

# Session 7

## Quantitative Analysis of Financial Markets

### Stationary Processes

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# Broad Lesson Plan

- 1 Introduction
- 2 Stationary Processes
- 3 Sample ACF
- 4 Stationarity & Invertibility
- 5 Yule-Walker
- 6 Partial ACF
- 7 Takeaways

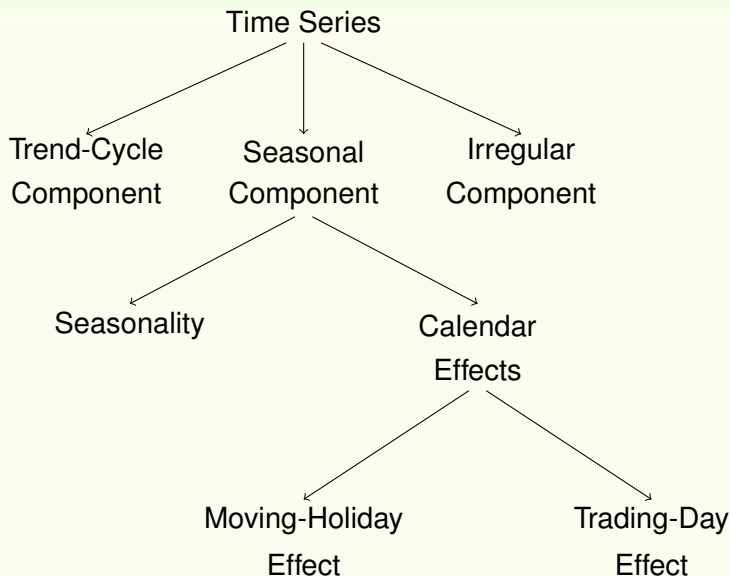
# Learning Outcomes

- ✂ Understand thoroughly the nature of white noise.
- ✂ Describe AR, MA, and ARMA time series using white noise as the building block.
- ✂ Compute the unconditional and conditional means, as well as variances of these stationary processes.
- ✂ Describe the autocorrelation function and how the function is estimated and tested for statistical significance (Box and Pierce Q-statistic, Ljung and Box statistic).
- ✂ Define back-shift operator  $B^n$  and describe the relationship between MA and AR( $\infty$ ) processes.
- ✂ Thoroughly understand the Yule-Walker equations and their applications to obtain partial autocorrelation function.

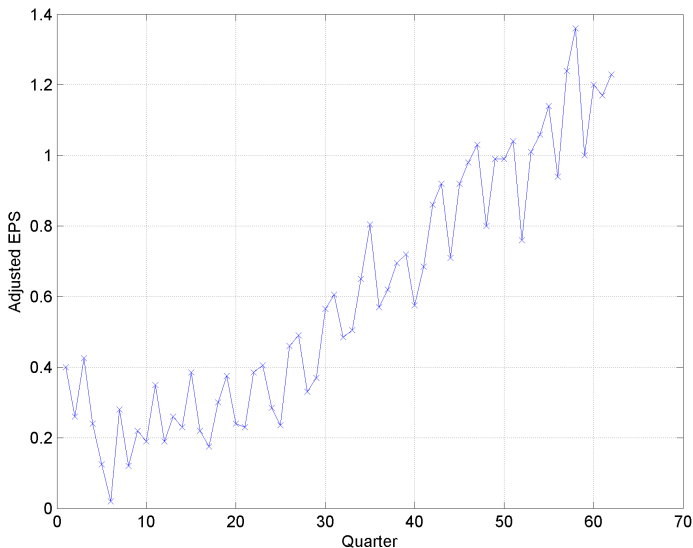
# Components of a Time Series

☛ In general, a time series  $Y_t$  has the following components:

- (a) **trend-cycle (TC) component**: the combined long-term and growth cycle movement of the time series
- (b) **seasonal (S) component**: the systematic variations of the time series
- (c) **irregular (I) component**: the random fluctuations of short-term movements of the time series.



