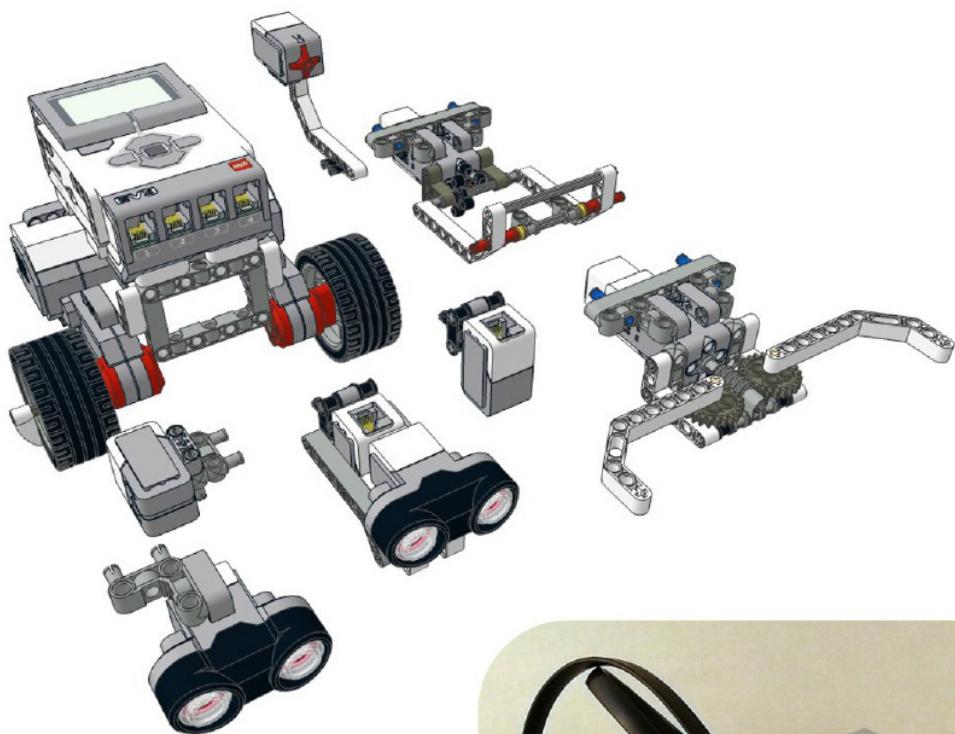


# Instrucciones de Montaje

## Diseño y Accesorios de la Base Rover



# **Accesorios Sensores y Motores para el Diseño de la Base Rover**



**Sensor Ultrasónico**



**Sensor de Color**



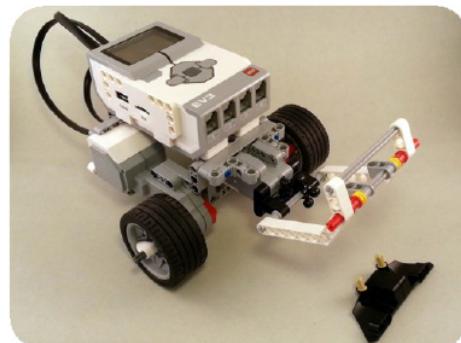
**Sensor de Giro**



**Pinza**

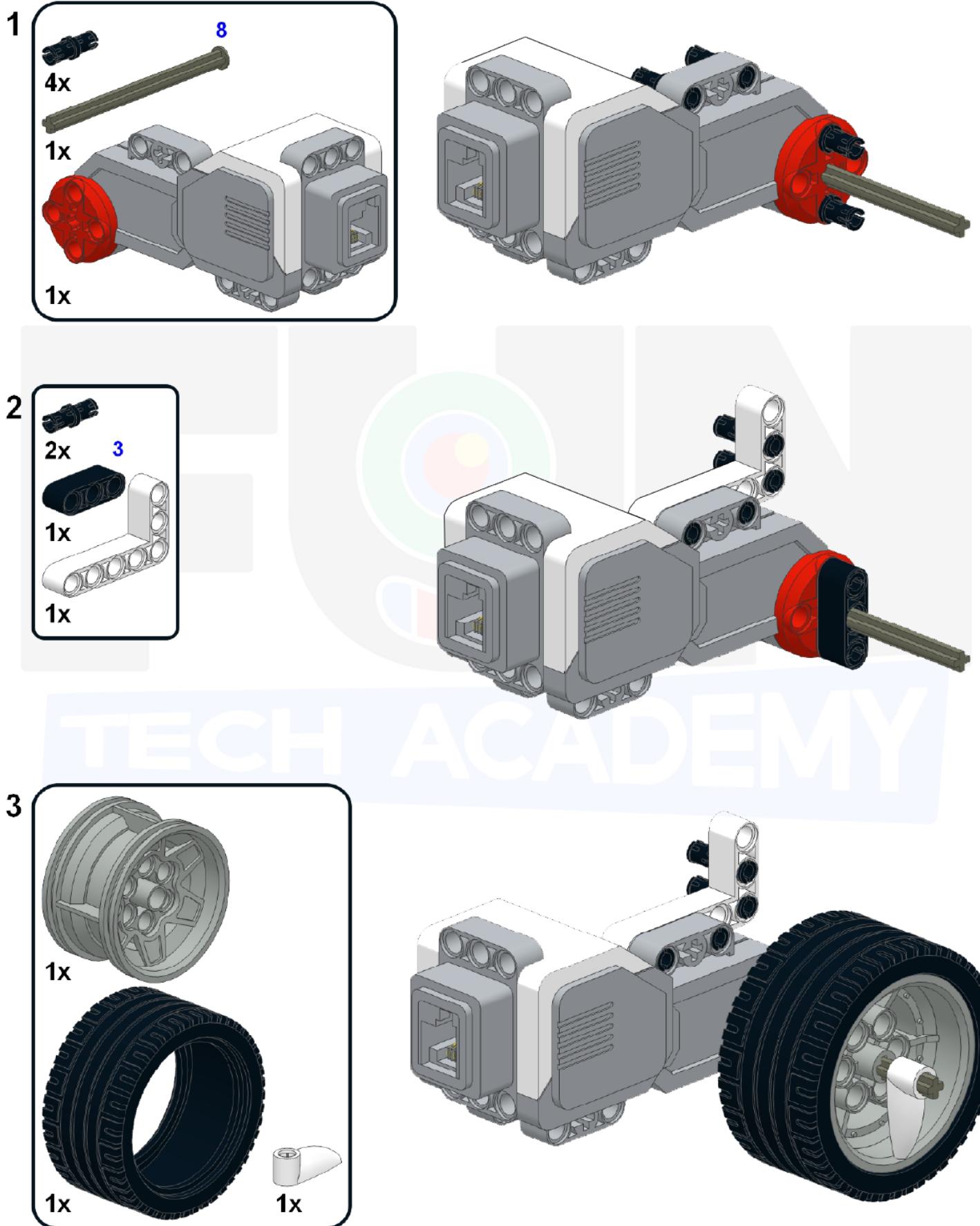


**Combinación  
Color / Ultrasónico**



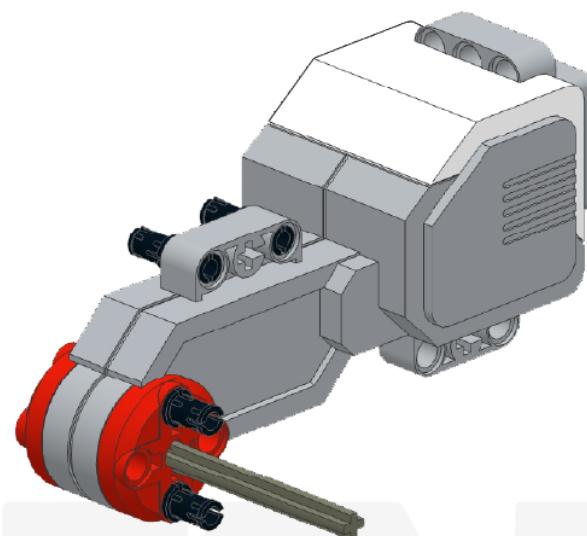
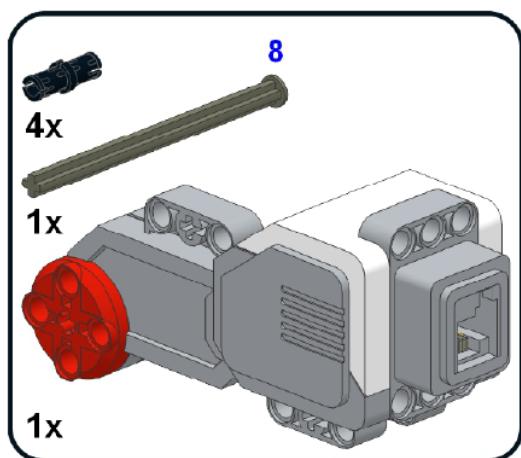
**Entrega de Carga**

