

# Interpolation

<https://docs.scipy.org/doc/scipy/reference/tutorial/interpolate.html>

<https://docs.scipy.org/doc/scipy/reference/generated/scipy.interpolate.interp1d.html>

## scipy.interpolate.interp1d

```
def __init__(self, x, y, kind='linear', axis=-1,
             copy=True, bounds_error=None, fill_value=np.nan,
             assume_sorted=False):
```

```
class scipy.interpolate.interp1d(x, y, kind='linear', axis=-1, copy=True, bounds_error=None,
                                fill_value=np.nan, assume_sorted=False) \[source\]
```

Interpolate a 1-D function.

How to return a function?

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$x$  and  $y$  are arrays of values used to approximate some function  $f$ :  $y = f(x)$ . This class returns a function whose call method uses interpolation to find the value of new points.

Note that calling `interp1d` with NaNs present in input values results in undefined behaviour.

**kind** : *str or int, optional*

Specifies the kind of interpolation as a string ('linear', 'nearest', 'zero', 'slinear', 'quadratic', 'cubic', 'previous', 'next', where 'zero', 'slinear', 'quadratic' and 'cubic' refer to a spline interpolation of zeroth, first, second or third order; 'previous' and 'next' simply return the previous or next value of the point) or as an integer specifying the order of the spline interpolator to use. Default is 'linear'.





```
import numpy as np
import matplotlib.pyplot as plt
from scipy import interpolate
x = np.arange(0, 10)
y = np.exp(-x/3.0)
f = interpolate.interp1d(x, y)
```

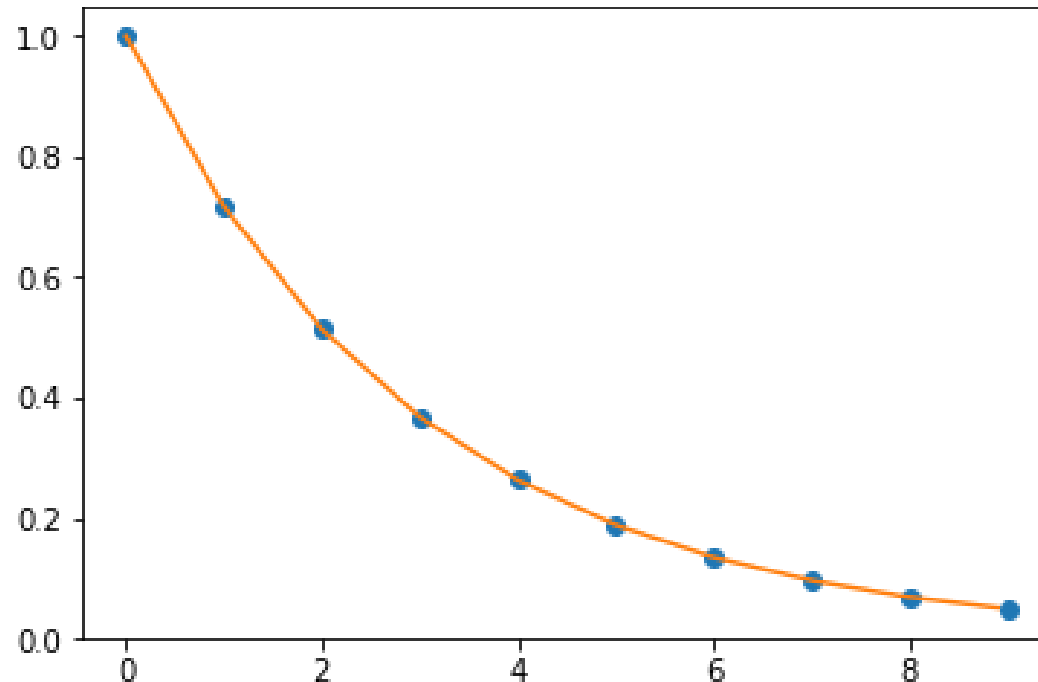


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$f$  is an instance.

```
xnew = np.arange(0, 9, 0.1)
ynew = f(xnew) # use interpolation function returned by `interp1d`
plt.plot(x, y, 'o', xnew, ynew, '-')
plt.show()
```

$f$  is a callable  
instance.



How to return a  
piecewise- defined  
function?



f. `__dict__`



```
{'_call': <function scipy.interpolate.interpolate.interp1d._call_linear>,  
 '_extrapolate': False,  
 '_fill_value_above': array([nan]),  
 '_fill_value_below': array([nan]),  
 '_fill_value_orig': array(nan),  
 '_kind': 'linear',  
 '_y': array([[1.          ],  
              [0.71653131],  
              [0.51341712],  
              [0.36787944],  
              [0.26359714],  
              [0.1888756  ],  
              [0.13533528],  
              [0.09697197],  
              [0.06948345],  
              [0.04978707]]),  
 'axis': 0,  
 'bounds_error': True,  
 'copy': True,  
 'x': array([0, 1, 2, 3, 4, 5, 6, 7, 8, 9]),  
 'y': array([1.          , 0.71653131, 0.51341712, 0.36787944, 0.26359714,  
            0.1888756 , 0.13533528, 0.09697197, 0.06948345, 0.04978707])}
```

`f` is a callable object,  
with instance  
attributes `x` and `y`.

