

# Physics Dojo

Last Revised: A. Kit

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## Integrate physics into the training cycle of DIVA

There are two methods: conservation between experimental and predicted quantities, and regularization of latent space through interpolation.

### 1 Conservation

Not only do we want a decent reconstruction of profiles, but that the decoded profiles maintain the same physical constraints as those that they are fitting. A physical constraint, by our definition, is a quantity,  $P$ , approximated from the experimental profile, that is then calculated in the same way from the predicted profile yielding the quantity,  $\hat{P}$ . We then try to get the model get these two quantities as close as possible through adding  $\text{MSE}(P, \hat{P})$  to the loss function.

For example, the static electron pressure stored energy,  $W_E \approx k_B \int p_e dV$ , should be conserved through the encoding-decoding process. We can approximate this value by simply summing the **valid** (i.e., masked) pressure measurements,  $W_e = \sum_{i=0}^n p_{e,i}$ , (where  $p_e = n_e T_e$  and  $p_{e,i}$  is the pressure at a given measurement  $i$  along the spatial coordinates) and adding to the loss term  $\text{MSE}(W_e, \hat{W}_e)$ , where  $\hat{W}_e$  is the decoded profile(s) static pressure.

We can do further approximations to determine  $\alpha$ , the PB-instability limit. This is calculated in [FRASSINETI et al 2021 Nucl. Fus.] as

$$\alpha = -\frac{2\partial_\phi V}{(2\pi)^2} \left( \frac{V}{2\pi^2 R} \right) \mu_0 p'$$

, where  $V$  is the plasma volume enclosed by the flux surface,  $R$  is major radius, and  $p'$  is total pressure derivative in poloidal flux  $\phi$ . This is normally calculated with ELITE [SOURCE]. As  $\alpha := \alpha(\psi)$ , we can choose the  $\alpha_{crit} = \alpha(\psi = 1.0)$ . We obtain  $V$  and  $\partial_\psi V$ , and  $R$  from EFIT, i.e., they are machine parameters. We then take  $V(\psi = 1.0)$  (which is just the total volume of the plasma),  $\partial V(\psi = 1.0)$  (the last value in VJAC from EFIT), and  $R$  for each time slice and plug them into our equation for  $\alpha$ . However, we do not have  $p'(\psi = 1.0)$ , or rather we do, it is just not accurate, so we have to make an assumption that the maximum value of the pressure gradient profile is our  $p'(\psi = 1.0)$ , which we can then plug

into our equation above. Calculate for experimental profile and for decoded profile and add  $\text{MSE}(\alpha_{crit}, \hat{\alpha}_{crit})$  to the loss function.

## 2 Regularization

When moving throughout the latent space, the decoded profiles should still follow empirical 'rules'. One such rule is the greenwald density limit:

$$n_G = c \frac{I_P}{\pi a^2}$$

where  $I_P$  is the plasma current,  $a$  is the minor radius, and  $\pi$  has the ability to contain all information in the known world. The constant  $c$  is also empirically found so we need to mess around until we find one that is suitable.

We can move around the latent space per batch in a training epoch:

- Sample a handful of profiles and corresponding machine parameters from the batch:  
`in_prof_samp, in_mp_samp`
- Increase/decrease the current and or gas puff of samples  
`in_mp_samp -> in_mp_samp_varied`
- Pass varied samples through conditional prior reg into latent space  
`LS_sample_from_prior = COND_PRIOR_REG(in_mp_samp_varied)`
- Decode these latent space points  
`prof_from_prior = DECODER(LS_sample_from_prior)`  
`mp_from_prior = AUXREG(LS_sample_from_prior)`
- Check that profiles follow density limits by taking the MSE of density points w.r.t to density limit for points that land above/below density limits, the density limit is calculated using the **output** machine parameters.  
`MSE_from_density_limit`
- Also take MSE between expected current and output of AUXREG since we used above outputs to calculate density limit.  
`MSE_expected_machine_parameters(in_mp_samp_varied, mp_from_prior)`
- Pass the encoded profile from prior into the encoder to get LS sample  
`LS_sample_from_enc = ENCODER(prof_from_prior)`
- Take MSE between the latent space samples (from encoder vs from prior)  
`MSE_enc_vs_prior = MSE(LS_sample_from_enc, LS_sample_from_prior)`
- Backpropagate the three MSEs.

