

We close this section by listing some miscellaneous properties of compact sets.

Theorem 12.5.10. *Let (X, d) be a metric space.*

- (a) *If Y is a compact subset of X , and $Z \subseteq Y$, then Z is compact if and only if Z is closed.*
- (b) *If Y_1, \dots, Y_n are a finite collection of compact subsets of X , then their union $Y_1 \cup \dots \cup Y_n$ is also compact.*
- (c) *Every finite subset of X (including the empty set) is compact.*

Proof. See Exercise 12.5.7. □

Exercise 12.5.1. Show that Definitions 9.1.22 and 12.5.3 match when talking about subsets of the real line with the standard metric.

Exercise 12.5.2. Prove Proposition 12.5.5. (Hint: prove the completeness and boundedness separately. For both claims, use proof by contradiction. You will need the axiom of choice, as in Lemma 8.4.5.)

Exercise 12.5.3. Prove Theorem 12.5.7. (Hint: use Proposition 12.1.18 and Theorem 9.1.24.)

Exercise 12.5.4. Let (\mathbf{R}, d) be the real line with the standard metric. Give an example of a continuous function $f : \mathbf{R} \rightarrow \mathbf{R}$, and an open set $V \subseteq \mathbf{R}$, such that the image $f(V) := \{f(x) : x \in V\}$ of V is *not* open.

Exercise 12.5.5. Let (\mathbf{R}, d) be the real line with the standard metric. Give an example of a continuous function $f : \mathbf{R} \rightarrow \mathbf{R}$, and a closed set $F \subseteq \mathbf{R}$, such that $f(F)$ is *not* closed.

Exercise 12.5.6. Prove Corollary 12.5.9. (Hint: work in the compact metric space $(K_1, d|_{K_1 \times K_1})$, and consider the sets $V_n := K_1 \setminus K_n$, which are open on K_1 . Assume for sake of contradiction that $\bigcap_{n=1}^{\infty} K_n = \emptyset$, and then apply Theorem 12.5.8.)

Exercise 12.5.7. Prove Theorem 12.5.10. (Hint: for part (c), you may wish to use (b), and first prove that every singleton set is compact.)

Exercise 12.5.8. Let (X, d_{l^1}) be the metric space from Exercise 12.1.15. For each natural number n , let $e^{(n)} = (e_j^{(n)})_{j=0}^\infty$ be the sequence in X such that $e_j^{(n)} := 1$ when $n = j$ and $e_j^{(n)} := 0$ when $n \neq j$. Show that the set $\{e^{(n)} : n \in \mathbb{N}\}$ is a closed and bounded subset of X , but is not compact. (This is despite the fact that (X, d_{l^1}) is even a complete metric space - a fact which we will not prove here. The problem is that not that X is incomplete, but rather that it is “infinite-dimensional”, in a sense that we will not discuss here.)

Exercise 12.5.9. Show that a metric space (X, d) is compact if and only if every sequence in X has at least one limit point.

Exercise 12.5.10. A metric space (X, d) is called *totally bounded* if for every $\varepsilon > 0$, there exists a positive integer n and a finite number of balls $B(x^{(1)}, \varepsilon), \dots, B(x^{(n)}, \varepsilon)$ which cover X (i.e., $X = \bigcup_{i=1}^n B(x^{(i)}, \varepsilon)$).

- (a) Show that every totally bounded space is bounded.
- (b) Show the following stronger version of Proposition 12.5.5: if (X, d) is compact, then complete and totally bounded. (Hint: if X is not totally bounded, then there is some $\varepsilon > 0$ such that X cannot be covered by finitely many ε -balls. Then use Exercise 8.5.20 to find an infinite sequence of balls $B(x^{(n)}, \varepsilon/2)$ which are disjoint from each other. Use this to then construct a sequence which has no convergent subsequence.)
- (c) Conversely, show that if X is complete and totally bounded, then X is compact. (Hint: if $(x^{(n)})_{n=1}^\infty$ is a sequence in X , use the total boundedness hypothesis to recursively construct a sequence of subsequences $(x^{(n;j)})_{n=1}^\infty$ of $(x^{(n)})_{n=1}^\infty$ for each positive integer j , such that for each j , the elements of the sequence $(x^{(n;j)})_{n=1}^\infty$ are contained in a single ball of radius $1/j$, and also that each sequence $(x^{(n;j+1)})_{n=1}^\infty$ is a subsequence of the previous one $(x^{(n;j)})_{n=1}^\infty$. Then show that the “diagonal” sequence $(x^{(n;n)})_{n=1}^\infty$ is a Cauchy sequence, and then use the completeness hypothesis.)