# Example: Nike's EPS



# Basic Building Block: White Noise $\{u_t\}$

## ♪ Properties of white noise

- ✱ Identically distributed, stationary process
- ✱  $\mathbb{E}(u_t) = 0$
- ✱  $\mathbb{V}(u_t) = \sigma_u^2$
- ✱  $\mathbb{C}(u_t, u_{t+k}) = 0$  for any  $k \neq 0$
- ✱ Stronger definition:  $u_t$  is independent of  $u_{t+k}$  for all  $k \neq 0$

## ♪ How does white noise sound like?

- ✱ Generate white noise with Matlab: `u = randn(8192*10, 1);`
- ✱ Create an audioplayer object: `pu = audioplayer(u, 8192);`
- ✱ Listen to white noise: `play(pu);`

# AR, MA, and ARMA

With basic white noise process  $\{u_t\}$ ,  $t = -\infty, \dots, \infty$ , the following processes are generated:

- Autoregressive order one: AR(1) process

$$Y_t = \theta + \lambda Y_{t-1} + u_t$$

- Moving Average order one: MA(1) process

$$Y_t = \theta + u_t + \alpha u_{t-1}$$

- Autoregressive Moving Average order one: ARMA(1, 1) process

$$Y_t = \theta + \lambda Y_{t-1} + u_t + \alpha u_{t-1}$$



# Autoregressive Process AR(1)

⊥ Repeated substitution for  $Y_t$  in the AR(1) process

$$Y_t = \theta + \lambda(\theta + \lambda Y_{t-2} + u_{t-1}) + u_t$$

leads to

$$Y_t = (1 + \lambda + \lambda^2 + \cdots)\theta + (u_t + \lambda u_{t-1} + \lambda^2 u_{t-2} + \cdots).$$

⊥ For each  $t$ , provided  $|\lambda| < 1$ ,

$$\mathbb{E}(Y_t) = (1 + \lambda + \lambda^2 + \cdots)\theta = \frac{\theta}{1 - \lambda};$$

$$\begin{aligned}\mathbb{V}(Y_t) &= \mathbb{V}(u_t + \lambda u_{t-1} + \lambda^2 u_{t-2} + \cdots) = \sigma_u^2(1 + \lambda^2 + \lambda^4 + \cdots) \\ &= \frac{\sigma_u^2}{1 - \lambda^2};\end{aligned}$$

$$\mathbb{C}(Y_t, Y_{t-1}) = \mathbb{C}(\theta + \lambda Y_{t-1} + u_t, Y_{t-1}) = \lambda \frac{\sigma_u^2}{1 - \lambda^2}.$$

# Autocorrelation Coefficients of AR(1)

→ Autocovariance at lag  $k$  is a function of  $k$  only

$$\mathbb{C}(Y_t, Y_{t-k}) = \mathbb{C}\left(\theta \sum_{j=0}^{k-1} \lambda^j + \lambda^k Y_{t-k} + \sum_{j=0}^{k-1} \lambda^j u_{t-j}, Y_{t-k}\right) = \lambda^k \mathbb{V}(Y_t) =: \gamma(k)$$

→ Accordingly, the serial correlation is

$$\text{Corr}(Y_t, Y_{t-k}) = \frac{\mathbb{C}(Y_t, Y_{t-k})}{\mathbb{V}(Y_t)} = \lambda^k$$

→ For a symmetrical time shift  $t \rightarrow t+k$ ,

$$\text{Corr}(Y_{t+k}, Y_t) = \frac{\mathbb{C}(Y_{t+k}, Y_t)}{\mathbb{V}(Y_{t+k})} = \lambda^k$$

→ Hence

$$\rho(k) := \text{Corr}(Y_t, Y_{t \pm k}) = \lambda^{|k|}$$

# Illustrative Example of an AR(1) Process

⌚ Suppose

$$Y_t = 2.5 + 0.5Y_{t-1} + u_t, \quad \text{where } \mathbb{E}(u_t) = 0, \mathbb{V}(u_t) = 3$$

- 1 What is the mean of  $Y_t$ ?
- 2 What is the variance of  $Y_t$ ?
- 3 What is the first-order autocovariance of this AR(1) process?
- 4 What is the first-order autocorrelation of this AR(1) process?
- 5 What is the third-order autocorrelation of this AR(1) process?

