

# LAPLACE TRANSFORM

# The Laplace transform

Figure 2.10 illustrates the definition of the **Laplace transform**. Given a signal  $x(t)$  and a complex number  $s = \sigma + j\omega$ , we define

$$X(s) \triangleq \int_{-\infty}^{\infty} x(t)e^{-st} dt = \int_{-\infty}^{\infty} x(t)e^{-(\sigma+j\omega)t} dt.$$

The above integral may diverge for some values of  $s$ . The set of all complex numbers  $s$  for which the above integral converges is called the **region of convergence (ROC)** of the Laplace transform of  $x(t)$ .

This is called the **bilateral** (or **two-sided**) Laplace transform. We can also define the **unilateral** (or **one-sided**) Laplace transform:

$$X(s) = \int_0^{\infty} x(t)e^{-st} dt.$$

We will deal with the one-sided Laplace transform, because that will allow us to deal conveniently with systems that have nonzero initial conditions.

## The Laplace transform: an example

As an example, let us consider  $x(t) = e^{-bt}u(t)$ , where  $b$  is real or complex.

$$\begin{aligned} X(s) &= \int_0^{\infty} x(t)e^{-st} dt \\ &= \int_0^{\infty} e^{-(b+s)t} dt \\ &= \lim_{T \rightarrow \infty} \left[ -\frac{1}{b+s} e^{-(b+s)t} \right]_0^T \\ &= \frac{1}{b+s} - \frac{1}{b+s} \lim_{T \rightarrow \infty} \left[ e^{-(b+s)T} \right]. \end{aligned}$$

The above limit will be equal to 0 if  $\text{Re}(b+s) > 0$ ; otherwise, it does not exist. Hence,

$$X(s) = \frac{1}{s+b}, \quad \text{if } \text{Re}(b+s) > 0.$$

Thus, the ROC is the set of all complex numbers  $s$ , such that  $\text{Re } s > -\text{Re } b$ .

# Properties of the Laplace transform

Just as the Fourier transform, the Laplace transform has a number of useful properties which we will learn to exploit. We will look at and prove a few of these.

We will use the notation  $x(t) \leftrightarrow X(s)$  to denote the fact that  $X(s)$  is the Laplace transform of  $x(t)$ ; we will also use the notation  $X(s) = \mathcal{L}[x(t)]$ . First of all, the Laplace transform is linear: if  $X_1(s) = \mathcal{L}[x_1(t)]$  and  $X_2(s) = \mathcal{L}[x_2(t)]$ , then for any constants  $a_1$  and  $a_2$

$$\mathcal{L}[a_1x_1(t) + a_2x_2(t)] = a_1\mathcal{L}[x_1(t)] + a_2\mathcal{L}[x_2(t)] = a_1X_1(s) + a_2X_2(s).$$

This is obvious from definitions.

## Properties: right shift in time

IF  $X(s) = \mathcal{L}[x(t)]$ , then for any real number  $c > 0$  we have

$$x(t - c)u(t - c) \leftrightarrow e^{-cs}X(s).$$

**Proof:**

$$\begin{aligned}\mathcal{L}[x(t - c)u(t - c)] &= \int_0^{\infty} x(t - c)u(t - c)e^{-st}dt \\ &= \int_c^{\infty} x(t - c)e^{-st}dt \\ &= \int_0^{\infty} x(t)e^{-s(t+c)}dt \\ &= e^{-cs} \int_0^{\infty} x(t)e^{-st}dt \\ &= e^{-cs}X(s).\end{aligned}$$

## Right shift in time: example

**Ex.:** consider the rectangular pulse

$$x(t) = \begin{cases} 1, & 0 \leq t < c \\ 0, & \text{otherwise} \end{cases}$$

We can write

$$x(t) = u(t) - u(t - c).$$

Then, using linearity and shift property we get

$$X(s) = \frac{1}{s} - \frac{e^{-cs}}{s} = \frac{1 - e^{-cs}}{s}.$$

The ROC is  $\{s \in \mathbb{C} : \operatorname{Re} s > 0\}$ .