`x`: sorted



```
import numpy as np
class myinterp1d(object):
    def __init__(self, x, y):
        self.x=x
        self.y=y
```

```
    def __call__(self, xnew):
        ynew=[]
```

```
        for x0 in xnew:
```

```
            if x0<=self.x[0]:
```

```
                ynew.append(self.y[0])
```

```
            elif x0>=self.x[-1]:
```

```
                ynew.append(self.y[-1])
```

```
            else:
```

```
                hi=next(filter(lambda x: x0<x[1], enumerate(self.x)))[0]
```

```
                lo=hi-1
```

```
                m=(self.y[hi]-self.y[lo])/(self.x[hi]-self.x[lo])
```

```
                ynew.append(self.y[lo]+m*(x0-self.x[lo]))
```

```
        ynew=np.array(ynew)
```

```
        return ynew
```

```
x = np.arange(0, 10)
```

```
y = np.exp(-x/3.0)
```

```
f = myinterp1d(x, y)
```

```
xnew = np.arange(0, 9, 0.1)
```

```
ynew = f(xnew) # use interpolation function returned by `interp1d`
```

```
plt.plot(x, y, 'o', xnew, ynew, '-')
```

```
plt.show()
```

# class myinterp1d

For each item in **xnew**, denoted as **x0**, compute **y0**

1. find interval **i**:  $x[i-1] < x0 \leq x[i]$
2.  $m = (y[i] - y[i-1]) / (x[i] - x[i-1])$
3.  $y0 = y[i] + m * (x0 - x[i-1])$



# How to return a list of functions as piecewise-defined function ???

```
import numpy as np
import matplotlib.pyplot as plt
class myinterp1d(object):
    def __init__(self, x, y):
        self.x=x
        self.y=y
        self.nInt=len(x)-1 #number of intervals
        self.f=self._linear()
```

```
def _linear(self):
    f=[]
    for i in range(self.nInt):
        m=(y[i+1]-y[i])/(x[i+1]-x[i])
        b=y[i]-m*x[i]
        f.append(lambda x: m*x+b)
    return f
```

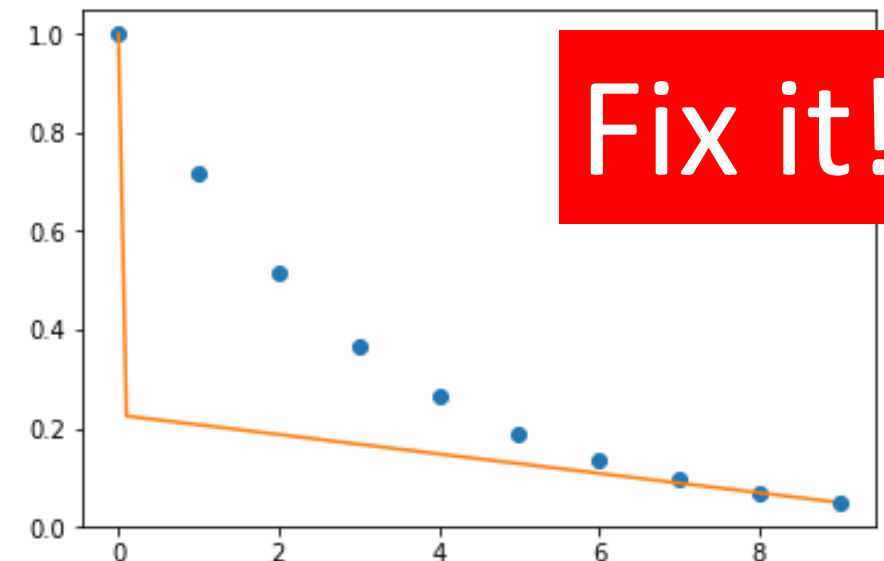
```
def _linear_interp(self, x0):
    if x0<=self.x[0]:
        return y[0]
    elif x0>=self.x[-1]:
        return y[-1]
    else:
        i=next(filter(lambda s: x0<s[1], enumerate(self.x)))[0]
        return self.f[i-1](x0)
```

```
def __call__(self, xnew):
    return np.array([self._linear_interp(x0) for x0 in xnew])
```

