

Stochastic Modelling Assignment 1.

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1.

$$\begin{aligned} a) P(W_2 < 0 \mid W_1 > 0) &= P(W_2 \text{ moves down}) \times P(|W_2 - W_1| > |W_1 - W_0|) \\ &= \frac{1}{2} \times \frac{1}{2} = \frac{1}{4} \end{aligned}$$

$$\begin{aligned} b) P(W_1 \times W_2 < 0) &= \underbrace{P(W_2 < 0 \cap W_1 > 0)} + P(W_2 > 0 \cap W_1 < 0) \\ &\hookrightarrow P(W_2 < 0 \mid W_1 > 0) \cdot P(W_1 > 0) = \frac{1}{4} \times \frac{1}{2} = \frac{1}{8} \\ &\frac{1}{8} \times 2 = \frac{1}{4} \end{aligned}$$

$$\begin{aligned} c) P(W_1 < 0 \cap W_2 < 0) &= P(W_2 < 0 \mid W_1 < 0) \times P(W_1 < 0) \\ &= \frac{3}{4} \times \frac{1}{2} = \frac{3}{8} \end{aligned}$$

$$\begin{aligned} 2. E[|W_{t+\Delta t} - W_t|] &= \underbrace{E[W_{t+\Delta t} - W_t]}_{\text{when } W_{t+\Delta t} > W_t} + \underbrace{E[-W_{t+\Delta t} + W_t]}_{\text{when } W_{t+\Delta t} < W_t} \\ &= 2E[W_{t+\Delta t} - W_t] \quad (W_{t+\Delta t} > W_t) \end{aligned}$$

here, $W_{t+\Delta t} - W_t = X \sim N(0, \Delta t)$

$$\begin{aligned} \therefore 2E[W_{t+\Delta t} - W_t] &= 2 \times \int_0^{\infty} x \frac{1}{\sqrt{2\pi\Delta t}} e^{-\frac{x^2}{2\Delta t}} dx \\ &= 2 \times \frac{1}{2} \frac{\sqrt{2\Delta t}}{\sqrt{\pi}} \\ &= \frac{\sqrt{2\Delta t}}{\sqrt{\pi}} \end{aligned}$$

$$\begin{aligned}
 3. \quad V[(W_t - W_s)^2] &= E[(W_t - W_s)^4] - E[(W_t - W_s)^2]^2 \\
 &= E[(t-s)^2 X^4] - (t-s)^2 \quad (X \sim N(0,1)) \\
 &= 3(t-s)^2 - (t-s)^2 \\
 &= 2(t-s)^2
 \end{aligned}$$

4.

a) $X_t = W_t^2 = f(x)$

$$\begin{aligned}
 dX_t &= f'(x) \cdot dW_t + \frac{1}{2} f''(x) (dW_t)^2 \\
 &= 2 \cdot W_t dW_t + \frac{1}{2} \cdot 2 \cdot dt
 \end{aligned}$$

$$dX_t = 2W_t dW_t + dt$$

b) $X_t = t + e^{W_t} = f(t, x)$

$$\begin{aligned}
 dX_t &= \frac{\partial f}{\partial t} dt + \frac{\partial f}{\partial x} dW_t + \frac{1}{2} \frac{\partial^2 f}{\partial x^2} (dW_t)^2 \\
 &= dt + e^{W_t} dW_t + \frac{1}{2} e^{W_t} dt
 \end{aligned}$$

$$dX_t = \left(1 + \frac{1}{2} e^{W_t}\right) dt + e^{W_t} dW_t$$

c) $X_t = W_t^3 - 3tW_t = f(t, x)$

$$\begin{aligned}
 dX_t &= \frac{\partial f}{\partial t} dt + \frac{\partial f}{\partial x} dW_t + \frac{1}{2} \frac{\partial^2 f}{\partial x^2} (dW_t)^2 \\
 &= -3W_t dt + (3W_t^2 - 3t) dW_t + \frac{1}{2} 6W_t dt
 \end{aligned}$$

$$dX_t = (3W_t^2 - 3t) dW_t$$

$$d) \quad X_t = e^{t+W_t}$$

$$dX_t = e^{t+W_t} dt + e^{t+W_t} dW_t + \frac{1}{2} e^{t+W_t} dt$$

$$dX_t = \frac{3}{2} e^{t+W_t} dt + e^{t+W_t} dW_t = \frac{3}{2} X_t dt + X_t dW_t$$

