Numerical Analysis homework 07: Matrix Eigenvalues

Due on Tuesday, April 18, 2017

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1 Introduction

In previous homework, we had already use power method and inverse power method to find the largest and smallest eigenvalue. However, both of them cannot be used to find all the eigenvalue of a matrix A; therefore, it this project, we will use \mathbf{QR} Method to find all the eigenvalues.

1.1 API

In MAT.h and MAT.cpp, I implement the following functions:

- 1. void QRFact(const MAT &A, MAT &Q, MAT &R);
- 2. int EVqr(MAT &A, double tol, int maxiter);
- 3. int EVqrShifted(MAT &A, double mu, double tol, int maxiter);

QRFact will apply QR Decomposition to A and store them into Q and R. EVqr and EVqrShifted is the implementation of QR Iteration and Shifted QR Iteration. In this assignment, tol should be set to 10^{-9} and mu should be 0.5. We have to find the three largest and the three smallest eigenvalues of m3.dat, m4.dat, m5.dat, m6.dat, m7.dat, m8.dat.

1.2 Error Calculation

According to **Gram-Schmidt Process**, we should get a final matrix with 0 in the non-diagonal from **QR Iteration**. Therefore, it makes sense that we can check whether all non-diagonal elements are zero or not. However, for saving execution time, we simply this checking to the following fomula:

$$error = \max_{2 \le i \le n} |a_{i,i-1}|$$

For each iteration, we only check the one-line elements below diagonal, which will be faster a lot than checking all non-diagonal elements.

2 Implementation

Algorithm 1 QR Decomposition

```
A = \{a_1, a_2, ..., a_n\}, a_i \text{ is column vector,} \\ r_{11} = \sqrt{(a_1)^T a_1} \\ q_1 = \frac{a_1}{r_{11}} \\ \text{for each } j \in \{2, ..., n\} \text{ do} \\ q_j = a_j \\ \text{for each } i \in \{1, ..., j\text{-}1\} \text{ do} \\ r_{ij} = (q_i)^T q_j \\ q_j - = r_{ij} q_i \\ \text{end for} \\ r_{jj} = \sqrt{(q_j)^T q_j} \\ q_j = \sqrt{sum((q_j)^2)} \\ \text{end for} \\ does not consider the sum of the s
```

Algorithm 2 QR Iteration

```
T^{(0)} = A for each k \in \{1, ..., maxIter\} do T^k = Q^k R^k T^{k+1} = R^k Q^k if error < tol then break end if end for
```

Algorithm 3 Shifted QR Iteration

```
T^{(0)}=A for each \mathbf{k}\in\{1,...,\mathrm{maxIter}\} do T^k-\mu I=Q^kR^k T^{k+1}=R^kQ^k+\mu I if error < tol then break end if end for
```

2.1 Complexity

For **QR Decomposition**, the double for-loop do $\frac{n(n+1)}{2}$ times of operation, and $(q_i)^T q_j$ in each operation make **QR Decomposition** be a $O(n^3)$ problem.

For each iteration of **QR Iteration**, there are **QR Decomposition** and **mat** \times **mat**. So it is also $O(n^3)$ problem.

3 Discussion

In the section, we will discuss the following topics:

- 1. Eigenvalues of m3, ..., m15.dat
- 2. Runtime of EVqr
- 3. Runtime of EVqrShifted

3.1 Eigenvalues

Table 1 and 2 show eigenvalue calculated by EVqr and EVqrShifted, respectively.

| EVqr | N | E_large_1 | E_large_2 | E_large_3 | E_small_1 | E_small_2 | E_small_3 |
|------|----|------------|------------|-------------|-----------|-----------|-----------|
| m3 | 3 | 0.627719 | 2 | 6.372281 | 0.627719 | 2 | 6.372281 |
| m4 | 10 | 4.455992 | 20.431729 | 67.840399 | 0.512543 | 0.55164 | 0.629808 |
| m5 | 20 | 17.235222 | 81.223819 | 270.495189 | 0.503097 | 0.512479 | 0.528819 |
| m6 | 30 | 38.53868 | 182.544889 | 608.253606 | 0.501373 | 0.505511 | 0.512543 |
| m7 | 40 | 68.364136 | 324.394506 | 1081.115447 | 0.500772 | 0.503093 | 0.507004 |
| m8 | 50 | 106.711318 | 506.772618 | 1689.080688 | 0.500494 | 0.501978 | 0.504468 |

Table 1: Eigenvalue of EVqr

| EVqrShifted | N | E_large_1 | E_large_2 | E_large_3 | E_small_1 | E_small_2 | E_small_3 |
|-------------|-----|------------|-------------|--------------|-----------|-----------|-----------|
| m3 | 3 | 0.627719 | 2 | 6.372281 | 0.627719 | 2 | 6.372281 |
| m4 | 10 | 4.455992 | 20.431729 | 67.840399 | 0.512543 | 0.55164 | 0.629808 |
| m5 | 20 | 17.235222 | 81.223819 | 270.495189 | 0.503097 | 0.512479 | 0.528819 |
| m6 | 30 | 38.53868 | 182.544889 | 608.253606 | 0.501373 | 0.505511 | 0.512543 |
| m7 | 40 | 68.364136 | 324.394506 | 1081.115447 | 0.500772 | 0.503093 | 0.507004 |
| m8 | 50 | 106.711318 | 506.772618 | 1689.080688 | 0.500494 | 0.501978 | 0.504468 |
| m9 | 60 | 153.580161 | 729.679212 | 2432.149321 | 0.500343 | 0.501373 | 0.503097 |
| m10 | 70 | 208.970642 | 993.114283 | 3310.321344 | 0.500252 | 0.501008 | 0.502273 |
| m11 | 80 | 272.882751 | 1297.07783 | 4323.596758 | 0.500193 | 0.500772 | 0.501739 |
| m12 | 90 | 345.316483 | 1641.569852 | 5471.97556 | 0.500152 | 0.50061 | 0.501373 |
| m13 | 100 | 426.271836 | 2026.590348 | 6755.457752 | 0.500123 | 0.500494 | 0.501112 |
| m14 | 120 | 613.747401 | 2918.216761 | 9727.732302 | 0.500086 | 0.500343 | 0.500772 |
| m15 | 150 | 958.872886 | 4559.619934 | 15199.419543 | 0.500055 | 0.500219 | 0.500494 |

Table 2: Eigenvalue of EVqrShifted