

Session 6

Quantitative Analysis of Financial Markets

Modeling and Forecasting Trend

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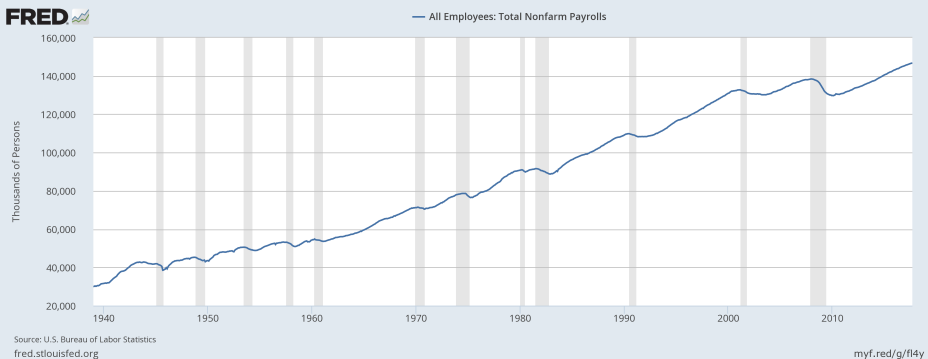
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An Example of Trend



- Is it a linear, quadratic, or generally nonlinear trend?
- Can the trend be modeled? How?
- How can we use the model to forecast future value?

QA-10 Modeling and Forecasting Trend

Chapter 5.

Francis X. Diebold, Elements of Forecasting, 4th Edition (Mason, Ohio: Cengage Learning, 2006).



Describe **linear** and **nonlinear trends**.



Describe **trend models** to estimate and forecast trends.



Compare and evaluate **model selection criteria**, including **mean squared error** (MSE), s^2 (unbiased variance of residuals), the **Akaike information criterion** (AIC), and the **Schwarz information criterion** (SIC).



Explain the necessary conditions for a model selection criterion to demonstrate consistency.

Modeling with TIME

- Model 1: Trend_t is a simple linear function of time

$$\text{Trend}_t = \beta_0 + \beta_1 \text{TIME}_t,$$

- The (deterministic) variable TIME is constructed artificially and is called a **time trend** or **time dummy**.
- $\text{TIME}_t = t$, where $t = 1, 2, \dots, T$.
- β_0 is the regression intercept; it's the value of the trend at $t = 0$.
- β_1 is the regression slope
 - positive if the trend is increasing
 - negative if the trend is decreasing.

Quadratic

- Model 1: Trend_t is a quadratic function of time

$$\text{Trend}_t = \beta_0 + \beta_1 \text{TIME}_t + \beta_2 \text{TIME}_t^2.$$

- $\beta_1 > 0$ and $\beta_2 > 0$: the trend is monotonically increasing.
- $\beta_1 < 0$ and $\beta_2 < 0$: the trend is monotonically decreasing.
- $\beta_1 < 0$ and $\beta_2 > 0$: the trend has a U shape.
- $\beta_1 > 0$ and $\beta_2 < 0$: the trend has an inverted U shape.

Trend of Constant Growth

- If trend is characterized by constant growth at rate, then we can write

$$\text{Trend}_t = \beta_0 e^{\beta_1 \text{TIME}_t}.$$

- The trend is a nonlinear (exponential) function of time in levels, but in logarithms we have

$$\ln(\text{Trend}_t) = \ln(\beta_0) + \beta_1 \text{TIME}_t.$$

- Thus, $\ln(\text{Trend}_t)$ is a linear function of time.

Estimation

- Least squares proceeds by finding the argument (in this case, the value of θ) that minimizes the sum of squared residuals.
- Thus, the least squares estimator is the “argmin” of the sum of squared residuals function.

$$\hat{\theta} = \arg \min_{\theta} \sum_{t=1}^T (y_t - \text{Trend}_t(\theta))^2,$$

where θ denotes the set of parameters to be estimated.

