

Session 4

Quantitative Analysis of Financial Markets

Model k and OLS

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October 29, 2018

Broad Lesson Plan

- 1 Nuggets of Statistics
- 2 Model k
- 3 Ordinary Linear Regression
- 4 MLR Tutorial
- 5 Goodness of Fit
- 6 Takeaways

What's the Variance of Sample Mean?

👉 The mean estimate $\hat{\mu}$ is a random variable as a result of **random sampling**.

👉 Assume that X_i is i.i.d. for each i , $i = 1, 2, \dots, n$. With $\mathbb{C}(X_i, X_j) = 0$ for $i \neq j$,

$$\begin{aligned}\mathbb{E}\left((\hat{\mu} - \mu)^2\right) &\equiv \mathbb{V}(\hat{\mu}) = \mathbb{V}\left(\sum_{i=1}^n \frac{X_i}{n}\right) = \sum_{i=1}^n \mathbb{V}\left(\frac{X_i}{n}\right) \\ &= \sum_{i=1}^n \frac{\mathbb{V}(X_i)}{n^2} = \frac{1}{n^2} \sum_{i=1}^n \mathbb{V}(X_i) = \frac{1}{n^2} \cdot n\sigma^2 \\ &= \frac{\sigma^2}{n}.\end{aligned}$$

👉 What is the implication of this result?

You think you know basic statistics?

What is the information the following estimator extracts from the sample $\{x_i\}_{i=1}^n$?

$$\hat{\Sigma} := \frac{1}{n(n-1)} \sum_{i < j} (x_i - x_j)^2$$

Sample mean: $\hat{\mu} = \frac{1}{n} \sum_{i=1}^n x_i$.

Answer: _____

$$\begin{aligned}
 \sum_{i < j} (x_i - x_j)^2 &= \sum_{j=2}^n \sum_{i=1; i < j}^{n-1} (x_i - x_j)^2 = \sum_{j=2}^n \sum_{i=1; i < j}^{n-1} (x_i^2 + x_j^2 - 2x_i x_j) \\
 &= (n-1) \sum_{i=1}^n x_i^2 - 2 \sum_{j=2}^n \sum_{i=1; i < j}^{n-1} x_i x_j \\
 &= n \sum_{i=1}^n x_i^2 - \sum_{i=1}^n x_i^2 - \sum_{j=1}^n \sum_{i=1; i \neq j}^n x_i x_j = n \sum_{i=1}^n x_i^2 - \sum_{j=1}^n \sum_{i,j=1}^n x_i x_j \\
 &= n \sum_{i=1}^n x_i^2 - \sum_{i=1}^n x_i \sum_{j=1}^n x_j = n \sum_{i=1}^n x_i^2 - n^2 \hat{\mu}^2
 \end{aligned}$$

Therefore

$$\hat{\mathbb{J}} = \frac{1}{n(n-1)} \left(n \sum_{i=1}^n x_i^2 - n^2 \hat{\mu}^2 \right) = \frac{\sum_{i=1}^n x_i^2 - n \hat{\mu}^2}{n-1}$$

More on Covariance

Proposition 1

Let X_i and Y_j be random variables. Then

$$\mathbb{C}(X_i, Y_j) = 0, \text{ if } i \neq j.$$

Proof:

- 👉 Suppose Y and X are related by a mapping, i.e., $Y_j = f(X_j)$.
- 👉 The mapping involves the paired copies because each Y_j is independent of Y_i due to random sampling.
- 👉 Otherwise, if $Y_j = f(X_i, X_j)$, then Y_j may depend on Y_i indirectly since $Y_i = f(X_h, X_i)$.



An Estimator of Covariance

Definition 1: Sample Covariance

Given the paired data, $(x_i, y_i), i = 1, 2, \dots, n$, the sample covariance is defined as

$$\hat{\sigma}_{XY} := \frac{1}{n-1} \sum_{i=1}^n (x_i - \hat{\mu}_X)(y_i - \hat{\mu}_Y).$$

Show that

$$\text{1} \quad \sum_{i=1}^n (X_i - \hat{\mu}_X)(Y_i - \hat{\mu}_Y) = \sum_{i=1}^n X_i Y_i - n \bar{X}_n \bar{Y}_n.$$

2 Use these results to show that the sample covariance is unbiased.

A Problem about Mean Squared Errors

Problem

Prove that, if one predicts a random variable y by a constant a , the constant which gives the best mean squared errors MSE is $a = \mathbb{E}[y]$, and the best MSE one can get is $\mathbb{V}[y]$.

