## 1 Definitions

You should be able to define each of the following terms

- Error correcting code
- message
- (valid) codeword
- Hamming distance
- redundancy (of a code)
- directed graph
- incidence matrix for a directed graph
- spanning tree
- cycle basis
- determinant
- (d-dimensional) unit cube
- parallelepiped
- signed volume
- orientation (chirality)
- cofactor
- rotation matrix
- reflection matrix
- eigenvector
- eigenvalue
- characteristic polynomial
- algebraic multiplicity (of an eigenvalue)
- geometric multiplicity (of an eigenvalue)
- similar matrices

- diagonalizable matrix
- Markov matrix
- Markov chain
- transition probabilities (in a Markov chain)
- steady state
- attracting steady state
- complex number
- complex conjugate
- magnitude (of a complex number)
- positive definite matrix
- positive semidefinite matrix
- Singular value decomposition (rank r and full format)
- singular values
- singular vectors
- Frobenius norm of a matrix

## 2 Computations

You should be able to

- Construct the parity check matrix and generator matrix for a Hamming code.
- Encode messages and decode codewords (with error correction) using a Hamming code.
- Find a spanning tree for a graph using a basis for the row space of its incidence matrix.
- Find a cycle basis for a graph using a basis for the left null space of its incidence matrix.
- Interpret determinant of A as ratio of signed volume of a region before and after transformation by A.
- Compute the determinant of a square matrix using LU decomposition.
- Compute the determinant of an  $n \times n$  matrix using n! terms, one for each  $n \times n$  permutation matrix.

- Compute the determinant of a square matrix using cofactor formulas.
- Find the inverse of a matrix using cofactors.
- Find the matrix for a linear tranformation based on the image of the standard basis vectors.
- Find the matrix for rotation or reflection transformations of the plane.
- Find the characteristic polynomial  $det(A \lambda I)$  of a square matrix.
- Use the characteristic polynomial to find eigenvalues and eigenvectors of a matrix.
- Use a basis of eigenvectors to diagonalize a matrix.
- Compute large powers of a diagonalizable matrix.
- Use powers of a matrix and eigenvectors to analyze dynamical systems and recurrences.
- Formulate dynamical systems like population, weather, and random walks as Markov chains, with corresponding Markov matrices.
- Use Markov matrices to analyze long term behavior of a Markov chain.
- Find a "square root" for a positive definite (or semidefinite) matrix.
- Find singular values, singular vectors, and singular value decomposition of any matrix.
- Use SVD to interpret a linear transformation as a composition of rotations or reflections with dilation (stretch).
- Use SVD of A to write A as a sum of rank 1 matrices.

## 3 Theorems and proofs

You should be able to prove or explain why

- A Hamming code can correct one error but not two.
- Valid codewords for a Hamming code are at Hamming distance 3 or more from each other.
- Hamming codes can be constructed with redundancy arbitrarily close to 1.
- A set of rows forming a basis for the row space of an incidence matrix of a graph corresponds to a spanning tree.
- A basis for the left nullspace of an incidence matrix of a graph corresponds to a cycle basis for the graph.

- Adding a scalar multiple of one row to another leaves the determinant unchanged.
- The determinant of a triangular matrix is the product of its diagonal entries.
- The determinant of an invertible matrix is the product of its pivots.
- The determinant function is multiplicative  $(\det(AB) = \det(A) \det(B))$ .
- The determinant of a permutation matrix is  $(-1)^x$ , where x is the number of row swaps required to obtain the identity matrix.
- A is invertible if and only if  $\det A \neq 0$ .
- If A is invertible,  $det(A^{-1}) = 1/\det A$ .
- The determinant of a matrix and its transpose are the same.
- Every statement about determinants and rows has a corresponding statement about columns.
- If Q is an orthogonal matrix, then  $\det Q = 1$  or -1.
- Rotation and reflection matrices are orthogonal.
- If A is invertible and C is its matrix of cofactors, then  $A^{-1} = \frac{1}{\det A}C^T$ .
- The standard basis vectors are eigenvectors of a diagonal matrix.
- The eigenvalues of a matrix are the roots of its characteristic polynomial.
- Similar matrices have the same eigenvalues.
- If  $A = BCB^{-1}$  and C has the eigenvector  $\mathbf{x}$ , then A has the eigenvector  $B\mathbf{x}$ .
- If an  $n \times n$  matrix A has n independent eigenvectors  $\mathbf{x}_1, \dots, \mathbf{x}_n$ , then  $A = X\Lambda X^{-1}$ , where  $\Lambda$  is the diagonal matrix of eigenvalues.
- If A is invertible, then the eigenvalues of  $A^{-1}$  are the reciprocals of the eigenvalues of A.
- If A is invertible, then A and  $A^{-1}$  have the same eigenvectors.
- If two eigenvectors  $\mathbf{x}_1$  and  $\mathbf{x}_2$  have the same eigenvalue  $\lambda$ , then any linear combination of  $\mathbf{x}_1$  and  $\mathbf{x}_2$  is also an eigenvector with eigenvalue  $\lambda$ .
- The determinant of a matrix is the product of its eigenvalues.
- If A and B have the same eigenvalues and same corresponding eigenvectors, then A = B.
- If **x** is an eigenvector of A with eigenvalue  $\lambda$ , then for all  $c \neq 0$ , c**x** is an eigenvector of A with eigenvalue  $\lambda$ .