# Simulating an AR(1) Process



Simulation parameters:

✱ number of samples 5,000

✱  $\sigma_u^2 = 3$

✱  $\theta = 2.5, \quad \lambda_1 = 0.5$

```
n = 5000
```

```
su2 = 3
```

```
theta, lambda1 = 2.5, 0.5
```

```
np.random.seed(20180219)
```

```
u = np.random.normal(0, 1, n)
```

```
mu, su = np.mean(u), np.std(u, ddof=1)
```

```
u -= mu      # ensure that mean of u is really 0
```

```
u /= su;     # ensure that variance of u is really 1
```

```
u *= np.sqrt(su2)
```

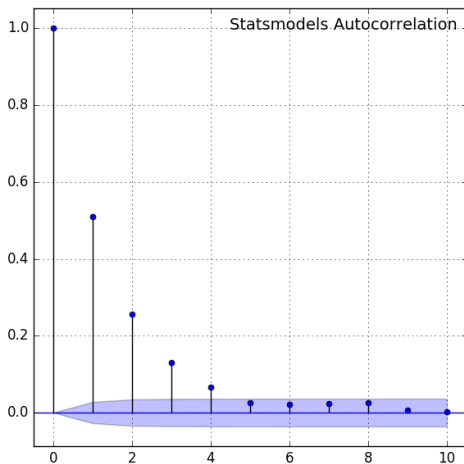
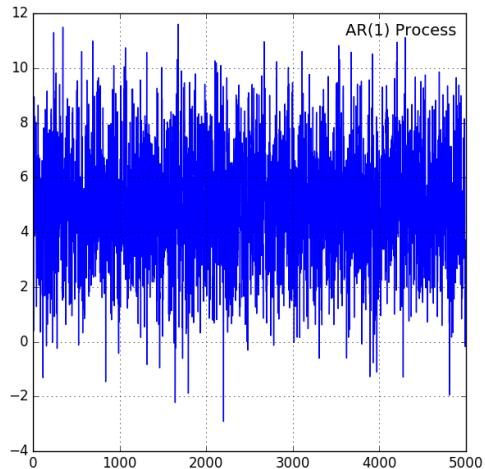
```
Y = np.zeros(n, dtype=float)
```

```
Y[0] = theta + u[0]
```

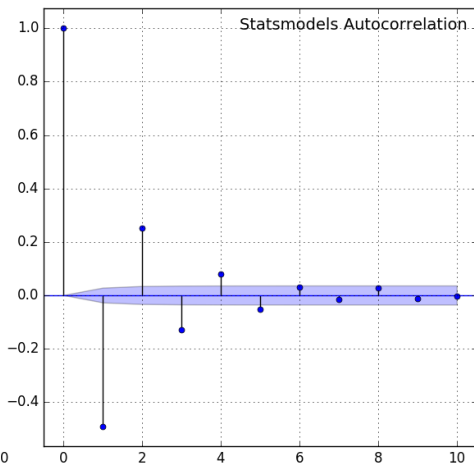
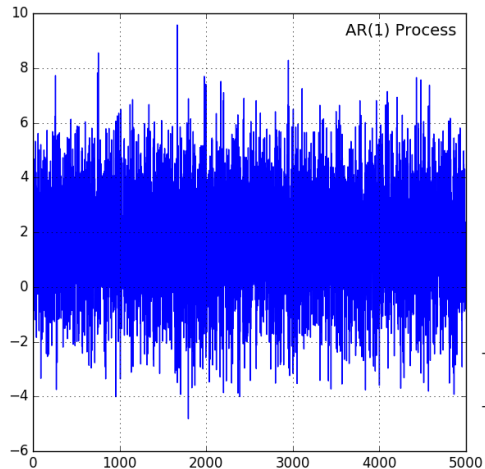
```
for t in range(1, n):
```

```
    Y[t] = theta + lambda1*Y[t-1] + u[t]
```

# Sample Autocorrelation Function of AR(1)



# Another Example of AR(1), $\lambda = -0.5$



## Moving Average Process MA(1)

⇒ For MA(1) process  $Y_t = \theta + u_t + \alpha u_{t-1}$ ,

$$\mathbb{E}(Y_t) = \theta$$

$$\mathbb{V}(Y_t) = (1 + \alpha^2)\sigma_u^2$$

$$\mathbb{C}(Y_t, Y_{t-1}) = \mathbb{C}(\theta + u_t + \alpha u_{t-1}, \theta + u_{t-1} + \alpha u_{t-2}) = \alpha \sigma_u^2$$

$$\text{Corr}(Y_t, Y_{t-1}) = \frac{\alpha}{1 + \alpha^2}$$

$$\text{Corr}(Y_t, Y_{t-k}) = 0 \quad \text{for } k > 1$$

⇒ Hence, MA(1) process is covariance-stationary with constant mean  $\theta$ , constant variance  $\sigma_u^2(1 + \alpha^2)$  and autocorrelation function of  $k = 1$  only nonzero.

