Sistem Programlama

Final Ödevi:

Character Device uygulaması-arduino ile iletişim

Grup Adi:ALFA

Grup Üyeleri:

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1.Kodlar

CharacterDev

```
#include<linux/kernel.h>
#includeux/init.h>
#include<linux/module.h>
#includeux/syscalls.h>
#includeux/string.h>
#include<linux/file.h>
#include<linux/fs.h>
#includeux/fcntl.h>
#include<asm/uaccess.h>
#includeux/delay.h>
#define FILE_DIR "/dev/ttyUSBO" //Arduino cihazının bağlı olduğu port
//Module nitelikleri
MODULE_LICENSE("GPL");
MODULE_DESCRIPTION("Character Device Program");
MODULE_AUTHOR("ALFA");
static char msg[50]; //Argüman metnini tutar
static short readPos=0; //Okuma pozisyonu
static int times=0; //Character device erişim sayısını tutar
static int dev_open(struct inode *,struct file *);
static int dev_rls(struct inode *,struct file *);
static ssize_t dev_read(struct file *,char *,size_t,loff_t *);
static ssize_t dev_write(struct file *,const char*,size_t,loff_t *);
static void write_file(const char*,const char*);
static struct file_operations cmd_file_ops={
    .read=dev_read,
    .open=dev_open,
    .write=dev write,
    .release=dev rls
};
int init_module(){
  printk(KERNEL_INFO "Init module girdi\n");
    int MajorNum=register_chrdev(70,"CharacterDev",&cmd_file_ops);
    if(MajorNum<0)printk(KERN_ALERT "Yüklenirken hata oldu..\n");
    else printk(KERN_INFO "Yüklendi\n");
```

```
return MajorNum;
}
void cleanup_module(){
   unregister_chrdev(70,"CharacterDev");
    printk(KERN_INFO"Silindi\n");
}
static int dev_open(struct inode *inod,struct file *fil){
    times++;
    printk(KERN_INFO "Cihaz %d kere açıldı\n",times);
    return 0;
}
static ssize_t dev_read(struct file*filp,char *buff,size_t len,loff_t *off)
  printk(KERN_INFO "dev_read a girdi\n");
    short count =0; //Okunan karakter sayısını tutan değişken
    while(len && (msg[readPos]!=0))
{
    put_user(msg[readPos],buff++);
    count++;
    len--;
    readPos++;
}
    return count;
}
static ssize_t dev_write(struct file *filp,const char *buff,size_t len,loff_t *off)
  printk(KERN_INFO "dev_write a girdi\n");
    short ind =0;
    short count=0;
    memset(msg,0,50); //Metin için hafıza tahsis edilir
    readPos=0;
    while(len>0){
         msg[count++]=buff[ind++];
    len--;
}
    write_file(FILE_DIR,msg);
    return count;
static int dev_rls(struct inode *inod,struct file *fil){
    printk(KERN_INFO"Cihaz kapandı\n");
    return 0;
}
```

```
static void write_file(const char*filename,const char* data){
  printk(KERN_INFO "write file a girdi");
    struct file *filp;
mm_segment_t oldfs;
    int ret;
    int count;
    filp=filp_open(filename,O_RDWR|O_APPEND,0644);
    if(IS_ERR(filp))
    {
    printk("Açılma hatası...\n");
    return;
    }
    for(count=0;data[count]!='\0';count++);
    msleep(5000);
    printk(KERN_INFO"Mesaj: %s",data);
    oldfs=get_fs();
    set_fs(get_ds());
    ret=kernel_write(filp,data,count,&filp->f_pos);
    set_fs(oldfs);
    filp_close(filp,NULL);
}
```

