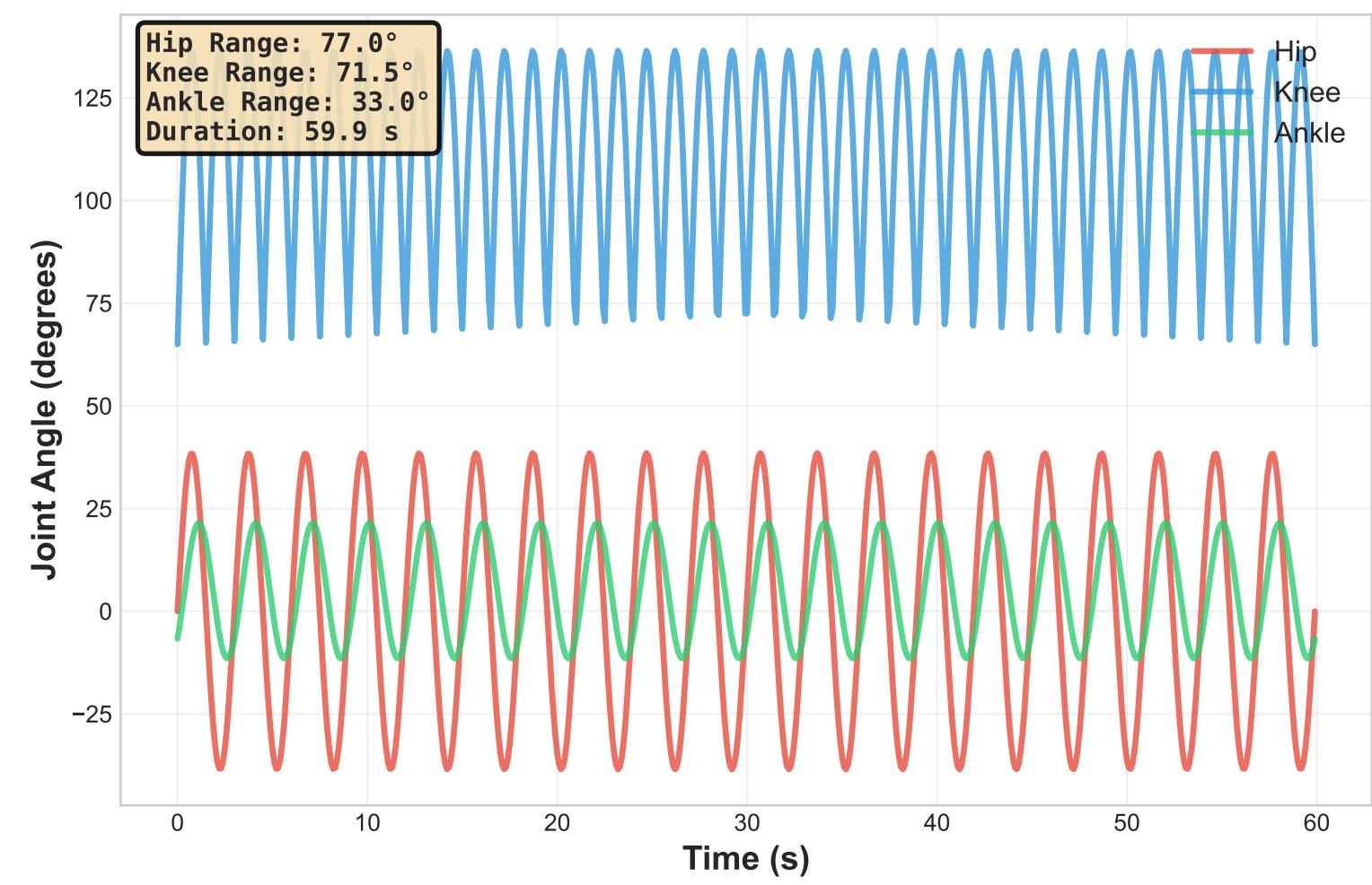