# Illustrative Example of an MA(1) Process

⌚ Suppose

$$Y_t = 2.5 + u_t + 0.5u_{t-1}, \quad \text{where } \mathbb{E}(u_t) = 0, \mathbb{V}(u_t) = 3$$

- 1 What is the mean of  $Y_t$ ?
- 2 What is the variance of  $Y_t$ ?
- 3 What is the first-order autocovariance of this MA(1) process?
- 4 What is the first-order autocorrelation of this MA(1) process?
- 5 What is the third-order autocorrelation of this MA(1) process?



# Simulating an MA(1) Process

## ⚽ Simulation parameters:

✱ number of samples 5,000

✱  $\sigma_u^2 = 3$

✱  $\theta = 2.5, \quad \alpha = 0.5$

```
n = 5000
```

```
su2 = 3
```

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theta, alpha = 2.5, 0.5
```

```
np.random.seed(20180219)
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u = np.random.normal(0, 1, n)
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mu, su = np.mean(u), np.std(u, ddof=1)
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u -= mu      # ensure that mean of u is really 0
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u /= su;     # ensure that variance of u is really 1
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u *= np.sqrt(su2)
```

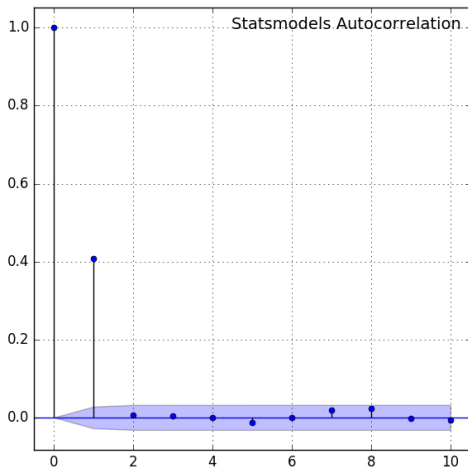
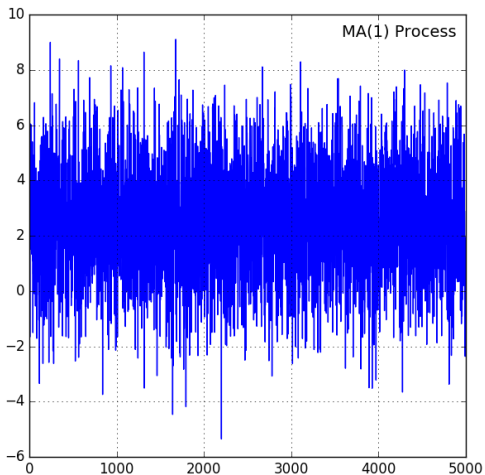
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Y = np.zeros(n, dtype=float)
```

```
Y[0] = theta + u[0]
```

```
for t in range(1, n):
```

```
    Y[t] = theta + alpha*u[t-1] + u[t]
```

# Sample ACF of MA(1) Process



# ARMA(1,1)

⇒ Repeated substitution of  $Y_t = \theta + \lambda Y_{t-1} + u_t + \alpha u_{t-1}$  leads to

$$Y_t = \theta \sum_{i=0}^{\infty} \lambda^i + u_t + (\lambda + \alpha) \sum_{i=0}^{\infty} \lambda^i u_{t-i}.$$