Exercise 12.5.11. Let (X, d) have the property that every open cover of X has a finite subcover. Show that X is compact. (Hint: if X is not compact, then by Exercise 12.5.9, there is a sequence $(x^{(n)})_{n=1}^\infty$ with no limit points. Then for every $x \in X$ there exists a ball $B(x, \varepsilon)$ containing x which contains at most finitely many elements of this sequence. Now use the hypothesis.)

Exercise 12.5.12. Let (X, d_{disc}) be a metric space with the discrete metric d_{disc} .

- (a) Show that X is always complete.
- (b) When is X compact, and when is X not compact? Prove your claim. (Hint: the Heine-Borel theorem will be useless here since that only applies to Euclidean spaces with the Euclidean metric.)

Exercise 12.5.13. Let E and F be two compact subsets of \mathbf{R} (with the standard metric $d(x, y) = |x - y|$). Show that the Cartesian product $E \times F := \{(x, y) : x \in E, y \in F\}$ is a compact subset of \mathbf{R}^2 (with the Euclidean metric d_{l^2}).

Exercise 12.5.14. Let (X, d) be a metric space, let E be a non-empty compact subset of X , and let x_0 be a point in X . Show that there exists a point $x \in E$ such that

$$d(x_0, x) = \inf\{d(x_0, y) : y \in E\},$$

i.e., x is the closest point in E to x_0 . (Hint: let R be the quantity $R := \inf\{d(x_0, y) : y \in E\}$. Construct a sequence $(x^{(n)})_{n=1}^\infty$ in E such that $d(x_0, x^{(n)}) \leq R + \frac{1}{n}$, and then use the compactness of E .)

Exercise 12.5.15. Let (X, d) be a compact metric space. Suppose that $(K_\alpha)_{\alpha \in I}$ is a collection of closed sets in X with the property that any finite subcollection of these sets necessarily has non-empty intersection, thus $\bigcap_{\alpha \in F} K_\alpha \neq \emptyset$ for all finite $F \subseteq I$. (This property is known as the *finite intersection property*.) Show that the *entire* collection has non-empty intersection, thus $\bigcap_{\alpha \in I} K_\alpha = \emptyset$. Show that by counterexample this statement fails if X is not compact.

Chapter 13

Continuous functions on metric spaces

13.1 Continuous functions

In the previous chapter we studied a single metric space (X, d) , and the various types of sets one could find in that space. While this is already quite a rich subject, the theory of metric spaces becomes even richer, and of more importance to analysis, when one considers not just a single metric space, but rather *pairs* (X, d_X) and (Y, d_Y) of metric spaces, as well as *continuous functions* $f : X \rightarrow Y$ between such spaces. To define this concept, we generalize Definition 9.4.1 as follows:

Definition 13.1.1 (Continuous functions). Let (X, d_X) be a metric space, and let (Y, d_Y) be another metric space, and let $f : X \rightarrow Y$ be a function. If $x_0 \in X$, we say that f is *continuous at x_0* iff for every $\varepsilon > 0$, there exists a $\delta > 0$ such that $d_Y(f(x), f(x_0)) < \varepsilon$ whenever $d_X(x, x_0) < \delta$. We say that f is *continuous* iff it is continuous at every point $x \in X$.

Remark 13.1.2. Continuous functions are also sometimes called *continuous maps*. Mathematically, there is no distinction between the two terminologies.