## Montaje del motor derecho

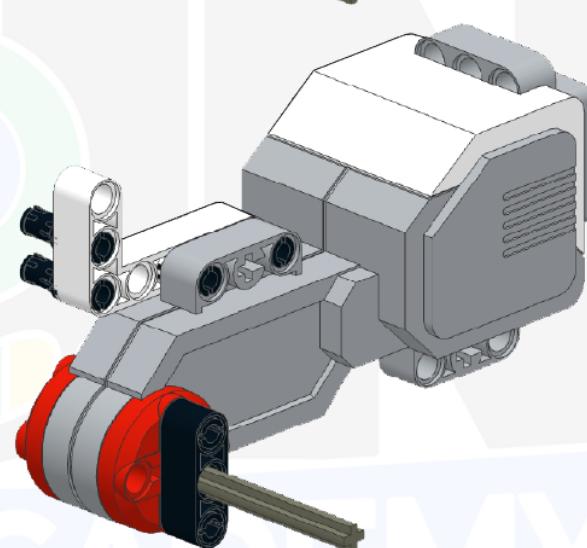
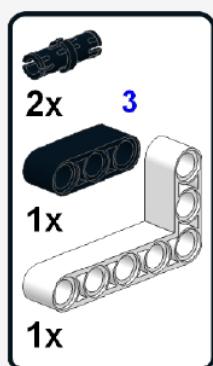


## Montaje del motor izquierdo

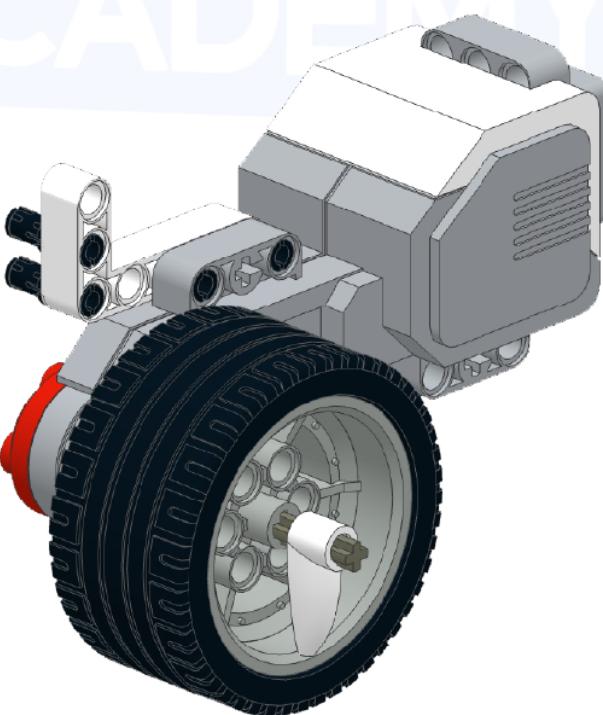
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2

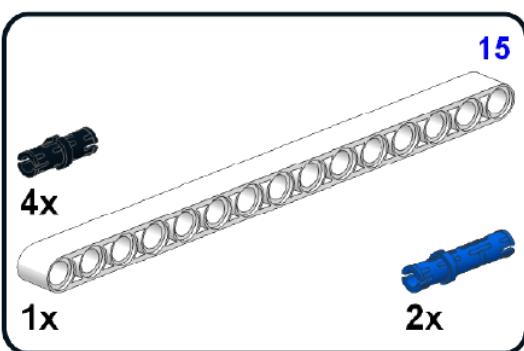


3



## Montaje de la rueda trasera

1

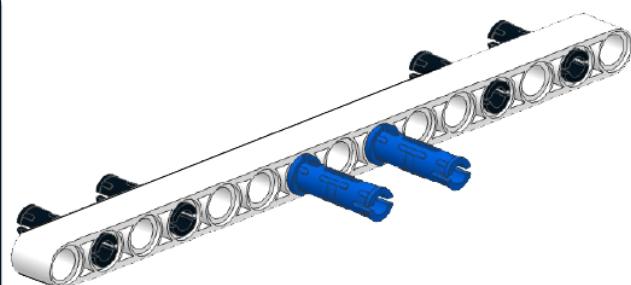


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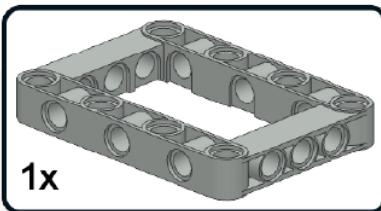
4x

1x

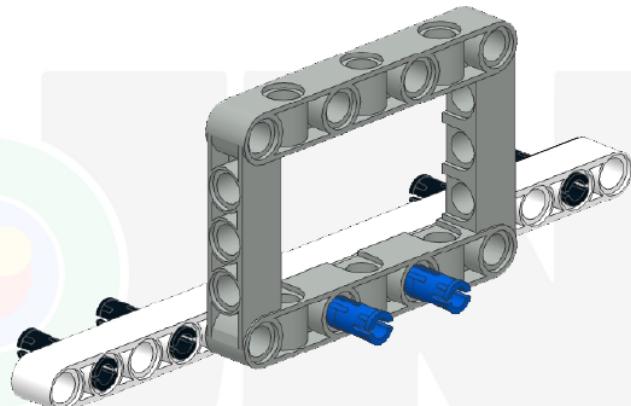
2x



2



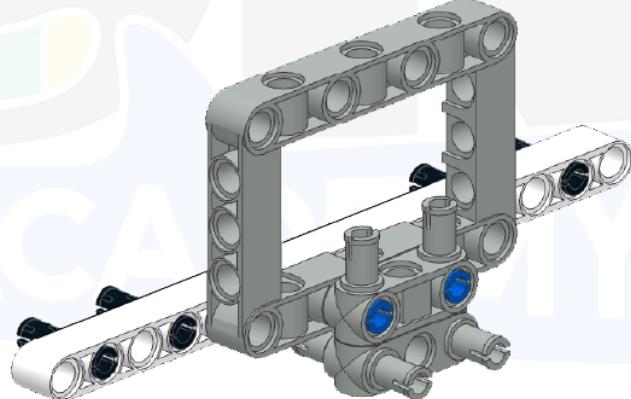
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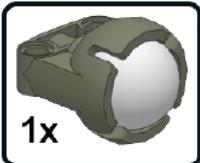
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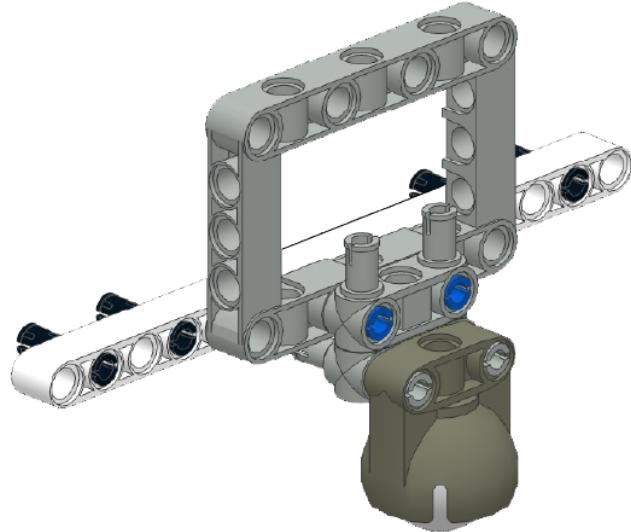
2x



4

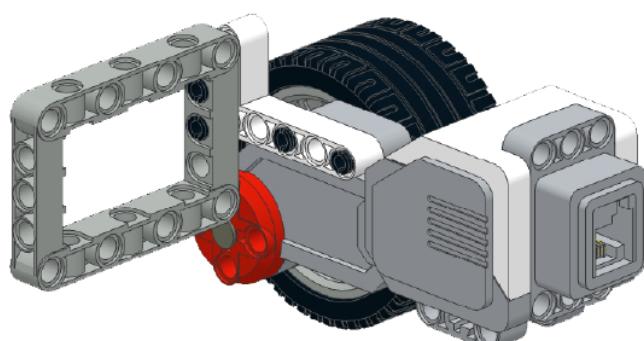
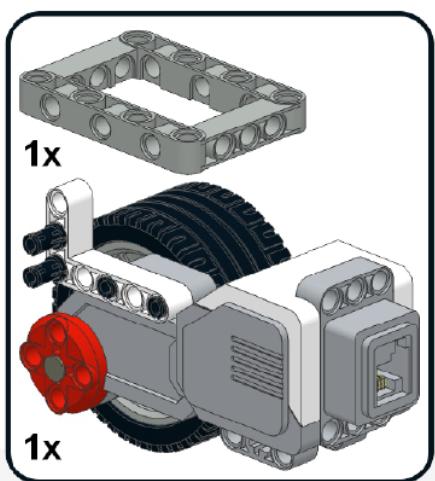