⇒ For each  $t$ , provided  $|\lambda| < 1$

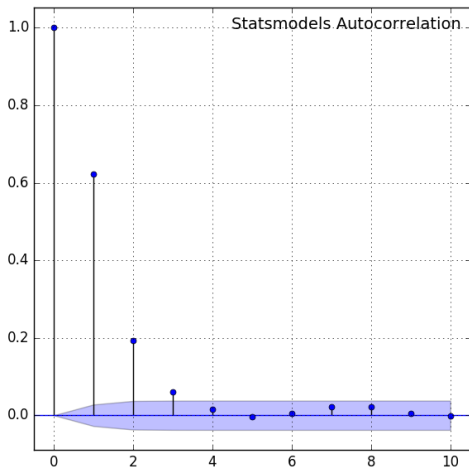
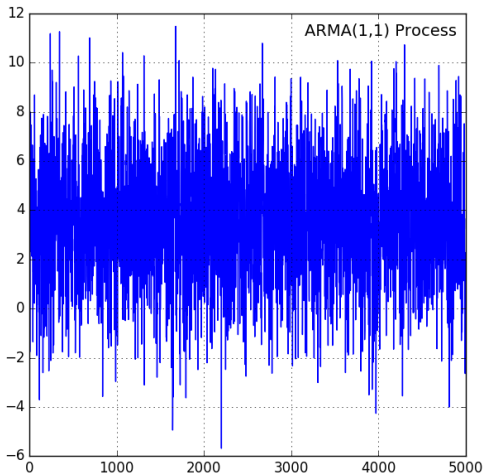
$$\mathbb{E}(Y_t) = \frac{\theta}{1 - \lambda}, \quad \mathbb{V}(Y_t) = \sigma_u^2 \left( 1 + (\lambda + \alpha)^2 \sum_{i=0}^{\infty} \lambda^{2i} \right) = \sigma_u^2 \left( 1 + \frac{(\lambda + \alpha)^2}{1 - \lambda^2} \right)$$

$$\mathbb{C}(Y_t, Y_{t-1}) = \lambda \mathbb{V}(Y_{t-1}) + \alpha \sigma_u^2$$

$$\mathbb{C}(Y_t, Y_{t-k}) = \lambda^k \mathbb{V}(Y_{t-k}), \quad \text{for } k > 1$$

⇒ Hence, ARMA(1,1) process is covariance-stationary with constant mean  $\frac{\theta}{1 - \lambda}$ , constant variance  $\sigma_u^2 \left( 1 + \frac{(\lambda + \alpha)^2}{1 - \lambda^2} \right)$ , and autocovariance of a function of  $k$  only.

# Sample ACF of ARMA(1,1) Process



# Autocorrelation Function of ARMA(1,1)

🔗 Question 1: Derive the autocorrelation function of ARMA(1,1) process

🔗 Question 2: If  $\lambda = -\alpha$ , what is the ACF of ARMA(1,1) at lag 1?

# Changing Conditional Means

## AR(1)

✗ At  $t + 1$ , information about  $Y_t$  is already known, so for AR(1) process, conditional mean is a random variable

$$\mathbb{E}(Y_{t+1}|Y_t) = \theta + \lambda Y_t + \mathbb{E}(u_{t+1}|Y_t) = \theta + \lambda Y_t \neq \frac{\theta}{1 - \lambda}$$

✗ Conditional variance is constant

$$\mathbb{V}(Y_{t+1}|Y_t) = \mathbb{V}(u_{t+1}|Y_t) = \sigma_u^2 < \frac{\sigma_u^2}{1 - \lambda^2}$$

## MA(1)

✗ Conditional mean is stochastic but conditional variance is constant:

$$\begin{aligned}\mathbb{E}(Y_{t+1}|Y_t) &= \theta + \alpha u_t \\ \mathbb{V}(Y_{t+1}|Y_t) &= \sigma_u^2 < \sigma_u^2(1 + \alpha^2)\end{aligned}$$

# Sample Autocorrelation Function

◇ Sample autocovariance lag  $k$ , for  $k = 0, 1, 2, \dots, p$ , with  $p < T/4$ .

$$c(k) = \frac{1}{T} \sum_{t=1}^{T-k} (Y_t - \bar{Y})(Y_{t+k} - \bar{Y})$$

◇ The estimator  $c(k)$  is consistent, as  $\lim_{T \uparrow \infty} c(k) = \mathbb{C}(Y_k, Y_{t-k})$ .

