

# A Function-Space Tour of Data Science: Banach Spaces and Sparse Methods

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## 1 Dual Spaces and Predual Spaces

**Definition 1.1** (Dual space). Let  $\mathcal{F}$  be a normed space. The (*continuous*) *dual space* of  $\mathcal{F}$  is denoted by  $\mathcal{F}'$  and is the space of continuous linear functionals on  $\mathcal{F}$ . We write the canonical pairing as  $\langle \cdot, \cdot \rangle : \mathcal{F} \times \mathcal{F}' \rightarrow \mathbb{R}$ , i.e., if  $f \in \mathcal{F}$  and  $g \in \mathcal{F}'$ ,  $\langle f, g \rangle = g[f]$ .

**Definition 1.2** (Bidual and canonical embedding). The *bidual* is  $\mathcal{F}'' := (\mathcal{F}')'$ . There is a canonical linear map  $\iota : \mathcal{F} \rightarrow \mathcal{F}''$  defined by

$$(\iota(f))(g) := g[f] = \langle f, g \rangle, \quad g \in \mathcal{F}'. \quad (1)$$

*Remark 1.3.* We always have that  $\|\iota(f)\|_{\mathcal{F}''} = \|f\|_{\mathcal{F}}$  (so  $\iota$  is an isometry). In particular, we can always identify  $\mathcal{F} \subset \mathcal{F}''$ . If  $\iota$  is onto, we say  $\mathcal{F}$  is *reflexive* and we can identify  $\mathcal{F} = \mathcal{F}''$ .

**Definition 1.4** (Dual norm). For  $g \in \mathcal{F}'$ , we define the *dual norm* as

$$\|g\|_{\mathcal{F}'} := \sup_{\substack{f \in \mathcal{F} \\ \|f\|_{\mathcal{F}} \leq 1}} |\langle f, g \rangle|. \quad (2)$$

When endowed with this norm, the dual space  $\mathcal{F}'$  is a Banach space.

**Definition 1.5** (Predual). A Banach space  $\mathcal{X}$  is a *predual* of a Banach space  $\mathcal{F}$  if  $\mathcal{F} = \mathcal{X}'$  (isometrically). In this case we write the pairing as  $\langle g, f \rangle$  for  $g \in \mathcal{X}$  and  $f \in \mathcal{F} = \mathcal{X}'$ .

*Remark 1.6.* Not every Banach space admits a predual. For example,  $L^1(\mathbb{R})$  has no predual.

**Definition 1.7** (Strong and weak convergence). Let  $\mathcal{F}$  be a Banach space. A sequence  $\{f_n\}_{n \in \mathbb{N}} \subset \mathcal{F}$  converges *strongly* (in norm) to  $f \in \mathcal{F}$  if

$$\|f_n - f\|_{\mathcal{F}} \rightarrow 0 \text{ as } n \rightarrow \infty. \quad (3)$$

A sequence  $\{f_n\}_{n \in \mathbb{N}} \subset \mathcal{F}$  converges *weakly* to  $f \in \mathcal{F}$  if

$$\langle f_n, g \rangle \rightarrow \langle f, g \rangle \text{ as } n \rightarrow \infty \text{ for all } g \in \mathcal{F}'. \quad (4)$$

*Remark 1.8.* The weak topology is still typically too fine for closed and bounded sets to be compact.

**Definition 1.9** (Weak\* convergence). Let  $\mathcal{F}$  be a Banach space such that  $\mathcal{F} = \mathcal{X}'$  is a dual space with predual  $\mathcal{X}$ . A sequence  $\{f_n\}_{n \in \mathbb{N}} \subset \mathcal{F}$  converges *weak\** to  $f \in \mathcal{F}$  if

$$\langle g, f_n \rangle \rightarrow \langle g, f \rangle \text{ as } n \rightarrow \infty \text{ for all } g \in \mathcal{X}. \quad (5)$$

