

linear transformation T .

For example, suppose V is a vector space of dimension n over F and we choose a basis for V . Then giving a linear transformation T of V to itself is the same thing as giving an $n \times n$ matrix A with coefficients in F (and choosing a different basis for V gives a different matrix B for T which is similar to A i.e., is of the form $P^{-1}AP$ for some invertible matrix P which defines the change of basis). We shall see that the Fundamental Theorem in this situation implies (under the assumption that the field F contains all the “eigenvalues” for the given linear transformation T) that there is a basis for V so that the associated matrix for T is *as close to being a diagonal matrix as possible* and so has a particularly simple form. This is the *Jordan canonical form*. The *rational canonical form* is another simple form for the matrix for T (that does not require the eigenvalues for T to be elements of F). In this way we shall be able to give canonical forms for arbitrary $n \times n$ matrices over fields F , that is, find matrices which are similar to a given $n \times n$ matrix and which are particularly simple (almost diagonal, for example).

Example

Let $V = \mathbb{Q}^3 = \{(x, y, z) \mid x, y, z \in \mathbb{Q}\}$ be the usual 3-dimensional vector space of ordered 3-tuples with entries from the field $F = \mathbb{Q}$ of rational numbers and suppose T is the linear transformation

$$T(x, y, z) = (9x + 4y + 5z, -4x - 3z, -6x - 4y - 2z), \quad x, y, z \in \mathbb{Q}.$$

If we take the standard basis $e_1 = (1, 0, 0)$, $e_2 = (0, 1, 0)$, $e_3 = (0, 0, 1)$ for V then the matrix A representing this linear transformation is

$$A = \begin{pmatrix} 9 & 4 & 5 \\ -4 & 0 & -3 \\ -6 & -4 & -2 \end{pmatrix}.$$

We shall see that the Jordan canonical form for this matrix A is the much simpler matrix

$$B = \begin{pmatrix} 2 & 1 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{pmatrix}$$

obtained by taking instead the basis $f_1 = (2, -1, -2)$, $f_2 = (1, 0, -1)$, $f_3 = (3, -2, -2)$ for V , since in this case

$$T(f_1) = T(2, -1, -2) = (4, -2, -4) = 2 \cdot f_1 + 0 \cdot f_2 + 0 \cdot f_3$$

$$T(f_2) = T(1, 0, -1) = (4, -1, -4) = 1 \cdot f_1 + 2 \cdot f_2 + 0 \cdot f_3$$

$$T(f_3) = T(3, -2, -2) = (9, -6, -6) = 0 \cdot f_1 + 0 \cdot f_2 + 3 \cdot f_3,$$

so the columns of the matrix representing T with respect to this basis are $(2, 0, 0)$, $(1, 2, 0)$ and $(0, 0, 3)$, i.e., T has matrix B with respect to this basis. In particular A is similar to the simpler matrix B .

In fact this linear transformation T *cannot* be diagonalized (i.e., there is no choice of basis for V for which the corresponding matrix is a diagonal matrix) so that the matrix B is as close to a diagonal matrix for T as is possible.

The first section below gives some general definitions and states and proves the Fundamental Theorem over an arbitrary P.I.D., after which we return to the application to canonical forms (the application to abelian groups appears in Chapter 5). These applications can be read independently of the general proof. An alternate and computationally useful proof valid for Euclidean Domains (so in particular for the rings \mathbb{Z} and $F[x]$) along the lines of row and column operations is outlined in the exercises.

12.1 THE BASIC THEORY

We first describe some general finiteness conditions. Let R be a ring and let M be a left R -module.

Definition.

- (1) The left R -module M is said to be a *Noetherian R -module* or to satisfy the *ascending chain condition on submodules* (or *A.C.C. on submodules*) if there are no infinite increasing chains of submodules, i.e., whenever

$$M_1 \subseteq M_2 \subseteq M_3 \subseteq \cdots$$

is an increasing chain of submodules of M , then there is a positive integer m such that for all $k \geq m$, $M_k = M_m$ (so the chain becomes stationary at stage m : $M_m = M_{m+1} = M_{m+2} = \cdots$).