◇ Sample autocorrelation at lag  $k$  is then

$$r(k) = \frac{c(k)}{c(0)} = \frac{\sum_{t=1}^{T-k} (Y_t - \bar{Y})(Y_{t+k} - \bar{Y})}{\sum_{t=1}^T (Y_t - \bar{Y})^2},$$

which is also consistent, as  $\lim_{T \uparrow \infty} r(k) = \rho(k)$ .

◇ Variance of  $r(k)$  for AR(1) process

$$\mathbb{V}(r(k)) \approx \frac{1}{T} \left( \frac{(1 + \lambda^2)(1 - \lambda^{2k})}{1 - \lambda^2} - 2k\lambda^{2k} \right)$$

## Test for $\rho = 0$ , AR(1)

♡ Test hypothesis  $H_0 : \rho(j) = 0$  for all  $j > 0$  or  $H_0 = \lambda = 0$ . Then,

$$\mathbb{V}(r(k)) \approx \frac{1}{T}.$$

♡ To test that the  $j^{th}$  autocorrelation is zero, the test statistic is

$$z_j = \frac{r(j) - 0}{\sqrt{1/T}} \stackrel{d}{\sim} N(0, 1).$$

♡ Reject  $H_0 : \rho(j) = 0$  at 5% significance level if  $|z| > 1.96$ .



## Test for $\rho = 0$ , $\text{MA}(q)$

For  $\text{MA}(q)$  processes, the variance of  $r(k)$  is

$$\mathbb{V}(r(k)) \approx \frac{1}{T} \left( 1 + 2 \sum_{i=1}^q \rho(i)^2 \right).$$

Thus for  $\text{MA}(1)$  process,  $\mathbb{V}(r(k))$  for  $k > 1$  is estimated by

$$\frac{1}{T} (1 + 2r(1)^2) > \frac{1}{T},$$

and rejection of the null hypothesis allows the identification of  $\text{MA}(1)$ .

# Joint Test Statistic

‡ To test if  $m$  autocorrelations are jointly zero, the null hypothesis is

$$H_0 : \rho(1) = \rho(2) = \cdots = \rho(m) = 0.$$

‡ The **Box and Pierce  $Q$ -statistic** for asymptotic test is

$$Q_m = T \sum_{k=1}^m r(k)^2 = \sum_{k=1}^m (\sqrt{T} r(k))^2 = \sum_{k=1}^m z_k^2 \stackrel{d}{\sim} \chi_m^2.$$

‡ The **Ljung and Box test statistic** provides an approximate correction for finite sample:

$$Q_m = T(T+2) \sum_{k=1}^m \frac{r(k)^2}{T-k} \stackrel{d}{\sim} \chi_m^2.$$

# Backward Shift Operator & Characteristic Equation

- ⊗ Backward shift operator  $B$ :

$$BY_t := Y_{t-1}$$

- ⊗ Applying the backward shift operator  $k$  times,

$$B^k Y_t = Y_{t-k}$$

- ⊗  $AR(p)$  process

$$Y_t = \theta + \lambda_1 Y_{t-1} + \lambda_2 Y_{t-2} + \cdots + \lambda_p Y_{t-p} + u_t = \theta + \sum_{i=1}^p \lambda_i B^i Y_t + u_t$$

$$\phi(B)Y_t := \left(1 - \sum_{i=1}^p \lambda_i B^i\right) Y_t = \theta + u_t$$

- ⊗ The equation  $\phi(B) = 0$  is called the **characteristic equation** of the  $AR(p)$  process. For  $AR(p)$  to be stationary, the roots of the characteristic equation must lie **outside** the unit circle.

# Representation of MA(1)

‡ MA(1) process is representable as AR( $\infty$ ) process

$$Y_t = \theta + u_t + \alpha u_{t-1}$$

$$= \theta + (1 + \alpha B)u_t$$

$$(1 + \alpha B)^{-1}Y_t = (1 + \alpha B)^{-1}\theta + u_t$$

$$(1 - \alpha B + \alpha^2 B^2 - \alpha^3 B^3 + \cdots)Y_t = c + u_t$$

where  $c := (1 + \alpha B)^{-1}\theta$ . Hence

$$Y_t = c + \alpha Y_{t-1} - \alpha^2 Y_{t-2} + \alpha^3 Y_{t-3} - \alpha^4 Y_{t-4} + \cdots + u_t$$

‡ Invertibility requires  $(1 + \alpha B) = 0$  lie outside the unit circle, which is satisfied if  $|\alpha| < 1$ .