Answer

$\mathbb{E}[(y - a)^2] = \mathbb{E}[y^2] - 2a \mathbb{E}[y] + a^2$. Differentiate with respect to a and set zero to get $a = \mathbb{E}[y]$. □

Assumptions

□ A total of n sets of observations (x_t, y_t) are given. The observation noise or error term is denoted by $\boldsymbol{\varepsilon} = (\varepsilon_1 \ \varepsilon_2 \ \cdots \ \varepsilon_n)'$.

(A1) $\mathbb{E}[\varepsilon_t] = 0$ for every t

(A2) $\mathbb{E}[\varepsilon_t^2] = \sigma_{\varepsilon}^2$ for every t

(A3) $\mathbb{E}[\varepsilon_t \varepsilon_u] = 0$ for every $t \neq u$

(A4) x_t is non-stochastic “constants”.

□ A compact way of representing these assumptions is

★ $\mathbb{E}[\boldsymbol{\varepsilon}] = \mathbf{o} := (0 \ 0 \ \cdots \ 0)'$ (the null vector)

★ $\mathbb{V}[\boldsymbol{\varepsilon}] = \sigma_{\varepsilon}^2 \mathbf{I}$, where \mathbf{I} is the n by n identity matrix.

Model 0: Sample Average

Model 0 is the simplest estimation problem with n independent observations y_1, \dots, y_n from the same distribution, for which mean μ and variance σ_ε^2 exist.

Define $\varepsilon_i = y_i - \mu$, and the vectors $\mathbf{y} := (y_1 \ y_2 \ \cdots \ y_n)'$ and $\boldsymbol{\iota} = (1 \ 1 \ \cdots \ 1)'$,

Then Model 0 in the vector form is

$$\mathbf{y} = \boldsymbol{\iota}\mu + \boldsymbol{\varepsilon}, \quad \boldsymbol{\varepsilon} \sim (\mathbf{0}, \sigma_\varepsilon^2 \mathbf{I}) \quad (1)$$

μ is the deterministic part of y_i , and ε_i is the random part.

Model 1: Simple Regression

- Each element of \mathbf{y} is a constant α plus a constant multiple of the corresponding element of the nonrandom vector \mathbf{x} plus a random error term ε_t :

$$y_t = \alpha + x_t\beta + \varepsilon_t, \quad t = 1, \dots, n.$$

- In vector-matrix form, Model 1 is written as

$$\begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix} = \begin{pmatrix} 1 \\ \vdots \\ 1 \end{pmatrix} \alpha + \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \beta + \begin{pmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{pmatrix} = \begin{pmatrix} 1 & x_1 \\ \vdots & \vdots \\ 1 & x_n \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} + \begin{pmatrix} \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{pmatrix} \quad (2)$$

or

$$\boxed{\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon}, \quad \boldsymbol{\varepsilon} \sim (\mathbf{0}, \sigma^2 \mathbf{I})} \quad (3)$$

Model M : Multiple Linear Regression

- ☐ If y depends on multiple variables, then we have **multiple linear regression**, Model k .
- ☐ Mathematically, multiple linear regression has the same form (3), except X now it has more than two columns.
- ☐ The additional assumption is that all columns are linearly independent.
- ☐ Model M has Models 0 and 1 as special cases.
- ☐ Summary

| | observed | unobserved |
|-----------|----------|------------------------------|
| random | y | ϵ |
| nonrandom | X | $\beta, \sigma_{\epsilon}^2$ |

Interchangeability of Inverse and Transpose

Proposition

For a square matrix \mathbf{X} that has an inverse, the order of transpose and inverse operations is interchangeable.

$$(\mathbf{X}')^{-1} = (\mathbf{X}^{-1})'.$$

Proof: By the definition of inverse,

$$\mathbf{X}'(\mathbf{X}')^{-1} = \mathbf{I}.$$

Transpose both sides to yield

$$\left((\mathbf{X}')^{-1}\right)' \mathbf{X} = \mathbf{I}.$$

Multiply both sides by \mathbf{X}^{-1} from the right to yield

$$\left((\mathbf{X}')^{-1}\right)' = \mathbf{X}^{-1}.$$

Transpose both sides again to yield $(\mathbf{X}')^{-1} = (\mathbf{X}^{-1})'$ as required. □

Residual as Projection

Problem

Assume that X has full column rank. Show that $\hat{\varepsilon} = M\mathbf{y}$ where $M = I - X(X'X)^{-1}X'$. Show that M is symmetric and idempotent.

