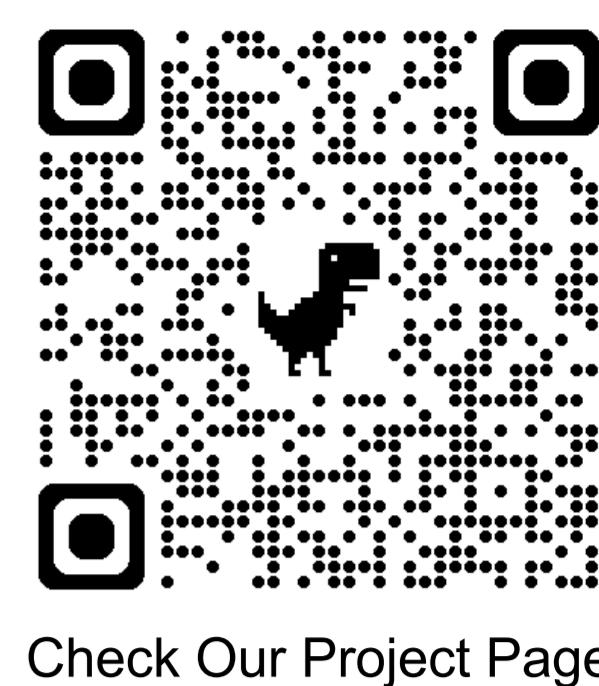




Check Our GitHub Repo



Check Our Project Page

Motivation

Based on "Tour into the Picture" (TIP) [2] approach, we aim to develop autonomous algorithms that infer two key structures from a single 2D image: the regular, program-like textures or patterns on 2D planes and the 3D positioning of these planes within the scene.

For example, from a single Metro Station image in Fig.1, we can infer the camera pose, partition the image into distinct planes (walls, floor, ceiling, and far plane), and recognize repeated patterns.

Contributed by Hongru Li.

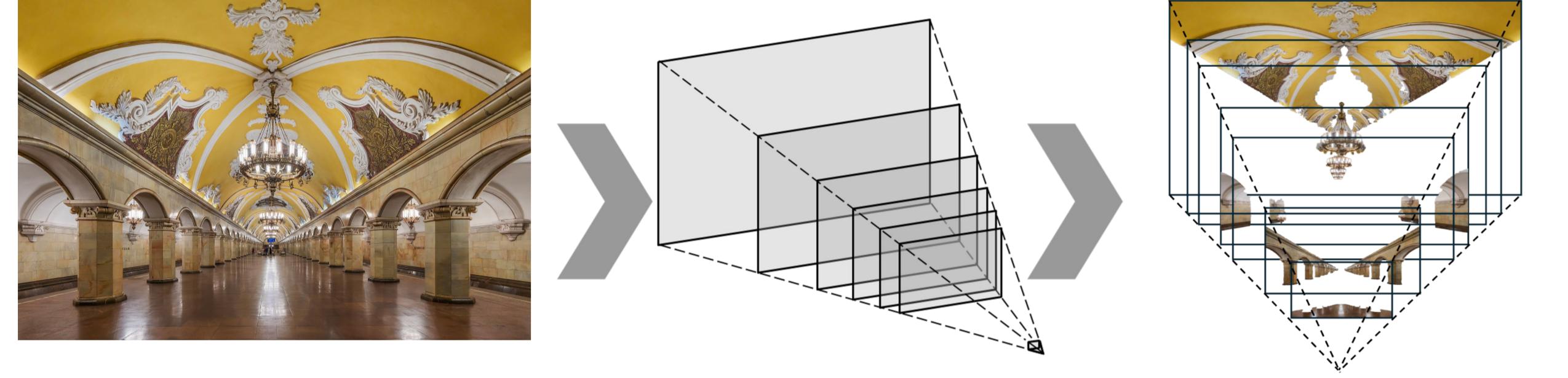


Figure 1. Illustration of Image Decomposition - Wenbo Ji

Introduction

The project aims to develop a graphical user interface (GUI) that allows users to extract a simple scene model from a single 2D image, facilitating easy animation and scene manipulation.

