Math 145 HW

1.3) Sr is given as

So SIS IS For rong 15 is given as: goes between 12,334 & 83 1.4) So can think of this as holding 1 element on top, then rotating it luice to make all symmetries. Making 4x3 total Starting as

Starting as

1 1 we clearly

see le 1, 13 generates those 3 assembles

w/ 1. To get 4 on top, it requires one 5, and it follows clearly that 5, 50, 800 generates that list To push 2 on top, requires 115 as need two rotations to act it in position. Also right of the it follows 155 . To get the last one, rotate again w/ 1551. Lostly, need to put 3 on top. So, see rs puts 3 on top, then isr, isser are that positions

B= {eggross son rong 2.3)
[ab][de]-[ad+be ae+bf]
[bc][ef]-[bd+ce be+cf]

So not closed under group operation.

and not a a group [ab][de]=[ad+bf ae+bd]. [eal]fdJ=[cd+af ce+ad] So not a group aparations adofto as acydfto so closed under operation. Matrix multiplication is associative and T=[10] is in the group and [ab] [ab] [ab] [ab] [ac] As acto, det for so [ab] Therefore, this is a group. v) Notagraps A=[12] detA=0

We know A = - 1 [4 - 2] & the group

So therefore the collection isn't a

group.

Invective tet fire > IR2 be an isometry under some distance function fis sinuective if f(a)=f(b)=) a=b If f(a)=f(b), then d(f(a), f(b))=0 and as fis an isometry, then d(a,b)=0 so a=b and f) is invicative Let a, b, c GIR and be unique.
As fis injective, f(a) & f(b) & f(c) et yEIR so let 10CFCa) y)=X, If we draw 3 circles, of Padius

X, X2, X2 centered an flat, flat, flat

they intersect at unique pointy Miquel's Thm. This point in the image is unique, as: fit's not, then fish't injective.

So, get the unique x that maps to the presence distance and then using the Presence distance.

To show this is a group. Isometries are closed under composition. Let fig be isometries fog is an isometry, as for a, bGR

d(a,b) = c = d(a,a), q(b))= c

) d(f(a,a)), f(a,b) = c Function compositions are associal so the group is associative As isometrics are billective they are invertible and for isometry frits inverse files the function that maps any point back to it's initial Pointiality. Its The identity is I x -> x as fo T = P
and I of 2 f as I maps every point Therefore, the isometries under Composition are a grou