$$e) \quad X_t = e^{\frac{t}{2}} \sin(W_t)$$

$$dX_t = \frac{1}{2} e^{\frac{t}{2}} \sin(W_t) dt + e^{\frac{t}{2}} \cos(W_t) dW_t - \frac{1}{2} e^{\frac{t}{2}} \sin(W_t) dt$$

$$dX_t = e^{\frac{t}{2}} \cos(W_t) dW_t$$

$$f) \quad X_t = e^{W_t - \frac{t}{2}}$$

$$dX_t = -\frac{1}{2} e^{W_t - \frac{t}{2}} dt + e^{W_t - \frac{t}{2}} dW_t + \frac{1}{2} e^{W_t - \frac{t}{2}} dt$$

$$dX_t = e^{W_t - \frac{t}{2}} dW_t = X_t dW_t$$

$$5. \quad X_t = Y_t Z_t$$

$$dX_t = Y_t dZ_t + Z_t dY_t + dY_t dZ_t$$

$$= Y_t A(t) dt + Y_t B(t) dW_t + Z_t b(t) Y_t dW_t + b(t) Y_t B(t) dt$$

$$= (A(t) + b(t) B(t)) Y_t dt + (B(t) + Z_t b(t)) Y_t dW_t$$

$$6. Y_t = \frac{W_t}{\tilde{W}_t} = f(W_t, \tilde{W}_t).$$

Let W_t and \tilde{W}_t , x and y respectively

$$Y_t = \frac{\partial f}{\partial x} dW_t + \frac{\partial f}{\partial y} d\tilde{W}_t + \frac{1}{2} \frac{\partial^2 f}{\partial x^2} (dW_t)^2 + \frac{1}{2} \frac{\partial^2 f}{\partial y^2} (d\tilde{W}_t)^2$$

$$= \frac{1}{\tilde{W}_t} dW_t - \frac{W_t}{\tilde{W}_t^2} d\tilde{W}_t + \frac{1}{2} \times 2 \times \frac{W_t}{\tilde{W}_t^3} dt$$

$$= \frac{1}{\tilde{W}_t} dW_t - \frac{W_t}{\tilde{W}_t^2} d\tilde{W}_t + \frac{W_t}{\tilde{W}_t^3} dt$$

7.

$$a) dr_t = \theta dt + \sigma dW_t$$

$$\int_0^T dr_t = \int_0^T \theta dt + \int_0^T \sigma dW_t.$$

$$r_T - r_0 = \theta T + \sigma W_T$$

$$E\left(\int_0^T r_t dt\right) = E\left(\int_0^T (r_0 + \theta t + \sigma W_t) dt\right)$$

$$= r_0 T + \theta \cdot \frac{1}{2} T^2 + \sigma \int_0^T E(W_t) dt$$

$$= r_0 T + \frac{\theta}{2} T^2$$

$$b) V\left[\int_0^T r_t dt\right] = E\left[\left(\int_0^T r_t dt\right)^2\right] - T^2 \left(r_0 + \frac{\theta T}{2}\right)^2$$

$$= E\left[\left(\int_0^T (r_0 + \theta t + \sigma W_t) dt\right)^2\right] - T^2 \left(r_0 + \frac{\theta T}{2}\right)^2$$

$$= E\left[\left(T\left(r_0 + \frac{\theta T}{2}\right) + \int_0^T \sigma W_t dt\right)^2\right] - T^2 \left(r_0 + \frac{\theta T}{2}\right)^2$$

$$E \left[\cancel{T^2 \left(r_0 + \frac{\theta T}{2} \right)^2} + \left(\int_0^T \sigma W_t dt \right)^2 + 2T \left(r_0 + \theta \int_0^T \sigma W_t dt \right) - \cancel{T^2 \left(r_0 + \frac{\theta T}{2} \right)^2} \right]$$

$$= E \left[\left(\int_0^T \sigma W_t dt \right)^2 \right] = \sigma^2 E \left[\left(\int_0^T W_t dt \right)^2 \right]$$

$$= \sigma^2 \frac{T^3}{3}$$