

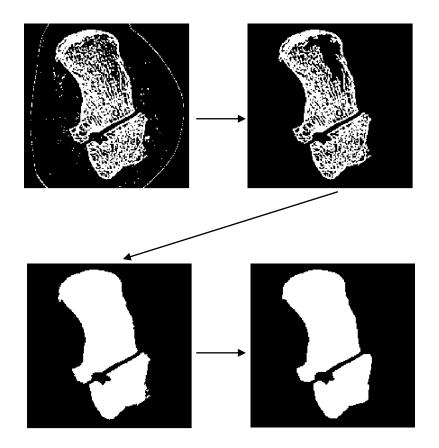
CSE 554 Lecture 2: Shape Analysis (Part I)

Fall 2016

Review



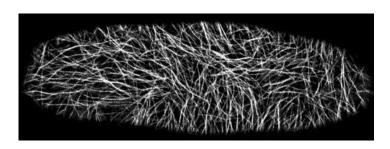
- Binary pictures
 - Tresholding grayscale images
 - Basic operations
 - Connected component labeling
 - Morphological operators



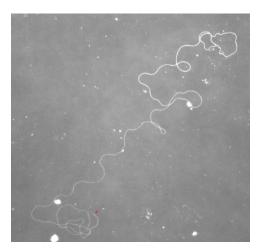
Shape analysis



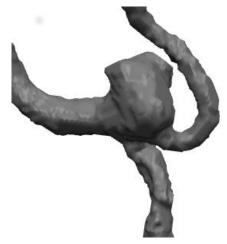
- Questions about shapes:
 - Metrics: length? Width? orientation?
 - What are the parts?
 - How similar are two shapes?



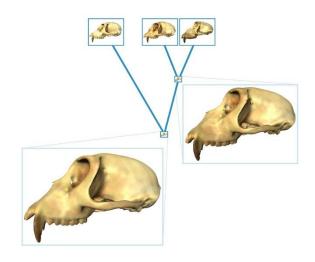
Microtubules on the cell surface



Sperms of fruit flies



Cerebral artery aneurysms

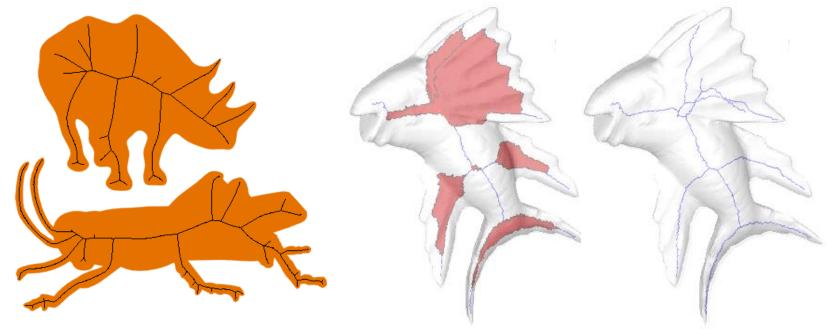


Monkey skulls

Skeletons



- Geometry at the center of the object
 - Compact, and capturing protruding shape parts



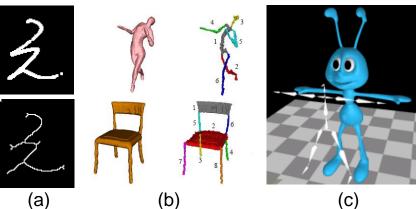
Skeleton of 2D shapes: 1D curves

Skeleton of 3D shapes: 1D curves and 2D surfaces

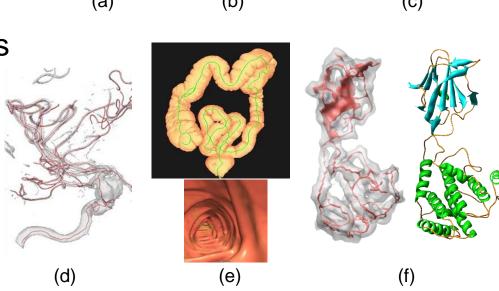
Applications



- Computer graphics and vision
 - Optical character recognition (a)
 - Shape retrieval (b)
 - Animating articulated shapes (c)

