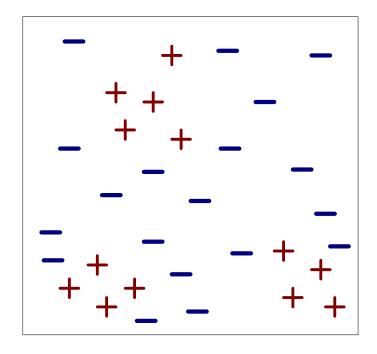
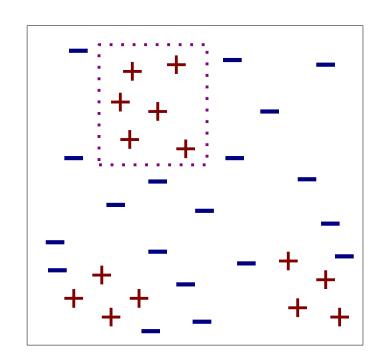
Direct Method: Sequential Covering

- 1. Start from an empty rule
- 2. Grow a rule using the Learn-One-Rule function
- 3. Remove training records covered by the rule
- Repeat Step (2) and (3) until stopping criterion is met

Example of Sequential Covering

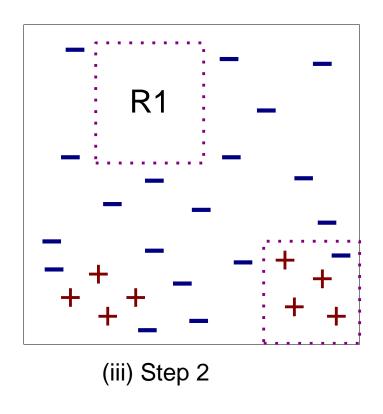


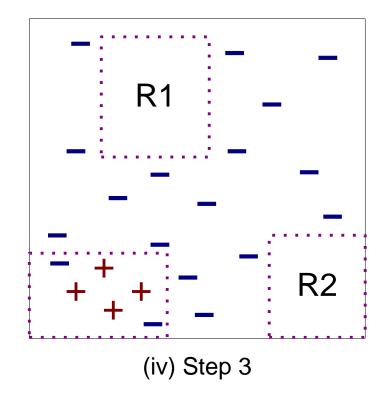
(i) Original Data



(ii) Step 1

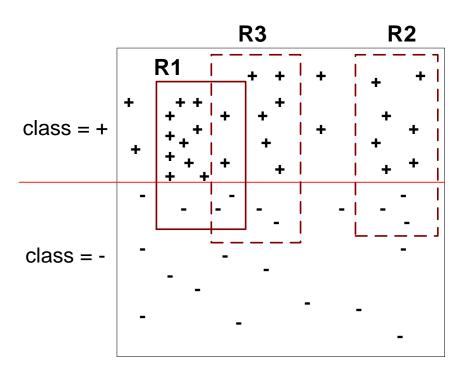
Example of Sequential Covering...





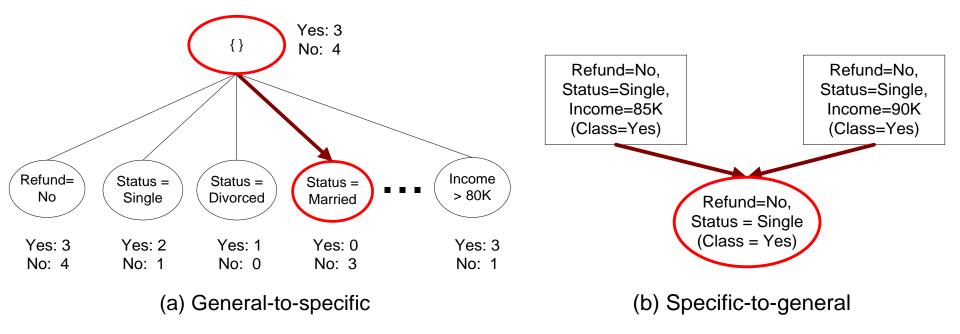
Instance Elimination

- Why do we need to eliminate instances?
 - Otherwise, the next rule is identical to previous rule
- Why do we remove positive instances?
 - Ensure that the next rule is different
- Why do we remove negative instances?
 - Prevent underestimating accuracy of rule
 - Compare rules R2 and R3 in the diagram



Rule Growing

Two common strategies



Rule Evaluation

Foil's Information Gain

FOIL: First Order Inductive Learner – an early rulebased learning algorithm

- R0: {} => class (initial rule)
- R1: {A} => class (rule after adding conjunct)
- Gain(R0, R1) = t [log (p1/(p1+n1)) log (p0/(p0 + n0))]
- where t: number of positive instances covered by both R0 and R1
 - p0: number of positive instances covered by R0
 - n0: number of negative instances covered by R0
 - p1: number of positive instances covered by R1
 - n1: number of negative instances covered by R1

- For 2-class problem, choose one of the classes as positive class, and the other as negative class
 - Learn rules for positive class
 - Negative class will be default class
- For multi-class problem
 - Order the classes according to increasing class prevalence (fraction of instances that belong to a particular class)
 - Learn the rule set for smallest class first, treat the rest as negative class
 - Repeat with next smallest class as positive class

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- Growing a rule:
 - Start from empty rule
 - Add conjuncts as long as they improve FOIL's information gain
 - Stop when rule no longer covers negative examples
 - Prune the rule immediately using incremental reduced error pruning
 - Measure for pruning: v = (p-n)/(p+n)
 - p: number of positive examples covered by the rule in the validation set
 - n: number of negative examples covered by the rule in the validation set
 - Pruning method: delete any final sequence of conditions that maximizes v

- Building a Rule Set:
 - Use sequential covering algorithm
 - Finds the best rule that covers the current set of positive examples
 - Eliminate both positive and negative examples covered by the rule
 - Each time a rule is added to the rule set, compute the new description length
 - Stop adding new rules when the new description length is d bits longer than the smallest description length obtained so far

- Optimize the rule set:
 - For each rule r in the rule set R
 - Consider 2 alternative rules:
 - Replacement rule (r*): grow new rule from scratch
 - Revised rule(r'): add conjuncts to extend the rule r
 - Compare the rule set for r against the rule set for r* and r'
 - Choose rule set that minimizes MDL principle
 - Repeat rule generation and rule optimization for the remaining positive examples