

Numerical Analysis
homework 07: Matrix Eigenvalues

Due on Tuesday, April 18, 2017

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1 Introduction

In previous homework, we had already use power method and inverse power method to find the largest and smallest eigenvalue. However, both of them cannot be used to find all the eigenvalue of a matrix A ; therefore, in this project, we will use **QR Method** to find all the eigenvalues.

1.1 API

In **MAT.h** and **MAT.cpp**, I implement the following functions:

1. `void QRFact(const MAT &A, MAT &Q, MAT &R);`
2. `int EVqr(MAT &A, double tol, int maxiter);`
3. `int EVqrShifted(MAT &A, double mu, double tol, int maxiter);`

QRFact will apply **QR Decomposition** to A and store them into Q and R . **EVqr** and **EVqrShifted** is the implementation of **QR Iteration** and **Shifted QR Iteration**. In this assignment, **tol** should be set to 10^{-9} and **mu** should be 0.5. We have to find the three largest and the three smallest eigenvalues of **m3.dat**, **m4.dat**, **m5.dat**, **m6.dat**, **m7.dat**, **m8.dat**.

1.2 Error Calculation

According to **Gram-Schmidt Process**, we should get a final matrix with 0 in the non-diagonal from **QR Iteration**. Therefore, it makes sense that we can check whether all non-diagonal elements are zero or not. However, for saving execution time, we simply this checking to the following fomula:

$$error = \max_{2 \leq i \leq n} |a_{i,i-1}|$$

For each iteration, we only check the one-line elements below diagonal, which will be faster a lot than checking all non-diagonal elements.

2 Implementation

Algorithm 1 QR Decomposition

```

 $A = \{a_1, a_2, \dots, a_n\}$ ,  $a_i$  is column vector,
 $r_{11} = \sqrt{(a_1)^T a_1}$ 
 $q_1 = \frac{a_1}{r_{11}}$ 
for each  $j \in \{2, \dots, n\}$  do
     $q_j = a_j$ 
    for each  $i \in \{1, \dots, j-1\}$  do
         $r_{ij} = (q_i)^T q_j$ 
         $q_j = q_j - r_{ij} q_i$ 
    end for
     $r_{jj} = \sqrt{(q_j)^T q_j}$ 
     $q_j = \frac{q_j}{r_{jj}}$ 
end for

```

Algorithm 2 QR Iteration

```

 $T^{(0)} = A$ 
for each  $k \in \{1, \dots, \text{maxIter}\}$  do
   $T^k = Q^k R^k$ 
   $T^{k+1} = R^k Q^k$ 
  if error < tol then
    break
  end if
end for

```

Algorithm 3 Shifted QR Iteration

```

 $T^{(0)} = A$ 
for each  $k \in \{1, \dots, \text{maxIter}\}$  do
   $T^k - \mu I = Q^k R^k$ 
   $T^{k+1} = R^k Q^k + \mu I$ 
  if error < tol then
    break
  end if
end for

```

2.1 Complexity

For **QR Decomposition**, the double for-loop do $\frac{n(n+1)}{2}$ times of operation, and $(q_i)^T q_j$ in each operation make **QR Decomposition** be a $O(n^3)$ problem.

For each iteration of **QR Iteration**, there are **QR Decomposition** and **mat** \times **mat**. So it is also $O(n^3)$ problem.

3 Discussion

In the section, we will discuss the following topics:

1. Eigenvalues of m3, ..., m15.dat
2. Runtime of EVqr
3. Runtime of EVqrShifted

3.1 Eigenvalues

Table 1 and 2 show eigenvalue calculated by **EVqr** and **EVqrShifted**, respectively.

EVqr	N	E_large_1	E_large_2	E_large_3	E_small_1	E_small_2	E_small_3
m3	3	0.627719	2	6.372281	0.627719	2	6.372281
m4	10	4.455992	20.431729	67.840399	0.512543	0.55164	0.629808
m5	20	17.235222	81.223819	270.495189	0.503097	0.512479	0.528819
m6	30	38.53868	182.544889	608.253606	0.501373	0.505511	0.512543
m7	40	68.364136	324.394506	1081.115447	0.500772	0.503093	0.507004
m8	50	106.711318	506.772618	1689.080688	0.500494	0.501978	0.504468

Table 1: Eigenvalue of EVqr

EVqrShifted	N	E_large_1	E_large_2	E_large_3	E_small_1	E_small_2	E_small_3
m3	3	0.627719	2	6.372281	0.627719	2	6.372281
m4	10	4.455992	20.431729	67.840399	0.512543	0.55164	0.629808
m5	20	17.235222	81.223819	270.495189	0.503097	0.512479	0.528819
m6	30	38.53868	182.544889	608.253606	0.501373	0.505511	0.512543
m7	40	68.364136	324.394506	1081.115447	0.500772	0.503093	0.507004
m8	50	106.711318	506.772618	1689.080688	0.500494	0.501978	0.504468
m9	60	153.580161	729.679212	2432.149321	0.500343	0.501373	0.503097
m10	70	208.970642	993.114283	3310.321344	0.500252	0.501008	0.502273
m11	80	272.882751	1297.07783	4323.596758	0.500193	0.500772	0.501739
m12	90	345.316483	1641.569852	5471.97556	0.500152	0.50061	0.501373
m13	100	426.271836	2026.590348	6755.457752	0.500123	0.500494	0.501112
m14	120	613.747401	2918.216761	9727.732302	0.500086	0.500343	0.500772
m15	150	958.872886	4559.619934	15199.419543	0.500055	0.500219	0.500494