Estimation of Linear Trends

Linear trend

$$(\hat{\beta}_0, \hat{\beta}_1) = \arg \min_{\hat{\beta}_0, \hat{\beta}_1} \sum_{t=1}^T (y_t - \beta_0 - \beta_1 \text{TIME}_t)^2.$$

Quadratic trend

$$(\hat{\beta}_0, \hat{\beta}_1, \hat{\beta}_2) = \arg \min_{\hat{\beta}_0, \hat{\beta}_1, \hat{\beta}_2} \sum_{t=1}^T (y_t - \beta_0 - \beta_1 \text{TIME}_t - \beta_2 \text{TIME}_t^2)^2.$$

Log linear trend

$$(\hat{\beta}_0, \hat{\beta}_1) = \arg \min_{\hat{\beta}_0, \hat{\beta}_1} \sum_{t=1}^T (\ln y_t - \ln \beta_0 - \beta_1 \text{TIME}_t)^2.$$

Forecast

- The linear trend model, which holds for any time t , is

$$y_t = \beta_0 + \beta_1 \text{TIME}_t + \epsilon_t.$$

- At time $T + h$, the future time of interest, the forecast made at T is

$$y_{T+h} = \beta_0 + \beta_1 \text{TIME}_{T+h} + \epsilon_{T+h}.$$

- Key idea: TIME_{T+h} is known at time T , because the artificially-constructed time variable is perfectly predictable; specifically,

$$\text{TIME}_{T+h} = T + h.$$

- The point forecast is for time $T + h$ and is made at time T .

$$y_{T+h,T} = \beta_0 + \beta_1 \text{TIME}_{T+h}.$$

Forecast in Practice

- Replace unknown parameters with their least squares estimates, yielding the point estimate:

$$\hat{y}_{T+h,T} = \hat{\beta}_0 + \hat{\beta}_1 \text{TIME}_{T+h}.$$

- To form an interval forecast with 95% confidence, we use $\hat{y}_{T+h,T} \pm 1.96\hat{\sigma}$, where $\hat{\sigma}$ is the standard error of the trend regression.
- To form a density forecast, we again assume that the trend regression disturbance is normally distributed

$$N(\hat{y}_{T+h,T}, \hat{\sigma}^2).$$

Motivating Questions and Problems

- ⤴ How do we select among them when fitting a trend to a specific series?
- ⤴ What are the consequences, for example, of fitting a number of trend models and selecting the model with highest R^2 ?
- ⤴ It turns out that model-selection strategies such as selecting the model with highest R^2 do not produce good out-of-sample forecasting models.
- ⤴ **In-sample overfitting and data mining**
Including more variables in a forecasting model won't necessarily improve its out-of-sample forecasting performance

Mean Squared Error (MSE)

人 Fitted Model 1

$$\hat{y}_t := \hat{\beta}_0 + \hat{\beta}_1 \text{TIME}_t.$$

人 Residual

$$\hat{e}_t := y_t - \hat{y}_t,$$

人 Definition of MSE

$$\text{MSE} := \frac{\sum_{t=1}^T \hat{e}_t^2}{T},$$

where T is the sample size.

R^2 and Mean Squared Error

⚡ MSE's connection with R^2

$$R^2 = 1 - \frac{\sum_{t=1}^T \hat{e}_t^2}{\sum_{t=1}^T (y_t - \bar{y})^2}.$$

⚡ Mean squared error corrected for degrees of freedom

$$s^2 = \frac{\sum_{t=1}^T \hat{e}_t^2}{T - K},$$

where K is the total number of degrees of freedom used in model fitting.

R^2 and \bar{R}^2

⚡ s^2 is just the usual unbiased estimate of the regression disturbance variance. That is, it is the square of the usual standard error of the regression.

⚡ Connection with adjusted R^2

$$\bar{R}^2 = 1 - \frac{\frac{\sum_{t=1}^T \hat{e}_t^2}{T - k}}{\frac{\sum_{t=1}^T (y_t - \bar{y})^2}{T - 1}} = 1 - \frac{s^2}{\frac{\sum_{t=1}^T (y_t - \bar{y})^2}{T - 1}}$$

⚡ Note that the denominator depends only on the data want to fit, not the particular model fit.