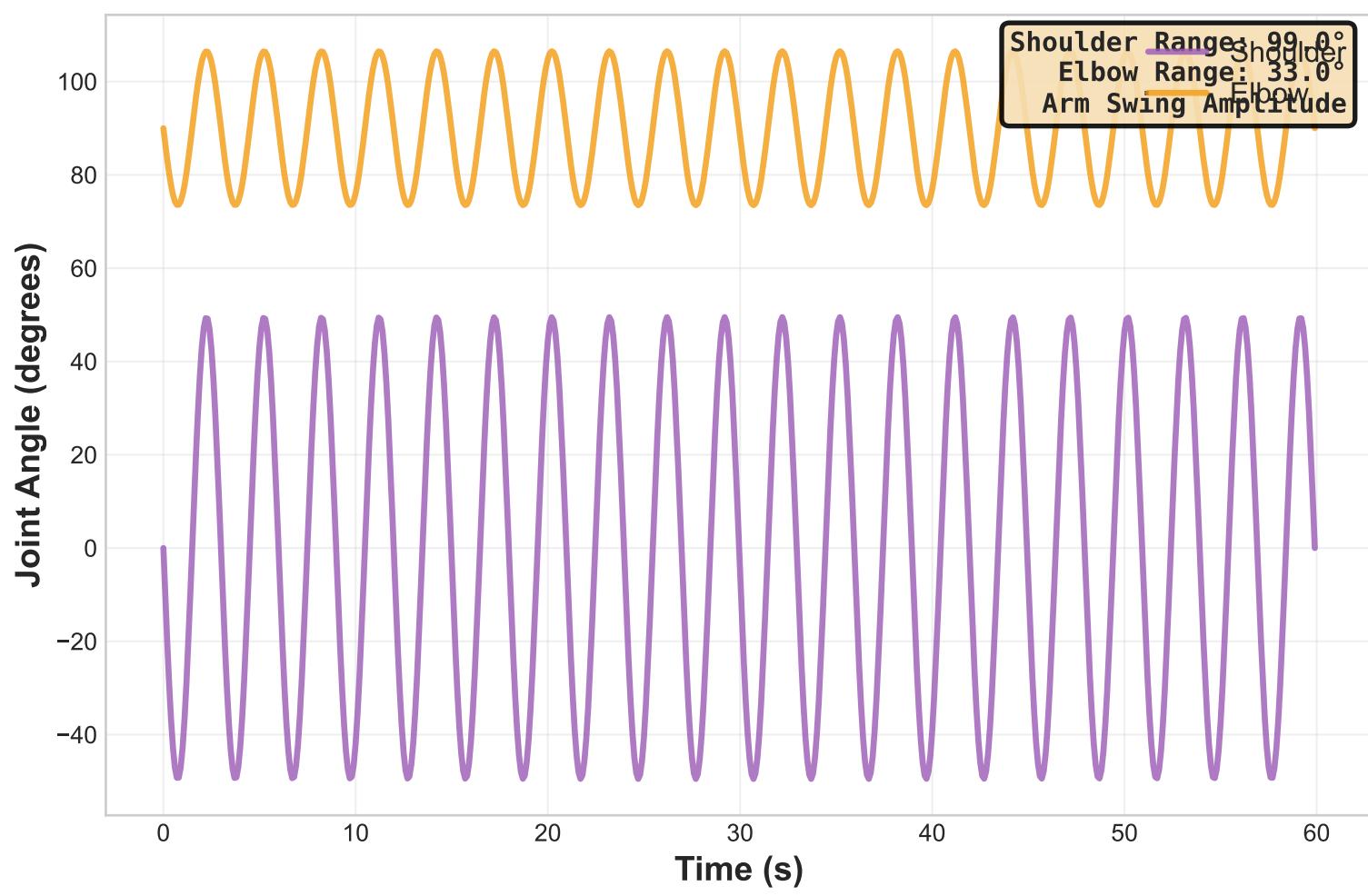


