EE 159/CS 168 - Convex Optimization Scott Fullenbaum

Homework 2

1. First, we can define our second regression equation as $\tilde{y} = \tilde{x}^T \beta + v$. We can take the difference of this with our original equation getting:

 $|\hat{y} - \widetilde{y}| = |x^T \beta + v - (\widetilde{x}^T \beta + v)| = |x^T \beta - \widetilde{x}^T \beta|$. Since this is a scalar, we can take the transpose of the right side, getting $|\beta^T x^T - \beta^T \widetilde{x}| = |\beta^T (x^T - \widetilde{x})|$. This is a dot product of two vectors, so we can use the Cauchy-Schwarz inequality and $|\hat{y} - \tilde{y}| = |\beta^T(x^T - \tilde{x})| \le ||\beta|| ||x - \tilde{x}||$, which proves: $|\hat{y} - \widetilde{y}| \le ||\beta|| ||x - \widetilde{x}||$

2.
$$\frac{\partial Q}{\partial x} = 2ax + 4y + 2az$$
, $\frac{\partial Q}{\partial y} = 8ay + 4x + 4z$, $\frac{\partial Q}{\partial z} = 8az + 2ax + 4y$.
$$\nabla Q = \begin{bmatrix} 2ax + 4y + 2az \\ 8ay + 4x + 4z \\ 8az + 2ax + 4y \end{bmatrix}$$
. To find the Hessian, we need to find the second partials, and can

use the fact that the order in which they are taken doesn't matter

$$\frac{\partial Q}{\partial x \partial x} = 2a \ \frac{\partial Q}{\partial x \partial y} = 4 \ \frac{\partial Q}{\partial x \partial z} = 2a \ \frac{\partial Q}{\partial y \partial y} = 8a \ \frac{\partial Q}{\partial y \partial z} = 4. \ \nabla^2 Q = \begin{bmatrix} 2a & 4 & 2a \\ 4 & 8a & 4 \\ 2a & 4 & 8a \end{bmatrix}$$

To see if the Hessian is positive semi definite, we can use Sylvester's criterion and evaluate the determinant of the upper 1x1 matrix, 2x2 matrix, and determinant of the matrix is ≥ 0 . $1x1: \det(2a) = 2a \ge 0 \text{ for } a \ge 0$

$$2x2$$
: $\begin{vmatrix} 2a & 4 \\ 4 & 8a \end{vmatrix} = 16a^2 - 16 \ge 0 \text{ for } a \le -1 \text{ or } a \ge 1$

$$3x3$$
: $2a\begin{vmatrix} 8a & 4 \\ 4 & 8a \end{vmatrix} - 4\begin{vmatrix} 4 & 4 \\ 2a & 8a \end{vmatrix} + 2a\begin{vmatrix} 4 & 8a \\ 2a & 4 \end{vmatrix} = 96a^3 - 96a \ge 0 \text{ for } -1 \le a \le 0 \text{ or } a \ge 1$

Combining all three restrictions, for all to be positive, $a \ge 1$, meaning the Hessian is PSD if

3. (a) $J(z) = \sum_{i=1}^{L} ||x_i - z||^2 = \sum_{i=1}^{L} ||x_i - \bar{x} + \bar{x} - z||^2 = \sum_{i=1}^{L} ||(x_i - \bar{x}) - (z - \bar{x})||^2 = \sum_{i=1}^{L} ||x_i - \bar{x}||^2 = \sum_{i=1}^{L} ||x_i - \bar{x$ $\sum_{i=1}^{L} \langle (x_i - \bar{x}) - (z - \bar{x}), (x_i - \bar{x}) - (z - \bar{x}) \rangle = \sum_{i=1}^{L} \langle x_i - \bar{x}, x_i - \bar{x} \rangle - 2 \langle x_i - x, z - \bar{x} \rangle + \langle z - \bar{x}, z - \bar{x} \rangle$ $= \sum_{i=1}^{L} ||x_i - \bar{x}||^2 - 2(x_i - x)^T (z - \bar{x}) + ||z - \bar{x}||^2 = \sum_{i=1}^{L} (||x_i - \bar{x}||^2 - 2(x_i - x)^T (z - \bar{x})) + L||z - \bar{x}||^2.$

The last step can be made as $||z - \bar{x}||^2$ is constant

(b)
$$\sum_{i=1}^{L} (x_i - \bar{x})^T (z - \bar{x}) = \sum_{i=1}^{L} ((x_i - \bar{x})^T) * (z - \bar{x}) = (\sum_{i=1}^{L} (x_i - \bar{x}))^T * (z - \bar{x}).$$

$$\sum_{i=1}^{L} x_i - \bar{x} = \sum_{i=1}^{L} x_i - L\bar{x} = \sum_{i=1}^{L} x_i - L\frac{1}{L} \sum_{i=1}^{L} x_i = \sum_{i=1}^{L} x_i - \sum_{i=1}^{L} x_i = 0, \text{ so this equation is equal to } 0.$$

(c) As
$$J(z) = \sum_{i=1}^{L} (\|x_i - \bar{x}\|^2 - 2(x_i - x)^T(z - \bar{x})) + L\|z - \bar{x}\|^2 = \sum_{i=1}^{L} \|x_i - \bar{x}\|^2 + L\|z - \bar{x}\|^2$$
.
 $L\|z - \bar{x}\|^2 \ge 0$, and is equal to 0 only when $z = \bar{x}$, meaning $L\|z - \bar{x}\|^2 > 0$ for $z \ne \bar{x}$, and as the term in the summation is constant for any z , then $J(z) > J(\bar{x})$ for $z \ne \bar{x}$ and $z = \bar{x}$ minimizes $J(z)$.

