

**Proposition 17.** Let  $\varphi : V \rightarrow X$  and  $\psi : W \rightarrow Y$  be linear transformations of finite dimensional vector spaces. Then the Kronecker product of matrices representing  $\varphi$  and  $\psi$  is a matrix representation of  $\varphi \otimes \psi$ .

### Example

Let  $V = X = \mathbb{R}^3$ , both with basis  $v_1, v_2, v_3$ , and  $W = Y = \mathbb{R}^2$ , both with basis  $w_1, w_2$ . Suppose  $\varphi : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  is the linear transformation given by  $\varphi(av_1 + bv_2 + cv_3) = cv_1 + 2av_2 - 3bv_3$  and  $\psi : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  is the linear transformation given by  $\psi(aw_1 + bw_2) = (a + 3b)w_1 + (4b - 2a)w_2$ . With respect to the chosen bases, the matrices for  $\varphi$  and  $\psi$  are

$$\begin{pmatrix} 0 & 0 & 1 \\ 2 & 0 & 0 \\ 0 & -3 & 0 \end{pmatrix} \quad \text{and} \quad \begin{pmatrix} 1 & 3 \\ -2 & 4 \end{pmatrix},$$

respectively. Then with respect to the ordered basis

$$\mathcal{B} = \{v_1 \otimes w_1, v_1 \otimes w_2, v_2 \otimes w_1, v_2 \otimes w_2, v_3 \otimes w_1, v_3 \otimes w_2\}$$

we have

$$M_{\mathcal{B}}^{\mathcal{B}}(\varphi \otimes \psi) = \left( \begin{array}{cc|cc|cc} 0 & 0 & 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 0 & -2 & 4 \\ \hline 2 & 6 & 0 & 0 & 0 & 0 \\ -4 & 8 & 0 & 0 & 0 & 0 \\ \hline 0 & 0 & -3 & -9 & 0 & 0 \\ 0 & 0 & 6 & -12 & 0 & 0 \end{array} \right),$$

obtained (as indicated by the dashed lines) by multiplying the  $2 \times 2$  matrix for  $\psi$  successively by the entries in the matrix for  $\varphi$ .

## EXERCISES

1. Let  $V$  be the collection of polynomials with coefficients in  $\mathbb{Q}$  in the variable  $x$  of degree at most 5. Determine the transition matrix from the basis  $1, x, x^2, \dots, x^5$  for  $V$  to the basis  $1, 1+x, 1+x+x^2, \dots, 1+x+x^2+x^3+x^4+x^5$  for  $V$ .
2. Let  $V$  be the vector space of the preceding exercise. Let  $\varphi = d/dx$  be the linear transformation of  $V$  to itself given by usual differentiation of a polynomial with respect to  $x$ . Determine the matrix of  $\varphi$  with respect to the two bases for  $V$  in the previous exercise.
3. Let  $V$  be the collection of polynomials with coefficients in  $F$  in the variable  $x$  of degree at most  $n$ . Determine the transition matrix from the basis  $1, x, x^2, \dots, x^n$  for  $V$  to the elements

$$1, x - \lambda, \dots, (x - \lambda)^{n-1}, (x - \lambda)^n$$

where  $\lambda$  is a fixed element of  $F$ . Conclude that these elements are a basis for  $V$ .

4. Let  $\varphi$  be the linear transformation of  $\mathbb{R}^2$  to itself given by rotation counterclockwise around the origin through an angle  $\theta$ . Show that the matrix of  $\varphi$  with respect to the standard basis for  $\mathbb{R}^2$  is  $\begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$ .
5. Show that the  $m \times n$  matrix  $A$  is nonsingular if and only if the linear transformation  $\varphi$  is a nonsingular linear transformation from the  $n$ -dimensional space  $V$  to the  $m$ -dimensional space  $W$ , where  $A = M_{\mathcal{B}}^{\mathcal{E}}(\varphi)$ , regardless of the choice of bases  $\mathcal{B}$  and  $\mathcal{E}$ .