1x

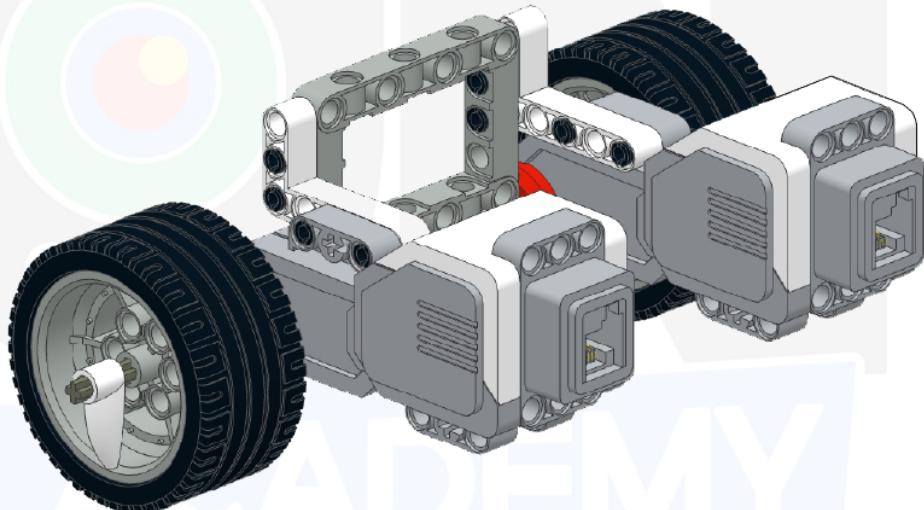
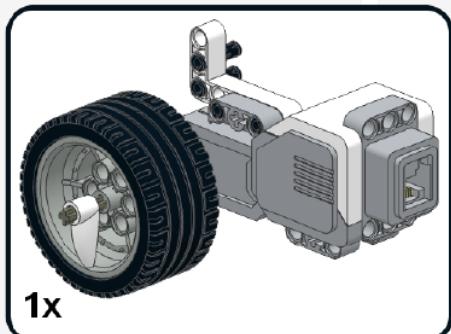


## Ensamblaje de motores derecho, izquierdo y rueda trasera

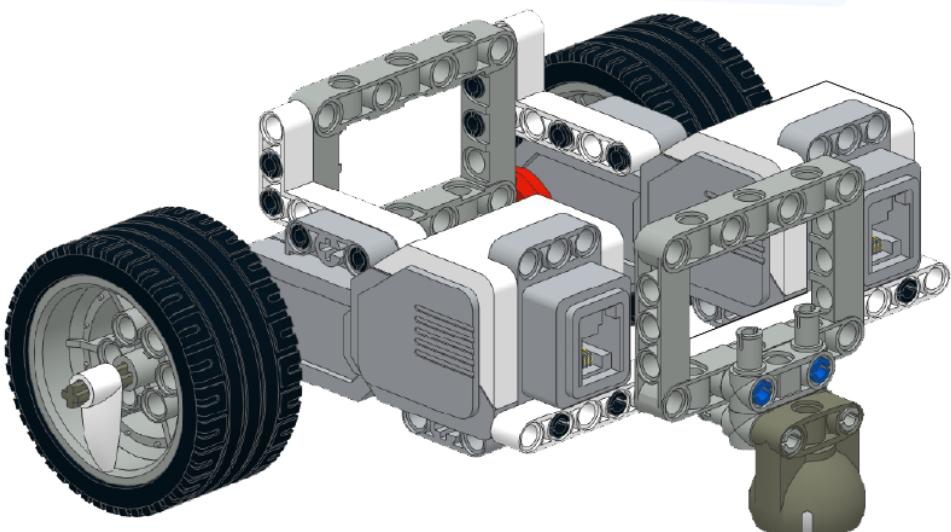
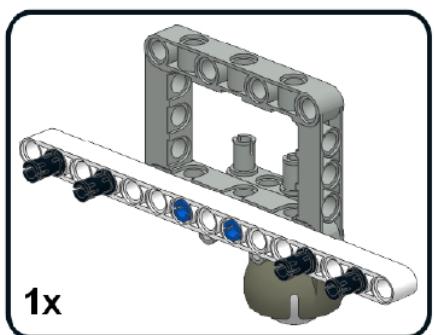
1



2

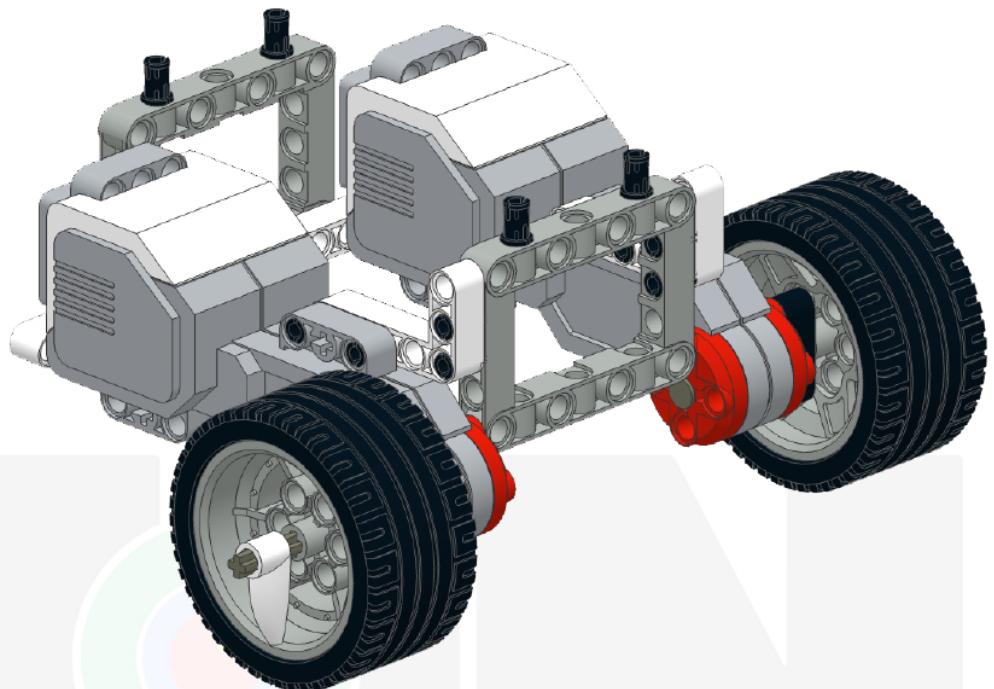


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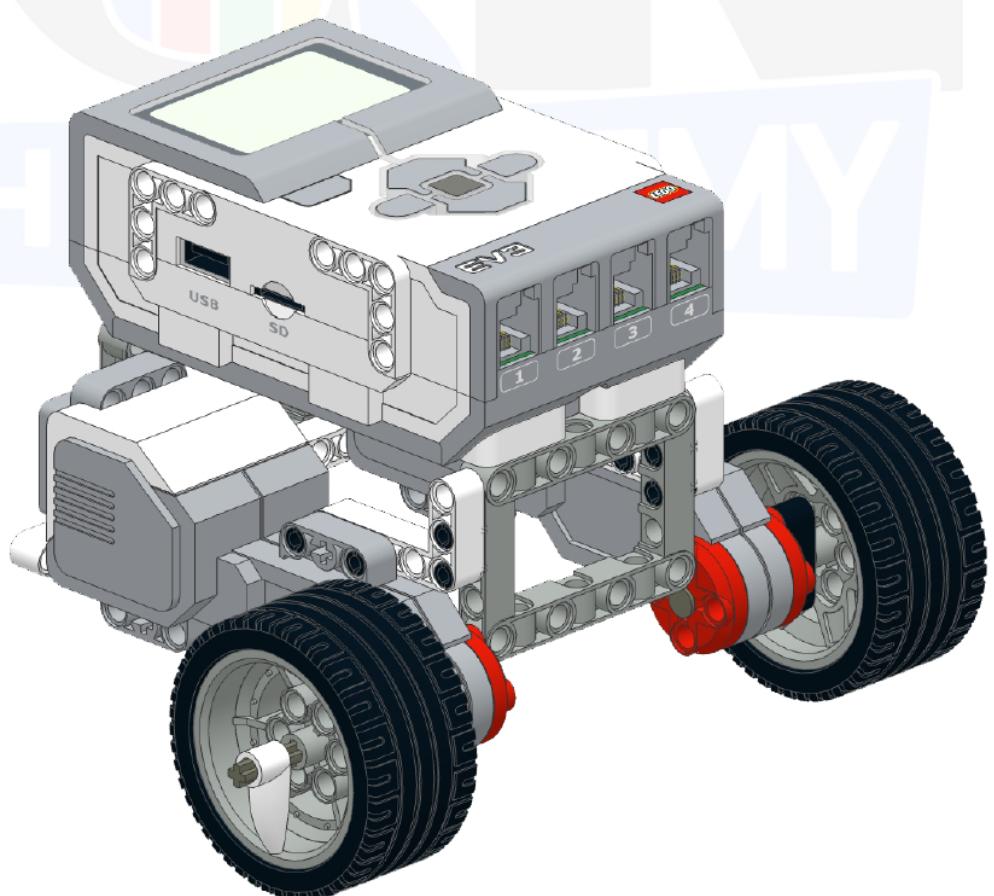
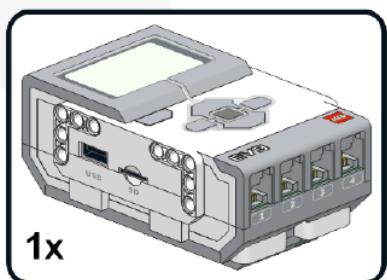