4. To find the gradient and Hessian, and can use the chain rule, rewriting f(x) as f(x) = g(h(x)) where $h(x) = 1 + ||Ax + b||_2^2$ and g(y) = log(y).

Gradient:
$$\nabla f(x) = g'h(x)\nabla h(x) = \frac{1}{1 + \|Ax + b\|_2^2}\nabla h(x) = \frac{2A^TAx + 2A^Tb}{1 + \|Ax + b\|_2^2}$$

$$\begin{aligned} & \text{Hessian: } \nabla^2 f(x) = g''(h) \nabla h(x) \nabla^T h(x) + g'(h) \nabla^2 h(x) = \\ & \frac{-1}{(1 + \|Ax + b\|_2^2)^2} * (2A^T Ax + 2A^T b) (2A^T Ax + 2A^T b)^T + \frac{2A^T A}{1 + \|Ax + b\|_2^2} \\ & = \frac{-(2A^T Ax + 2A^T b) (2A^T Ax + 2A^T b)^T}{(1 + \|Ax + b\|_2^2)^2} + \frac{2A^T A}{1 + \|Ax + b\|_2^2} \end{aligned}$$

5. (a) Start with the likelihood function:

$$l(R, a) = -(Nn)/2log(2\pi) - (N/2)logdet(R) - 1/2\sum_{k=1}^{N} (y_k - a)^T R^{-1}(y_k - a).$$

Since most of the simplification is done with the third term, I will be ignoring the first two until the end. Since the sum is constant, the trace of it is equal to itself, so we can rewrite as:

$$-1/2 \sum_{k=1}^{N} tr((y_k - a)^T R^{-1} (y_k - a)) = -1/2 \sum_{k=1}^{N} tr((y_k - a) (y_k - a)^T R^{-1})$$

$$=-1/2tr(\sum_{k=1}^{N}(y_k-a)(y_k-a)^TR^{-1})$$
. Now, let $y_k-a=((y_k-\mu)-(a-\mu))$, so our sum

is:

$$= -1/2tr(\sum_{k=1}^{N}((y_k - \mu) - (a - \mu))((y_k - \mu) - (a - \mu))^T R^{-1})$$

$$= -1/2tr((\sum_{k=1}^{N} (y - y_k)(y - y_k)^T + N(a - \mu)(a - \mu)^T)R^{-1})$$

There is a step between these two, involving terms in a matrix by $-2(y_k - \mu)(a - \mu)^T$. However, it gets a bit messy to type out and using the same logic from question 3.b, which holds for each component, all the terms in that matrix are 0. Also, as $(a - \mu)(a - \mu)^T$ is constant across the summation, we can just multiply itself by N. Now note $\sum_{i=1}^{N} (y - y_k)(y - y_k)^T = NY$, so the equation is:

$$= -1/2(tr(NY + N(a - \mu)(a - \mu)^{T})R^{-1})$$

Distributing and using the property of traces that tr(A + B) = tr(A) + tr(B) we can rewrite this sum as:

$$= -1/2(tr(NYR^{-1}) + tr(N(a-\mu)(a-\mu)^TR^{-1}).$$

Since tr(cB) where c is a scalar = c*tr(B) and tr(AB) = tr(BA), the equation becomes:

$$= -1/2(N*tr(R^{-1}Y) + N*tr((a-\mu)(a-\mu)^TR^{-1}))$$

$$= -1/2(N * tr(R^{-1}Y) + N * tr((a - \mu)^{T}R^{-1}(a - \mu)))$$

Since the second term is a scalar, and $tr(c) = c \forall c \in R$

$$= \frac{N}{2} (tr(R^{-1}Y) - (a - \mu)^T R^{-1} (a - \mu))$$

Combining this with the other two terms and factoring out N/2 from them gives:

$$l(R, a) = \frac{N}{2}(-nlog(2\pi) - logdet(R) - tr(R^{-1}Y) - (a - \mu)^{T}R^{-1}(a - \mu))$$

(b) First,
$$\nabla_a = \frac{-N}{2} 2R^{-1}(a-\mu) = -NR^{-1}(a-\mu)$$
 and $\nabla_a^2 = -NR^{-1}$

To find
$$\nabla_R$$
, ignoring terms from the likelihood without R, the equation is
$$l(R,a) = \frac{N}{2}(-logdetR - tr(R^{-1}Y) - (a-\mu)^T R^{-1}(a-\mu)), \text{ using the table we get:}$$

$$\nabla_R = \frac{N}{2}((-R^{-1})^T - (-R^{-1}YR^{-1})^T)$$

To find the ML estimates, set ∇_a and $\nabla_R = 0$. For ∇_a , $-NR^{-1}(a-\mu) = 0$, so a unique minimum is reached at $a = \mu$.

For R, $\nabla_R = \frac{N}{2}((-R^{-1})^T - (-R^{-1}YR^{-1})^T) = 0$. Since Y > 0, Y is invertible, so there exists a unique matrix, Y^{-1} such that $YY^{-1} = I$ that is it's inverse. If we let Y = R, $\nabla_R = (-Y^{-1})^T - (-Y^{-1}YY^{-1})^T = (-Y^{-1})^T - (-Y^{-1})^T = \mathbf{0}$

So, the ML estimates are $a = \mu$ and R = Y. They are unique as $(a - \mu)$ has one minimum, and there is only one inverse Y as it is invertible.