# Joint Angle Kinematics During Running

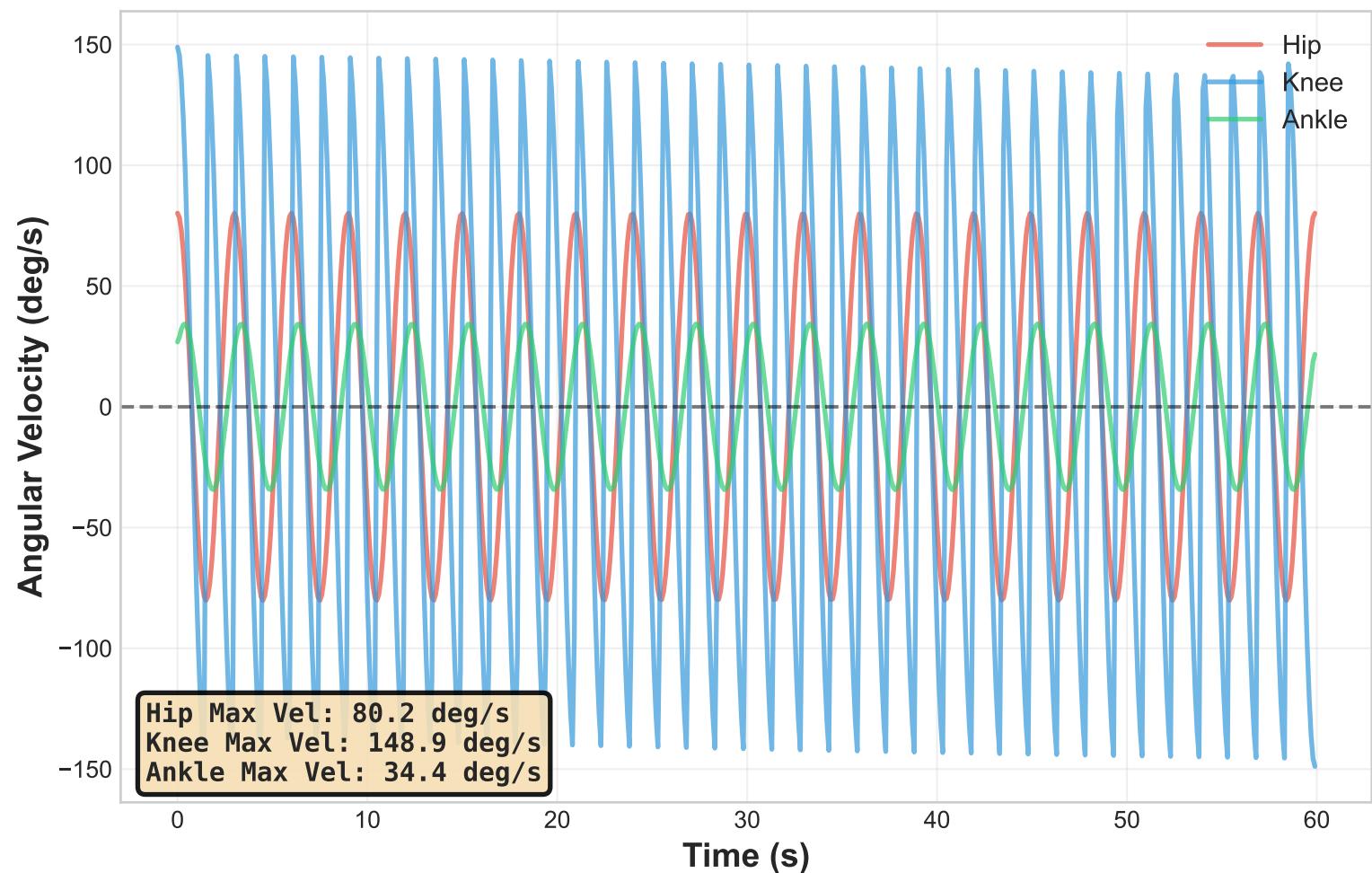
**A**



**B**



**C**



**D**