Table 2: Eigenvalue of EVqrShifted

3.2 EVqr

Table 3 show the average iteration time(**iter_avg**) and iteration number(**iter_num**) for m3 m8.dat.

EVqr	N	iter_num	runtime(s)	iter_avg
m3	3	20	7.20E-05	3.6000E-06
m4	10	249	0.005884	2.3631E-05
m5	20	909	0.110081	1.2110E-04
m6	30	1942	0.693329	3.5702E-04
m7	40	3325	2.88519	8.6773E-04
m8	50	5041	9.79014	1.9421E-03

Table 3: Itertion number and iter_avg of EVqr

From Table 3, we can plot iter_avg vs N and iter_num vs N as shown in Figure 1 and 2.

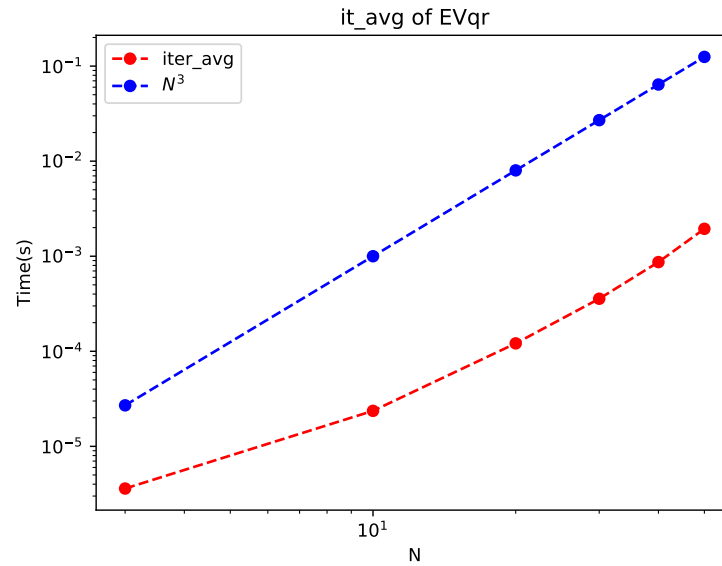


Figure 1: iter_avg vs N(EVqr)

In Figure 1, we can find that the slope of iter_avg is same as N^3 , which means the complexity of each iteration of EVqr is $O(n^3)$ and satisfies my analysis in Section 2.1.

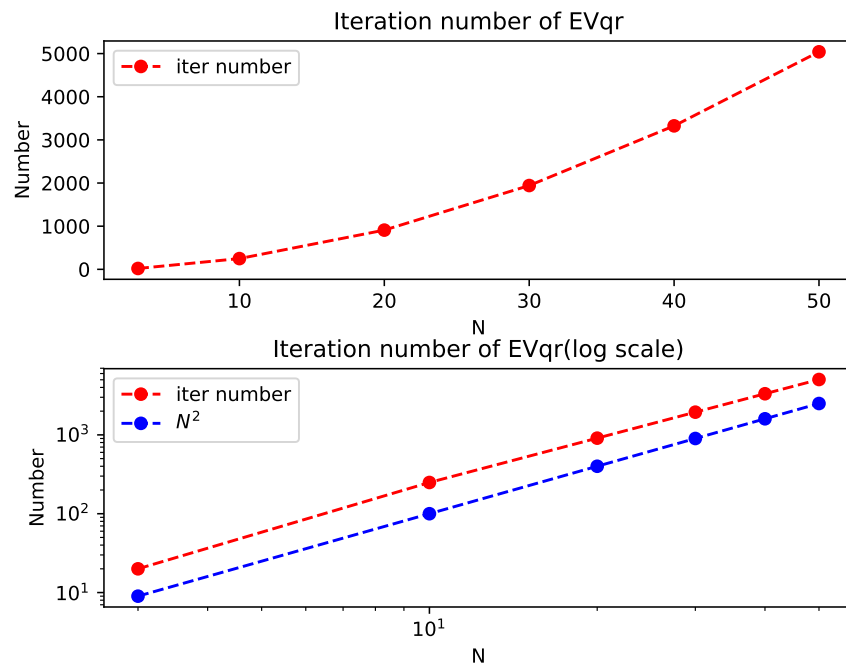


Figure 2: iter_num vs N(EVqr) in normal scale(top) and log scale(bottom)