Remark 13.1.3. If $f : X \rightarrow Y$ is continuous, and K is any subset of X , then the restriction $f|_K : K \rightarrow Y$ of f to K is also continuous (why?).

We now generalize much of the discussion in Chapter 9. We first observe that continuous functions preserve convergence:

Theorem 13.1.4 (Continuity preserves convergence). *Suppose that (X, d_X) and (Y, d_Y) are metric spaces. Let $f : X \rightarrow Y$ be a function, and let $x_0 \in X$ be a point in X . Then the following three statements are logically equivalent:*

- (a) *f is continuous at x_0 .*
- (b) *Whenever $(x^{(n)})_{n=1}^{\infty}$ is a sequence in X which converges to x_0 with respect to the metric d_X , the sequence $(f(x^{(n)}))_{n=1}^{\infty}$ converges to $f(x_0)$ with respect to the metric d_Y .*
- (c) *For every open set $V \subset Y$ that contains $f(x_0)$, there exists an open set $U \subset X$ containing x_0 such that $f(U) \subseteq V$.*

Proof. See Exercise 13.1.1. □

Another important characterization of continuous functions involves open sets.

Theorem 13.1.5. *Let (X, d_X) be a metric space, and let (Y, d_Y) be another metric space. Let $f : X \rightarrow Y$ be a function. Then the following four statements are equivalent:*

- (a) *f is continuous.*
- (b) *Whenever $(x^{(n)})_{n=1}^{\infty}$ is a sequence in X which converges to some point $x_0 \in X$ with respect to the metric d_X , the sequence $(f(x^{(n)}))_{n=1}^{\infty}$ converges to $f(x_0)$ with respect to the metric d_Y .*
- (c) *Whenever V is an open set in Y , the set $f^{-1}(V) := \{x \in X : f(x) \in V\}$ is an open set in X .*
- (d) *Whenever F is a closed set in Y , the set $f^{-1}(F) := \{x \in X : f(x) \in F\}$ is a closed set in X .*

Proof. See Exercise 13.1.2. □

Remark 13.1.6. It may seem strange that continuity ensures that the *inverse* image of an open set is open. One may guess instead that the *reverse* should be true, that the *forward* image of an open set is open; but this is not true; see Exercises 12.5.4, 12.5.5.

As a quick corollary of the above two Theorems we obtain

Corollary 13.1.7 (Continuity preserved by composition). *Let (X, d_X) , (Y, d_Y) , and (Z, d_Z) be metric spaces.*

- (a) *If $f : X \rightarrow Y$ is continuous at a point $x_0 \in X$, and $g : Y \rightarrow Z$ is continuous at $f(x_0)$, then the composition $g \circ f : X \rightarrow Z$, defined by $g \circ f(x) := g(f(x))$, is continuous at x_0 .*
- (b) *If $f : X \rightarrow Y$ is continuous, and $g : Y \rightarrow Z$ is continuous, then $g \circ f : X \rightarrow Z$ is also continuous.*

Proof. See Exercise 13.1.3. □

Example 13.1.8. If $f : X \rightarrow \mathbf{R}$ is a continuous function, then the function $f^2 : X \rightarrow \mathbf{R}$ defined by $f^2(x) := f(x)^2$ is automatically continuous also. This is because we have $f^2 = g \circ f$, where $g : \mathbf{R} \rightarrow \mathbf{R}$ is the squaring function $g(x) := x^2$, and g is a continuous function.

Exercise 13.1.1. Prove Theorem 13.1.4. (Hint: review your proof of Proposition 9.4.7.)

Exercise 13.1.2. Prove Theorem 13.1.5. (Hint: Theorem 13.1.4 already shows that (a) and (b) are equivalent.)

Exercise 13.1.3. Use Theorem 13.1.4 and Theorem 13.1.5 to prove Corollary 13.1.7.

