

1. (a) We add a source s and sink t into $P \cup I$. Then we add edges $\{(s, p) | p \in P\}$ and $\{(i, t) | i \in I\}$ into E . So $V' = \{s, t\} \cup P \cup I$, and $E' = \{(s, p) | p \in P\} \cup \{(i, t) | i \in I\} \cup E$.

For $e \in E'$, the lower bound $l(e)$, capacity $c(e)$, demand $r(v)$ are set by follows:

$$(l(e), c(e)) = \begin{cases} (0, 1), & e \in E \\ (b_p, t_p), & e = (s, p) \in \{(s, p) | p \in P\} \\ (l_i, u_i), & e = (i, t) \in \{(i, t) | i \in I\} \end{cases}$$

$$r(v) = \begin{cases} 0, & v \in P \cup I \end{cases}$$

So we got a graph $G' = \{V', E'\}$. Obviously if we find a routing with lower bounds, a issue i will be answered by at least l_i persons and at most u_i persons because of the limitation by lower bound $l(e) = l_i$ and capacity $c(e) = u_i$ of the edge (i, t) . A person p will be question by at least b_p issues and at most t_p issues because of the limitaion by lower bound $l(e) = b_p$ and capacity $c(e) = t_p$ of the edge (s, p) .

Now the parameter feasibility problem have been formulated as the problem of finding a routing with lower bounds.

- (b)
- We add an edge from the target t to source s . The new edges limitation is $[0, \text{INF}]$. We should make the conservation of the flow in the network. So the problem is trying to convert into the max-flow problem where there is no lower bound.
 - Remove the lower bound of each edge. Introduce new source s_{new} and target t_{new} into the network to make the conservation of the flow in the network. For each edge $e = (u, v) : l(e) > 0$, we add a edge (u, t_{new}) with capacity $l(e)$ and a edge (s_{new}, v) with capacity $l(e)$. Then we update the capacity of $e = (u, v)$ with $c(e) - l(e)$. Now we remove the lower bound from the origin network.
 - Then, we calculate the max-flow from the new source to new target. If and only if all of the flow from new source s_{new} and flow into new sink t_{new} is full, it means that there is a feasible routing from the origin source to origin target which satisfy the lower bound the network.

So we get the $\hat{G} = \hat{V}, \hat{E}$, in which $\hat{V} = \{s_{new}, t_{new}\} \cup V'$ and $\hat{E} = E' \cup \{(s_{new}, v), (u, t_{new}) | e(u, v) \in E' \ \& \ l(e) > 0\}$. The capacity $c(e) = c(e) - l(e)$ for each $e \in E'$. And the capacity of $(s_{new}, v), (u, t_{new})$ both are $l(e)$, in which $e = (u, v)$.

- (c) We implement the conversion in the function `solution.problem2_c()` in `solytion.py`.
 - (d) We implement the FordFulkerson algorithm and use it to solve the problem in the function `solution.problem2_d()` in `solution.py`.
 - (e) We implement the test case generator in `solution.problem2_e()` in `solution.py`.
2. (a) We can solve this problem with dynamic programming.

Take the example of the network graph provided in the problem.

We define $f(A)$ as the number of different ways that the spider can reach the node A. Obviously $f(A) = 1, f(J) = 1, f(H) = 1$. And $f(B), f(S), f(K), f(G)$ can be caculated by $f(A), f(J), f(H)$. We iterative caculate the other node. At last we got $f(fly)$ by $f(fly) = f(D) + f(O) + f(E)$.

We use a bipartite graph $G = \{V, E\}$ to represent whether there is a way from node u to node v: $(u, v) \in E$.

Step 1. Init a vertex set V_{reach} to store the nodes which have reached, and put the start node **Spider** into V_{reach} . And set $f(Spider) = 1$.

Step 2. For every $v \in V, \notin V_{reach}$, caculate $U = \{u | (u, v) \in E\}$. If $U \subseteq V_{reach}$, then put v into V_{reach} . And caculate $f(v) = \sum_{(u,v) \in E} f(u)$.

Step 3. Repeat Step 2 until the node *fly* put into the set V_{reach} .

- (b) We implement the algorithm as the function `problem4()` in `solution.py`
 We use `problem4_test()` to generater a Graph as input for probelm4().
 The graph provided in this problem has **141** ways from 'Spider' to 'Fly'. We use `networkx.all_simple_paths()` to check our result and it is correct.

3. (a) If n is odd, it is true that at least one person not hit by a bollon.

We defined a distance tuple $(personA, personB, dis)$ to represent the distance between $personA$ and $personB$.

The algorithm takes input as a distance tuple list and the number of the persons and it outputs a list of person who was hit by bollon.

At first, the algorithm sort the distance tuple list in ascending order. Then it traversal the distance tuple list. For every tuple $(personA, personB, dis)$, if $personA$ is not in $person_hurl$ set, it puts $personA$ into the $person_hurl$ set and $personB$ into the $neighbor_hit$ set. Do the same if $personB$ is not in $person_hurl$ set.

If the $len(neighbor_hit) < n$, it is true that at least one person not hit by a bollon, otherwise it is flase.

```
problem5(dis_list, num_person){
    sort(dis_list)
    for dis in dis_list
        if dis.personA not in person_hurl:
            person_hurl.add(personA)
            neighbor_hit.add(personB)

        if dis.personB not in person_hurl:
            person_hurl.add(personB)
            neighbor_hit.add(personA)

    if len(neighbor_hit) < n:
        return True
    else:
        return false
}
```

- (b) We implement the algorithm in solution.py.

We also implement a algorithm to generate the data of person and distance which satisfies everyone has a unique nearest neighbor. Obviously if we put the n persons in random n position, some of the people may have two or more nearest neighbors. For example, everyone has two nearest neighbor if we put three people in the vertexs of equilateral triangle,

- (c) It can be proved that when n is odd, the answer is always true.

Lemma 1 (*Pigeonhole Principle*) *At least one person not hit by a balloon if and only if at least one person hit by two or more balloons.*

- Step 1. we can pop the minimum distance $(personA, personB, dis)$ from the distance tuple list. Obviously the $personA$ and $personB$ are the nearest neighbor of each other. Both of PersonA hit by the other one. We put $personA$ and $personB$ in the set $neighbor_hit$. There remain $n-2$ people not hit by balloon.
- Step 2. Then we pop the minimum distance $(personA, personB, dis)$ from the distance tuple list again.
 - $personA(or\ personB) \in neighbor_set$, $personA(or\ personB)$ would hurl the balloon at one of person in $neighbor_set$, which means one person hit by two balloon. We know that at least one person not hit by balloon by the Lemma. It proved.
 - else if $personA \notin neighbor_hit$ and $personB \notin neighbor_hit$, we put $personA, personB$ into $neighbor_set$. So there remains $n-4$ people not hit by ballon.
- Step 3. Repeat Step 2 until there is no person put into the $neighbor_set$. Because n is odd and the length k of $neigibor_set$ is even, there always remain $n - k$ people not hit by ballon.

Proved.

- (d) The length of distance tuple list is $(n * (n + 1))/2$. The time complexity of part of sort function is $O(n^2 \log(n))$. The time complexity of finding the people hit set is $O(n^2)$. So the time complexity is $O(n^2 \log(n))$.

Also we can solve the problem 5(a) in time complexity $O(n^2)$. We just need find the nearest neighbor of everyone ($O(n^2)$), caculate the number of people hitted.

We use our algorithm for clearly proving that it always is true when n is odd.