## Dar la vuelta a la base

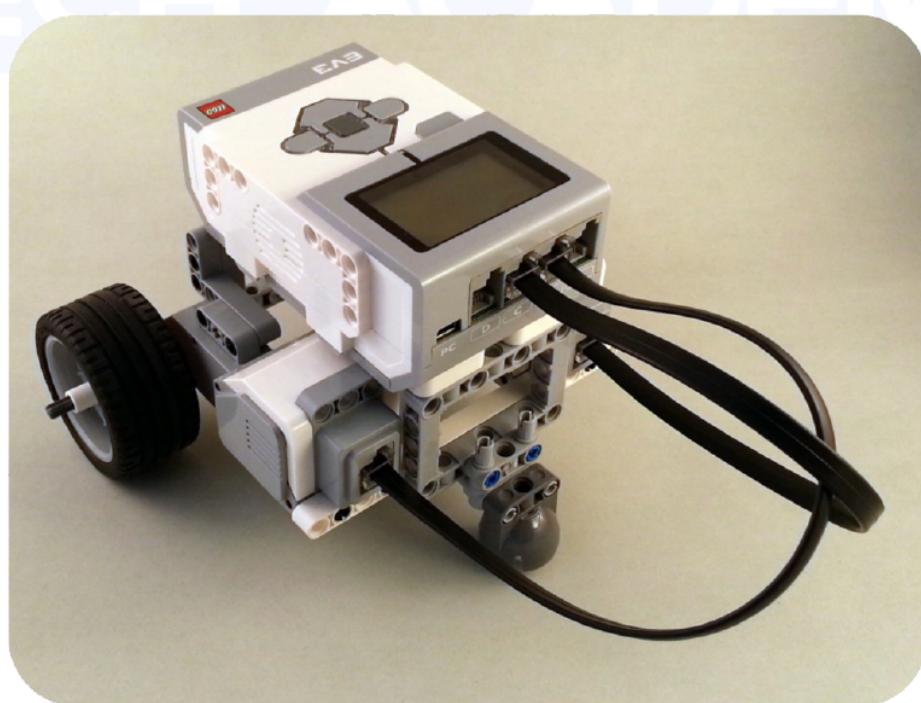
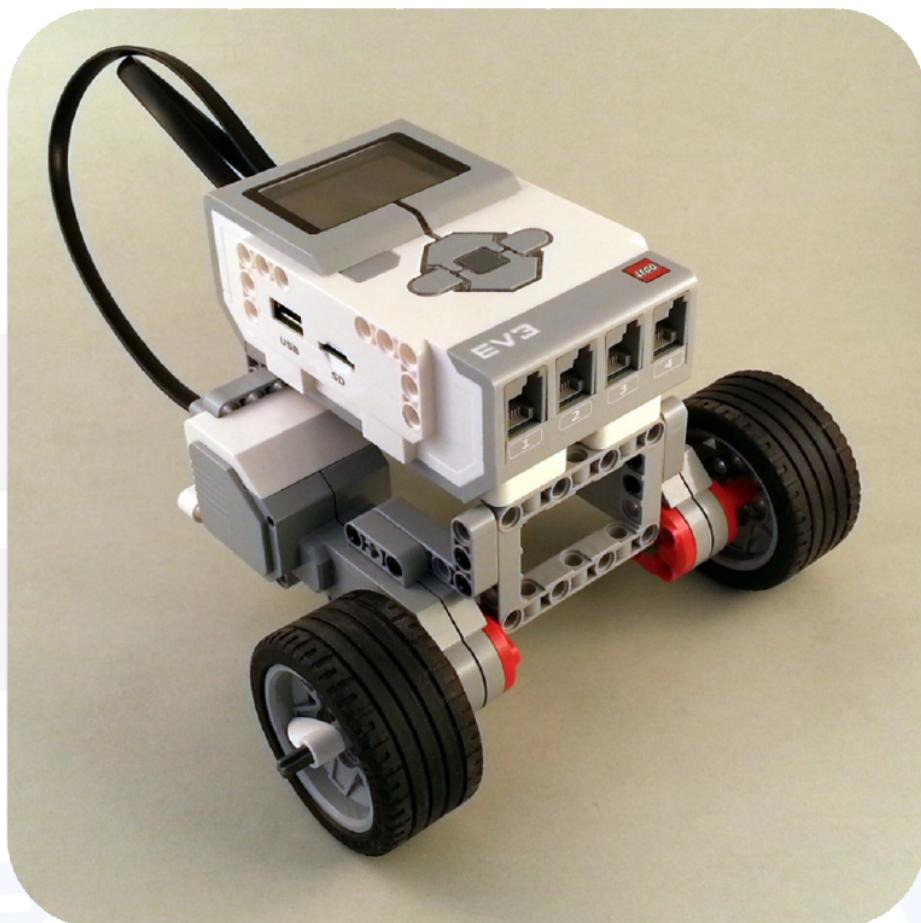
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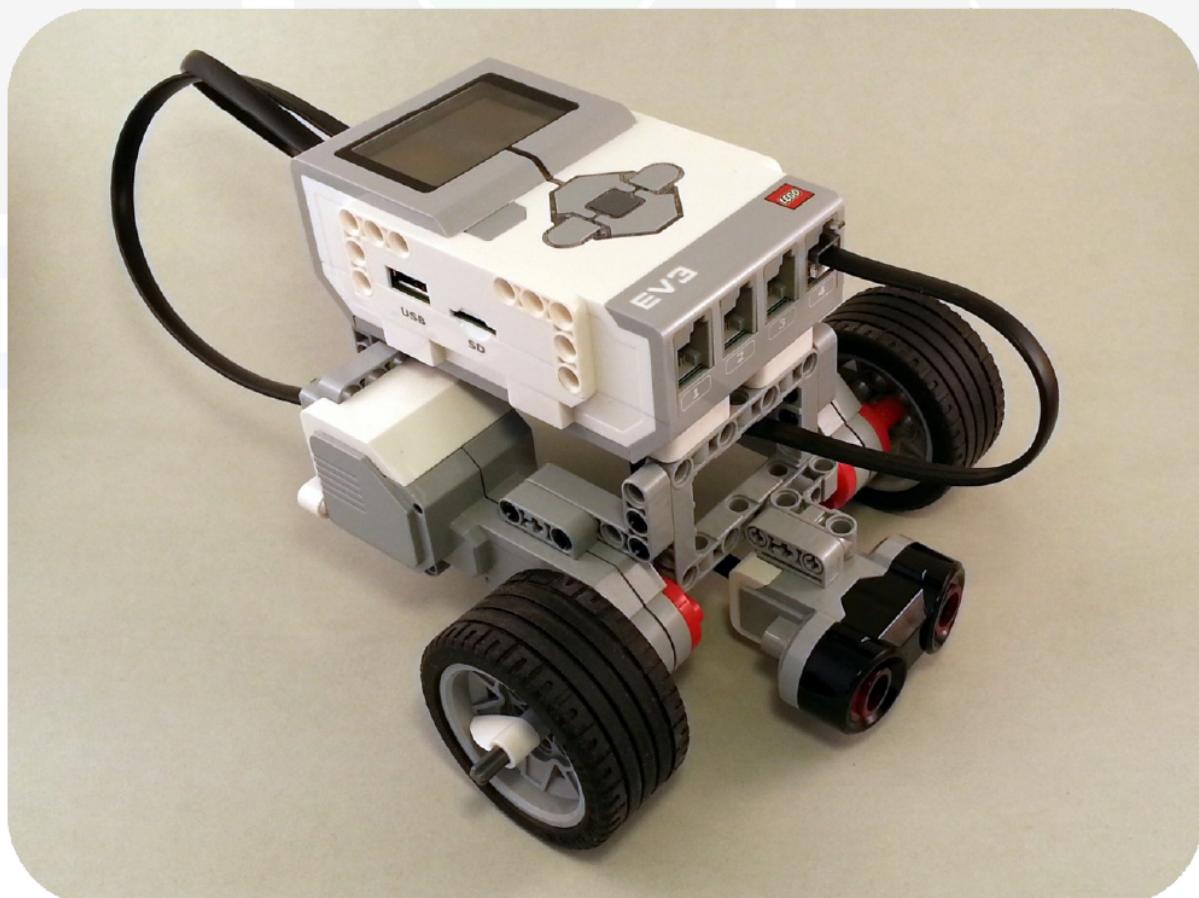
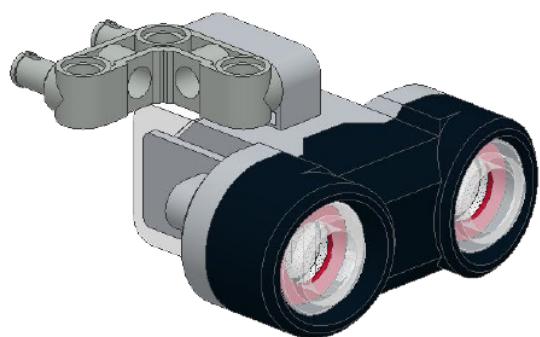
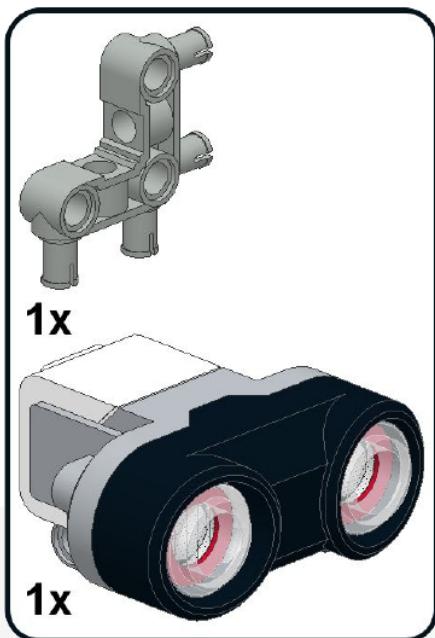
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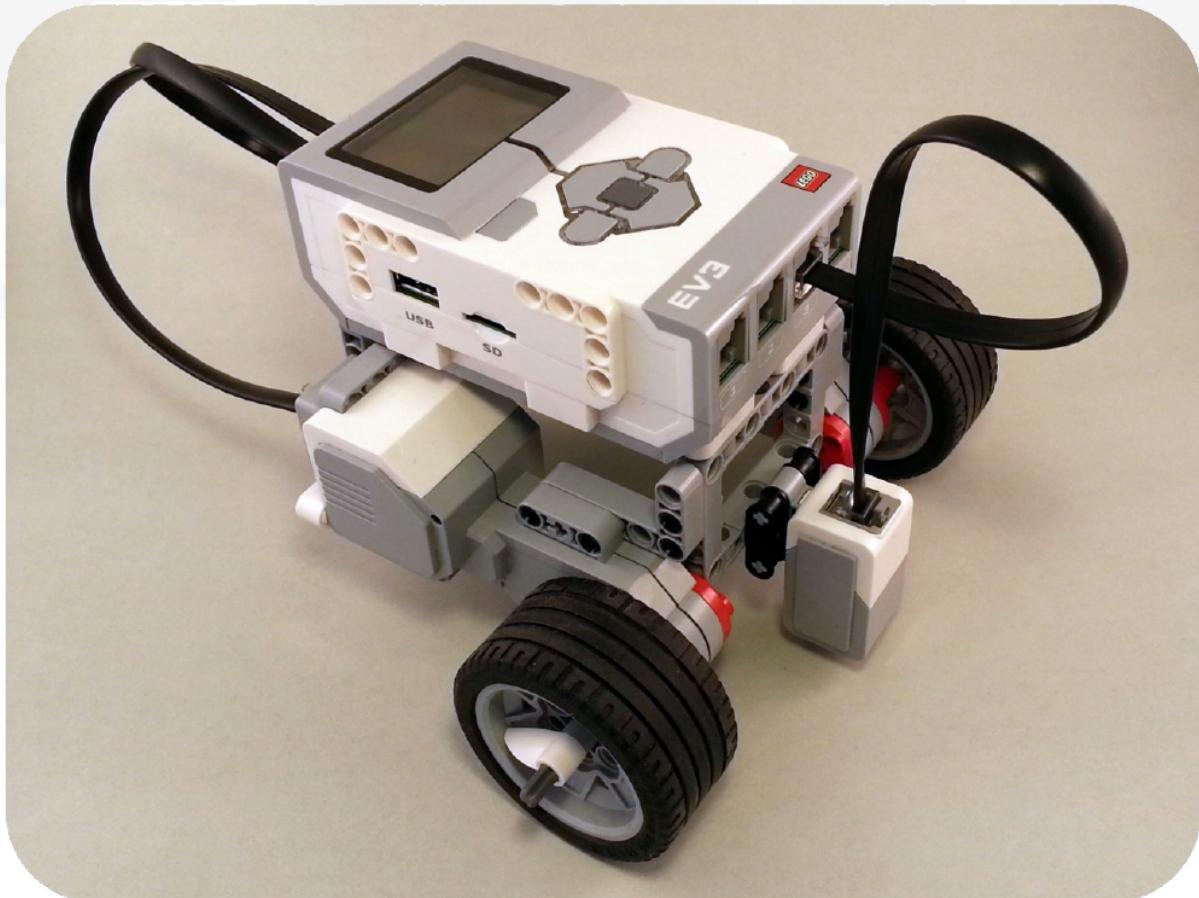
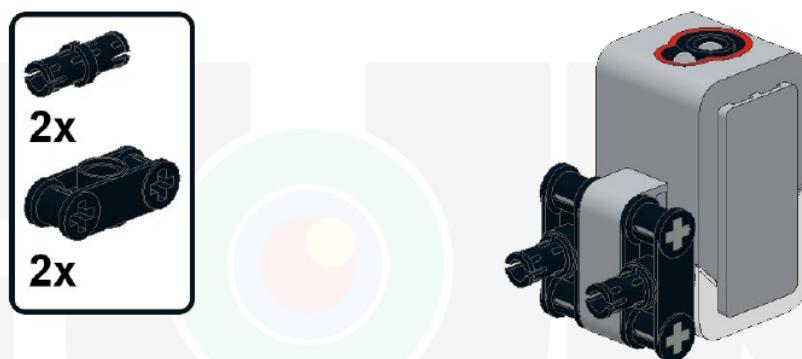
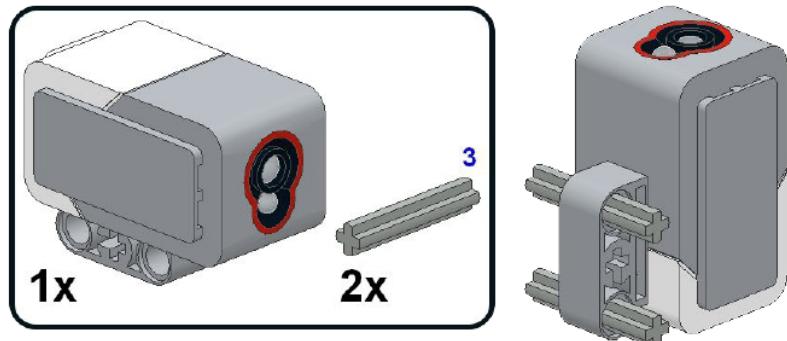
## Conectar los cables