Exercise 13.1.4. Give an example of functions $f : \mathbf{R} \rightarrow \mathbf{R}$ and $g : \mathbf{R} \rightarrow \mathbf{R}$ such that

- (a) f is not continuous, but g and $g \circ f$ are continuous;
- (b) g is not continuous, but f and $g \circ f$ are continuous;
- (c) f and g are not continuous, but $g \circ f$ is continuous.

Explain briefly why these examples do not contradict Corollary 13.1.7.

Exercise 13.1.5. Let (X, d) be a metric space, and let $(E, d|_{E \times E})$ be a subspace of (X, d) . Let $\iota_{E \rightarrow X} : E \rightarrow X$ be the inclusion map, defined by setting $\iota_{E \rightarrow X}(x) := x$ for all $x \in E$. Show that $\iota_{E \rightarrow X}$ is continuous.

Exercise 13.1.6. Let $f : X \rightarrow Y$ be a function from one metric space (X, d_X) to another (Y, d_Y) . Let E be a subset of X (which we give the induced metric $d_X|_{E \times E}$), and let $f|_E : E \rightarrow Y$ be the restriction of f to E , thus $f|_E(x) := f(x)$ when $x \in E$. If $x_0 \in E$ and f is continuous at x_0 , show that $f|_E$ is also continuous at x_0 . (Is the converse of this statement true? Explain.) Conclude that if f is continuous, then $f|_E$ is continuous. Thus restriction of the domain of a function does not destroy continuity. (Hint: use Exercise 13.1.5.)

Exercise 13.1.7. Let $f : X \rightarrow Y$ be a function from one metric space (X, d_X) to another (Y, d_Y) . Suppose that the image $f(X)$ of X is contained in some subset $E \subset Y$ of Y . Let $g : X \rightarrow E$ be the function which is the same as f but with the range restricted from Y to E , thus $g(x) = f(x)$ for all $x \in X$. We give E the metric $d_Y|_{E \times E}$ induced from Y . Show that for any $x_0 \in X$, that f is continuous at x_0 if and only if g is continuous at x_0 . Conclude that f is continuous if and only if g is continuous. (Thus the notion of continuity is not affected if one restricts the range of the function.)

13.2 Continuity and product spaces

Given two functions $f : X \rightarrow Y$ and $g : X \rightarrow Z$, one can define their *direct sum* $f \oplus g : X \rightarrow Y \times Z$ defined by $f \oplus g(x) := (f(x), g(x))$, i.e., this is the function taking values in the Cartesian product $Y \times Z$ whose first co-ordinate is $f(x)$ and whose second co-ordinate is $g(x)$ (cf. Exercise 3.5.7). For instance, if $f : \mathbf{R} \rightarrow \mathbf{R}$ is the function $f(x) := x^2 + 3$, and $g : \mathbf{R} \rightarrow \mathbf{R}$ is the function $g(x) = 4x$, then $f \oplus g : \mathbf{R} \rightarrow \mathbf{R}^2$ is the function $f \oplus g(x) := (x^2 + 3, 4x)$. The direct sum operation preserves continuity:

Lemma 13.2.1. *Let $f : X \rightarrow \mathbf{R}$ and $g : X \rightarrow \mathbf{R}$ be functions, and let $f \oplus g : X \rightarrow \mathbf{R}^2$ be their direct sum. We give \mathbf{R}^2 the Euclidean metric.*

- (a) *If $x_0 \in X$, then f and g are both continuous at x_0 if and only if $f \oplus g$ is continuous at x_0 .*

(b) f and g are both continuous if and only if $f \oplus g$ is continuous.