**Fact 1.10.** *If  $\mathcal{H}$  is a Hilbert space, then the weak and weak\* topologies coincide (after identifying  $\mathcal{H} = \mathcal{H}'$  via the Riesz Representation Theorem). More generally, if  $\mathcal{F}$  is reflexive, then the weak and weak\* coincide (by the identification  $\mathcal{F} = \mathcal{F}''$ ).*

## 2 Banach–Alaoglu and Dixmier–Ng Theorems and Compactness

**Theorem 2.1** (Banach–Alaoglu). *Let  $\mathcal{X}$  be a Banach space and let  $\mathcal{F} = \mathcal{X}'$ . Then the closed unit ball*

$$B_{\mathcal{F}} := \{f \in \mathcal{F} : \|f\|_{\mathcal{F}} \leq 1\} \quad (6)$$

*is compact in the weak\* topology on  $\mathcal{F}$  (induced by  $\mathcal{X}$ ).*

*Remark 2.2.* For optimization over dual Banach spaces, the weak\* topology is often the “correct” topology to work with.

**Theorem 2.3** (Dixmier–Ng). *Let  $\mathcal{F}$  be a normed space and let  $\tau$  be a locally convex Hausdorff topology on  $\mathcal{F}$ . The following are equivalent:*

- (1) *The closed unit ball  $B_{\mathcal{F}}$  is  $\tau$ -compact.*
- (2) *There exists a Banach space  $\mathcal{X}$  such that  $\mathcal{F} = \mathcal{X}'$ .*

*Remark 2.4.* The Dixmier–Ng establishes a fundamental impossibility result: If a Banach space does not have a predual, there does not exist any “reasonable” topology such that its closed unit ball is compact.

## 3 Riesz–Markov–Kakutani Representation Theorem

**Theorem 3.1** (Riesz–Markov–Kakutani). *Let  $\Xi$  be a compact (resp. locally compact) Hausdorff space. Let  $C(\Xi)$  (resp.  $C_0(\Xi)$ ) denote continuous real-valued functions on  $\Xi$  (continuous real-valued functions on  $\Xi$  vanishing at infinity) endowed with the  $L^\infty$ -norm. Then,  $C(\Xi)' = \mathcal{M}(\Xi)$  (resp.  $C_0(\Xi)' = \mathcal{M}(\Xi)$ ), where  $\mathcal{M}(\Xi)$  is the space of finite (signed) Radon measures on  $\Xi$ .*

## 4 Fisher–Jerome Theorem

Let  $\varphi : \Omega \times \Xi \rightarrow \mathbb{R}$  be such that for each  $x$ ,  $\varphi(x, \cdot)$  is in  $C(\Xi)$  (resp.  $C_0(\Xi)$ ) when  $\Xi$  is a compact (resp. locally compact) Hausdorff space. Define the notation  $\varphi_\xi(x) := \varphi(x, \xi)$ . Furthermore, define

$$f_\nu(x) := \int_{\Xi} \varphi_\xi(x) d\nu(\xi). \quad (7)$$

**Theorem 4.1.** *If, for every  $y \in \mathbb{R}$ , the loss function  $\mathcal{L}(y, \cdot) : \mathbb{R} \rightarrow \mathbb{R} \cup \{+\infty\}$  is lower semicontinuous (l.s.c.),  $\mathcal{L}(y, 0) < +\infty$ ,<sup>1</sup> and bounded from below, the solution set*

$$S := \arg \min_{\nu \in \mathcal{M}(\Xi)} \left\{ J(\nu) = \sum_{i=1}^n \mathcal{L}(y_i, f_\nu(x_i)) + \lambda \|\nu\|_{\mathcal{M}} \right\}, \quad \lambda > 0, \quad (8)$$

*is nonempty. Furthermore, there always exists a solution  $\nu^* \in S$  that yields the representation*

$$f_{\nu^*} = \sum_{k=1}^K v_k \varphi_{\xi_k}, \quad K \leq n. \quad (9)$$

*Proof.* Since  $\mathcal{L}(y, \cdot)$  is l.s.c.,  $J$  is weak\* l.s.c. Indeed,

- the functional  $\nu \mapsto f_\nu(x)$  is weak\* continuous for all  $x \in \Omega$  since

$$f_\nu(x) = \int_{\Xi} \varphi(x, \xi) d\nu(\xi) = \langle \varphi(x, \cdot), \nu \rangle \quad (10)$$

and  $\varphi(x, \cdot) \in C(\Xi)$  (resp.  $C_0(\Xi)$ ) when  $\Xi$  is compact (resp. locally compact).