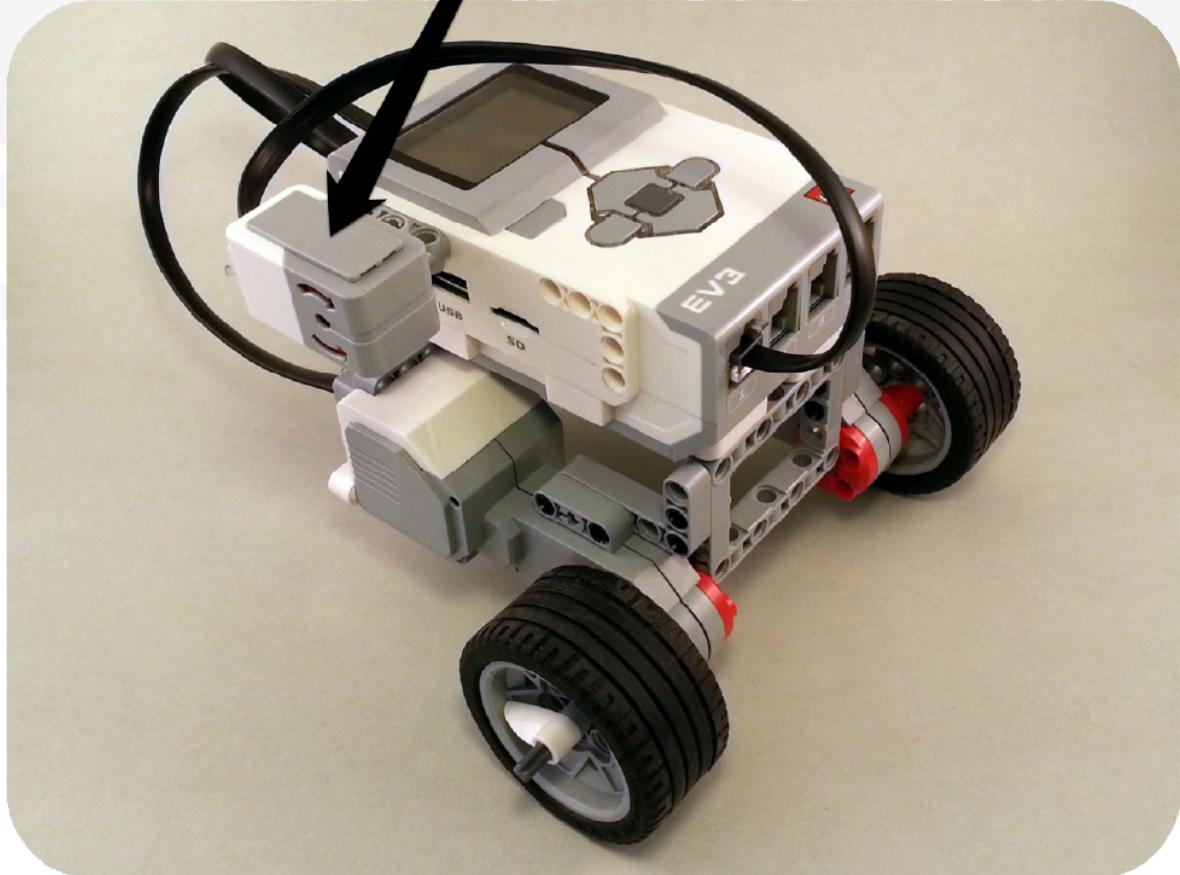
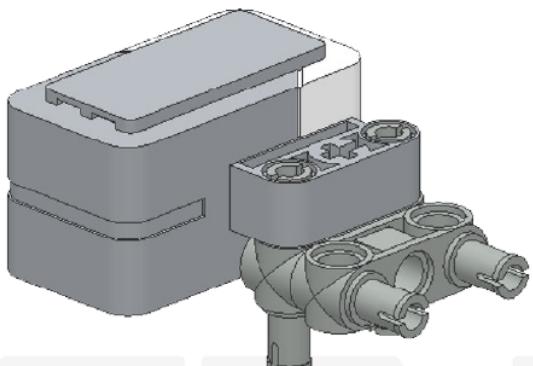
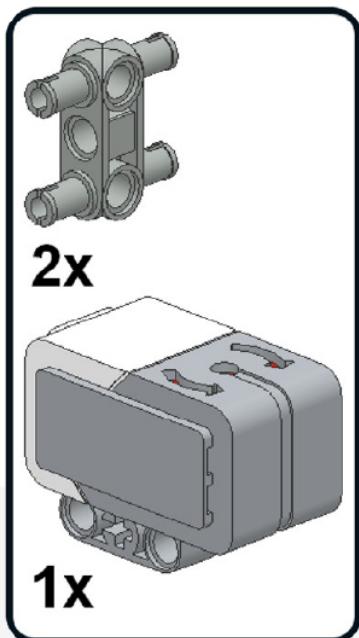
## Montaje del sensor ultrasónico