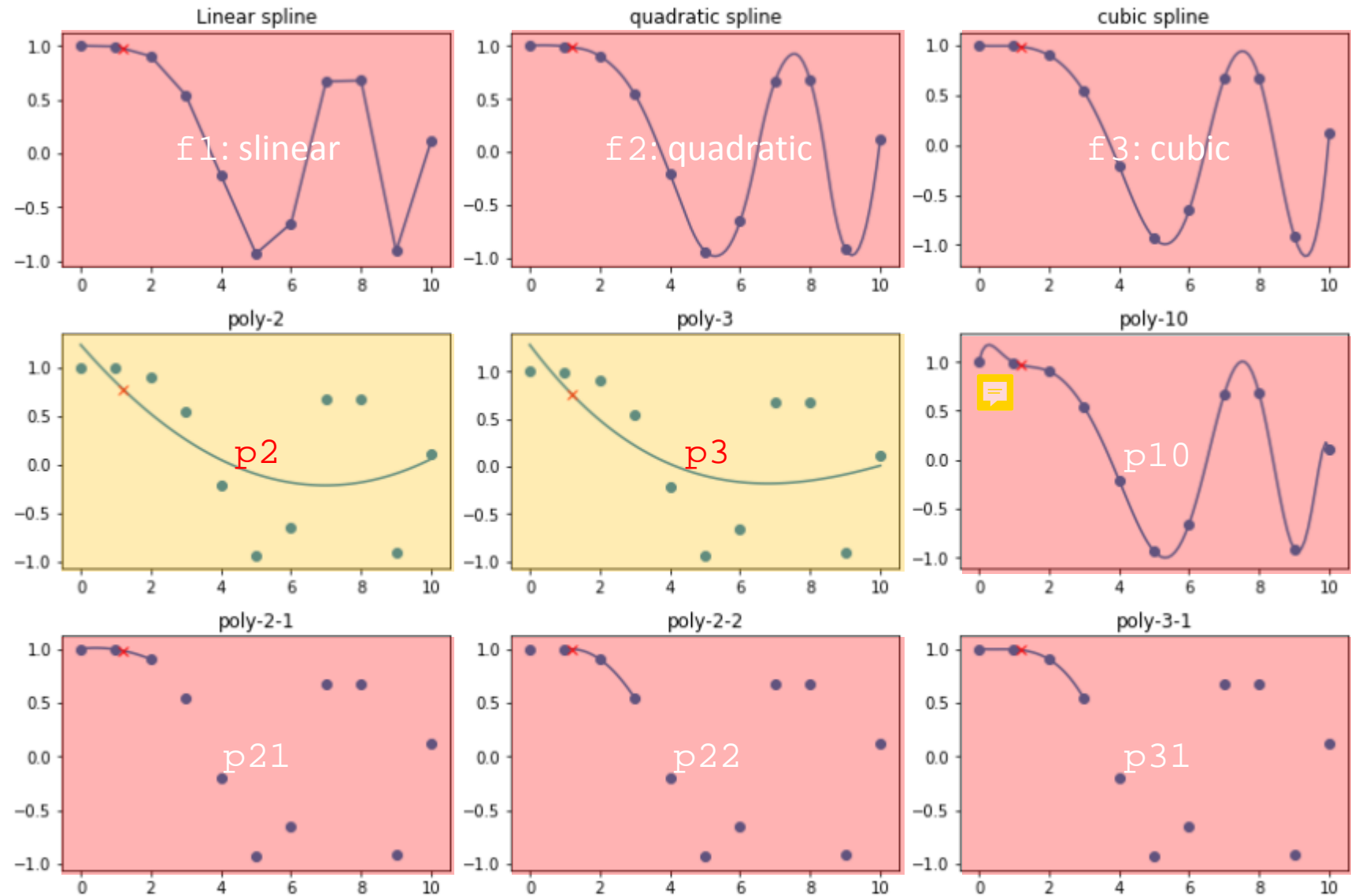
```
x = np.arange(0, 10)
y = np.exp(-x/3.0)
f = myinterp1d(x, y)
xnew = np.arange(0, 9, 0.1)
ynew = f(xnew) # use interpolation function returned by `interp1d`
plt.plot(x, y, 'o', xnew, ynew, '-')
plt.show()
```

```
def _linear(self):
    f=[]
    for i in range(self.nInt):
        m=(y[i+1]-y[i])/(x[i+1]-x[i])
        b=y[i]-m*x[i]
        Hint: => f.append(lambda x: m*x+b)
    return f
```

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# interpolation vs curve fitting



<https://docs.scipy.org/doc/numpy/reference/generated/numpy.polyfit.html>  
<https://docs.scipy.org/doc/numpy/reference/generated/numpy.polyval.html>

## numpy.polyfit

`numpy.polyfit(x, y, deg, rcond=None, full=False, w=None, cov=False)` [\[source\]](#)

Least squares polynomial fit.

Fit a polynomial  $p(x) = p[0] * x^{deg} + \dots + p[deg]$  of degree *deg* to points *(x, y)*. Returns a vector of coefficients *p* that minimises the squared error.



$x, y, \text{deg} \Rightarrow p$



$p, x \Rightarrow y$

This  $x$  is not that  $x$ .

## numpy.polyval

`numpy.polyval(p, x)` [\[source\]](#)

Evaluate a polynomial at specific values.

If *p* is of length *N*, this function returns the value:

$p[0]*x^{(N-1)} + p[1]*x^{(N-2)} + \dots + p[N-2]*x + p[N-1]$

If *x* is a sequence, then *p(x)* is returned for each element of *x*. If *x* is another polynomial then the composite polynomial *p(x(t))* is returned.