Proof. See Exercise 13.2.1. \square

To use this, we first need another continuity result:

Lemma 13.2.2. *The addition function $(x, y) \mapsto x+y$, the subtraction function $(x, y) \mapsto x-y$, the multiplication function $(x, y) \mapsto xy$, the maximum function $(x, y) \mapsto \max(x, y)$, and the minimum function $(x, y) \mapsto \min(x, y)$, are all continuous functions from \mathbf{R}^2 to \mathbf{R} . The division function $(x, y) \mapsto x/y$ is a continuous function from $\mathbf{R} \times (\mathbf{R} \setminus \{0\}) = \{(x, y) \in \mathbf{R}^2 : y \neq 0\}$ to \mathbf{R} . For any real number c , the function $x \mapsto cx$ is a continuous function from \mathbf{R} to \mathbf{R} .*

Proof. See Exercise 13.2.2. \square

Combining these lemmas we obtain

Corollary 13.2.3. *Let (X, d) be a metric space, let $f : X \rightarrow \mathbf{R}$ and $g : X \rightarrow \mathbf{R}$ be functions. Let c be a real number.*

- (a) *If $x_0 \in X$ and f and g are continuous at x_0 , then the functions $f + g : X \rightarrow \mathbf{R}$, $f - g : X \rightarrow \mathbf{R}$, $fg : X \rightarrow \mathbf{R}$, $\max(f, g) : X \rightarrow \mathbf{R}$, $\min(f, g) : X \rightarrow \mathbf{R}$, and $cf : X \rightarrow \mathbf{R}$ (see Definition 9.2.1 for definitions) are also continuous at x_0 . If $g(x) \neq 0$ for all $x \in X$, then $f/g : X \rightarrow \mathbf{R}$ is also continuous at x_0 .*
- (b) *If f and g are continuous, then the functions $f + g : X \rightarrow \mathbf{R}$, $f - g : X \rightarrow \mathbf{R}$, $fg : X \rightarrow \mathbf{R}$, $\max(f, g) : X \rightarrow \mathbf{R}$, $\min(f, g) : X \rightarrow \mathbf{R}$, and $cf : X \rightarrow \mathbf{R}$ are also continuous at x_0 . If $g(x) \neq 0$ for all $x \in X$, then $f/g : X \rightarrow \mathbf{R}$ is also continuous at x_0 .*

Proof. We first prove (a). Since f and g are continuous at x_0 , then by Lemma 13.2.1 $f \oplus g : X \rightarrow \mathbf{R}^2$ is also continuous at x_0 . On the other hand, from Lemma 13.2.2 the function $(x, y) \mapsto x+y$ is continuous at every point in \mathbf{R}^2 , and in particular is continuous at $f \oplus g(x_0)$. If we then compose these two functions using Corollary

13.1.7 we conclude that $f + g : X \rightarrow \mathbf{R}$ is continuous. A similar argument gives the continuity of $f - g$, fg , $\max(f, g)$, $\min(f, g)$ and cf . To prove the claim for f/g , we first use Exercise 13.1.7 to restrict the range of g from \mathbf{R} to $\mathbf{R} \setminus \{0\}$, and then one can argue as before. The claim (b) follows immediately from (a). \square

This corollary allows us to demonstrate the continuity of a large class of functions; we give some examples below.

Exercise 13.2.1. Prove Lemma 13.2.1. (Hint: use Proposition 12.1.18 and Theorem 13.1.4.)

Exercise 13.2.2. Prove Lemma 13.2.2. (Hint: use Theorem 13.1.5 and limit laws (Theorem 6.1.19).)

Exercise 13.2.3. Show that if $f : X \rightarrow \mathbf{R}$ is a continuous function, so is the function $|f| : X \rightarrow \mathbf{R}$ defined by $|f|(x) := |f(x)|$.

Exercise 13.2.4. Let $\pi_1 : \mathbf{R}^2 \rightarrow \mathbf{R}$ and $\pi_2 : \mathbf{R}^2 \rightarrow \mathbf{R}$ be the functions $\pi_1(x, y) := x$ and $\pi_2(x, y) := y$ (these two functions are sometimes called the *co-ordinate functions* on \mathbf{R}^2). Show that π_1 and π_2 are continuous. Conclude that if $f : \mathbf{R} \rightarrow X$ is any continuous function into a metric space (X, d) , then the functions $g_1 : \mathbf{R}^2 \rightarrow X$ and $g_2 : \mathbf{R}^2 \rightarrow X$ defined by $g_1(x, y) := f(x)$ and $g_2(x, y) := f(y)$ are also continuous.