‡ A stationary MA( $q$ ) process is said to be invertible if it can be represented as a stationary AR( $\infty$ ) process.

‡ What's the point of inverting an MA process?

## Yule-Walker Equations (1)

♪ Multiply both sides of  $AR(p)$  process by  $Y_{t-k}$ ,

$$Y_{t-k}Y_t = Y_{t-k}\theta + \lambda_1 Y_{t-k}Y_{t-1} + \lambda_2 Y_{t-k}Y_{t-2} + \cdots + \lambda_p Y_{t-k}Y_{t-p} + Y_{t-k}u_t$$

♪ Taking unconditional expectations on both sides and noting that  $\mathbb{E}(Y_{t-k}Y_t) = \gamma(k) + \mu^2$  for any  $k$ , then

$$\gamma(k) + \mu^2 = \mu\theta + \lambda_1(\gamma(k-1) + \mu^2) + \lambda_2(\gamma(k-2) + \mu^2) + \cdots + \lambda_p(\gamma(k-p) + \mu^2)$$

♪ The unconditional means of an  $AR(p)$  process is

$\mu = \theta + \lambda_1\mu + \cdots + \lambda_p\mu$ . So  $\mu^2 = \mu\theta + \lambda_1\mu^2 + \cdots + \lambda_p\mu^2$ . Hence for  $k > 1$ ,

$$\gamma(k) = \lambda_1\gamma(k-1) + \lambda_2\gamma(k-2) + \cdots + \lambda_p\gamma(k-p)$$

♪ Dividing both sides by  $\gamma(0)$  to obtain correlations:

$$\rho(k) = \lambda_1\rho(k-1) + \lambda_2\rho(k-2) + \cdots + \lambda_p\rho(k-p)$$

## Yule-Walker Equations (2)

♪ Note that  $\rho(0) = 1$  and  $\rho(j) = \rho(-j)$

♪ For each  $k$ , there is a corresponding equation with  $p$  parameters of  $\lambda_1, \lambda_2, \dots, \lambda_p$ , resulting in the Yule-Walker equations:

$$\begin{aligned}
 \rho(1) &= \lambda_1 & + \lambda_2 \rho(1) & + \dots + \lambda_p \rho(p-1) \\
 \rho(2) &= \lambda_1 \rho(1) & + \lambda_2 & + \dots + \lambda_p \rho(p-2) \\
 \rho(3) &= \lambda_1 \rho(2) & + \lambda_2 \rho(1) & + \dots + \lambda_p \rho(p-3) \\
 &\vdots & + \vdots & + \dots + \vdots \\
 \rho(p) &= \lambda_1 \rho(p-1) + \lambda_2 \rho(p-2) + \dots + \lambda_p
 \end{aligned}$$

# Yule-Walker Equations in Matrix Form (1)

☆ Replace the ACF  $\rho(p)$  by sample ACF  $r(k)$ , the  $p$  linear equations can be solved as

$$R := \begin{pmatrix} r(1) \\ r(2) \\ \vdots \\ r(p) \end{pmatrix}, \quad \Phi := \begin{pmatrix} 1 & r(1) & r(2) & \cdots & r(p-1) \\ r(1) & 1 & r(1) & \cdots & r(p-2) \\ r(2) & r(1) & 1 & \cdots & r(p-3) \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ r(p-1) & r(p-2) & r(p-3) & \cdots & 1 \end{pmatrix}$$

$$\Lambda := \begin{pmatrix} \lambda_1 \\ \lambda_2 \\ \vdots \\ \lambda_p \end{pmatrix}$$

## Yule-Walker Equations in Matrix Form (2)

☆ Write compactly as  $R = \Phi\Lambda$ , so the parameters can be estimated as

$$\hat{\Lambda} = \Phi^{-1}R,$$

along with  $\hat{\mu} = \frac{1}{T} \sum_{t=1}^T Y_t$ .