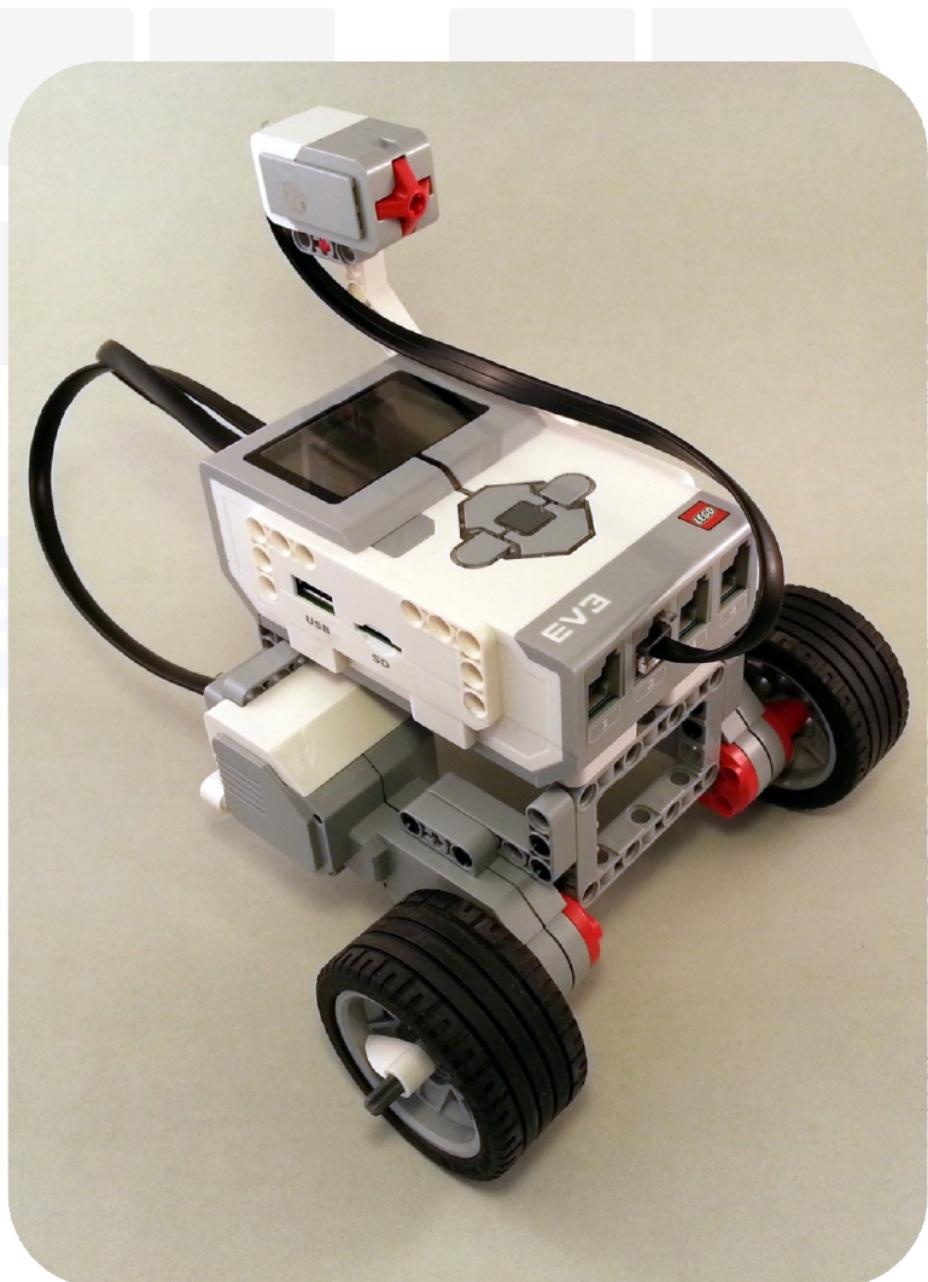
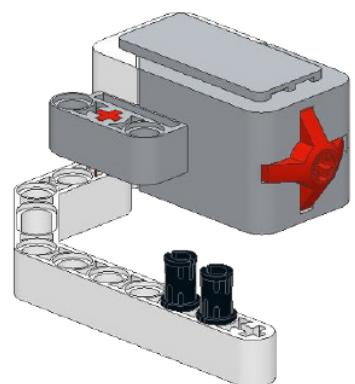
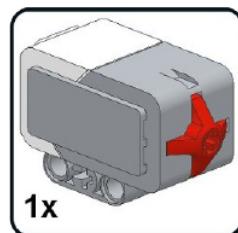
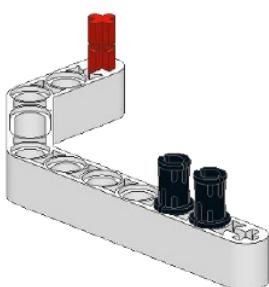
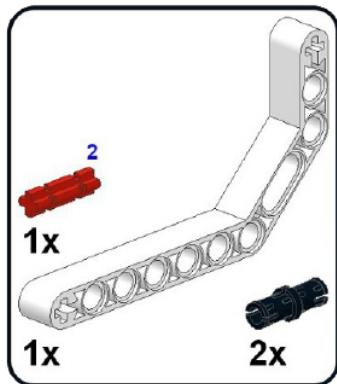
## Montaje del sensor de color



## Montaje del girosensor



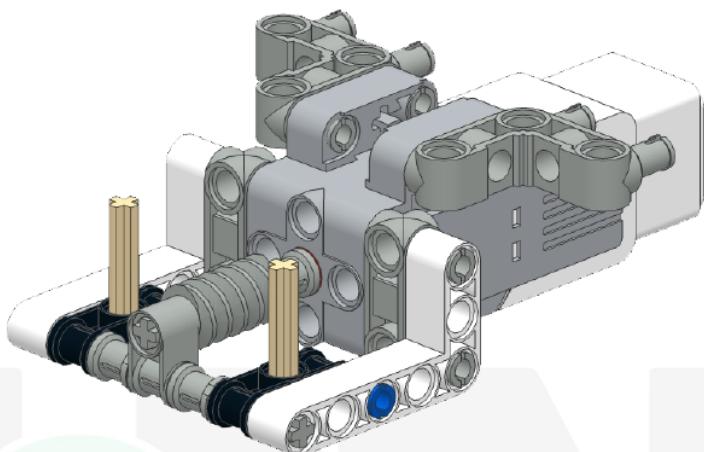
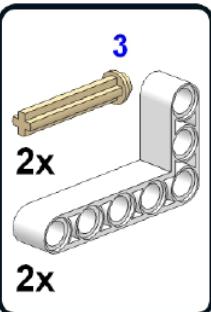
## Montaje del sensor táctil