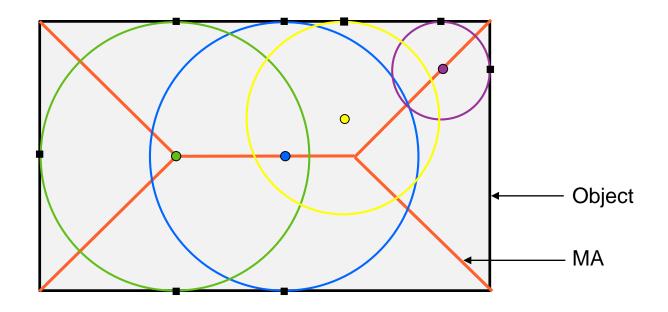


- Bio-medical image analysis
 - Vessel network analysis (d)
 - Virtual colonoscopy (e)
 - Protein modeling (f)



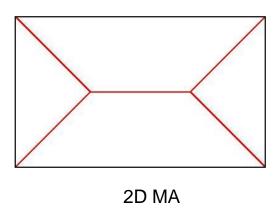


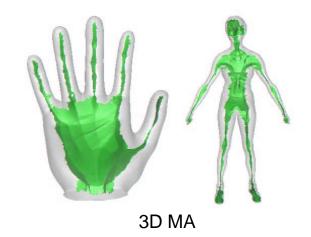
Interior points with multiple closest points on the boundary





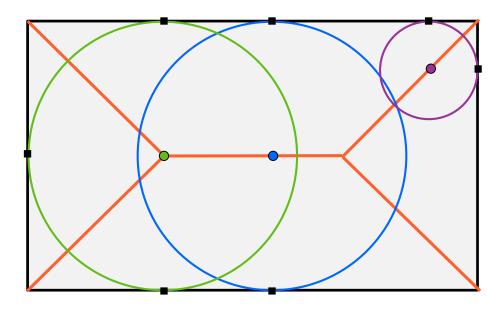
- Properties
 - ✓ Thin
 - MA are curves (1D) in a 2D object, and surfaces (2D) in a 3D object.







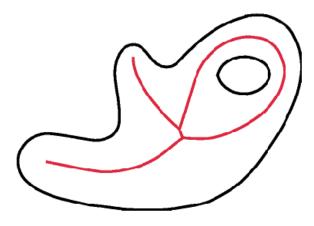
- Properties
 - ✓ Preserves object's shape
 - The object can be reconstructed from MA and its distances to the boundary



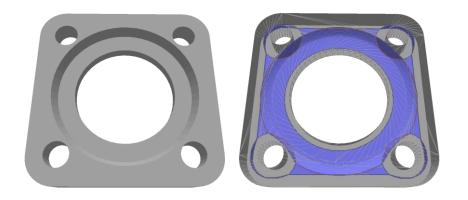


Properties

- ✓ Preserves object's topology
 - 2D: # of connected components of object and background
 - 3D: # of connected components of object and background, and # of tunnels



A 2D shape with 1 object component and 2 background components



A 3D shape with 5 tunnels



- Properties
 - Not stable under boundary perturbation





Skeletons



- Approximation of medial axes
 - Roughly corresponds to the stable parts of the medial axes
 - No unique or precise definition (e.g., application dependent)

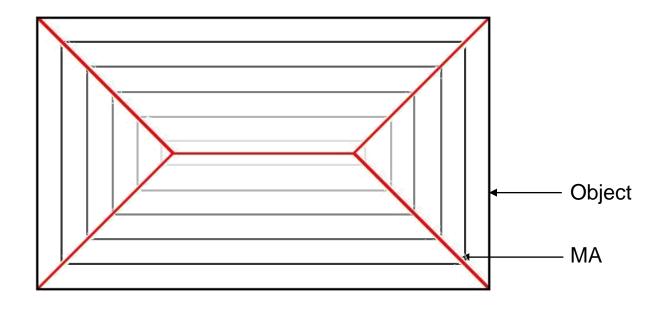
Computing Skeletons



- A classical method: thinning
 - Relatively simple to implement
 - Can create curve skeletons in 2D and curve or surface skeletons in 3D
- What we will cover:
 - Thinning on binary pictures (this lecture)
 - Thinning on cell complexes (next lecture)

