

## Math 70 HW 2

Question 1 By Theorem 3 of chapter 1, when  $Ax = \vec{b}$ , the equation has the same solution as  $x_1 a_1 + \dots + x_n a_n = \vec{b}$ , which has the same solution as the augmented matrix  $[a_1, a_2, \dots, a_n, \vec{b}]$ . If this system is consistent then  $x_1 a_1 + x_2 a_2 + x_3 a_3 + x_4 a_4 = \vec{b}$ , which is a linear combination of the columns of  $A$ .

Question 2 Let  $A_{m \times n} = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}$

$m \times n, n \times 1$   $Ax = \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & \vdots & \vdots \\ a_{m1} & \dots & a_{mn} \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$  To multiply, the # columns of  $A$  must equal the # rows of  $x$ . Assuming this condition is met,  $Ax = \begin{bmatrix} a_{11}x_1 + \dots + a_{1n}x_n \\ \vdots \\ a_{m1}x_1 + \dots + a_{mn}x_n \end{bmatrix}$  as the matrix resulting from  $Ax$  will have dimensions  $m \times 1$ . Further simplifying  $Ax$ , we get  $\begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix} \neq \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix}$ , meaning  $\vec{x} = \vec{0}$

is not in the solution set of  $Ax$ .

Question 3 If  $W$  is linearly dependent, then by the definition of linear dependence,  $C_1 \vec{v} + C_2 \vec{w} + C_3 (2\vec{v} - 3\vec{w}) = \vec{0}$ , has a nontrivial solution. The equation breaks into,  $\vec{v}(C_1 + 2C_3) + \vec{w}(C_2 - 3C_3) = \vec{0}$ , and for this to be true  $C_1 + 2C_3 = 0$ , and  $C_2 - 3C_3 = 0$ . From these equations,  $C_1 = -2C_3$  and  $C_2 = 3C_3$ , meaning  $C_3$  is a free variable. Since  $C_3$  is free, there are infinitely many values of  $C_1, C_2$ , and  $C_3$  that solve the equation, thus  $W$  is linear dependent, as a nontrivial solution exists.



Question 4 Since  $\vec{u}$  and  $\vec{v}$  are linearly independent then for  $\vec{u}$  and  $\vec{v}$ , then  $X_1\vec{u} + X_2\vec{v} = \vec{0}$ , only when has the trivial solution of  $X_1 = 0$  and  $X_2 = 0$ .

Since  $u$  and  $v$  are linearly independent,  $u$  and  $v$  must have basic variables and a pivot, in every column. Therefore, the reduced echelon form of  $Ax = \vec{u}$  is  $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$  meaning that  $x_1 = 0$  and  $x_2 = 0$ , giving us the trivial solution, and  $x_1$  and  $x_2$  must be basic variables.

Let  $\vec{v}$  be a solution to  $Ax = \vec{v}$ , thus  $A\vec{v} = \vec{v}$ .

Let  $\vec{v}'$  be a solution to  $Ax = \vec{v}$ , thus  $A\vec{v}' = \vec{v}$ .

This means that  $A\vec{v} = A\vec{v}' = \vec{v} = \vec{v}'$ .

assuming about  $A\vec{v} = A\vec{v}' = \vec{v} = \vec{v}'$ .

The unique solution to  $Ax = \vec{0}$  is  $\vec{x} = \vec{0}$ , meaning  $\vec{v}' - \vec{v} = \vec{0}$ , and  $\vec{v}' = \vec{v}$ . Since the two  $\vec{v}$  vectors are equal,  $Ax = \vec{v}$  can only have the unique solution  $\vec{v}$ .

$$\begin{bmatrix} a_{11}x_1 + a_{12}x_2 & u_1 \\ a_{21}x_1 + a_{22}x_2 & u_2 \end{bmatrix}$$

To prove  $\vec{u}$  and  $\vec{v}$  are linearly independent,

suppose they are linearly dependent, meaning

$\vec{v}$  is a multiple of  $\vec{u}$ . Thus  $\vec{v} = c\vec{u}$  where  $c$  is a constant.

Then  $A\vec{u} = cA\vec{v}$ , by multiplying by  $A$ .

Since  $A\vec{u} = \vec{u}$  and  $A\vec{v} = \vec{v}$ ,  $\vec{u} = c\vec{v}$ .

Since  $\vec{v}$  is a multiple of  $\vec{u}$ ,  $\vec{u}$  and  $\vec{v}$  are linearly dependent.

Since the contrapositive is true ( $\vec{u}$  and  $\vec{v}$  are linearly dependent, then  $\vec{u}$  and  $\vec{v}$  are linearly dependent), the original statement is true. Thus if  $\vec{u}$  and  $\vec{v}$  are linearly independent, then  $\vec{u}$  and  $\vec{v}$  are linearly independent.