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```
from scipy.interpolate import interp1d
#Linear interpolation by scipy.interpolate.interp1d
f1=interp1d(x,y,kind='slinear')

#Quadratic spline interpolation by scipy.interpolate.interp1d
f2=interp1d(x,y,kind='quadratic')

#Cubic spline interpolation by scipy.interpolate.interp1d
f3=interp1d(x,y,kind='cubic')

#Curve fitting (quadratic polynomial) by numpy.polyfit
p2=np.polyfit(x,y,2)

#Curve fitting (cubic polynomial) by numpy.polyfit
p3=np.polyfit(x,y,3)

#Curve fitting (polynomial of degree 10) by numpy.polyfit
p10=np.polyfit(x,y,10)

#Local quadratic interpolation
p21=np.polyfit(x[:3], y[:3],2)
p22=np.polyfit(x[1:4], y[1:4],2)

#Local cubic interpolation
p31=np.polyfit(x[:4], y[:4],3)
```

✓ interp1d

✓ polyfit





```
#Interpolation approximation of fucntion value at x0  
x0=1.2  
print('f1(x0):', f1(x0))  
print('f2(x0):', f2(x0))  
print('f3(x0):', f3(x0))  
print('p2(x0):', np.polyval(p2,x0))  
print('p3(x0):', np.polyval(p3,x0))  
print('p10(x0):', np.polyval(p10,x0))  
print('p21(x0):', np.polyval(p21,x0))  
print('p22(x0):', np.polyval(p22,x0))  
print('p31(x0):', np.polyval(p31,x0))
```

```
f1(x0): 0.6759084722655498  
f2(x0): 0.6698977406045836  
f3(x0): 0.6702554524022847  
p2(x0): 0.6983127386423347  
p3(x0): 0.6786229551598073  
p10(x0): 0.6703199161128766  
p21(x0): 0.6694801124347486  
p22(x0): 0.671302351171146  
p31(x0): 0.6702090079293077
```

✓ polyval



```
import matplotlib.pyplot as plt
plt.rcParams["figure.figsize"]=[12,8]

fig, ax = plt.subplots(3, 3)

xp=np.linspace(0,10,101)
yp=f1(xp)
ax[0,0].scatter(x, y)
ax[0,0].plot(xp, yp)
ax[0,0].plot(x0, f1(x0), 'rx')
ax[0,0].set_title('Linear spline')

xp=np.linspace(0,10,101)
yp=f2(xp)
ax[0,1].scatter(x, y)
ax[0,1].plot(xp, yp)
ax[0,1].plot(x0, f2(x0), 'rx')
ax[0,1].set_title('quadratic spline')

xp=np.linspace(0,10,101)
yp=f3(xp)
ax[0,2].scatter(x, y)
ax[0,2].plot(xp, yp)
ax[0,2].plot(x0, f3(x0), 'rx')
ax[0,2].set_title('cubic spline')

xp=np.linspace(0,10,101)
yp=np.polyval(p2,xp)
ax[1,0].scatter(x, y)
ax[1,0].plot(xp, yp)
ax[1,0].plot(x0, np.polyval(p2,x0), 'rx')
ax[1,0].set_title('poly-2')

xp=np.linspace(0,10,101)
yp=np.polyval(p3,xp)
ax[1,1].scatter(x, y)
ax[1,1].plot(xp, yp)
ax[1,1].plot(x0, np.polyval(p3,x0), 'rx')
ax[1,1].set_title('poly-3')
```

```
xp=np.linspace(0,10,101)
yp=np.polyval(p10,xp)
ax[1,2].scatter(x, y)
ax[1,2].plot(xp, yp)
ax[1,2].plot(x0, np.polyval(p10,x0), 'rx')
ax[1,2].set_title('poly-10')

xp=np.linspace(0,2,21)
yp=np.polyval(p21,xp)
ax[2,0].scatter(x, y)
ax[2,0].plot(xp, yp)
ax[2,0].plot(x0, np.polyval(p21,x0), 'rx')
ax[2,0].set_title('poly-2-1')

xp=np.linspace(1,3,21)
yp=np.polyval(p22,xp)
ax[2,1].scatter(x, y)
ax[2,1].plot(xp, yp)
ax[2,1].plot(x0, np.polyval(p22,x0), 'rx')
ax[2,1].set_title('poly-2-2')

xp=np.linspace(0,3,31)
yp=np.polyval(p31,xp)
ax[2,2].scatter(x, y)
ax[2,2].plot(xp, yp)
ax[2,2].plot(x0, np.polyval(p31,x0), 'rx')
ax[2,2].set_title('poly-3-1')

#plt.tight_layout(pad=0.4, w_pad=0.5, h_pad=1.0)
plt.tight_layout()
plt.show()
```



```
import matplotlib.pyplot as plt
plt.rcParams["figure.figsize"]=[12,8]

xp=np.linspace(0,10,101)
xp21=np.linspace(0,2,21)
xp22=np.linspace(1,3,21)
xp31=np.linspace(0,3,31)
xps=[[xp, xp, xp],
      [xp, xp, xp],
      [xp21, xp22, xp31]]

yps=[[f1(xp), f2(xp), f3(xp)],
      [np.polyval(p2,xp), np.polyval(p3,xp), np.polyval(p10,xp)],
      [np.polyval(p21,xp21), np.polyval(p22,xp22), np.polyval(p31,xp31)]]

yp0=[[f1(x0), f2(x0), f3(x0)],
      [np.polyval(p2,x0), np.polyval(p3,x0), np.polyval(p10,x0)],
      [np.polyval(p21,x0), np.polyval(p22,x0), np.polyval(p31,x0)]]

titles=[['Linear spline', 'quadratic spline', 'cubic spline'],
        ['poly-2', 'poly-3', 'poly-10'],
        ['poly-2-1', 'poly-2-2', 'poly-3-1']]

fig, ax = plt.subplots(3, 3)

for i in range(3):
    for j in range(3):
        ax[i,j].scatter(x, y)
        ax[i,j].plot(xps[i][j], yps[i][j])
        ax[i,j].plot(x0, yp0[i][j], 'rx')
        ax[i,j].set_title(titles[i][j])