## Properties: multiplication by a power of $t$

If  $X(s) = \mathcal{L}[x(t)]$ , then

$$\mathcal{L}[t^N x(t)] = (-1)^N \frac{d^N}{ds^N} X(s)$$

**Proof:** similar to the corresponding property of the Fourier transform.

**Ex.:**  $x(t) = t^N u(t)$ .

$$X(s) = (-1)^N \frac{d^N}{ds^N} \left( \frac{1}{s} \right) = \frac{N!}{s^{N+1}}.$$

In particular, for the unit ramp  $x(t) = tu(t)$  we have

$$X(s) = \frac{1}{s^2}.$$

**Ex.:**  $x(t) = te^{-bt}u(t)$ .

$$X(s) = (-1) \frac{d}{ds} \left( \frac{1}{s+b} \right) = \frac{1}{(s+b)^2}.$$

## Properties: multiplication by an exponential

If  $X(s) = \mathcal{L}[x(t)]$ , then

$$\mathcal{L}[e^{at}x(t)] = X(s - a)$$

for any  $a$ , real or complex.

**Proof:**

$$\begin{aligned}\mathcal{L}[e^{at}x(t)] &= \int_0^{\infty} x(t)e^{at}e^{-st}dt \\ &= \int_0^{\infty} x(t)e^{-(s-a)t}dt \\ &= X(s - a).\end{aligned}$$

**Ex.:**  $x(t) = [u(t) - u(t - c)]e^{at}$ , where  $c > 0$  and  $a$  is a real number.

Then

$$X(s) = \frac{1 - e^{-c(s-a)}}{s - a}.$$



## Laplace transform of cosine and sine

$$\textcircled{1} \quad x(t) = \cos(\omega_0 t)u(t) = \frac{1}{2} [e^{j\omega_0 t} + e^{-j\omega_0 t}] u(t)$$

$$\begin{aligned} X(s) &= \frac{1}{2} \left[ \frac{1}{s - j\omega_0} + \frac{1}{s + j\omega_0} \right] \\ &= \frac{1}{2} \cdot \frac{2s}{s^2 + \omega_0^2} \\ &= \frac{s}{s^2 + \omega_0^2}. \end{aligned}$$

$$\textcircled{2} \quad x(t) = \sin(\omega_0 t)u(t) = \frac{1}{2j} [e^{j\omega_0 t} - e^{-j\omega_0 t}]$$

$$\begin{aligned} X(s) &= \frac{1}{2j} \left[ \frac{1}{s - j\omega_0} - \frac{1}{s + j\omega_0} \right] \\ &= \frac{1}{2j} \cdot \frac{2j\omega_0}{s^2 + \omega_0^2 + 0} \\ &= \frac{\omega_0}{s^2 + \omega_0^2}. \end{aligned}$$

## Exponentially damped sinusoids

①  $x(t) = e^{-bt} \cos(\omega_0 t) u(t)$

$$X(s) = \frac{s + b}{(s + b)^2 + \omega_0^2}$$

②  $x(t) = e^{-bt} \sin(\omega_0 t) u(t)$

$$X(s) = \frac{\omega_0}{(s + b)^2 + \omega_0^2}$$

## Properties: differentiation in time domain

If  $X(s) = \mathcal{L}[x(t)]$ , then

$$\mathcal{L}\left[\frac{d}{dt}x(t)\right] = sX(s) - x(0),$$

(when  $x(t)$  is discontinuous at  $t = 0$  or if it contains an impulse or the derivative of an impulse at  $t = 0$ ,  $x(0)$  should be replaced by  $x(0^-)$ ).

**Proof:** assume that, as  $t \rightarrow \infty$ ,  $x(t)$  decays faster than an exponential, i.e.,  $|x(t)| < Ce^{-at}$  for  $t$  large enough and for some  $C \geq 0$  and  $a > 0$ . Then we integrate by parts to get

$$\begin{aligned}\mathcal{L}\left[\frac{d}{dt}x(t)\right] &= \int_0^\infty \left(\frac{d}{dt}x(t)\right) e^{-st} dt \\ &= [x(t)e^{-st}]_0^\infty + s \int_0^\infty x(t)e^{-st} dt \\ &= -x(0) + sX(s),\end{aligned}$$

where we have used the exponential decay of  $x(t)$ .