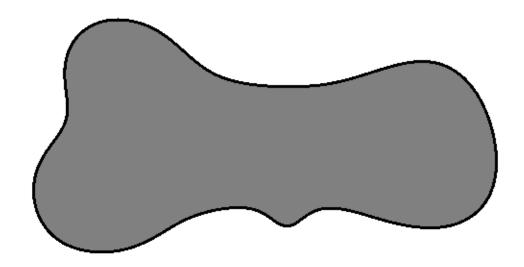


- Grassfire analogy:
 - Let the object represent a field of grass. A fire starts at the field boundary, and burns across the field at uniform speed.
 - MA are where the fire fronts meet.





- Grassfire analogy:
 - Let the object represent a field of grass. A fire starts at the field boundary, and burns across the field at uniform speed.
 - MA are where the fire fronts meet.





- Iterative process that shrinks a binary picture to a skeleton
 - Simulating the "grassfire burning" that defines MA





Shrink a binary picture by iterative erosion



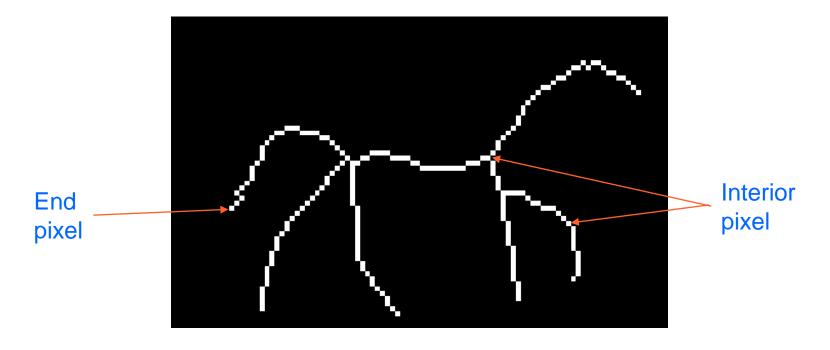


- Shrink a binary picture by iterative erosion
 - Identify pixels where the (digital) fire fronts quench



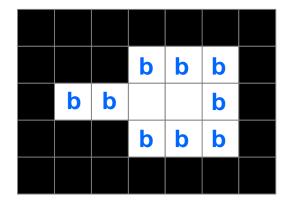


- Shrink a binary picture by iterative erosion
 - Identify pixels where the (digital) fire fronts quench
 - Two types of pixels

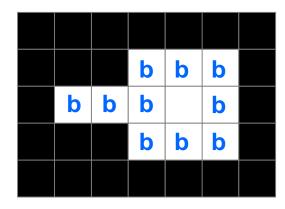




- Border pixels (to be removed by erosion)
 - Object pixel **p** is on the border if and only if **p** is connected to some background pixel
 - 4 or 8 connectivity: erosion by a cross or a square



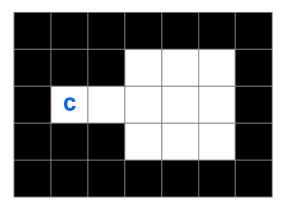
Border pixels for 4-connectivity



Border pixels for 8-connectivity



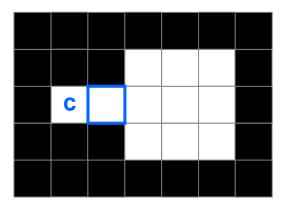
- Curve-end pixels
 - Object pixels lying at the ends of curves, whose removal would shrink the skeleton (and hence losing shape information).



Curve-end pixel



- Curve-end pixels criteria
 - Object pixel c is a curve-end pixel if and only if c is connected to exactly
 one object pixel.