Answer

$$\hat{\varepsilon} = \mathbf{y} - X\hat{\beta} = \mathbf{y} - X(X'X)^{-1}X'\mathbf{y} = (I - X(X'X)^{-1}X')\mathbf{y}.$$

To prove idempotent, i.e. $MM = M$, we compute

$$\begin{aligned} MM &= (I - X(X'X)^{-1}X')(I - X(X'X)^{-1}X') \\ &= I - X(X'X)^{-1}X' - X(X'X)^{-1}X' \\ &\quad + X(X'X)^{-1}X'X(X'X)^{-1}X' \\ &= I - 2X(X'X)^{-1}X' + X(X'X)^{-1}X' \\ &= I - X(X'X)^{-1}X' = M. \end{aligned}$$

To show symmetric, $M' = I' - (X(X'X)^{-1}X')' = M$.



Matrix Calculus

Let \mathbf{x} be a column k -vector. Consider the function

$$g(\mathbf{x}) = g(x_1, x_2, \dots, x_k) : \Re^k \rightarrow \Re.$$

The vector derivative is

$$\frac{\partial}{\partial \mathbf{x}} g(\mathbf{x}) = \begin{pmatrix} \frac{\partial}{\partial x_1} g(\mathbf{x}) \\ \frac{\partial}{\partial x_2} g(\mathbf{x}) \\ \vdots \\ \frac{\partial}{\partial x_k} g(\mathbf{x}) \end{pmatrix}.$$

and

$$\frac{\partial}{\partial \mathbf{x}'} g(\mathbf{x}) = \left(\frac{\partial}{\partial x_1} g(\mathbf{x}) \quad \frac{\partial}{\partial x_2} g(\mathbf{x}) \quad \cdots \quad \frac{\partial}{\partial x_k} g(\mathbf{x}) \right)$$

Matrix Calculus: Basic Properties

For constant vector a and matrix A ,

$$\frac{\partial}{\partial x}(a'x) = \frac{\partial}{\partial x}(x'a) = a, \quad \text{or} \quad \frac{\partial}{\partial x'}(a'x) = a'$$

$$\frac{\partial}{\partial x'}(Ax) = A$$

$$\frac{\partial}{\partial x}(x'Ax) = (A + A')x, \quad \text{or} \quad \frac{\partial}{\partial x'}(x'Ax) = x'(A + A')$$

$$\frac{\partial^2}{\partial x \partial x'}(x'Ax) = A + A'$$

Sum of Squared Errors (SSE) and OLS

- ‡ In the model $\mathbf{y} = \mathbf{X}\beta + \boldsymbol{\epsilon}$, where $\boldsymbol{\epsilon} \sim (0, \sigma_{\boldsymbol{\epsilon}}^2 \mathbf{I})$, the OLS-estimate $\hat{\beta}$ is defined to be that value $\beta = \hat{\beta}$ that minimizes

$$\text{SSE} = (\mathbf{y} - \mathbf{X}\beta)'(\mathbf{y} - \mathbf{X}\beta) = \mathbf{y}'\mathbf{y} - 2\mathbf{y}'\mathbf{X}\beta + \beta'\mathbf{X}'\mathbf{X}\beta. \quad (4)$$

- ‡ Note that $\mathbf{X}'\mathbf{X}$ is a square symmetric matrix. Hence, the first-order condition is

$$\frac{\partial \text{SSE}}{\partial \beta'} = -2\mathbf{y}'\mathbf{X} - 2\hat{\beta}'\mathbf{X}'\mathbf{X} = \mathbf{0}.$$

- ‡ Applying the transpose operation, we obtain $\mathbf{X}'\mathbf{X}\hat{\beta} = \mathbf{X}'\mathbf{y}$
- ‡ Due to our assumption that all columns of \mathbf{X} are linearly independent, $\mathbf{X}'\mathbf{X}$ has an inverse and one can premultiply both sides by $(\mathbf{X}'\mathbf{X})^{-1}$ to obtain

$$\hat{\beta} = (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y}.$$

Reduction to Model 0: Sample Average

Sample average is “regression” with an intercept only, i.e.,

$$y_t = \alpha + \varepsilon_t.$$

(5)

To see how Model 0 comes from Model k , suppose $\mathbf{X} = \boldsymbol{\iota}$.

