

Fixed point iteration

Definition The real number r is a fixed point of the function g if $g(r) = r$

Example $x^{(1)} = \cos(1)$
 $x^{(2)} = \cos(\cos^{(1)}) = \cos(x^{(1)})$
 $x^{(3)} = \cos(x^{(2)})$ and so on. This tends to the value $0.73908513 \equiv \alpha$

Note the fixed point iteration: $x^{(k+1)} = \cos(x^{(k)})$ $k = 0, 1, \dots$
 $x^{(0)} = 1$

$$\alpha = \cos(\alpha) \text{ where } \alpha = \lim_{k \rightarrow \infty} x^{(k)}$$

Generally, we have

$x_0 = \text{initial guess}$

$x_{i+1} = g(x_i)$ for $i = 0, 1, 2, \dots$

$$x_1 = g(x_0)$$

$$x_2 = g(x_1)$$

$$x_3 = g(x_2) \dots$$

If the x_i converge and g is continuous

$$g(r) = g\left(\lim_{i \rightarrow \infty} x_i\right) = \lim_{i \rightarrow \infty} g(x_i) = \lim_{i \rightarrow \infty} x_{i+1} = r$$

* We can turn root finding problems to fixed point problems

Example $x^3 + x - 1 = 0 \Rightarrow x = 1 - x^3$ (A)

$$\begin{aligned} g(x) &= 1 - x^3 \\ \Rightarrow x &= \sqrt[3]{1-x} \end{aligned}$$

$$g(x) = \sqrt[3]{1-x} \quad \text{(B)}$$

OR $3x^3 + x = 1 + 2x^3$

$$(3x^2 + 1)x = 1 + 2x^3$$

$$x = \frac{1 + 2x^3}{1 + 3x^2}$$

$$g(x) = \frac{1 + 2x^3}{1 + 3x^2} \quad \text{(C)}$$

(A) $g(x) = 1 - x^3$ with $x_0 = 0.5$ does not converge. It alternates between 0 and 1.

(B) $g(x) = \sqrt[3]{1-x}$ with $x_0 = 0.5$ converges to 0.6823

(C) $g(x) = \frac{1 + 2x^3}{1 + 3x^2}$ converges just in 4 iterations to 0.6822

Why are (A), (B) and (C) different?

contractive mapping theorem

$F \equiv$ contractive mapping

Let C be a closed set. If $F: C \rightarrow C$, then F has a unique fixed point. Moreover, the fixed point iteration scheme converges from any starting point x_0 .

Proof Uniqueness

Assume different fixed points r_1 and r_2
 $|r_1 - r_2| = |F(r_1) - F(r_2)|$

A function F is contractive if there exists $L < 1$ such that $|F(x) - F(y)| \leq L|x - y| \quad \forall x, y \in \text{domain}(F)$

$$\text{Therefore, } |F(r_1) - F(r_2)| \leq L|r_1 - r_2| < |r_1 - r_2|$$

$$\therefore |r_1 - r_2| < |r_1 - r_2| \Rightarrow r_1 = r_2$$

convergence

$$\begin{aligned} 0 \leq |x^{(k+1)} - r| &= |F(x^{(k)}) - F(r)| \\ &\leq L|F(x^{(k)}) - r| \\ &\leq L^2|x^{(k-1)} - r| \dots \leq L^{k+1}|x^{(0)} - r| \end{aligned}$$

$$\text{Therefore, } \frac{|x^{(k)} - r|}{|x^{(0)} - r|} \leq L^k$$

$$\lim_{k \rightarrow \infty} |x^{(k)} - r| = 0 \Rightarrow x^{(k)} \text{ converges to } r$$

Exercise Why is there a fixed point in C in the above proof?

Solution Note $C = [a, b]$ $F(a) \in C \Rightarrow F(a) - a \geq 0$

$$F(b) \in C \Rightarrow F(b) - b \leq 0$$

APPLY IVT, there is a zero for $F(x) - x$ □

Theorem

Let r be a fixed point of a continuously differentiable function g in an interval around r . If $|g'(r)| < 1$, then there exists $\delta > 0$ such that $\{x^{(k)}\}$ converges to r provided $|x^{(0)} - r| < \delta$.

proof $x_{i+1} - r = g(x_i) - g(r)$
 $= g'(c_i) (x_i - r)$ c_i is between x_i and r

$$|x_{i+1} - r| = |g'(c_i)| |x_i - r|$$

$$e_{i+1} = |g'(c_i)| e_i$$

Note $g'(x)$ is continuous. Let $\delta = |g'(r)|$
 $\delta < 1$

There is a neighborhood around r such that
 $|g'(x)| \leq \frac{\delta + 1}{2}$

$$\left[\begin{aligned} |g'(x)| &= |g'(r) + g'(x) - g'(r)| \\ &\leq |g'(r)| + |g'(x) - g'(r)| \\ &\leq \delta + \left(\frac{1-\delta}{2}\right) \end{aligned} \right]$$

$$e_{i+1} \leq \left(\frac{\delta + 1}{2}\right) e_i \quad \left(\text{assuming } x_i \text{ is in that neighborhood} \right)$$

similar to before, $\lim_{i \rightarrow \infty} x_i = r$

$$\lim_{i \rightarrow \infty} \frac{e_{i+1}}{e_i} = |g'(r)| = \delta$$

Multivariable Problems

$$f: \mathbb{R}^n \rightarrow \mathbb{R}^m$$

Jacobian matrix: $(Df)_{ij} = \frac{\partial f_i}{\partial x_j}$

Example $f(x, y) = \begin{pmatrix} 5x \\ -x^2 y^2 \\ x + 7y \end{pmatrix}$

$$Df(x, y) = \begin{pmatrix} 5 & 0 \\ -2xy^2 & -2x^2 y \\ 1 & 7 \end{pmatrix}$$

First order approximation: $f(\vec{x}) \approx f(\vec{x}_k) + Df(\vec{x}_k) \cdot (\vec{x} - \vec{x}_k)$ set $f(\vec{x}) = 0$
 $Df(\vec{x}_k) \cdot (\vec{x} - \vec{x}_k) = -f(\vec{x}_k)$
 Linear system

If Df is invertible

$$\vec{x}_{k+1} = \vec{x}_k - [Df(x_k)]^{-1} f(x_k)$$

If it is not invertible, use pseudo inverse (To be discussed later)

Directional derivative $\equiv Df \cdot \vec{v}$
of f in direction v

$$J_k \cdot (x_k - x_{k-1}) = f(x_k) - f(x_{k-1})$$

minimize $\|J_k - J_{k-1}\|_F^2$

$$J_k \cdot (x_k - x_{k-1}) = f(x_k) - f(x_{k-1})$$