- (2) The ring R is said to be *Noetherian* if it is Noetherian as a left module over itself, i.e., if there are no infinite increasing chains of left ideals in R .

One can formulate analogous notions of A.C.C. on right and on two-sided ideals in a (possibly noncommutative) ring R . For noncommutative rings these properties need not be related.

Theorem 1. Let R be a ring and let M be a left R -module. Then the following are equivalent:

- (1) M is a Noetherian R -module.
- (2) Every nonempty set of submodules of M contains a maximal element under inclusion.
- (3) Every submodule of M is finitely generated.

Proof: [(1) implies (2)] Assume M is Noetherian and let Σ be any nonempty collection of submodules of M . Choose any $M_1 \in \Sigma$. If M_1 is a maximal element of Σ , (2) holds, so assume M_1 is not maximal. Then there is some $M_2 \in \Sigma$ such that $M_1 \subset M_2$. If M_2 is maximal in Σ , (2) holds, so we may assume there is an $M_3 \in \Sigma$ properly containing M_2 . Proceeding in this way one sees that if (2) fails we can produce by the Axiom of Choice an infinite strictly increasing chain of elements of Σ , contrary to (1).

[(2) implies (3)] Assume (2) holds and let N be any submodule of M . Let Σ be the collection of all finitely generated submodules of N . Since $\{0\} \in \Sigma$, this collection is nonempty. By (2) Σ contains a maximal element N' . If $N' \neq N$, let $x \in N - N'$. Since $N' \in \Sigma$, the submodule N' is finitely generated by assumption, hence also the

submodule generated by N' and x is finitely generated. This contradicts the maximality of N' , so $N = N'$ is finitely generated.

[(3) implies (1)] Assume (3) holds and let $M_1 \subseteq M_2 \subseteq M_3 \dots$ be a chain of submodules of M . Let

$$N = \bigcup_{i=1}^{\infty} M_i$$

and note that N is a submodule. By (3) N is finitely generated by, say, a_1, a_2, \dots, a_n . Since $a_i \in N$ for all i , each a_i lies in one of the submodules in the chain, say M_{j_i} . Let $m = \max \{j_1, j_2, \dots, j_n\}$. Then $a_i \in M_m$ for all i so the module they generate is contained in M_m , i.e., $N \subseteq M_m$. This implies $M_m = N = M_k$ for all $k \geq m$, which proves (1).

Corollary 2. If R is a P.I.D. then every nonempty set of ideals of R has a maximal element and R is a Noetherian ring.

Proof: The P.I.D. R satisfies condition (3) in the theorem with $M = R$.

Recall that even if M itself is a finitely generated R -module, submodules of M need not be finitely generated, so the condition that M be a Noetherian R -module is in general stronger than the condition that M be a finitely generated R -module.

We require a result on “linear dependence” before turning to the main results of this chapter.

Proposition 3. Let R be an integral domain and let M be a free R -module of rank $n < \infty$. Then any $n + 1$ elements of M are R -linearly dependent, i.e., for any $y_1, y_2, \dots, y_{n+1} \in M$ there are elements $r_1, r_2, \dots, r_{n+1} \in R$, not all zero, such that

$$r_1 y_1 + r_2 y_2 + \dots + r_{n+1} y_{n+1} = 0.$$

Proof: The quickest way of proving this is to embed R in its quotient field F (since R is an integral domain) and observe that since $M \cong R \oplus R \oplus \dots \oplus R$ (n times) we obtain $M \subseteq F \oplus F \oplus \dots \oplus F$. The latter is an n -dimensional vector space over F so any $n + 1$ elements of M are F -linearly dependent. By clearing the denominators of the scalars (by multiplying through by the product of all the denominators, for example), we obtain an R -linear dependence relation among the $n + 1$ elements of M .

