

CS5050 ADVANCED ALGORITHMS

Fall 2023

Assignment 6: Algorithm Analysis

Due Date: 11:59:59 p.m., *Sunday, Dec 3, 2023*

Total Points: 70

Note: In this assignment, we assume that all input graphs are represented by **adjacency lists**. If you want to start early, you should be able to do Problems 1 and 2 now. For Problems 3 and 4, you may want to wait until after Thursday's class on Nov 30.

1. Given a **directed** graph G of n vertices and m edges, let s be a vertex of G .
 - (a) Design an $O(m+n)$ time algorithm to determine whether the following is true: there exists a path from s to v in G for every vertex v of G . **(10 points)**
 - (b) Design an $O(m+n)$ time algorithm to determine whether the following is true: there exists a path from v to s in G for every vertex v of G . **(10 points)**

Note: The input is the adjacency lists for G . This means that all information needed in your algorithm must be computed from the adjacency lists of G . For example, if you want to convert G to a new graph G' , then you must compute the adjacency lists of G' using the adjacency lists of G .

Note: Here is an application of your algorithms for (a) and (b). We say that a directed graph G is *strongly connected* if for every pair of vertices u and v , there exists a path from u to v and there also exists a path from v to u in G . An interesting observation is that G is *strongly connected* if and only if there exists a path in G from s to v and there is also a path from v to s for every vertex v of G (you may think about how to prove this observation). In light of the observation, we can determine whether G is strongly connected in $O(m+n)$ time by using your algorithms for the above two questions (a) and (b).

2. **(20 points)** Given a **directed-acyclic-graph (DAG)** G of n vertices and m edges, let s and t be two vertices of G . There might be multiple different paths (not necessarily shortest paths) from s to t (e.g., see Fig. 1 for an example). Design an $O(m+n)$ time algorithm to compute the number of different paths in G from s to t .

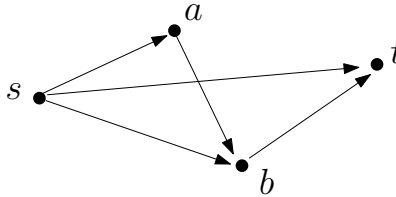


Figure 1: There are three different paths from s to t : $s \rightarrow t$, $s \rightarrow b \rightarrow t$, and $s \rightarrow a \rightarrow b \rightarrow t$.

3. **(20 points)** Given a directed graph G of n vertices and m edges, each edge (u, v) has a weight $w(u, v)$, which can be positive, zero, or negative. The *bottleneck-weight* of any path in G is defined to be the **largest** weight of all edges in the path. Let s and t be two vertices of G . A *minimum bottleneck-weight path* from s to t is a path with the smallest bottleneck-weight among all paths from s to t in G . Refer to Figure 2 for an example.

Modify Dijkstra's algorithm to compute minimum bottleneck-weight paths from s to all other vertices of G . Your algorithm does not have to output all paths but only need to compute the correct predecessor information for all vertices (which forms a *minimum bottleneck-weight path tree* with s as the root), as we did in class for Dijkstra's algorithm. Your algorithm is required to have the same time complexity as Dijkstra's algorithm, i.e., $O((n + m) \log n)$ time.

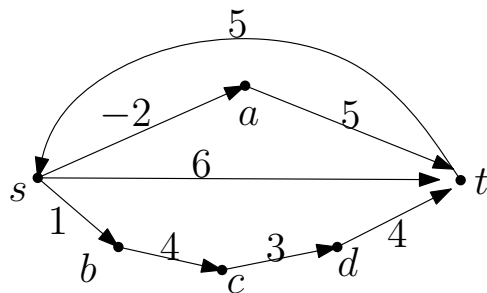


Figure 2: Here is a minimum bottleneck-weight path from s to t : s, b, c, d, t , whose bottleneck-weight is 4.

4. **(10 points)** Let G be an undirected connected graph of n vertices and m edges. Suppose each edge of G has a color of either *blue* or *red*. Design an algorithm to find a spanning tree T of G such that T has as few red edges as possible. Your algorithm should run in $O((n + m) \log n)$ time.