Exercise 13.2.5. Let $n, m \geq 0$ be integers. Suppose that for every $0 \leq i \leq n$ and $0 \leq j \leq m$ we have a real number c_{ij} . Form the function $P : \mathbf{R}^2 \rightarrow \mathbf{R}$ defined by

$$P(x, y) := \sum_{i=0}^n \sum_{j=0}^m c_{ij} x^i y^j.$$

(Such a function is known as a *polynomial of two variables*; a typical example of such a polynomial is $P(x, y) = x^3 + 2xy^2 - x^2 + 3y + 6$.) Show that P is continuous. (Hint: use Exercise 13.2.4 and Corollary 13.2.3.) Conclude that if $f : X \rightarrow \mathbf{R}$ and $g : X \rightarrow \mathbf{R}$ are continuous functions, then the function $P(f, g) : X \rightarrow \mathbf{R}$ defined by $P(f, g)(x) := P(f(x), g(x))$ is also continuous.

Exercise 13.2.6. Let \mathbf{R}^m and \mathbf{R}^n be Euclidean spaces. If $f : X \rightarrow \mathbf{R}^m$ and $g : X \rightarrow \mathbf{R}^n$ are continuous functions, show that $f \oplus g : X \rightarrow \mathbf{R}^{m+n}$ is also continuous, where we have identified $\mathbf{R}^m \times \mathbf{R}^n$ with \mathbf{R}^{m+n} in the obvious manner. Is the converse statement true?

Exercise 13.2.7. Let $k \geq 1$, let I be a finite subset of \mathbb{N}^k , and let $c : I \rightarrow \mathbf{R}$ be a function. Form the function $P : \mathbf{R}^k \rightarrow \mathbf{R}$ defined by

$$P(x_1, \dots, x_k) := \sum_{(i_1, \dots, i_k) \in I} c(i_1, \dots, i_k) x_1^{i_1} \dots x_k^{i_k}.$$

(Such a function is known as a *polynomial of k variables*; a typical example of such a polynomial is $P(x_1, x_2, x_3) = 3x_1^3x_2x_3^2 - x_2x_3^2 + x_1 + 5$.) Show that P is continuous. (Hint: use induction on k , Exercise 13.2.6, and either Exercise 13.2.5 or Lemma 13.2.2.)

Exercise 13.2.8. Let (X, d_X) and (Y, d_Y) be metric spaces. Define the metric $d_{X \times Y} : (X \times Y) \times (X \times Y) \rightarrow [0, \infty)$ by the formula

$$d_{X \times Y}((x, y), (x', y')) := d_X(x, x') + d_Y(y, y').$$

Show that $(X \times Y, d_{X \times Y})$ is a metric space, and deduce an analogue of Proposition 12.1.18 and Lemma 13.2.1.

Exercise 13.2.9. Let $f : \mathbf{R}^2 \rightarrow X$ be a function from \mathbf{R}^2 to a metric space X . Let (x_0, y_0) be a point in \mathbf{R}^2 . If f is continuous at (x_0, y_0) , show that

$$\lim_{x \rightarrow x_0} \limsup_{y \rightarrow y_0} f(x, y) = \lim_{y \rightarrow y_0} \limsup_{x \rightarrow x_0} f(x, y) = f(x_0, y_0)$$

and

$$\lim_{x \rightarrow x_0} \liminf_{y \rightarrow y_0} f(x, y) = \lim_{y \rightarrow y_0} \liminf_{x \rightarrow x_0} f(x, y) = f(x_0, y_0).$$

In particular, we have

$$\lim_{x \rightarrow x_0} \lim_{y \rightarrow y_0} f(x, y) = \lim_{y \rightarrow y_0} \lim_{x \rightarrow x_0} f(x, y)$$

whenever the limits on both sides exist. (Note that the limits do not necessarily exist in general; consider for instance the function $f : \mathbf{R}^2 \rightarrow \mathbf{R}$ such that $f(x, y) = y \sin \frac{1}{x}$ when $xy \neq 0$ and $f(x, y) = 0$ otherwise.) Discuss the comparison between this result and Example 1.2.7.