#plt.tight_layout(pad=0.4, w_pad=0.5, h_pad=1.0)
plt.tight_layout()
plt.show()
```



Use loop

# Interpolation (1)

<https://www.mathworks.com/help/matlab/interpolation.html>

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<code>interp1</code>	1-D data interpolation (table lookup)
<code>interp2</code>	Interpolation for 2-D gridded data in meshgrid format
<code>interp3</code>	Interpolation for 3-D gridded data in meshgrid format
<code>interpvn</code>	Interpolation for 1-D, 2-D, 3-D, and N-D gridded data in ndgrid format
<code>griddedInterpolant</code>	Gridded data interpolation
<code>pchip</code>	Piecewise Cubic Hermite Interpolating Polynomial (PCHIP)
<code>spline</code>	Cubic spline data interpolation
<code>ppval</code>	Evaluate piecewise polynomial
<code>mkpp</code>	Make piecewise polynomial
<code>unmkpp</code>	Extract piecewise polynomial details
<code>padecoeff</code>	Padé approximation of time delays
<code>interpft</code>	1-D interpolation (FFT method)



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# interp1

1-D data interpolation (table lookup)

## Syntax

Cubic spline **end conditions**:

- ✓ Not-a-knot
- Clamped
- Natural
- Periodic

```
vq = interp1(x,v,xq)
```

```
vq = interp1(x,v,xq,method)
```

```
vq = interp1(x,v,xq,method,extrapolation)
```

```
vq = interp1(v,xq)
```

```
vq = interp1(v,xq,method)
```

```
vq = interp1(v,xq,method,extrapolation)
```

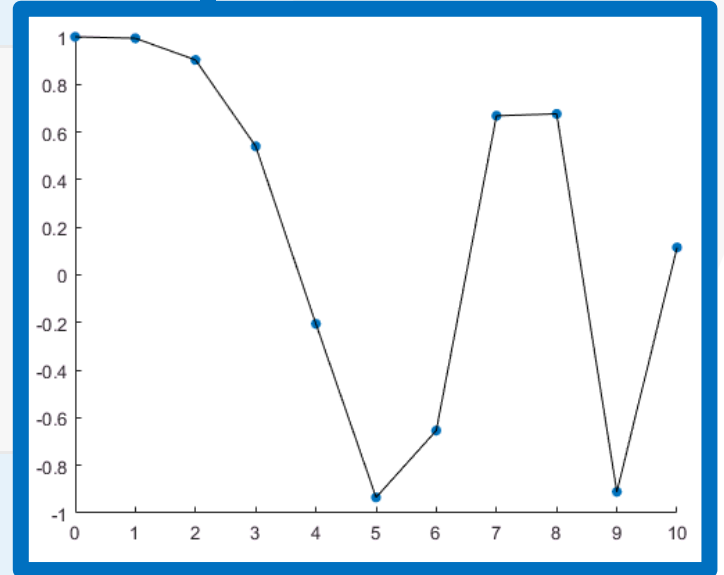
```
pp = interp1(x,v,method,'pp')
```

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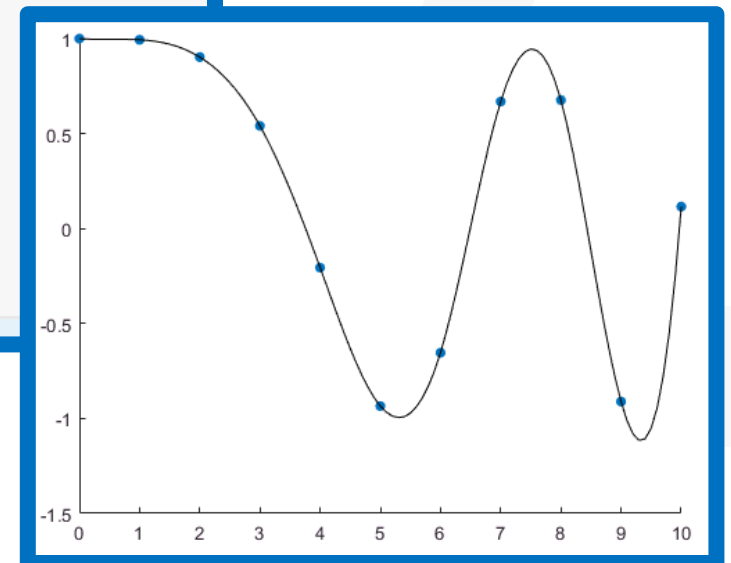


## Interpolation

```
% (Default) linear interpolation  
figure();  
scatter(x,y,30,'filled');  
hold on;  
xq=linspace(0,10,101);  
yq=interp1(x,y,xq);  
plot(xq,yq,'k-')
```



```
% 'spline': cubic spline with not-a-knot end condition  
% x0, x1, ..., xN: third derivative is continuous at x1 and xN-1  
figure();  
scatter(x,y,30,'filled');  
hold on;  
xq=linspace(0,10,101);  
yq=interp1(x,y,xq,'spline');  
plot(xq,yq,'k-')
```



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# Polynomials

<https://www.mathworks.com/help/matlab/polynomials.html>

# polyfit and polyval



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## polyfit

Polynomial curve fitting

### Syntax