Therefore $\mathbf{X}'\mathbf{X} = \boldsymbol{\iota}'\boldsymbol{\iota} = n$, and $(\mathbf{X}'\mathbf{X})^{-1} = \frac{1}{n}$.

Consequently,

$$\hat{\alpha} = \frac{1}{n} \boldsymbol{\iota}' \mathbf{y} = \frac{1}{n} \sum_{t=1}^n y_t =: \bar{y}.$$

Reduction to Model 1: Simple Regression

- Simple regression is regression with an intercept and one explanatory variable only, i.e.,

$$y_t = \alpha + \beta x_t + \varepsilon_t.$$

(6)

- Here $\mathbf{X} = \begin{pmatrix} 1 & x \end{pmatrix}$ and $\boldsymbol{\beta} = (\alpha \quad \beta)'$.

$$\mathbf{X}'\mathbf{X} = \begin{pmatrix} 1' \\ x' \end{pmatrix} \begin{pmatrix} 1 & x \end{pmatrix} = \begin{pmatrix} 1'1 & 1'x \\ x'1 & x'x \end{pmatrix} = \begin{pmatrix} n & \sum x_t \\ \sum x_t & \sum x_t^2 \end{pmatrix}$$

$$(\mathbf{X}'\mathbf{X})^{-1} = \frac{1}{n \sum x_t^2 - (\sum x_t)^2} \begin{pmatrix} \sum x_t^2 & -\sum x_t \\ -\sum x_t & n \end{pmatrix}$$

$$\mathbf{X}'\mathbf{y} = \begin{pmatrix} 1'\mathbf{y} \\ x'\mathbf{y} \end{pmatrix} = \begin{pmatrix} \sum y_t \\ \sum x_t y_t \end{pmatrix}$$

OLS Estimates for Simple Regression

Therefore $(X'X)^{-1}X'y$ gives $\hat{\beta} = [\hat{\alpha} \ \hat{\beta}]'$:

$$\hat{\alpha} = \frac{\sum x_t^2 \sum y_t - \sum x_t \sum x_t y_t}{n \sum x_t^2 - (\sum x_t)^2} \quad (7)$$

$$\hat{\beta} = \frac{n \sum x_t y_t - \sum x_t \sum y_t}{n \sum x_t^2 - (\sum x_t)^2} \quad (8)$$

Formula for the Slope Estimate

‡ Since $\sum x_i = n\bar{x}$ and $\sum y_i = n\bar{y}$, we have

$$\hat{\beta} = \frac{n \sum x_t y_t - n^2 \bar{x} \bar{y}}{n \sum x_t^2 - n^2 \bar{x}^2} = \frac{\sum x_t y_t - n \bar{x} \bar{y}}{\sum x_t^2 - n \bar{x}^2}. \quad (9)$$

‡ Now, note that

$$\sum_{t=1}^n (x_t - \bar{x})(y_t - \bar{y}) = \sum_{t=1}^n x_t y_t - n \bar{x} \bar{y}. \quad (10)$$

‡ Hence

$$\hat{\beta} = \frac{\sum_{t=1}^n (x_t - \bar{x})(y_t - \bar{y})}{\sum_{t=1}^n (x_t - \bar{x})^2}. \quad (11)$$

Formula for the Intercept Estimate

For simple regression $y_t = \alpha + \beta x_t + \epsilon_t$, or $\epsilon_t = y_t - \alpha - \beta x_t$, the sum of squared errors can also be written as

$$\text{SSE} = \boldsymbol{\epsilon}^\top \boldsymbol{\epsilon} = \sum_{t=1}^n \epsilon_t^2 = \sum_{t=1}^n (y_t - \alpha - \beta x_t)^2.$$

The first-order condition for the intercept α is

$$\frac{\partial \text{SSE}}{\partial \alpha} = -2 \sum_{t=1}^n (y_t - \alpha - \beta x_t) = 0.$$