CKod

```
#include<stdio.h>
#include<fcntl.h>
#include<assert.h>
#include<string.h>
#include<ctype.h>
#include<stdlib.h>
#include<unistd.h>

int main(int argc,char *argv[]){

assert(argc>1); //Terminalden argüman girilip girilmediği kontrol edilir

FILE *arduino;
int index; //Argüman indislerini tutan değişken

char buf[20]; //Argüman olarak alınan metni tutan değişken
```

```
//metin için hafıza tahsis edilir
  memset(buf,0,20);
  strcpy(buf,argv[1]);
  for(index=2;index<argc;index++){</pre>
    strcat(buf," ");
    strcat(buf,argv[index]);
  }
  int fd=open("/dev/CharacterDev",O_RDWR);
  write(fd,buf,strlen(buf));
  close(fd);
  return 0;
}
Arduino Kodu
#include <LiquidCrystal.h>
LiquidCrystal lcd(12, 11, 5, 4, 3, 2);
void setup() {
 lcd.begin(16, 2);
 lcd.print("Grup Adi : Alfa..");
 Serial.begin(9600);
}
 if(Serial.available()>0){
  lcd.setCursor(0,0);
  for (int i = 0; i < 16; ++i){
   lcd.print(' ');
  qz}
  lcd.setCursor(0,0);
  lcd.print("Grup uyeleri : ");
```

```
lcd.setCursor(0,1);
String input = Serial.readString();
Serial.println(input);
lcd.print(input);
}
```

Makefile

```
obj-m += CharacterDev.o

all:
    make -C /lib/modules/$(shell uname -r)/build M=$(PWD) modules

clean:
    make -C /lib/modules/$(shell uname -r)/build M=$(PWD) clean

test:
    cc -o CKod CKod.c
```

2. Ekran Görüntüleri

make komutu

```
fundaaysel@fundaaysel-VirtualBox:~/Masaüstü/modules$ sudo su root@fundaaysel-VirtualBox:/home/fundaaysel/Masaüstü/modules# pico CharacterDev.c root@fundaaysel-VirtualBox:/home/fundaaysel/Masaüstü/modules# make make -C /lib/modules/4.18.12/build M=/home/fundaaysel/Masaüstü/modules modules make[1]: Entering directory '/home/fundaaysel/Masaüstü/linux-4.18.12'  
CC [M] /home/fundaaysel/Masaüstü/modules/CharacterDev.o Building modules, stage 2.  
MODPOST 1 modules  
CC /home/fundaaysel/Masaüstü/modules/CharacterDev.mod.o  
LD [M] /home/fundaaysel/Masaüstü/modules/CharacterDev.ko  
make[1]: Leaving directory '/home/fundaaysel/Masaüstü/linux-4.18.12'
```

insmod komutu

```
root@fundaaysel-VirtualBox:/home/fundaaysel/Masaüstü/modules# insmod CharacterDev.ko
root@fundaaysel-VirtualBox:/home/fundaaysel/Masaüstü/modules# mknod /dev/CharacterDev c 70 0
root@fundaaysel-VirtualBox:/home/fundaaysel/Masaüstü/modules# chmod a+rw /dev/CharacterDev
root@fundaaysel-VirtualBox:/home/fundaaysel/Masaüstü/modules# gcc -o CKod CKod.c
root@fundaaysel-VirtualBox:/home/fundaaysel/Masaüstü/modules#
```

dmesg

```
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```

Arduino'ya veri gönderme

```
root@fundaaysel-VirtualBox:/home/fundaaysel/Masaüstü/modules

Dosya Düzenle Görünüm Ara Uçbirim Yardım

root@fundaaysel-VirtualBox:/home/fundaaysel/Masaüstü/modules#./CKod Funda
root@fundaaysel-VirtualBox:/home/fundaaysel/Masaüstü/modules#./CKod Gokhan
root@fundaaysel-VirtualBox:/home/fundaaysel/Masaüstü/modules#./CKod Omer
root@fundaaysel-VirtualBox:/home/fundaaysel/Masaüsti/modules#./CKod Unal
root@fundaaysel-VirtualBox:/home/fundaaysel/Masaüstu/modules#./

/CKod Unal
```