6. Prove if  $\varphi \in \text{Hom}_F(F^n, F^m)$ , and  $\mathcal{B}, \mathcal{E}$  are the natural bases of  $F^n, F^m$  respectively, then the range of  $\varphi$  equals the span of the set of columns of  $M_{\mathcal{E}}^{\mathcal{B}}(\varphi)$ . Deduce that the rank of  $\varphi$  (as a linear transformation) equals the column rank of  $M_{\mathcal{E}}^{\mathcal{B}}(\varphi)$ .
7. Prove that any two similar matrices have the same row rank and the same column rank.
8. Let  $V$  be an  $n$ -dimensional vector space over  $F$  and let  $\varphi$  be a linear transformation of the vector space  $V$  to itself.
  - (a) Prove that if  $V$  has a basis consisting of eigenvectors for  $\varphi$  (cf. Exercise 8 of Section 1) then the matrix representing  $\varphi$  with respect to this basis (for both domain and range) is diagonal with the eigenvalues as diagonal entries.
  - (b) If  $A$  is the  $n \times n$  matrix representing  $\varphi$  with respect to a given basis for  $V$  (for both domain and range) prove that  $A$  is similar to a diagonal matrix if and only if  $V$  has a basis of eigenvectors for  $\varphi$ .
9. If  $W$  is a subspace of the vector space  $V$  stable under the linear transformation  $\varphi$  (i.e.,  $\varphi(W) \subseteq W$ ), show that  $\varphi$  induces linear transformations  $\varphi|_W$  on  $W$  and  $\tilde{\varphi}$  on the quotient vector space  $V/W$ . If  $\varphi|_W$  and  $\tilde{\varphi}$  are nonsingular prove  $\varphi$  is nonsingular. Prove the converse holds if  $V$  has finite dimension and give a counterexample with  $V$  infinite dimensional.
10. Let  $V$  be an  $n$ -dimensional vector space and let  $\varphi$  be a linear transformation of  $V$  to itself. Suppose  $W$  is a subspace of  $V$  of dimension  $m$  that is stable under  $\varphi$ .
  - (a) Prove that there is a basis for  $V$  with respect to which the matrix for  $\varphi$  is of the form

$$\begin{pmatrix} A & B \\ 0 & C \end{pmatrix}$$

where  $A$  is an  $m \times m$  matrix,  $B$  is an  $m \times (n-m)$  matrix and  $C$  is an  $(n-m) \times (n-m)$  matrix (such a matrix is called *block upper triangular*).

- (b) Prove that if there is a subspace  $W'$  invariant under  $\varphi$  so that  $V = W \oplus W'$  decomposes as a direct sum then the bases for  $W$  and  $W'$  give a basis for  $V$  with respect to which the matrix for  $\varphi$  is *block diagonal*:

$$\begin{pmatrix} A & 0 \\ 0 & C \end{pmatrix}$$

where  $A$  is an  $m \times m$  matrix and  $C$  is an  $(n-m) \times (n-m)$  matrix.

- (c) Prove conversely that if there is a basis for  $V$  with respect to which  $\varphi$  is block diagonal as in (b) then there are  $\varphi$ -invariant subspaces  $W$  and  $W'$  of dimensions  $m$  and  $n-m$ , respectively, with  $V = W \oplus W'$ .
11. Let  $\varphi$  be a linear transformation from the finite dimensional vector space  $V$  to itself such that  $\varphi^2 = \varphi$ .
    - (a) Prove that  $\text{image } \varphi \cap \ker \varphi = 0$ .
    - (b) Prove that  $V = \text{image } \varphi \oplus \ker \varphi$ .
    - (c) Prove that there is a basis of  $V$  such that the matrix of  $\varphi$  with respect to this basis is a diagonal matrix whose entries are all 0 or 1.

A linear transformation  $\varphi$  satisfying  $\varphi^2 = \varphi$  is called an *idempotent* linear transformation. This exercise proves that idempotent linear transformations are simply projections onto some subspace.

12. Let  $V = \mathbb{R}^2$ ,  $v_1 = (1, 0)$ ,  $v_2 = (0, 1)$ , so that  $v_1, v_2$  are a basis for  $V$ . Let  $\varphi$  be the linear transformation of  $V$  to itself whose matrix with respect to this basis is  $\begin{pmatrix} 2 & 1 \\ 0 & 2 \end{pmatrix}$ . Prove that if  $W$  is the subspace generated by  $v_1$  then  $W$  is stable under the action of  $\varphi$ . Prove that there is no subspace  $W'$  invariant under  $\varphi$  so that  $V = W \oplus W'$ .

13. Let  $V$  be a vector space of dimension  $n$  and let  $W$  be a vector space of dimension  $m$  over a field  $F$ . Suppose  $A$  is the  $m \times n$  matrix representing a linear transformation  $\varphi$  from  $V$  to  $W$  with respect to the bases  $\mathcal{B}_1$  for  $V$  and  $\mathcal{E}_1$  for  $W$ . Suppose similarly that  $B$  is the  $m \times n$  matrix representing  $\varphi$  with respect to the bases  $\mathcal{B}_2$  for  $V$  and  $\mathcal{E}_2$  for  $W$ . Let  $P = M_{\mathcal{B}_2}^{\mathcal{B}_1}(I)$  where  $I$  denotes the identity map from  $V$  to  $V$ , and let  $Q = M_{\mathcal{E}_2}^{\mathcal{E}_1}(I)$  where  $I$  denotes the identity map from  $W$  to  $W$ . Prove that  $Q^{-1} = M_{\mathcal{E}_1}^{\mathcal{E}_2}(I)$  and that  $Q^{-1}AP = B$ , giving the general relation between matrices representing the same linear transformation but with respect to different choices of bases.

The following exercises recall the *Gauss–Jordan* elimination process. This is one of the fastest computational methods for the solution of a number of problems involving vector spaces — solving systems of linear equations, determining inverses of matrices, computing determinants, determining the span of a set of vectors, determining linear independence of a set of vectors etc.