- If **x** is an eigenvector of A with eigenvalue  $\lambda$ , then for  $k \geq 1$ , **x** is an eigenvector of  $A^k$  with eigenvalue  $\lambda^k$ .
- If  $A = X\Lambda X^{-1}$  then A and  $\Lambda$  are the same transformation with respect to different bases. X is the "change of basis" matrix.
- Every Markov matrix has eigenvalue  $\lambda = 1$ .
- If  $\lambda$  is an eigenvalue of a Markov matrix, then  $|\lambda| \leq 1$ .
- A and  $A^T$  have the same eigenvalues.
- If A and B are Markov matrices, then so is AB. Any power of a Markov matrix is Markov.
- If a diagonalizable  $n \times n$  Markov matrix has eigenvector  $\mathbf{x}_1$  with  $\lambda_1 = 1$ , and  $|\lambda_i| < 1$  for all  $i \geq 2$ , then  $\mathbf{x}_i$  is an attracting steady state vector.
- For all matrices (not just Markov), the largest eigenvector determines behavior of  $A^k$  when k is large.
- Spectral theorem: Every real symmetric matrix is orthogonally diagonalizable with real eigenvalues.  $S = Q\Lambda Q^{-1} = Q\Lambda Q^{T}$ .
- The conjugate of a sum is the sum of the conjugates.
- The conjugate of a product is the product of the conjugates.
- A complex number is real if and only if it is equal to its conjugate.
- A symmetric matrix S has all eigenvalues  $> 0 \ (\geq 0)$  if and only if for all  $\mathbf{x}$ ,  $\mathbf{x}^T S \mathbf{x} > 0 \ (\geq 0)$ .
- If S is a symmetric matrix, then  $S = A^T A$  for a matrix A with independent columns (some dependent columns) if and only if for all  $\mathbf{x}$ ,  $\mathbf{x}^T S \mathbf{x} > 0$  ( $\geq 0$ ).
- The singular vectors  $\mathbf{v}_1, \dots \mathbf{v}_r$  for A are eigenvectors of  $A^T A$ .
- The singular vectors  $\mathbf{u}_1, \dots \mathbf{u}_r$  for A are eigenvectors of  $AA^T$ .
- The singular values  $\sigma_1, \ldots, \sigma_r$  for A are the square roots of the positive eigenvalues of  $A^T A$  and  $AA^T$ .
- The singular vectors  $\mathbf{v}_1, \dots \mathbf{v}_r$  for A are an orthonormal basis for  $C(A^T)$ .
- The singular vectors  $\mathbf{u}_1, \dots \mathbf{u}_r$  for A are an orthonormal basis for C(A).
- For a matrix A with singular value decomposition  $A = U\Sigma V^T$ ,  $A\mathbf{v}_i = \sigma_i \mathbf{u}_i$ .
- For a matrix  $A = U\Sigma V^T$ ,  $A = \sigma_1 \mathbf{u}_1 \mathbf{v}_1^T + \cdots + \sigma_1 \mathbf{u}_r \mathbf{v}_r^T$ .

## 4 Equivalent statements about square matrices

Suppose A is an  $n \times n$  matrix. Then each column contains equivalent statements.

A ia nonsingular A is singular A is invertible A is not invertible

The columns are independent

The rows are independent

The rows are independent  $A\mathbf{x} = \mathbf{0}$  has one solution,  $\mathbf{x} = \mathbf{0}$ The columns are dependent

The rows are dependent  $A\mathbf{x} = \mathbf{0}$  has many solutions

 $A\mathbf{x} = \mathbf{b}$  has one solution  $\mathbf{x} = A^{-1}\mathbf{b}$   $A\mathbf{x} = \mathbf{b}$  has no solution or infinitely many

A has n (nonzero) pivots A has full rank r = n A has rank r < n

The reduced row echelon form is R = I R has at least one zero row

The column space is all of  $\mathbb{R}^n$  The row space has dimension r < nThe row space has dimension r < nThe latest interest in the column space has dimension r < n

The determinant is not zero

All eigenvalues are nonzero  $A^TA$  is symmetric positive definite A has n (positive) singular values

The determinant is zero

Zero is an eigenvalue of A  $A^TA$  is only semidefinite A has r < n singular values