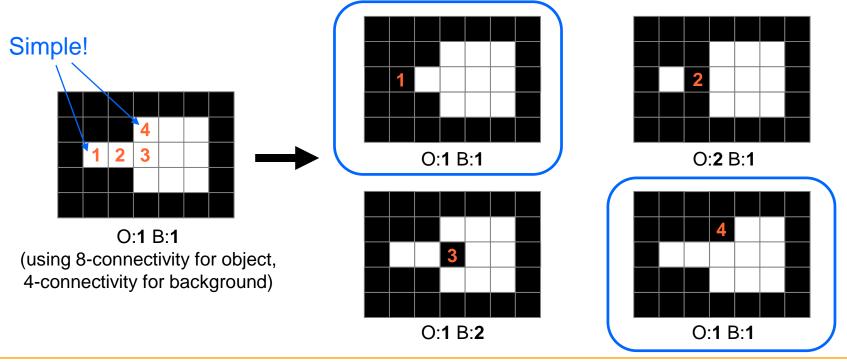


Curve-end pixel and its connected pixel



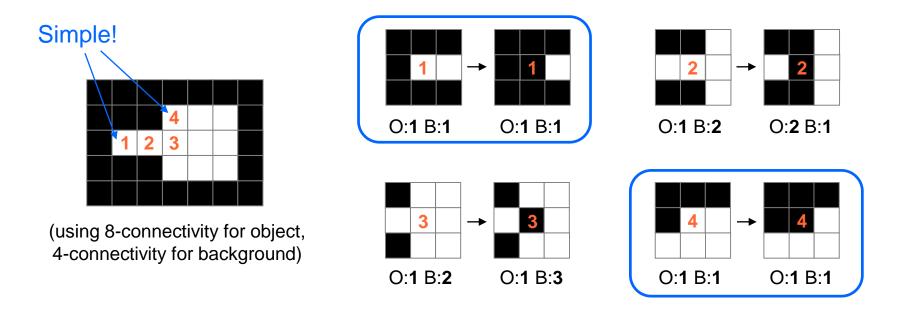
Simple pixels

 Object pixels whose removal from the object does not change topology (i.e., # of components of object and background)



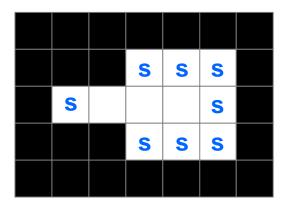


- Simple pixels criteria
 - Object pixel **p** is simple if and only if setting **p** to background does not change the # of components of either the object or background in the 3x3 neighborhood of **p**.





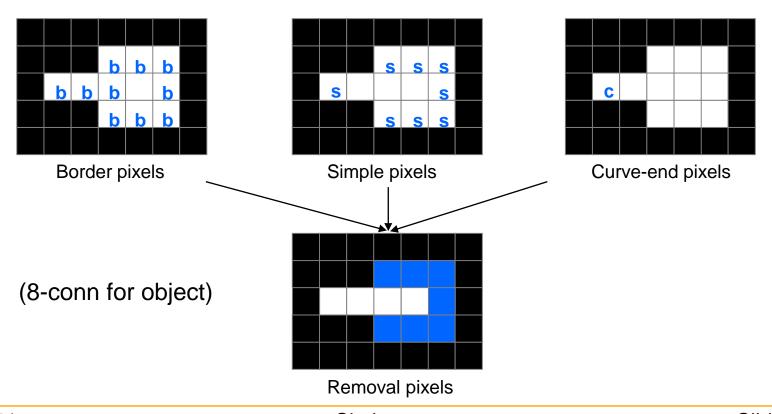
- Simple pixels criteria
 - Object pixel **p** is simple if and only if setting **p** to background does not change the # of components of either the object or background in the 3x3 neighborhood of **p**.



All simple pixels



- Putting together: Removable pixels
 - Border pixels that are simple and not curve-end





- Algorithm (attempt) 1
 - Simultaneous removal of all removable points ("Parallel thinning")

```
// Parallel thinning on a binary image I
1. Repeat:
    1. Collect all removable pixels as S
    2. If S is empty, Break.
    3. Set all pixels in S to be background in I
2. Output I
```

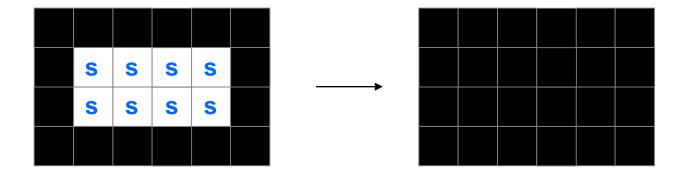


- Algorithm (attempt) 1
 - Simultaneous removal of all removable points ("Parallel thinning")