☆ Also,


$$\hat{\theta} = \hat{\mu} \left( 1 - \hat{\lambda}_1 - \hat{\lambda}_2 - \cdots - \hat{\lambda}_p \right).$$


☆ The estimate for the variance of  $u_t$  is


$$\hat{\sigma}_u^2 = \left( \frac{1}{T} \sum_{t=1}^T (Y_t - \hat{\mu})^2 \right) \left( 1 - \hat{\lambda}_1 r(1) - \hat{\lambda}_2 r(2) - \cdots - \hat{\lambda}_p r(p) \right).$$




## Partial Autocorrelation Function

 The sample ACF allows the identification of either an AR or an MA process depending on whether the sample  $r(k)$  decays slowly or are clearly zero after some lag  $k$ .

 However, even if an  $AR(p)$  is identified, it is still difficult to identify the order  $p$ , since all  $AR(p)$  processes show similar decay patterns of ACF.

 Is it possible to identify the order of an AR process?

 Yes, use the Yule-Walker equations to generate a sequence of  $\hat{\lambda}_{kk}, k = 1, 2, \dots, p$  which is the **PACF**.

## Sample PACF Calculation (1)

☺ Suppose the true process is  $AR(p)$ . Take  $k = 1$  and based on  $AR(1)$

$$Y_t = \theta + \lambda_{11}Y_{t-1} + u_t$$

The Yule-Walker equation for  $k = 1$  gives

$$\hat{\lambda}_{11} = r(1)$$

☺ Next take  $k = 2$ , i.e., assume that it is  $AR(2)$ . The Yule-Walker system is

$$\begin{pmatrix} \hat{\lambda}_{21} \\ \hat{\lambda}_{22} \end{pmatrix} = \begin{pmatrix} 1 & r(1) \\ r(1) & 1 \end{pmatrix}^{-1} \begin{pmatrix} r(1) \\ r(2) \end{pmatrix}$$

Solution for  $\hat{\lambda}_{22}$  is

$$\hat{\lambda}_{22} = \frac{r(2) - r(1)^2}{1 - r(1)^2}$$

## Sample PACF Calculation (2)

- ☺ In general, to calculate the  $p$ -th value, take  $k = p$  and the  $\text{AR}(p)$  is

$$Y_t = \theta + \lambda_{p1}Y_{t-1} + \lambda_{p2}Y_{t-2} + \cdots + \lambda_{kp}Y_{t-p} + u_t$$

- ☺ Solve the Yule-Walker equations

$$\hat{\Lambda} = \Phi^{-1}R,$$

- ☺ If the true order is  $p$ , theoretically,

$$\lambda_{11} \neq 0, \lambda_{22} \neq 0, \dots, \lambda_{pp} \neq 0$$

$$\lambda_{p+1p+1} = \lambda_{p+2p+2} = \cdots = 0$$

## Duality between AR and MA, ACF and PACF

- ☯ While an  $AR(p)$  process has a decaying ACF infinite in extent, the PACF cuts off after lag  $p$ .
- ☯ Recall that an  $MA(1)$  process is invertible into  $AR(\infty)$ . In general, this property holds for  $MA(q)$  processes.
- ☯ So while the ACF of an  $MA(q)$  process cuts off after lag  $q$ , the PACF is infinite in extent.
- ☯  $ARMA(p, q)$ 's ACF follows the same pattern as that of an  $AR(p)$  process after  $q - p + 1$  initial values  $\rho_0, \rho_1, \dots, \rho_{q-p}$  (if  $q - p < 0$ , no initial values), while its PACF (for lag  $k > p - q$ ) behaves like that of an  $MA(q)$  process.

## Takeaways

- ✱ White noise is the ultimate randomness.
- ✱ AR, MA, and ARMA are covariance stationary processes for modeling time series.
- ✱ Autocovariance and autocorrelation functions are dependent on the duration and not the absolute clock time.
- ✱ Simulation of AR, MA, and ARMA processes
- ✱ Ljung and Box test statistic for testing autocorrelations
- ✱ Characteristic equation from backward shift operator for checking stationarity
- ✱ Invertibility condition for MA processes
- ✱ Yule-Walker analysis of  $AR(p)$  processes
- ✱ PACF and ACF are needed in stationary time series analysis.