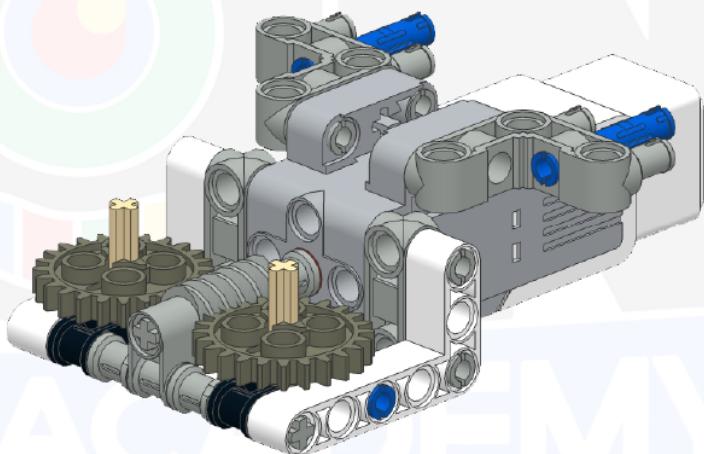
# Montaje de pinza

- 1**
- 2**
- 3**
- 4**

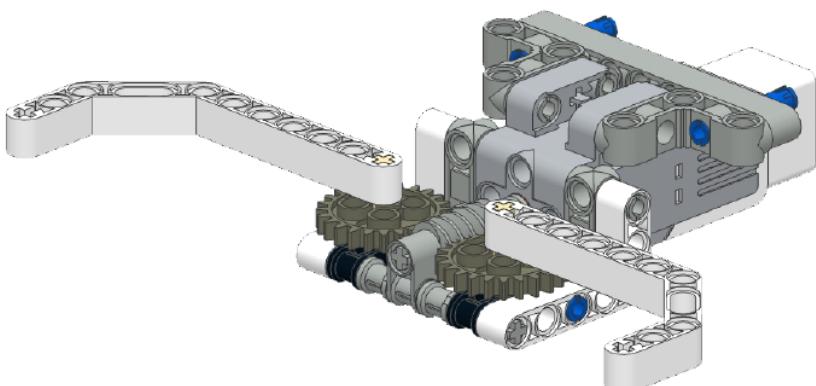
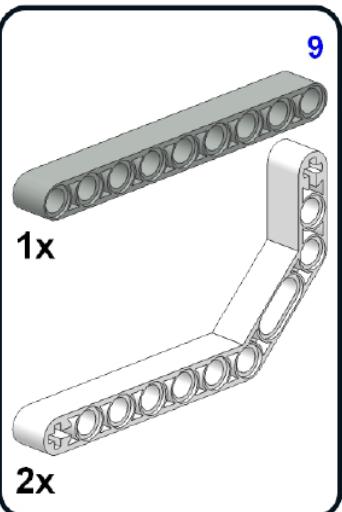
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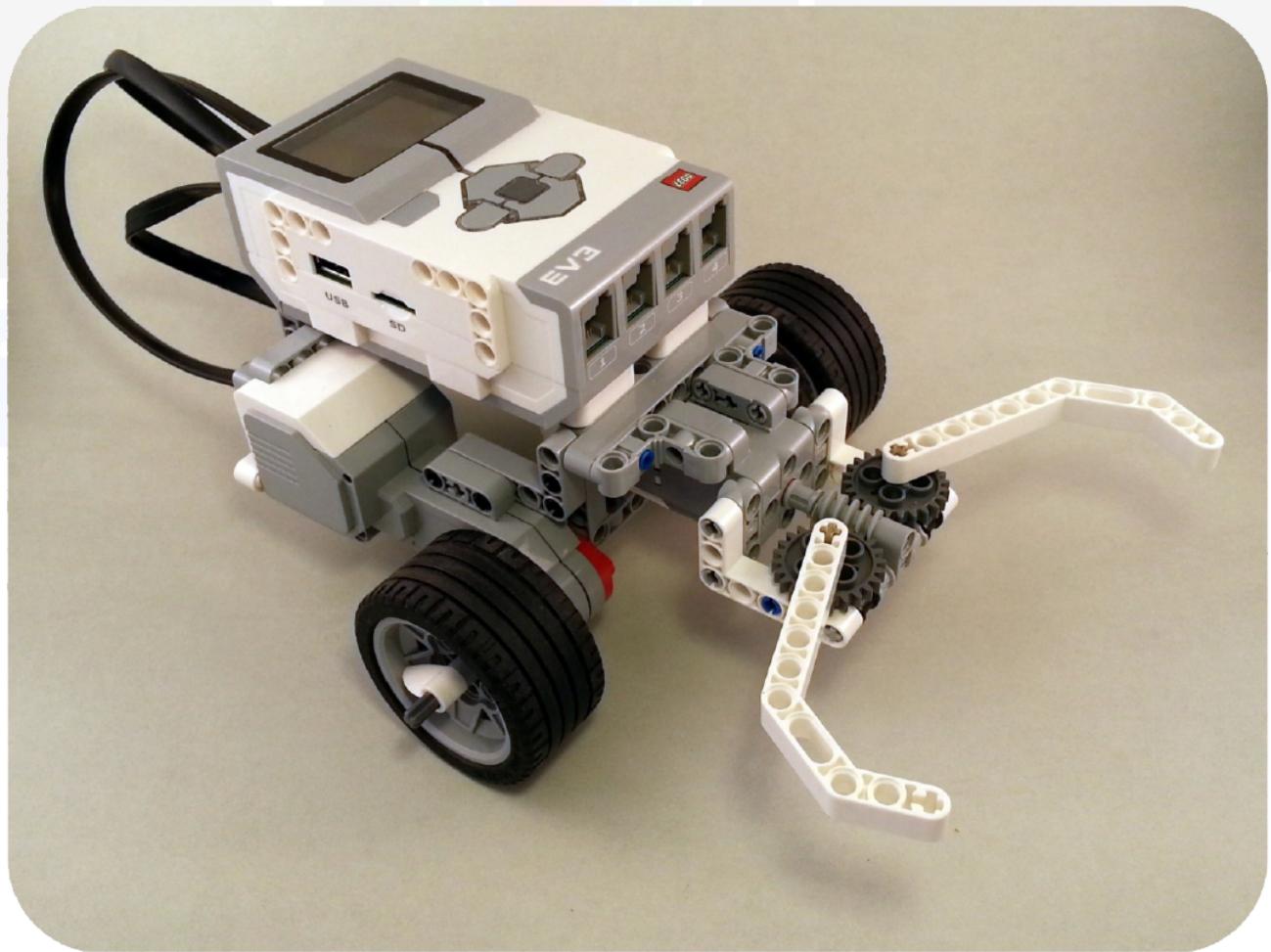
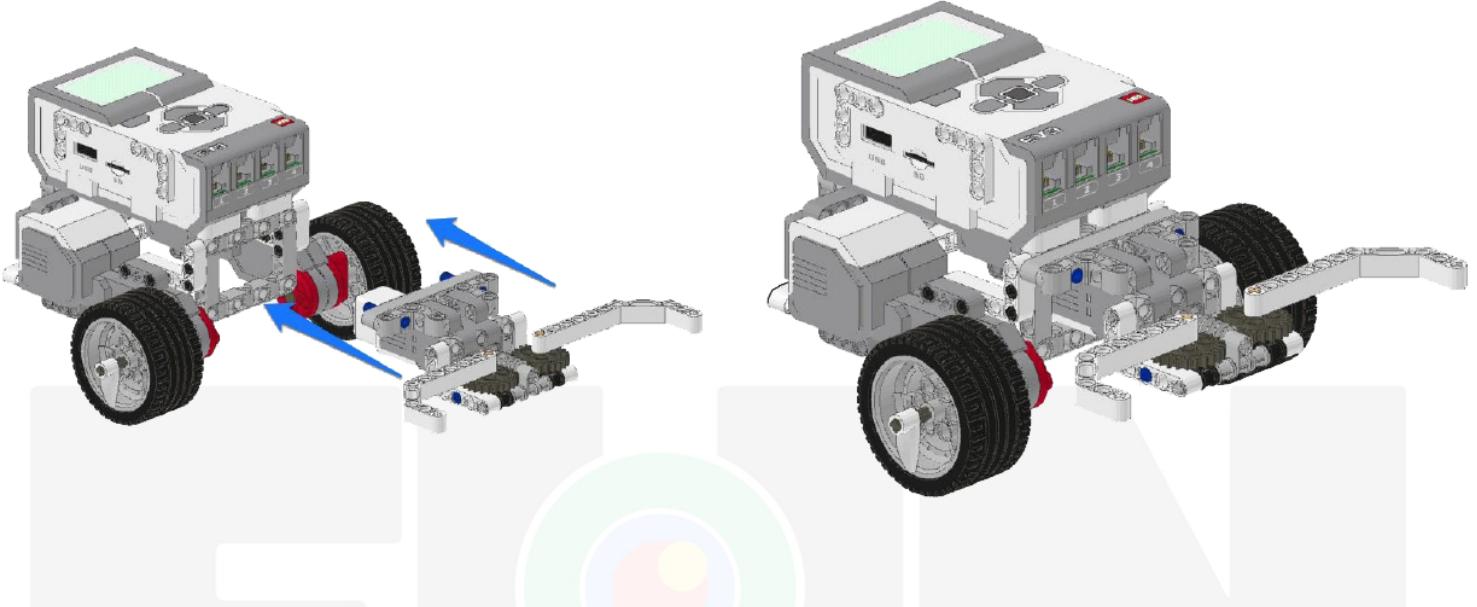
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**7**

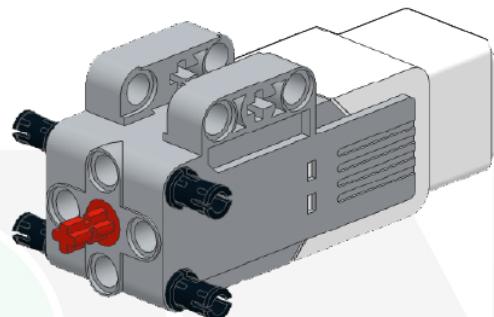
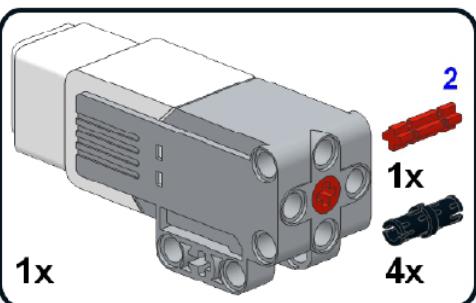