```
p = polyfit(x,y,n)
[p,S] = polyfit(x,y,n)
[p,S,mu] = polyfit(x,y,n)
```

### Description

`p = polyfit(x,y,n)` returns the coefficients for a polynomial  $p(x)$  of degree  $n$  that is a best fit (in a least-squares sense) for the data in  $y$ . The coefficients in  $p$  are in descending powers, and the length of  $p$  is  $n+1$ .

$$p(x) = p_1x^n + p_2x^{n-1} + \dots + p_nx + p_{n+1}.$$

## polyval

Polynomial evaluation

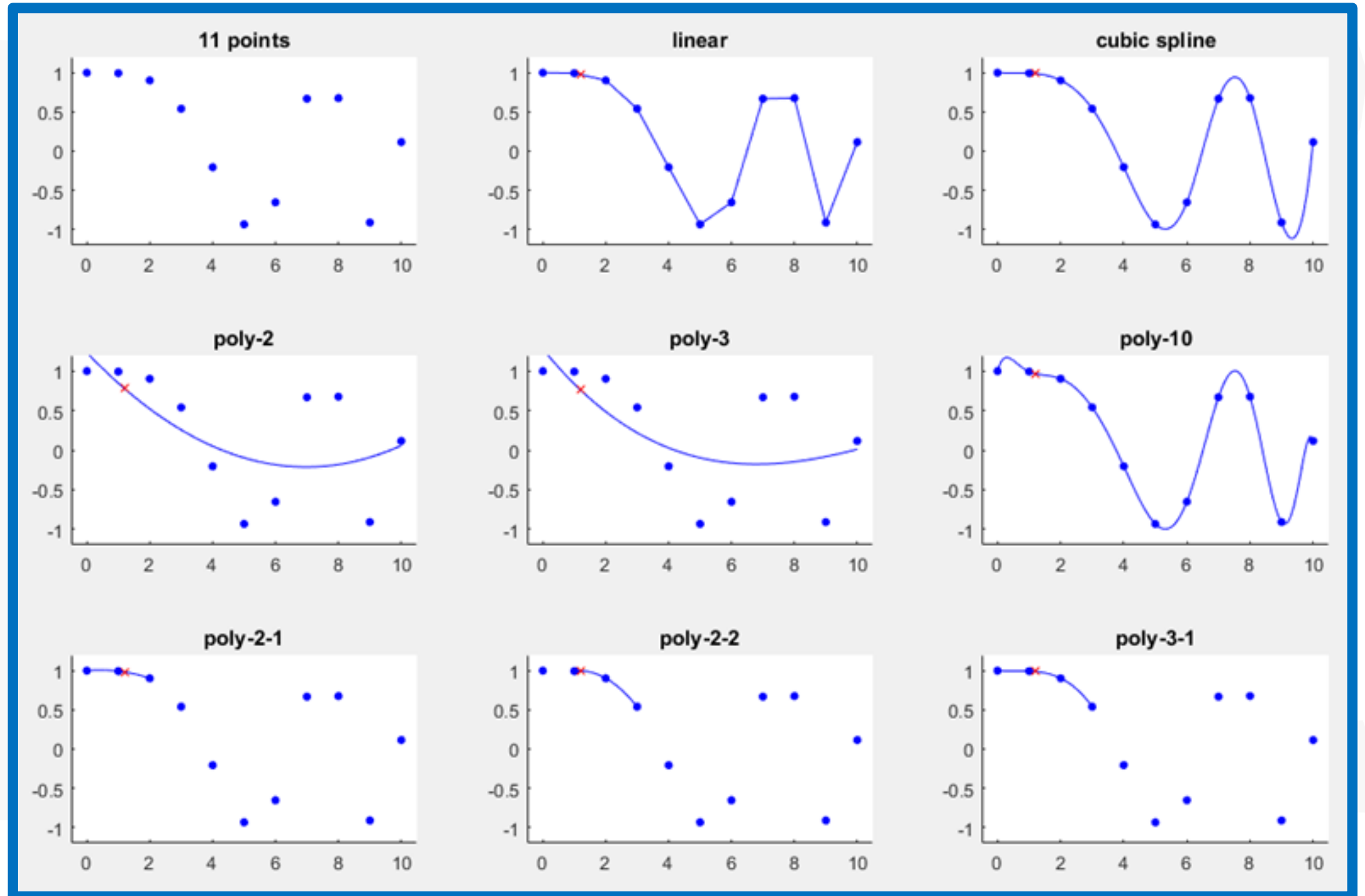
### Syntax

```
y = polyval(p,x)
[y,delta] = polyval(p,x,S)
y = polyval(p,x,[],mu)
[y,delta] = polyval(p,x,S,mu)
```

### Description

`y = polyval(p,x)` evaluates the polynomial  $p$  at each point in  $x$ . The argument  $p$  is a vector of length  $n+1$  whose elements are the coefficients (in descending powers) of an  $n$ th-degree polynomial:

$$p(x) = p_1x^n + p_2x^{n-1} + \dots + p_nx + p_{n+1}.$$







1