Contributed by Shilin Zhang.

Algorithm Structure

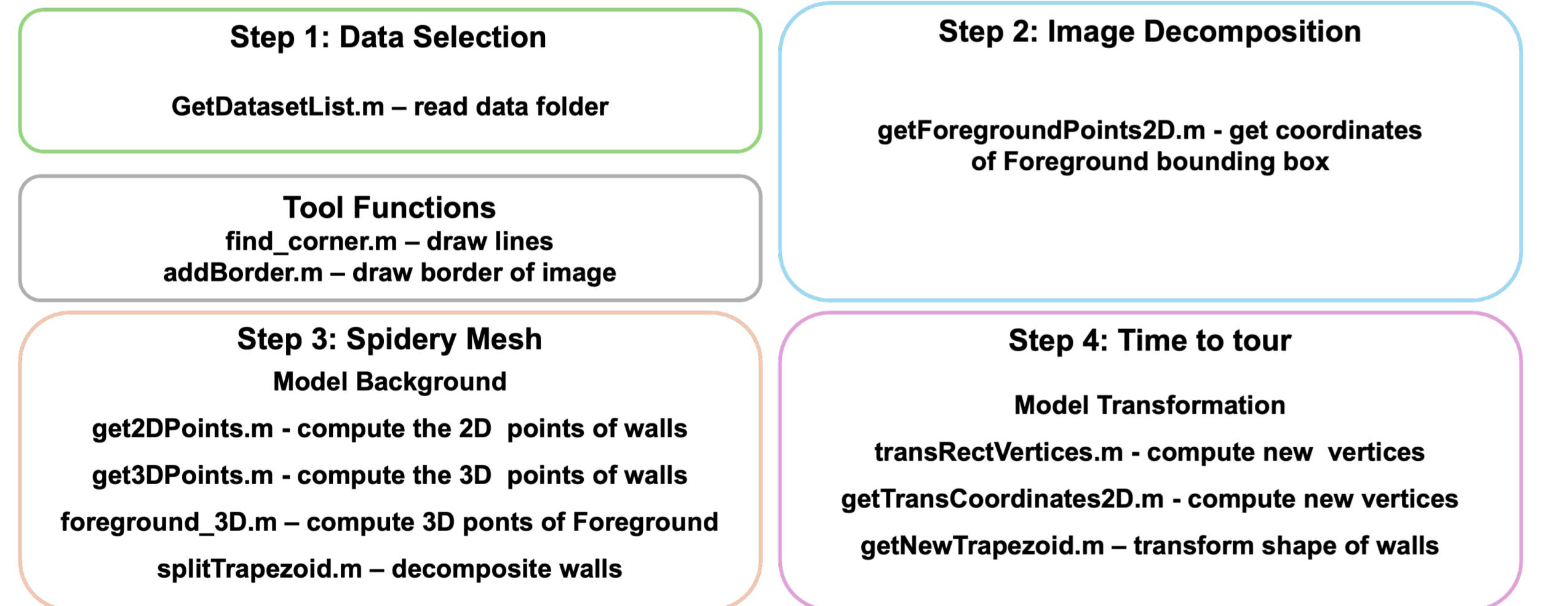


Figure 2. Illustration of Algorithm Structure - Wenbo Ji

Challenge & Solution

- Blurry Inpainting of Background** The segmentation of foreground objects can't get clean result. Also the inpainting of background sometimes fail to restore the occlusion areas.
- Possible Solution** We can employ new inpainting method such as diffusion-based Network.

Contributed by Wenbo Ji.

Method

The figure shows a MATLAB application window with four tabs: Step 1: Data Selection, Step 2: Image Decomposition, Step 3: Spidery Mesh, and Step 4: Time to tour. Each tab displays a screenshot of the application's interface. The Data Selection tab shows a file selection dialog. The Image Decomposition tab shows a foreground object highlighted with a polygon. The Spidery Mesh tab shows a 3D wireframe model of the scene. The Time to tour tab shows camera pose adjustment sliders and a QR code.

Contributed by Wenbo Ji.

Experiment Results



Contributed by Yuming Li.

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