Consider the system of  $m$  linear equations

$$\begin{aligned} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n &= c_1 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n &= c_2 \\ &\vdots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n &= c_m \end{aligned} \tag{11.4}$$

in the  $n$  unknowns  $x_1, x_2, \dots, x_n$  where  $a_{ij}, c_i, i = 1, 2, \dots, m, j = 1, 2, \dots, n$  are elements of the field  $F$ . Associated to this system is the *coefficient matrix*:

$$A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{pmatrix}$$

and the *augmented matrix*:

$$(A | C) = \left( \begin{array}{cccc|c} a_{11} & a_{12} & \dots & a_{1n} & c_1 \\ a_{21} & a_{22} & \dots & a_{2n} & c_2 \\ \vdots & \vdots & & \vdots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} & c_m \end{array} \right)$$

(the term *augmented* refers to the presence of the column matrix  $C = (c_i)$  in addition to the coefficient matrix  $A = (a_{ij})$ ). The set of solutions in  $F$  of this system of equations is not altered if we perform any of the following three operations:

- (1) interchange any two equations
- (2) add a multiple of one equation to another
- (3) multiply any equation by a nonzero element from  $F$ ,

which correspond to the following three *elementary row operations* on the augmented matrix:

- (1) interchange any two rows
- (2) add a multiple of one row to another
- (3) multiply any row by a unit in  $F$ , i.e., by any nonzero element in  $F$ .

If a matrix  $A$  can be transformed into a matrix  $C$  by a series of elementary row operations then  $A$  is said to be *row reduced* to  $C$ .

14. Prove that if  $A$  can be row reduced to  $C$  then  $C$  can be row reduced to  $A$ . Prove that the relation " $A \sim C$  if and only if  $A$  can be row reduced to  $C$ " is an equivalence relation. [Observe that the elementary row operations are reversible.]

Matrices lying in the same equivalence class under this equivalence relation are said to be *row equivalent*.

15. Prove that the row rank of two row equivalent matrices is the same. [It suffices to prove this for two matrices differing by an elementary row operation.]

An  $m \times n$  matrix is said to be in *reduced row echelon form* if

- (a) the first nonzero entry  $a_{ij}$  in row  $i$  is 1 and all other entries in the corresponding  $j_i^{\text{th}}$  column are zero, and  
 (b)  $j_1 < j_2 < \dots < j_r$  where  $r$  is the number of nonzero rows, i.e., the number of initial zeros in each row is strictly increasing (hence the term *echelon*).

An augmented matrix  $(A | C)$  is said to be in reduced row echelon form if its coefficient matrix  $A$  is in reduced row echelon form. For example, the following two matrices are in reduced row echelon form:

$$\left( \begin{array}{cccccc|c} 1 & 0 & 5 & 7 & 0 & 3 & 0 \\ 0 & 1 & -1 & 1 & 0 & -4 & -1 \\ 0 & 0 & 0 & 0 & 1 & 6 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right) \quad \left( \begin{array}{cccc|c} 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 & -3 \end{array} \right)$$

(with  $j_1 = 1, j_2 = 2, j_3 = 5$  for the first matrix and  $j_1 = 2, j_2 = 4$  for the second matrix). The first nonzero entry in any given row of the coefficient matrix of a reduced row echelon augmented matrix (in position  $(i, j_i)$  by definition) is sometimes referred to as a *pivotal* element (so the pivotal elements in the first matrix are in positions  $(1,1)$ ,  $(2,2)$  and  $(3,5)$  and the pivotal elements in the second matrix are in positions  $(1,2)$  and  $(2,4)$ ). The columns containing pivotal elements will be called *pivotal* columns and the columns of the coefficient matrix not containing pivotal elements will be called *nonpivotal*.

16. Prove by induction that any augmented matrix can be put in reduced row echelon form by a series of elementary row operations.  
 17. Let  $A$  and  $C$  be two matrices in reduced row echelon form. Prove that if  $A$  and  $C$  are row equivalent then  $A = C$ .  
 18. Prove that the row rank of a matrix in reduced row echelon form is the number of nonzero rows.  
 19. Prove that the reduced row echelon forms of the matrices

$$\left( \begin{array}{cccccc|c} 1 & 1 & 4 & 8 & 0 & -1 & -1 \\ 1 & 2 & 3 & 9 & 0 & -5 & -2 \\ 0 & -2 & 2 & -2 & 1 & 14 & 3 \\ 1 & 4 & 1 & 11 & 0 & -13 & -4 \end{array} \right) \quad \left( \begin{array}{cccc|c} 0 & -3 & 3 & 1 & 5 \\ 0 & 1 & -1 & 0 & 0 \\ 0 & 2 & -2 & 0 & -3 \end{array} \right)$$

are the two matrices preceding Exercise 16.

The point of the reduced row echelon form is that the corresponding system of linear equations is in a particularly simple form, from which the solutions to the system  $AX = C$  in (4) can be determined immediately:

20. (*Solving Systems of Linear Equations*) Let  $(A' | C')$  be the reduced row echelon form of the augmented matrix  $(A | C)$ . The number of zero rows of  $A'$  is clearly at least as great as the number of zero rows of  $(A' | C')$ .