```
%subplots
subplot(3,3,1);
x=linspace(0,10,11);
y=cos(-x.^2/9);
scatter(x,y,20,'blue','filled')
axis(ax)
title('11 points')
```



2

```
%subplots
subplot(3,3,2);
scatter(x,y,20,'blue','filled')
hold on;
xq=linspace(0,10,101);
yq=interp1(x,y,q);
y0=interp1(x,y,0);
plot(xq,yq,'b-')
plot(x0,y0,'rx')
axis(ax)
title('linear')
```

3

```
% subplots
subplot(3,3,3);
scatter(x,y,20,'blue','filled')
hold on;
xq=linspace(0,10,101);
yq=interp1(x,y,q,'spline');
y0=interp1(x,y,0,'spline');
plot(xq,yq,'b-')
plot(x0,y0,'rx')
axis(ax)
title('cubic spline')
```

4

```
% subplots
subplot(3,3,4);
scatter(x,y,20,'blue','filled')
hold on;
xq=linspace(0,10,101);
yq=polyval(polyfit(x,y,2),xq);
y0=polyval(polyfit(x,y,2),x0);
plot(xq,yq,'b-')
plot(x0,y0,'rx')
axis(ax)
title('poly-2')
```

5

```
% subplots
subplot(3,3,5);
scatter(x,y,20,'blue','filled')
hold on;
xq=linspace(0,10,101);
yq=polyval(polyfit(x,y,3),xq);
y0=polyval(polyfit(x,y,3),x0);
plot(xq,yq,'b-')
plot(x0,y0,'rx')
axis(ax)
title('poly-3')
```

6