Alternatively, let e_1, \dots, e_n be a basis of the free R -module M and let y_1, \dots, y_{n+1} be any $n + 1$ elements of M . For $1 \leq i \leq n + 1$ write $y_i = a_{i1}e_1 + a_{i2}e_2 + \dots + a_{in}e_n$ in terms of the basis e_1, e_2, \dots, e_n . Let A be the $(n + 1) \times (n + 1)$ matrix whose i, j entry is a_{ij} , $1 \leq i \leq n + 1$, $1 \leq j \leq n$ and whose last row is zero, so certainly $\det A = 0$. Since R is an integral domain, Corollary 27 of Section 11.4 shows that the columns of A are R -linearly dependent. Any dependence relation on the columns of A gives a dependence relation on the y_i ’s, completing the proof.

If R is any integral domain and M is any R -module recall that

$$\text{Tor}(M) = \{x \in M \mid rx = 0 \text{ for some nonzero } r \in R\}$$

is a submodule of M (called *the torsion submodule of M*) and if N is any submodule of $\text{Tor}(M)$, N is called *a torsion submodule of M* (so the torsion submodule of M is the union of all torsion submodules of M , i.e., is the maximal torsion submodule of M). If $\text{Tor}(M) = 0$, the module M is said to be *torsion free*.

For any submodule N of M , the *annihilator* of N is the ideal of R defined by

$$\text{Ann}(N) = \{r \in R \mid rn = 0 \text{ for all } n \in N\}.$$

Note that if N is not a torsion submodule of M then $\text{Ann}(N) = (0)$. It is easy to see that if N, L are submodules of M with $N \subseteq L$, then $\text{Ann}(L) \subseteq \text{Ann}(N)$. If R is a P.I.D. and $N \subseteq L \subseteq M$ with $\text{Ann}(N) = (a)$ and $\text{Ann}(L) = (b)$, then $a \mid b$. In particular, the annihilator of any element x of M divides the annihilator of M (this is implied by Lagrange's Theorem when $R = \mathbb{Z}$).

Definition. For any integral domain R the *rank* of an R -module M is the maximum number of R -linearly independent elements of M .

The preceding proposition states that for a free R -module M over an integral domain the rank of a submodule is bounded by the rank of M . This notion of rank agrees with previous uses of the same term. If the ring $R = F$ is a field, then the rank of an R -module M is the dimension of M as a vector space over F and any maximal set of F -linearly independent elements is a basis for M . For a general integral domain, however, an R -module M of rank n need not have a "basis," i.e., need not be a *free* R -module even if M is torsion free, so some care is necessary with the notion of rank, particularly with respect to the torsion elements of M . Exercises 1 to 6 and 20 give an alternate characterization of the rank and provide some examples of (torsion free) R -modules (of rank 1) that are not free.

The next important result shows that if N is a submodule of a free module of finite rank over a P.I.D. then N is again a free module of finite rank and furthermore it is possible to choose generators for the two modules which are related in a simple way.

Theorem 4. Let R be a Principal Ideal Domain, let M be a free R -module of finite rank n and let N be a submodule of M . Then

- (1) N is free of rank m , $m \leq n$ and
- (2) there exists a basis y_1, y_2, \dots, y_n of M so that $a_1y_1, a_2y_2, \dots, a_my_m$ is a basis of N where a_1, a_2, \dots, a_m are nonzero elements of R with the divisibility relations

$$a_1 \mid a_2 \mid \dots \mid a_m.$$

Proof: The theorem is trivial for $N = \{0\}$, so assume $N \neq \{0\}$. For each R -module homomorphism φ of M into R , the image $\varphi(N)$ of N is a submodule of R , i.e., an ideal in R . Since R is a P.I.D. this ideal must be principal, say $\varphi(N) = (a_\varphi)$, for some $a_\varphi \in R$. Let

$$\Sigma = \{(a_\varphi) \mid \varphi \in \text{Hom}_R(M, R)\}$$

be the collection of the principal ideals in R obtained in this way from the R -module homomorphisms of M into R . The collection Σ is certainly nonempty since taking φ