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<sup>1</sup>This ensures that  $J$  is proper on  $\mathcal{M}(\Xi)$ .

- the norm  $\|\cdot\|_{\mathcal{M}}$  is weak\* l.s.c. on  $\mathcal{M}(\Xi)$  since

$$\|\nu\|_{\mathcal{M}} = \sup_{\substack{\varphi \in C(\Xi) \text{ or } C_0(\Xi) \\ \|\varphi\|_{L^\infty} = 1}} |\langle \varphi, \nu \rangle|, \quad (11)$$

where we recall that the sup of weak\* continuous functions is weak\* l.s.c.

Since  $\mathcal{L}(y, \cdot)$  is bounded from below,  $J$  is coercive. Indeed,  $J$  is the sum of something bounded from below and something coercive (all norms are obviously coercive). Since  $J$  is weak\* l.s.c., it has weak\* closed sublevel sets. Furthermore, since  $J$  is coercive, it has bounded sublevel sets. Thus, it has weak\* compact sublevel sets and hence minimizers exist.

Let  $\widehat{\nu} \in S$  be any minimizer and set  $z_i := f_{\widehat{\nu}}(x_i)$  for  $i = 1, \dots, n$ . Consider the auxiliary problem

$$\min_{\nu \in \mathcal{M}(\Xi)} \|\nu\|_{\mathcal{M}} \quad \text{s.t.} \quad f_\nu(x_i) = z_i, i = 1, \dots, n. \quad (12)$$

Its feasible set is nonempty (it contains  $\widehat{\nu}$ ). Let  $S_z$  be its solution set. Because the constraint set is weak\*-closed and the objective is weak\* l.s.c. with weak\* compact sublevel sets,  $S_z$  is nonempty, weak\* compact, and convex. Thus,  $S_z$  has extreme points by the Krein–Milman theorem. Finally, any solution to (12) is a solution to the original problem (8). Thus, it suffices to show that there exists a solution to (12) that is supported on at most  $n$  points.

Let  $\nu^*$  be an extreme point of  $S_z$ . We claim that  $\nu^*$  is supported on at most  $n$  points. Assume for contradiction that  $\nu^*$  is supported on more than  $n$  points. Let  $\nu^* = \nu_+^* - \nu_-^*$  be its Jordan decomposition and let  $\Xi = P \sqcup N$  be a Hahn decomposition for  $\nu^*$  (so  $\nu^* \geq 0$  on  $P$  and  $\nu^* \leq 0$  on  $N$ ). Since  $|\nu^*|(\Xi) > 0$  and  $\text{supp}(|\nu^*|)$  has more than  $n$  points, we can find pairwise disjoint Borel sets  $A_1, \dots, A_{n+1} \subset \Xi$  such that  $|\nu^*|(A_j) > 0$  for each  $j$ , and each  $A_j$  lies entirely in  $P$  or entirely in  $N$ . Finally, define  $A_0 = \Xi \setminus \bigcup_{j=1}^{n+1} A_j$ . Define the restricted signed measures

$$\nu_j := \nu^*|_{A_j}, \quad j = 0, \dots, n+1. \quad (13)$$

Then,  $\nu^* = \sum_{j=0}^{n+1} \nu_j$ , and the signed measures  $\nu_0, \nu_1, \dots, \nu_{n+1}$  are pairwise mutually singular.

