPI_Recv(&in, 1, MPI_CHAR, src_rnk, tag, MPI_COMM_WORLD, &sta);
   // buffer in filled with values after call returns
   MPI Get count(&sta, MPI CHAR, &count);
```





Collective Operations

Rooted	All-to-all	Other
MPI_Gather/v	MPI_Allgather/v	MPI_Scan
MPI_Reduce	MPI_Alltoall/v/w	MPI_Exscan
MPI_Scatter/v	MPI_Allreduce	MPI_Barrier
MPI_Bcast	<pre>MPI_Reduce_scatter</pre>	

- Collective communication routines must involve **all** processes within the scope of a communicator.
- All processes are members in the communicator MPI_COMM_WORLD by default.







MPI Bcast

```
MPI_Bcast(buffer, count, dtype, root, comm)
```

Broadcast from root process to all processes in leaf group.

```
At root process:
```

```
// buffer initialized with values before call
MPI Bcast(buffer, count, root rank, comm)
```

```
MPI Bcast(buffer, count, root rank, comm)
// buffer filled with values after call returns
```







Rooted	All-to-all	Other
MPI_Gather/v	MPI_Allgather/v	MPI_Scan
MPI_Reduce	MPI_Alltoall/v/w	MPI_Exscan
MPI_Scatter/v	MPI_Allreduce	MPI_Barrier
MPI_Bcast	MPI_Reduce_scatter	

"Messages are **non-overtaking**: If a sender sends two messages in succession to the same destination, and both match the same receive, then this operation cannot receive the second message if the first one is still pending."







MPI Reduce

```
MPI_Reduce(sbuffer, rbuffer, count, dtype, op, root, comm)
```

Reduce values in sbuffer at processes in leaf group into rbuffer at root process.

At root process:

```
MPI Reduce(sbuf, rbuf, ..., MPI SUM, root rank, comm)
// rbuf filled with values after call returns
```

```
// sbuf initialized with values before call
MPI Reduce(sbuf, rbuf, ..., MPI SUM, root rank, comm)
```







MPI_Scatter

Scatter data **in rank order** from root process into receive buffers at leaf processes (i.e. inverse of MPI_Gather).

```
At root process:
```

```
// sbuf filled before call, receive arguments are ignored
MPI_Scatter(sbuf, scount, ..., root_rank, comm)
```

```
// send arguments are ignored
MPI_Scatter(sbuf, scount, ..., root_rank, comm)
```







MPI_Gather

Gather data in rank order from leaf processes into receive buffer at root process.

```
At root process:
```

```
// send arguments are ignored
MPI_Gather(sbuf, scount, ..., root_rank, comm)
```

```
// sbuf filled before call, receive arguments are ignored
MPI_Gather(sbuf, scount, ..., root_rank, comm)
```





Blocking vs. Non-blocking







Blocking vs. Non-blocking

Blocking:

Process waits to ensure the message data have achieved a particular state before processing can continue.

Non-blocking:

Process merely requests to start an operation and continues processing. Allows overlap of communication and communication.

```
Blocking, two-sided
// blocks until received:
MPI_Recv(...);
```

```
Non-blocking, two-sided
MPI Request req;
MPI_Irecv(..., &req);
some_local_computation();
// blocks until received:
MPI Wait(req, &status);
```





Two-sided vs. One-sided







Two-sided

- Memory is private to each process.
- When the sender calls the MPI_Send operation and the receiver calls the MPI_Recv operation, data in the sender memory is copied to a buffer then sent over the network, where it is copied to the receiver memory.
- **Drawback:** sender has to wait for the receiver to be ready to receive the data before it can send the data.
- Both sender and receiver have to state a specific call for the communication.

→ Coupled program flow





One-sided

- Sections in local memory are made accessible among processes.
- Requires only one process to transfer data, decouples data transfer from system synchronization.
- MPI 3.0 supports one-sided passive target communication without the intervention of the remote process via Remote Direct Memory Access (RDMA).
 - That is: send or receive data without any local action.
- → Decoupled program flow





One-sided

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- MPI 3.0 supports one-sided passive target communication without the intervention of the remote process via Remote Direct Memory Access (RDMA).
 - That is: send of receive data without any local action.
- → Decoupled program flow

In the real world, passive RDMA in most MPI implementations is either buggy, or inefficient (barrier spin-locks and other delightful hacks) or both, but it's getting better.





One-sided Operations

Standard Request-based

MPI_Put MPI_Rput

MPI_Get MPI_Rget

MPI_Accumulate MPI_Raccumulate

- All data movement operations are non-blocking.
- Requires explicit synchronization call to ensure completion, e.g.:

```
MPI_Wait(req)
MPI_Win_fence(win)
MPI_Win_flush(win)
```







MPI Get / MPI Put

Origin: calling (i.e. local) process

Target: remote process

```
MPI_Get(oaddr, ocount, otype,
        trank, tdisp, tcount, ttype, window)
```

Transfer elements from target in window[tdisp:tcount] into local buffer oaddr at origin.

```
MPI_Put(oaddr, ocount, otype,
        trank, tdisp, tcount, ttype, window)
```

Transfer elements from local buffer oaddr at origin to target into window[tdisp:tcount].







(Blocking / Nonblocking) x (One-sided x Two-sided)

	Blocking	Nonblocking
Two-sided	MPI_Send	MPI_Isend
One-sided	MPI_Put	MPI_Rput

One-sided communication can be used to implement collective operations.

Pop quiz: How would you implement a reduce operation using

one-sided communication?

Find minimum value in distributed array. **Example:**







One-sided true passive RMA Example

```
MPI Comm comm = MPI COMM WORLD;
// Create local window buffer of 4096 integers:
int * winbuf;
MPI Alloc mem(sizeof(int)*4096, MPI INFO NULL, &winbuf);
// Create window, collective operation:
MPI Win win;
MPI Win create(winbuf, sizeof(int)*4096, sizeof(int),
               MPI WIN INFO NULL, comm, &win);
// Start passive RMA epoch, collective operation:
MPI_Win_lock_all(0, win);
```





One-sided true passive RMA Example ctd.

What could go wrong?





One-sided true passive RMA Example ctd.

What could go wrong?





One-sided true passive RMA Example ctd.

Data races, as known from multi-threading.



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