QF627 Programming and Computational Finance

S0608: Scientific Tools in Python and MATLAB

(part 2)

- 24. True / False (Python) scipy.misc.derivative(func,x0,dx,n) computes the nth derivative of func at x0 with spacing dx. When n=1, it computes

 (func(x0+dx)-func(x0-dx))/(2*dx)
- 25. True / False (MATLAB) diff can be used to approximate derivatives with the syntax diff(f)/h.
- 26. (Python) Use **scipy.misc.derivative** and **BS_EuroCallV** to approximate Delta $\Delta = \frac{\partial V}{\partial S}$ and Vega $\mathcal{V} = \frac{\partial V}{\partial \sigma}$ for every row in **data**.

```
import pandas as pd
from scipy.stats import norm
                                                                                               q sigma
from scipy.misc import derivative
                                                                         0 1403 1350 0.0534 0.0118 0.260 0.102778 80.828
from math import log, sqrt, exp
                                                                         1 1403 1375 0.0534 0.0118 0.267 0.102778 66.084
def BS_EuroCallV(S, K, r, q, sigma, T):
   d1=(\log (S/K)+(r-q+sigma**2/2)*T)/(sigma*sqrt(T))
                                                                         2 1403 1400 0.0534 0.0118 0.231 0.102778 45.894
   d2=d1-sigma*sgrt(T)
                                                                         3 1403 1425 0.0534 0.0118 0.213 0.102778 30.955
   c=S*exp(-q*T)*norm.cdf(d1)-K*exp(-r*T)*norm.cdf(d2)
                                                                         4 1403 1450 0.0534 0.0118 0.198 0.102778 19.224
   return c
data=pd.read csv('dataset01.csv',header=0)
Use one command to apply scipy.misc.derivative and BS_EuroCallV to each row of data to compute Delta \Delta = \frac{\partial V}{\partial s} and save
the result to a new column in data and name this column Delta.
data['Delta']=data[['S','K','r','q','sigma','T']].apply(
     lambda x: derivative(lambda s: BS_EuroCallV(s, *(x[1:])),x[0],dx=0.01), axis=1)
Use one command to apply scipy.misc.derivative and BS_EuroCallV to each row of data to compute Vega \mathcal{V} = \frac{\partial V}{\partial x} and save
the result to a new column in data and name this column Vega.
data['Vega']=data[['S','K','r','q','sigma','T']].apply(
     lambda x: derivative(lambda s: BS\_EuroCallV(*(x[0:4]), s, x[5]), x[4], dx=0.01), axis=1)
```

27. (Python) **scipy.integrate.quad(fun, a, b)** computes the definite integral $\int_a^b f(x)dx$. For example, to compute $\int_0^4 x^2 dx$, we can use

```
from scipy import integrate integrate.quad(lambda x: x**2, 0, 4)
```

28. (MATLAB) **integral** (**fun**, **xmin**, **xmax**) numerically integrates function **fun** from **xmin** to **xmax** using global adaptive quadrature and default error tolerances. For example, to compute $\int_0^4 x^2 dx$, we can use

```
integral(@(x): x.^2, 0, 4)
```

29. Compute $\int_0^\infty e^{-x} dx$.

```
Python
from scipy import integrate
import numpy as np
func=lambda x: np.exp(-x)
integrate.quad(func, 0, np.inf)

MATLAB
fun=@(x): exp(-x);
integral(fun, 0, inf)
```

30. In Python, scipy.integrate.dblquad(fun, a, b, gfun, hfun) computes the definite integral $\int_a^b \int_{g(x)}^{h(x)} f(x,y) dy \, dx$. In MATLAB, integral2(fun, xmin, xmax, ymin, ymax) approximates the integral of the function z=fun(x,y) over the planar region $xmin \le x \le xmax$ and $ymin(x) \le y \le ymax(x)$. For example, to compute $\int_0^2 \int_0^1 xy^2 \, dy \, dx$, we can use

```
Python
from scipy import integrate
func=lambda x, y: x*y**2
integrate.dblquad(func, 0, 1, lambda y : 0, lambda y : 2)

MATLAB
fun=@(x,y): x.*(y.^2);
integral(fun, 0, 2, 0, 1)
```

31. True / False (Python) scipy.interpolate.interpld is a class which produces callable instances. The __init__ method has compulsory arguments x and y and the default interpolation method is the linear interpolation. To use cubic spline interpolation, use kind='cubic'. x and y are two of the instance attributes.

32. (Python) Define class myinterpld.

```
import matplotlib.pyplot as plt
import numpy as np
class myinterp1d(object):
   def __init__(self, x, y):
      self.x=x
      self.y=y
   def __call__(self, xnew):
      ynew=[]
      for x0 in xnew:
         if x0 \le self.x[0]:
            ynew.append(self.y[0])
         elif x0 >= self.x[-1]:
            ynew.append(y[-1])
         else:
            hi=next(filter(lambda x: x0<x[1], enumerate(self.x)))[0]
            lo=hi-1
            m=(self.y[hi]-self.y[lo])/(self.x[hi]-sel)
            ynew.append(self.y[lo]+m*(x0-self.x[lo]))
      ynew=np.array(ynew)
      return ynew
x = np.arange(0, 10)
y = np.exp(-x/3.0)
f = myinterpld(x, y)
xnew = np.arange(0, 9, 0.1)
ynew = f(xnew)
plt.plot(x, y, 'o', xnew, ynew, '-')
plt.show()
```

33. Fix the bug.

```
import numpy as np
import matplotlib.pyplot as plt
class myinterp1d(object):
    def __init__(self, x, y):
        self.x=x
        self.y=y
        self.nInt=len(x)-1 #number of intervals
        self.f=self. linear()
    def linear(self):
        f=[]
        for i in range(self.nInt):
            m=(y[i+1]-y[i])/(x[i+1]-x[i])
            b=y[i]-m*x[i]
            #f.append(lambda x: m*x+b)
            f.append(lambda x, m=m, b=b: m*x+b)
        return f
    def linear interp(self, x0):
        if x0 \le self.x[0]:
            return y[0]
        elif x0 >= self.x[-1]:
            return y[-1]
        else:
            i=next(filter(lambda s: x0<s[1], enumerate(self.x)))[0]</pre>
            return self.f[i-1](x0)
    def call (self, xnew):
        return np.array([self._linear_interp(x0) for x0 in xnew])
x = np.arange(0, 10)
y = np.exp(-x/3.0)
f = myinterpld(x, y)
xnew = np.arange(0, 9, 0.1)
ynew = f(xnew) # use interpolation function returned by `interp1d`
plt.plot(x, y, 'o', xnew, ynew, '-')
plt.show()
```

- 34. ☐ True / ☐ False (Python) numpy.polyfit(x,y,deg) fits a polynomial of degree deg to points (x, y). It returns a vector of coefficients p. numpy.polyval(p,x) evaluates a polynomial at x. When deg is greater than len(x) −1, the polynomial can be used as an interpolation function.
- 35. True / False (MATLAB) interp1 (x,v,xq,method) returns interpolated values of a 1-D function at specific query points xq using method. Vector x contains the sample points, and v contains the corresponding values. When method is spline, cubic spline interpolation with not-a-knot end conditions is used.
- 36. \square True / \square False (MATLAB) **polyfit** (x,y,n) and **polyval** (p,x) are similar to the Python functions **numpy**.polyfit and **numpy**.polyval.