Penalizing Degrees of Freedom

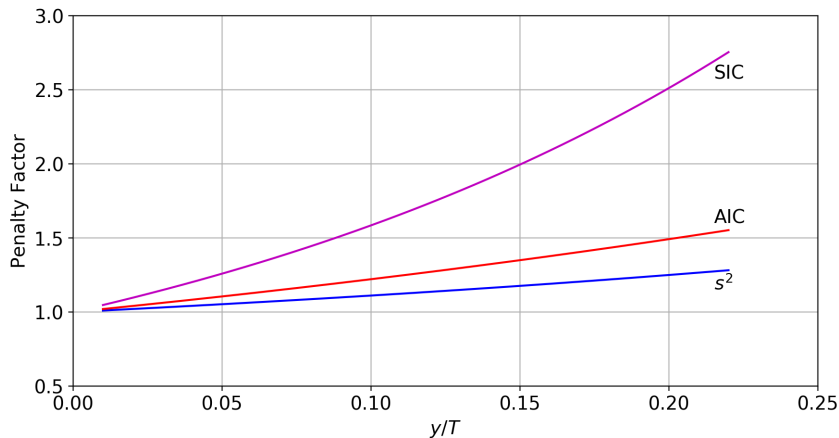
- ⤴ We need to correct somehow for degrees of freedom K when estimating out-of-sample MSE on the basis of in-sample MSE.
- ⤴ To highlight the degree-of-freedom penalty, rewrite s^2 as a penalty factor times the MSE,

$$s^2 = \left(\frac{T}{T-K} \right) \frac{\sum_{t=1}^T \hat{e}_t^2}{T} = \frac{1}{1 - \frac{K}{T}} \frac{\sum_{t=1}^T \hat{e}_t^2}{T} = \frac{1}{1 - \frac{K}{T}} \text{MSE}.$$


- ⤴ Two very important such criteria are the Akaike information criterion (AIC) and the Schwarz information criterion (SIC). Their formulas are

$$\text{AIC} = e^{\frac{2K}{T}} \text{MSE} \quad \text{and} \quad \text{SIC} = T^{\frac{K}{T}} \text{MSE}.$$

Comparison of Information Criteria



Definition of Consistency

-  A model selection criterion is consistent if the following conditions are met:
- A when the true model—that is, the **data-generating process (DGP)**—is among the models considered, the probability of selecting the true DGP approaches 1 as the sample size gets large
 - B when the true model is not among those considered, so that it's impossible to select the true DGP, the probability of selecting the best approximation to the true DGP approaches 1 as the sample size gets large.

Which Criterion Is Consistent?

- ✧ MSE is inconsistent, because it doesn't penalize for degrees of freedom.
- ✧ As T increases, s^2 becomes MSE, thus it is not a consistent model selection procedure.
- ✧ The AIC penalizes degrees of freedom more heavily than s^2 , but it too remains inconsistent, even as the sample size gets large.
- ✧ The AIC selects models that are too large ("overparameterized").
- ✧ The SIC, which penalizes degrees of freedom most heavily, is consistent.

Asymptotic Efficiency

- What if both the true DGP and the best approximation to it are much more complicated than any model we fit?
- An **asymptotically efficient model selection criterion** chooses a sequence of models, as the sample size gets large, whose 1-step-ahead forecast error variances approach the one that would be obtained using the true model with known parameters at a rate at least as fast as that of any other model selection criterion.
- The AIC, although inconsistent, is asymptotically efficient, whereas the SIC is not.

Takeaways

- Trend as a function of time
- Forecast: point estimate, interval, density
- Model of in-sample fit: MSE, R^2
- Model selection criteria: \overline{R}^2 , s^2 , AIC, SIC
- Main desired property of a criterion: Consistency