Ideally this enforces two things: 1.) the latent space is regularized such that sampling from will return a profile that follows the density limit, and 2.) all components of the network learn this regularization since data is passed through all components.

## 2.1 Linear extrapolation method: WORK IN PROGRESS

The method of linear extrapolation within the latent space needs to be explored, but generally it could look something like this:

- Take highest/lowest current in batches
- Determine interpolation vector for given batch
- Extrapolate linearly beyond the vector
- For each point along the interpolation, check for the profile decoding with the Greenwald density limit (upper and lower limits).
- For each density point that does not follow the limit, calculate the MSE of it with , and back propagate.

## 3 Code

Assuming we are using PyTorch.

### 3.1 Conservation Rules

```
og_profs, mask, og_mps, _* = get_batch_data()
decoded_profs, decoded_mps = model.forward(og_profs)
# output profile and input profile
# They both have shape [BatchSize, 2, N],
# N: spatial resolution

# have to de_standardize to get to the real values
# it need not be cloned,
in_prof_ds = torch.clone(og_profs)
in_prof_ds[:, 0] = de_standardize(in_prof_ds[:, 0], D_mu, D_var)
in_prof_ds[:, 1] = de_standardize(in_prof_ds[:, 1], T_mu, T_var)

out_prof_ds = torch.clone(decoded_profs)
out_prof_ds[:, 0] = de_standardize(out_prof_ds[:, 0], D_mu, D_var)
out_prof_ds[:, 1] = de_standardize(out_prof_ds[:, 1], T_mu, T_var)

in_mps_ds = torch.clone(og_mps)
in_mps_ds = de_standardize(in_mps_ds, MP_mu, MP_var)

out_mps_ds = torch.clone(decoded_mps)
out_mps_ds = de_standardize(out_mps_ds, MP_mu, MP_var)
```

""" STORED ENERGY """

```

def calc_static_pressure_stored_energy(in_profs_ds , out_profs_ds , mask):

    boltz_con = 1.380e-23

    # torch.prod multiplies the density and temperature
    # to get pressure
    in_pres = torch.prod(in_ds.masked_fill_(~mask, 0), 1)
    out_pres = torch.prod(out_ds.masked_fill_(~mask, 0), 1)
    # ~inverse of mask since masked_fill_ uses True values,
    # Where our mask says False for bad vals.

    # .sum() them across the spatial dimension.
    stored_E_in = boltz_con*(in_pres).sum(1)
    stored_E_out = boltz_con*(out_pres).sum(1)
    return stored_E_in , stored_E_out

""" ALPHA CRITICAL """
def calc_alpha_crit(in_profs_ds , out_profs_ds ,
                    in_mps_ds , out_mps_ds ,
                    V_index=-2, VJAC_index=-1, R_index):

    mu_0 = 1.256e-6
    V_in , VJAC_in = in_mps_ds[:, V_index] , in_mps_ds[:, VJAC_index]
    R_in = in_mps_ds[:, R_index]

    V_out , VJAC_out = out_mps_ds[:, V_index] , out_mps_ds[:, VJAC_index]
    R_out = out_mps_ds[:, R_index]

    # Jury is out if we should use masks here
    in_pres = torch.prod(in_ds , 1)
    out_pres = torch.prod(out_ds , 1)

    in_pres_grad = torch.gradient(in_pres , 1)
    out_pres_grad = torch.gradient(out_pres , 1)

    in_pres_grad_min = torch.argmin(in_pres_grad , dim=1, keepdim=True)
    out_pres_grad_min = torch.argmin(out_pres_grad , dim=1, keepdim=True)
    in_pres_min = in_pres[:, in_pres_grad_min]
    out_pres_min = out_pres[:, out_pres_grad_min]

    alpha_crit_in = -((2*V_JAC_in) / (2*torch.pi)**2)*
                    ((V_in / (2*R_in*torch.pi**2)**2) *
                     (mu_0 * in_press_min))
    alpha_crit_out = -((2*V_JAC_out) / (2*torch.pi)**2)*
                    ((V_out / (2*R_out*torch.pi**2)**2)*
                     (mu_0 * out_press_min))

```

```
return alpha_crit_in , alpha_crit_out
```