## Differentiation in time domain

**Ex.:**  $x(t) = \delta(t)$ . Since  $\delta(t) = (d/dt)u(t)$ , we have

$$\mathcal{L}[\delta(t)] = s \cdot \frac{1}{s} - u(0^-) = 1.$$

For the second derivative, we have

$$\mathcal{L} \left[ \frac{d^2}{dt^2} x(t) \right] = s^2 X(s) - sx(0) - x'(0),$$

where  $x(0)$  and  $x'(0)$  are, respectively, the values of  $x(t)$  and  $x'(t)$  at  $t = 0$ .

## Properties: integration in time domain

If  $X(s) = \mathcal{L}[x(t)]$ , then

$$\mathcal{L} \left[ \int_0^{\infty} x(\lambda) d\lambda \right] = \frac{1}{s} X(s).$$

**Proof:** define the function

$$v(t) = \begin{cases} \int_0^t x(\lambda) d\lambda, & t \geq 0 \\ 0, & t < 0 \end{cases}$$

Then  $v'(t) = x(t)$  for  $t \geq 0$ ; since we are dealing with the one-sided Laplace transform, we assume that  $x(t) = 0$  for  $t < 0$ . Hence, by the differentiation in time domain property we get

$$X(s) = sV(s),$$

so  $V(s) = (1/s)X(s)$ .

## Properties: convolution in time domain

If  $X(s) = \mathcal{L}[x(t)]$  and  $V(s) = \mathcal{L}[v(t)]$ , then

$$\mathcal{L}[x(t) \star v(t)] = X(s)V(s).$$

**Ex.:** let  $x(t) = v(t) = u(t) - u(t - 1)$ . Then

$$X(s) = \frac{1 - e^{-s}}{s}$$

and

$$\mathcal{L}[x(t) \star x(t)] = X^2(s) = \left( \frac{1 - e^{-s}}{s} \right)^2 = \frac{1 - 2e^{-s} + e^{-2s}}{s^2}.$$

We can actually invert this Laplace transform using its properties:

$$x(t) = tu(t) - 2(t - 1)u(t - 1) + (t - 2)u(t - 2).$$

## Properties: initial-value theorem

Given a signal  $x(t)$  with the Laplace transform  $X(s)$ , we can compute the initial values  $x(0)$  and  $x'(0)$  via

$$x(0) = \lim_{s \rightarrow \infty} sX(s)$$

and

$$x'(0) = \lim_{s \rightarrow \infty} [s^2 X(s) - sx(0)]$$

This property is called the **Initial-Value Theorem** (IVT).

**Ex.:** suppose the signal  $x(t)$  has the Laplace transform

$$X(s) = \frac{-s^2 + 1}{2s^3 + 3s^2 + 1}.$$

Then

$$x(0) = \lim_{s \rightarrow \infty} sX(s) = \lim_{s \rightarrow \infty} \frac{-s^3 + s}{2s^3 + 3s^2 + 1} = -\frac{1}{2}.$$

## Properties: final-value theorem

Given a signal  $x(t)$ , such that the limit

$$x(\infty) \triangleq \lim_{t \rightarrow \infty} x(t)$$

(called the **final value of**  $x(t)$ ) exists, we have

$$x(\infty) = \lim_{s \rightarrow 0} sX(s).$$

Note that the limit on the right-hand side may exist, but it will only equal  $x(\infty)$  if the latter limit is well-defined. This property is called the **Final-Value Theorem (FVT)**.

**Ex.:** suppose

$$X(s) = \frac{1}{s^2 + 1}.$$

Then

$$\lim_{s \rightarrow 0} sX(s) = \lim_{s \rightarrow 0} \frac{s}{s^2 + 1} = 0.$$

However,  $X(s) = \mathcal{L}[\sin(t)u(t)]$ , and  $\sin(t)u(t)$  does not have a final value.