Exercise 13.2.10. Let $f : \mathbf{R}^2 \rightarrow \mathbf{R}$ be a continuous function. Show that for each $x \in \mathbf{R}$, the function $y \mapsto f(x, y)$ is continuous on \mathbf{R} , and for each $y \in \mathbf{R}$, the function $x \mapsto f(x, y)$ is continuous on \mathbf{R} . Thus a function $f(x, y)$ which is jointly continuous in (x, y) is also continuous in each variable x, y separately.

Exercise 13.2.11. Let $f : \mathbf{R}^2 \rightarrow \mathbf{R}$ be the function defined by $f(x, y) := \frac{xy}{x^2+y^2}$ when $(x, y) \neq (0, 0)$, and $f(x, y) = 0$ otherwise. Show that for each fixed $x \in \mathbf{R}$, the function $y \mapsto f(x, y)$ is continuous on \mathbf{R} , and that for each fixed $y \in \mathbf{R}$, the function $x \mapsto f(x, y)$ is continuous on \mathbf{R} , but that the function $f : \mathbf{R}^2 \rightarrow \mathbf{R}$ is not continuous on \mathbf{R}^2 . This shows that the converse to Exercise 13.2.10 fails; it is possible to be continuous in each variable separately without being jointly continuous.

13.3 Continuity and compactness

Continuous functions interact well with the concept of compact sets defined in Definition 12.5.1.

Theorem 13.3.1 (Continuous maps preserve compactness). *Let $f : X \rightarrow Y$ be a continuous map from one metric space (X, d_X) to another (Y, d_Y) . Let $K \subseteq X$ be any compact subset of X . Then the image $f(K) := \{f(x) : x \in K\}$ of K is also compact.*

Proof. See Exercise 13.3.1. □

This theorem has an important consequence. Recall from Definition 9.6.5 the notion of a function $f : X \rightarrow \mathbf{R}$ attaining a maximum or minimum at a point. We may generalize Proposition 9.6.7 as follows:

Proposition 13.3.2 (Maximum principle). *Let (X, d) be a compact metric space, and let $f : X \rightarrow \mathbf{R}$ be a continuous function. Then f is bounded. Furthermore, f attains its maximum at some point $x_{\max} \in X$, and also attains its minimum at some point $x_{\min} \in X$.*

Proof. See Exercise 13.3.2. □

Remark 13.3.3. As was already noted in Exercise 9.6.1, this principle can fail if X is not compact. This proposition should be compared with Lemma 9.6.3 and Proposition 9.6.7.

Another advantage of continuous functions on compact sets is that they are *uniformly continuous*. We generalize Definition 9.9.2 as follows:

Definition 13.3.4 (Uniform continuity). Let $f : X \rightarrow Y$ be a map from one metric space (X, d_X) to another (Y, d_Y) . We say that f is *uniformly continuous* if, for every $\varepsilon > 0$, there exists a $\delta > 0$ such that $d_Y(f(x), f(x')) < \varepsilon$ whenever $x, x' \in X$ are such that $d_X(x, x') < \delta$.

Every uniformly continuous function is continuous, but not conversely (Exercise 13.3.3). But if the domain X is compact, then the two notions are equivalent:

Theorem 13.3.5. *Let (X, d_X) and (Y, d_Y) be metric spaces, and suppose that (X, d_X) is compact. If $f : X \rightarrow Y$ is function, then f is continuous if and only if it is uniformly continuous.*

Proof. If f is uniformly continuous then it is also continuous by Exercise 13.3.3. Now suppose that f is continuous. Fix $\varepsilon > 0$. For every $x_0 \in X$, the function f is continuous at x_0 . Thus there exists a $\delta(x_0) > 0$, depending on x_0 , such that $d_Y(f(x), f(x_0)) < \varepsilon/2$ whenever $d_X(x, x_0) < \delta(x_0)$. In particular, by the triangle inequality this implies that $d_Y(f(x), f(x')) < \varepsilon$ whenever $x \in B_{(X, d_X)}(x_0, \delta(x_0)/2)$ and $d_X(x', x) < \delta(x_0)/2$ (why?).