```
% subplots
subplot(3,3,6);
scatter(x,y,20,'blue','filled')
hold on;
xq=linspace(0,10,101);
yq=polyval(polyfit(x,y,10),xq);
y0=polyval(polyfit(x,y,10),x0);
plot(xq,yq,'b-')
plot(x0,y0,'rx')
axis(ax)
title('poly-10')
```

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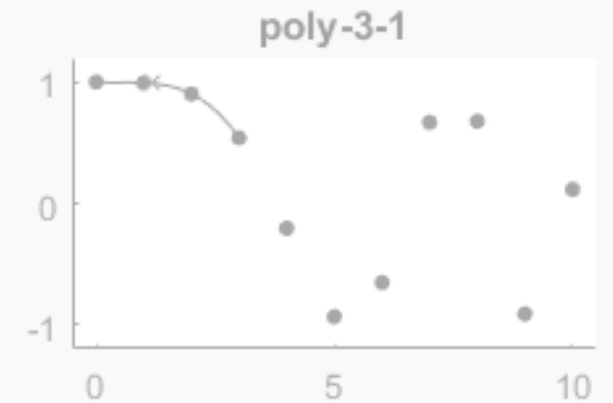
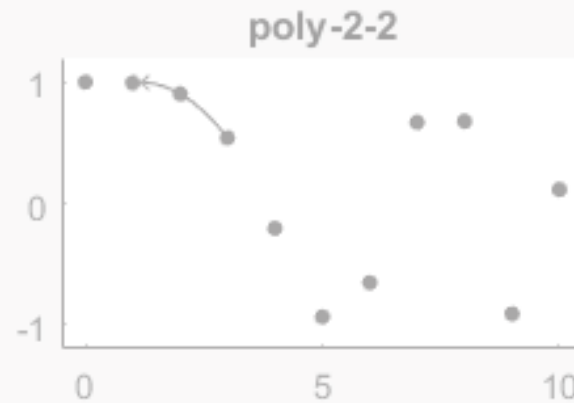
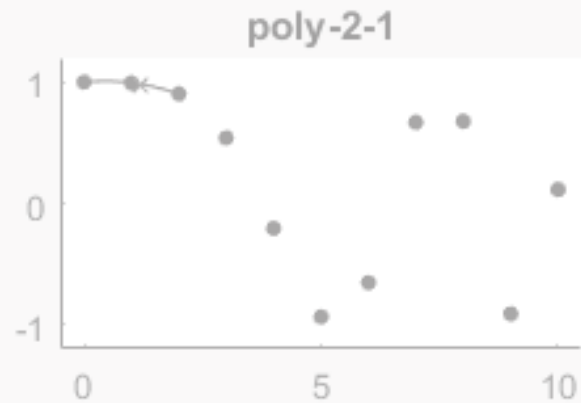
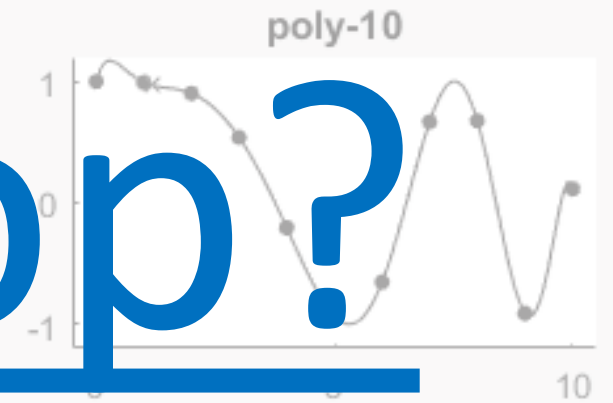
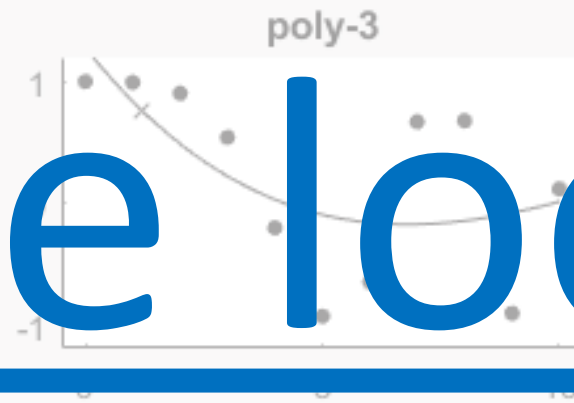
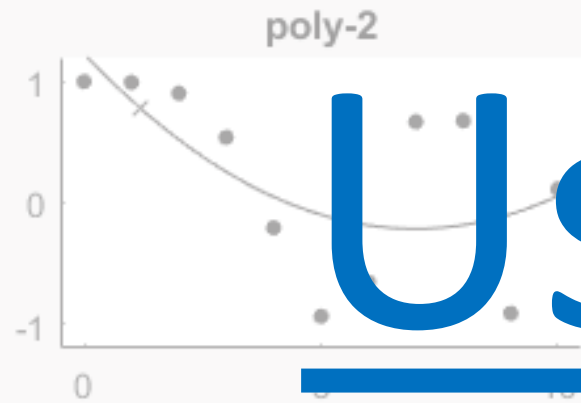
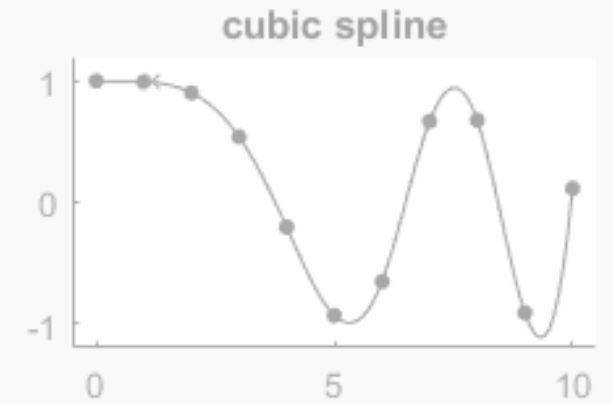
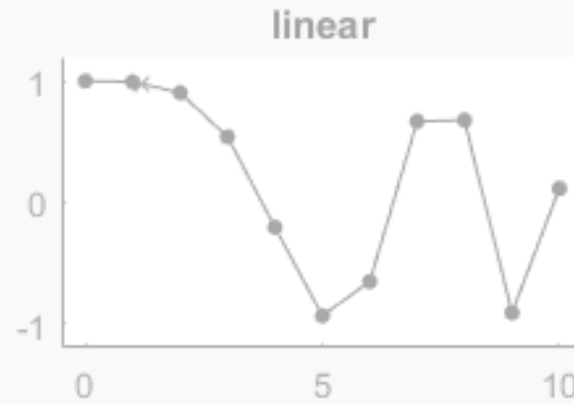
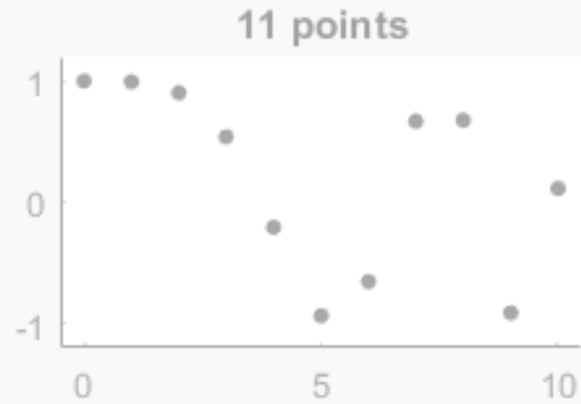
```
% subplots
subplot(3,3,7);
scatter(x,y,20,'blue','filled')
hold on;
xq=linspace(0,2,21);
yq=polyval(polyfit(x(1:3),y(1:3),2),xq);
y0=polyval(polyfit(x(1:3),y(1:3),2),x0);
plot(xq,yq,'b-')
plot(x0,y0,'rx')
axis(ax)
title('poly-2-1')
```

8

```
% subplots
subplot(3,3,8);
scatter(x,y,20,'blue','filled')
hold on;
xq=linspace(1,3,21);
yq=polyval(polyfit(x(2:4),y(2:4),2),xq);
y0=polyval(polyfit(x(2:4),y(2:4),2),x0);
plot(xq,yq,'b-')
plot(x0,y0,'rx')
axis(ax)
title('poly-2-2')
```

9

```
% subplots
subplot(3,3,9);
scatter(x,y,20,'blue','filled')
hold on;
xq=linspace(0,3,31);
yq=polyval(polyfit(x(1:4),y(1:4),3),xq);
y0=polyval(polyfit(x(1:4),y(1:4),3),x0);
plot(xq,yq,'b-')
plot(x0,y0,'rx')
axis(ax)
title('poly-3-1')
```



Use loop?



QF666  
Programming and  
Computational  
Finance



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# end