For each  $j$ , define  $b_j \in \mathbb{R}^n$  by

$$(b_j)_i := f_{\nu_j}(x_i), \quad i = 1, \dots, n. \quad (14)$$

Since we have  $n+1$  vectors in  $\mathbb{R}^n$ , they are linearly dependent. Thus, there exist scalars  $a_1, \dots, a_{n+1}$ , not all zero, such that  $\sum_{j=1}^{n+1} a_j b_j = 0$ . Let

$$\mu := \sum_{j=1}^{n+1} a_j \nu_j. \quad (15)$$

Then for each  $i$ ,

$$f_\mu(x_i) = \sum_{j=1}^{n+1} a_j f_{\nu_j}(x_i) = \sum_{j=1}^{n+1} a_j (b_j)_i = 0, \quad (16)$$

so  $\nu^* + t\mu$  satisfies the constraints in (12) for all  $t \in \mathbb{R}$ .

Because each  $\nu_j$  has constant sign, there exists  $\varepsilon > 0$  such that  $1 \pm \varepsilon a_j \geq 0$  for all  $j$  (e.g., take  $\varepsilon \leq \min_{a_j \neq 0} 1/(2|a_j|)$ ). For such an  $\varepsilon$ ,

$$\nu^* \pm \varepsilon \mu = \nu_0 + \sum_{j=1}^{n+1} (1 \pm \varepsilon a_j) \nu_j, \quad (17)$$

and no sign flips occur within each  $A_j$ . Consequently, for  $t \in [-\varepsilon, \varepsilon]$  the map  $t \mapsto \|\nu^* + t\mu\|_{\mathcal{M}}$  is affine:

$$\|\nu^* + t\mu\|_{\mathcal{M}} = \|\nu_0\|_{\mathcal{M}} + \sum_{j=1}^{n+1} \|(1 + ta_j)\nu_j\|_{\mathcal{M}} = \|\nu_0\|_{\mathcal{M}} + \sum_{j=1}^{n+1} (1 + ta_j) \|\nu_j\|_{\mathcal{M}}. \quad (18)$$

where we used the fact that the  $A_j$  are disjoint. But  $\nu^*$  minimizes  $\nu \mapsto \|\nu\|_{\mathcal{M}}$  over the feasible affine set, so  $t = 0$  is a minimizer of this affine function on  $[-\varepsilon, \varepsilon]$ . Therefore its slope must be zero, i.e.,

$$\sum_{j=1}^{n+1} a_j \|\nu_j\|_{\mathcal{M}} = 0, \quad (19)$$

and hence

$$\|\nu^* \pm \varepsilon \mu\|_{\mathcal{M}} = \|\nu^*\|_{\mathcal{M}}. \quad (20)$$

Thus,  $\nu^* \pm \varepsilon \mu \in S_z$  and they are distinct (since  $\mu \neq 0$ ). Thus,

$$\nu^* = \frac{1}{2}(\nu^* + \varepsilon \mu) + \frac{1}{2}(\nu^* - \varepsilon \mu), \quad (21)$$

contradicting that  $\nu^*$  is an extreme point of  $S_z$ .

We conclude that  $\nu^*$  is supported on at most  $n$  points, i.e.,

$$\nu^* = \sum_{k=1}^K v_k \delta_{\xi_k}, \quad K \leq n, \quad (22)$$

and therefore,

$$f_{\nu^*} = \int_{\Xi} \varphi_{\xi} d\nu^*(\xi) = \sum_{k=1}^K v_k \varphi_{\xi_k}, \quad (23)$$

which completes the proof.  $\square$

*Remark 4.2.* The  $\mathcal{M}$ -norm is not strictly convex, so uniqueness of minimizers for (8) is hard to guarantee, just like finite-dimensional  $\ell^1$ -minimization problems. In finite dimensions, compressed sensing gives conditions implying uniqueness. In infinite dimensions, various “off-the-grid” analogues exist which provide conditions for uniqueness using tools from convex duality.