Now consider the (possibly infinite) collection of balls

$$\{B_{(X, d_X)}(x_0, \delta(x_0)/2) : x_0 \in X\}.$$

Each ball in this collection is of course open, and the union of all these balls covers X , since each point x_0 in X is contained in its own ball $B_{(X, d_X)}(x_0, \delta(x_0)/2)$. Hence, by Theorem 12.5.8, there exist a finite number of points x_1, \dots, x_n such that the balls $B_{(X, d_X)}(x_j, \delta(x_j)/2)$ for $j = 1, \dots, n$ cover X :

$$X \subseteq \bigcup_{j=1}^n B_{(X, d_X)}(x_j, \delta(x_j)/2).$$

Now let $\delta := \min_{j=1}^n \delta(x_j)/2$. Since each of the $\delta(x_j)$ are positive, and there are only a finite number of j , we see that $\delta > 0$. Now let x, x' be any two points in X such that $d_X(x, x') < \delta$. Since the balls $B_{(X, d_X)}(x_j, \delta(x_j)/2)$ cover X , we see that there must exist

$1 \leq j \leq n$ such that $x \in B_{(X,d_X)}(x_j, \delta(x_j)/2)$. Since $d_X(x, x') < \delta$, we have $d_X(x, x') < \delta(x_j)/2$, and so by the previous discussion we have $d_Y(f(x), f(x')) < \varepsilon$. We have thus found a δ such that $d_Y(f(x), f(x')) < \varepsilon$ whenever $d(x, x') < \delta$, and this proves uniform continuity as desired. \square

Exercise 13.3.1. Prove Theorem 13.3.1.

Exercise 13.3.2. Prove Proposition 13.3.2. (Hint: modify the proof of Proposition 9.6.7.)

Exercise 13.3.3. Show that every uniformly continuous function is continuous, but give an example that shows that not every continuous function is uniformly continuous.

Exercise 13.3.4. Let (X, d_X) , (Y, d_Y) , (Z, d_Z) be metric spaces, and let $f : X \rightarrow Y$ and $g : Y \rightarrow Z$ be two uniformly continuous functions. Show that $g \circ f : X \rightarrow Z$ is also uniformly continuous.

Exercise 13.3.5. Let (X, d_X) be a metric space, and let $f : X \rightarrow \mathbf{R}$ and $g : X \rightarrow \mathbf{R}$ be uniformly continuous functions. Show that the direct sum $f \oplus g : X \rightarrow \mathbf{R}^2$ defined by $f \oplus g(x) := (f(x), g(x))$ is uniformly continuous.

Exercise 13.3.6. Show that the addition function $(x, y) \mapsto x + y$ and the subtraction function $(x, y) \mapsto x - y$ are uniformly continuous from \mathbf{R}^2 to \mathbf{R} , but the multiplication function $(x, y) \mapsto xy$ is not. Conclude that if $f : X \rightarrow \mathbf{R}$ and $g : X \rightarrow \mathbf{R}$ are uniformly continuous functions on a metric space (X, d) , then $f + g : X \rightarrow \mathbf{R}$ and $f - g : X \rightarrow \mathbf{R}$ are also uniformly continuous. Give an example to show that $fg : X \rightarrow \mathbf{R}$ need not be uniformly continuous. What is the situation for $\max(f, g)$, $\min(f, g)$, f/g , and cf for a real number c ?

13.4 Continuity and connectedness

We now describe another important concept in metric spaces, that of *connectedness*.

Definition 13.4.1 (Connected spaces). Let (X, d) be a metric space. We say that X is *disconnected* iff there exist disjoint non-empty open sets V and W in X such that $V \cup W = X$. (Equivalently, X is disconnected if and only if X contains a non-empty