## Añade la pinza a la parte delantera del robot

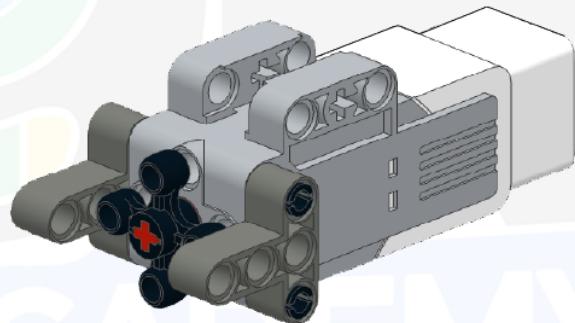
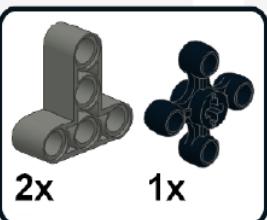


# Accesorio de recogida de carga

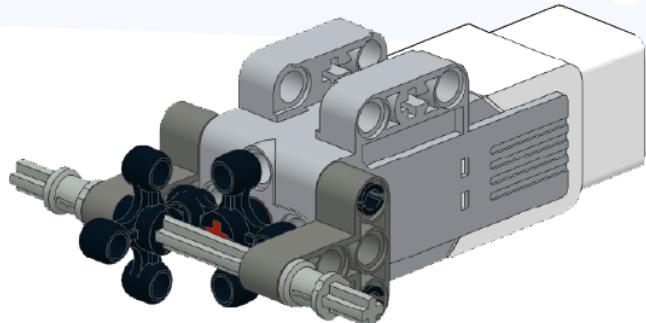
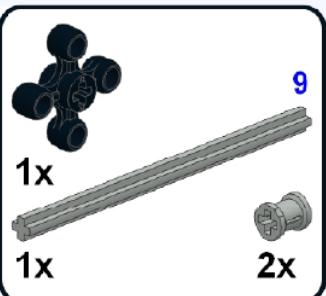
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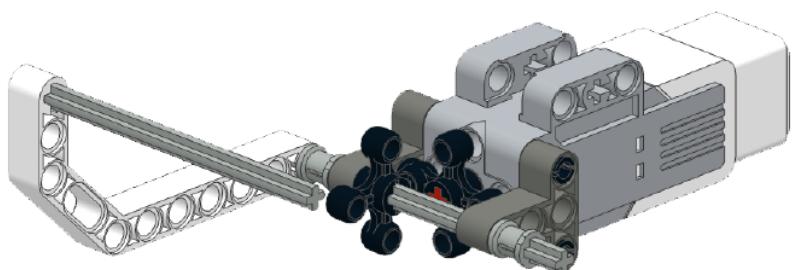
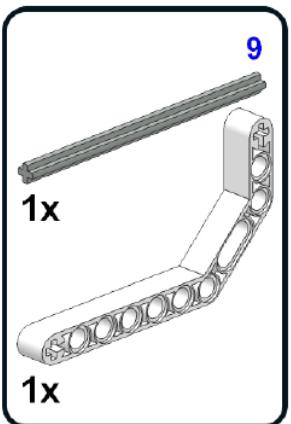
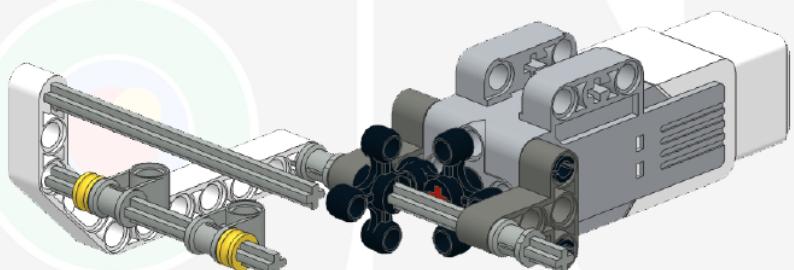
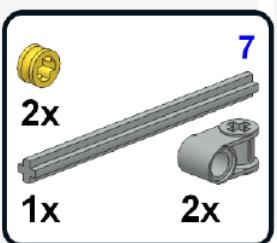
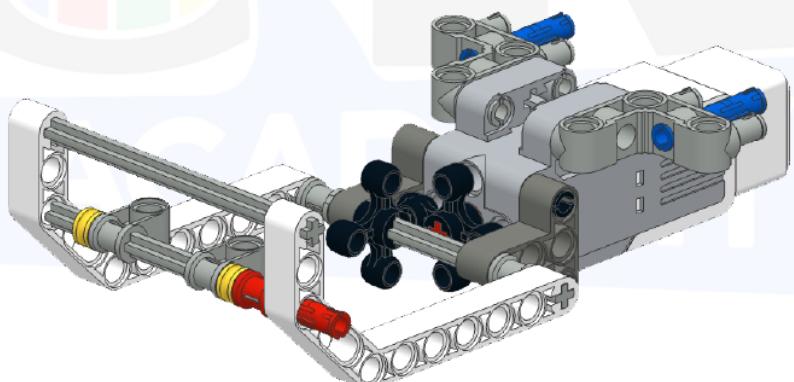
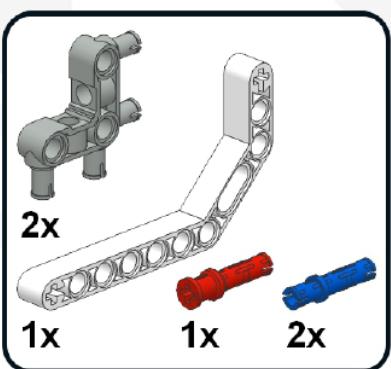
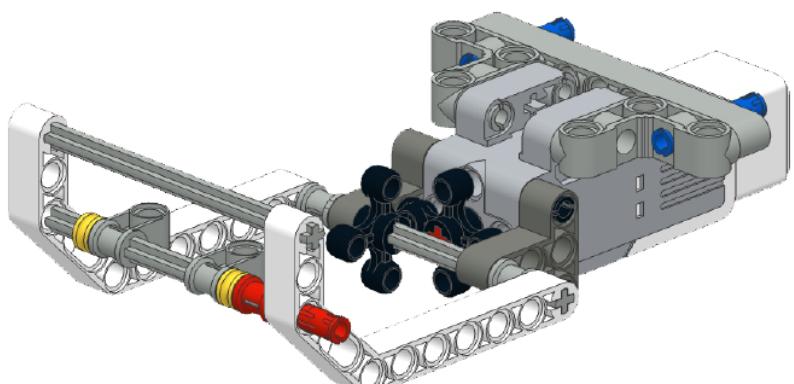
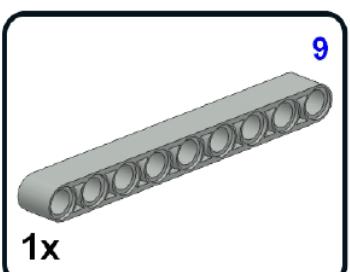


2



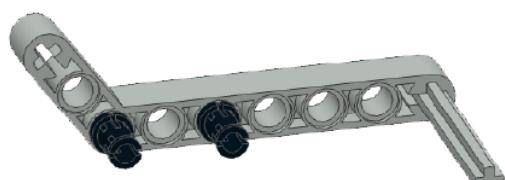
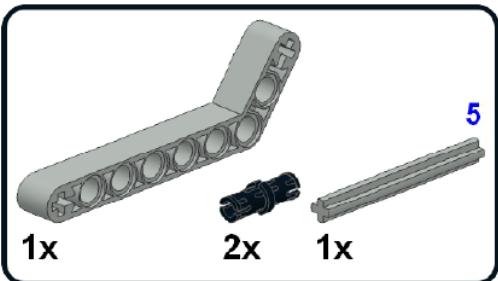
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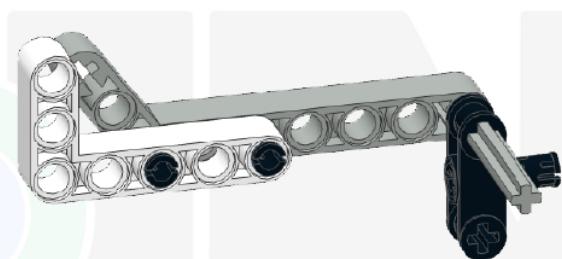
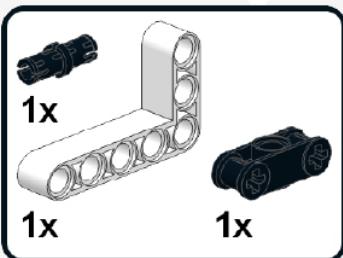
**4****5****6****7**

# Montaje combinado de sensores de color y ultrasónico

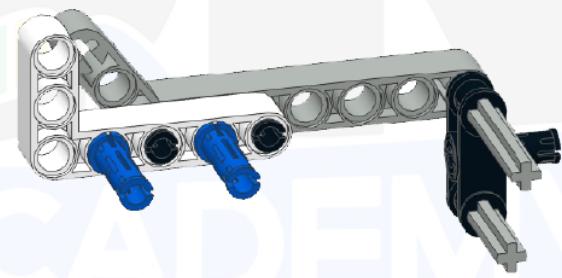
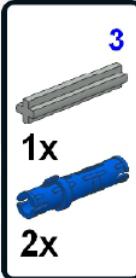
1



2



3



4