- Why does parallel thinning breaks topology?
 - Simple pixels, when removed together, may change topology





Algorithm 2

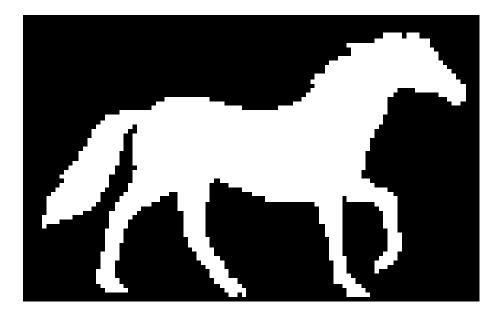
 Sequentially visit each removable pixel and check its simple-ness before removing the pixel. ("Serial Thinning")

```
// Serial thinning on a binary image I
1. Repeat:
    1. Collect all border pixels as S
    2. If S is empty, Break.
    3. Repeat for each pixel x in S (in certain order):
        1. If x is currently simple and not curve-end, set x to be background in I
2. Output I
```



Algorithm 2

 Sequentially visit each removable pixel and check its simple-ness before removing the pixel. ("Serial Thinning")



Serial thinning



Algorithm 2

- Sequentially visit each removable pixel and check its simple-ness before removing the pixel. ("Serial Thinning")
- Result is affected by the visiting "sequence"



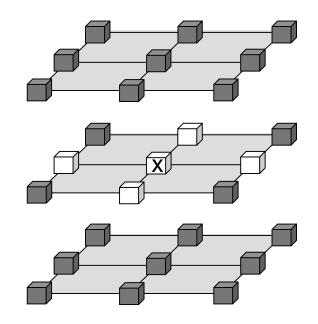


Serial thinning with two different visiting sequences of removable pixels



Identifying removable voxels

- Border voxels
 - Similar to 2D: object voxels connected to at least one background voxel
- Simple voxels
 - Harder to characterize than 2D:
 Maintaining # of connected components is not sufficient (need to consider # of tunnels too)
- Curve-end and surface-end voxels
 - Curve-end criteria same as in 2D
 - Surface-end criteria are much harder to describe (e.g., requires a table look-up)



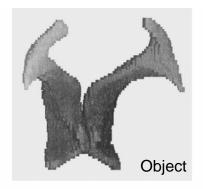
Setting voxel x to background creates a "tunnel" in the object (using 26-conn for object)

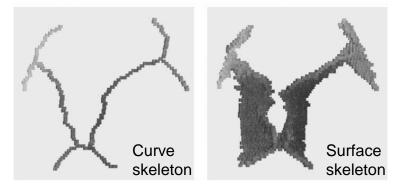


Two kinds of skeletons

- Curve skeletons: only curve-end voxels are preserved during thinning
- Surface skeletons: both curve-end and surface-end voxels are preserved

(see further readings)





Method of [Palagyi and Kuba, 1999]

Skeleton Pruning



- Thinning is sensitive to boundary noise
 - Due to the instability of medial axes
- Skeleton pruning
 - During thinning
 - E.g., using more selective criteria for end pixels (voxels)
 - After thinning
 - E.g., based on branch length
 - See Further Readings



Object with boundary noise



Resulting skeleton

Further Readings on: Binary Pictures, MA and Thinning



Books

- "Digital Geometry: geometric methods for digital picture analysis", by Klette and Rosenfeld (2004)
- "Medial representations: mathematics, algorithms and applications", by Siddiqi and Pizer (2008)

Papers

- "Digital topology: introduction and survey", by Kong and Rosenfeld (1989)
 - Theories of binary pictures
- "Thinning methodologies a comprehensive survey", by Lam et al. (1992)
 - A survey of 2D methods
- "A Parallel 3D 12-Subiteration Thinning Algorithm", by Palagyi and Kuba (1999)
 - Includes a good survey of 3D thinning methods
- "Pruning medial axes", by Shaked and Bruckstein (1998)
 - A survey of MA and skeleton pruning methods