The solution is

$$\sum_{t=1}^n \hat{\alpha} = \sum_{t=1}^n y_t - \hat{\beta} \sum_{t=1}^n x_t = n\bar{y} - n\hat{\beta}\bar{x},$$

which is

$$\hat{\alpha} = \bar{y} - \hat{\beta}\bar{x}.$$

(12)

True Parameter Values of Simple Regression

- ▮ If y is predicted by an affine expression of the form $a + bx$, then the lowest mean squared error MSE is obtained. Moreover,

$$b = \frac{\mathbb{C}[x, y]}{\mathbb{V}[x]}, \quad a = \mathbb{E}[y] - b \mathbb{E}[x].$$

- ▮ The MSE is variance plus squared bias, therefore

$$\begin{aligned} \text{MSE}[a + bx - y] &= \mathbb{V}[a + bx - y] + (\mathbb{E}[a + bx - y])^2 \\ &= \mathbb{V}[bx - y] + (a - \mathbb{E}[y] + b \mathbb{E}[x])^2. \end{aligned} \quad (13)$$

- ▮ Choose a so that the second term is zero, and then minimize the first term with respect to b . Since

$$\mathbb{V}[bx - y] = b^2 \mathbb{V}[x] - 2b \mathbb{C}[x, y] + \mathbb{V}[y], \quad (14)$$

the first order condition of equation (14) results in b .

Mean Squared Errors

Plugging the optimal a into (13), annuls the last term of (13) so that the MSE is given by (14).

If one inserts the optimal $b = \frac{\mathbb{C}[x, y]}{\mathbb{V}[x]}$ into (14), then

$$\text{MSE} = \left(\frac{\mathbb{C}[x, y]}{\mathbb{V}[x]} \right)^2 \mathbb{V}[x] - 2 \frac{\mathbb{C}[x, y]}{\mathbb{V}[x]} \mathbb{C}[x, y] + \mathbb{V}[y] \quad (15)$$

$$= \mathbb{V}[y] - \frac{(\mathbb{C}[x, y])^2}{\mathbb{V}[x]}. \quad (16)$$

Since $y = a + bx + e$ where e is the error term, we have

$$\mathbb{C}[x, y - a - bx] = \mathbb{C}[x, y] - b \mathbb{C}[x, x] = 0.$$

Therefore, the prediction error is uncorrelated with the observed x .

In-Class Exercise

Question in Class

The affine form is $y = a + bx + e$. Show that the mean square error, equation (16), is the variance of the error e , i.e.,

$$\sigma_e^2 := \mathbb{V}[e] = \text{MSE}.$$

Insight!

- ▮ The first-order conditions can be written as

$$X' (y - X\hat{\beta}) = 0,$$

which is

$$X'\hat{u} = 0. \quad (17)$$

The OLS residuals are orthogonal to X' .

- ▮ Consequently, if X has a column vector of ones, then the average of the residuals is zero. This is because there is one row of ones in X' and hence

$$\mathbf{1}'\hat{u} = \sum_{i=1}^n \hat{u}_i = 0.$$

OLS Algorithm for Model M

- 1 Estimate the model by OLS: $\hat{\beta} = (X'X)^{-1}X'y$
- 2 Compute the fitted values of y : $\hat{y}\hat{y} = X\hat{\beta}$
- 3 Compute the residuals or “surprise”: $\hat{u} = y - \hat{y}$
- 4 Compute the residual sum of squares (RSS)

$$\text{SSE} \equiv \text{RSS} = \hat{u}'\hat{u} = \sum_{i=1}^n \hat{u}_i^2$$

- 5 The variance of the residuals is

$$\hat{\sigma}_u^2 = \frac{1}{n - K} \hat{u}'\hat{u}$$

- 6 Let $\Omega := (X'X)^{-1}$. The variance of $\hat{\beta}_i$ is

$$\mathbb{V}(\hat{\beta}_i) = \hat{\sigma}_u^2 \Omega_{ii}.$$

Summary of OLS Regression

- ‡ The estimates are unbiased, i.e., $\mathbb{E}(\hat{\beta}) = \beta$.
- ‡ The variance of the residuals is unbiased $\mathbb{E}(\hat{\sigma}_u^2) = \sigma_u^2$.
- ‡ Efficiency: According to the Gauss-Markov theorem, among the classical linear regression models, the OLS estimator is the linear unbiased estimator of β with the minimum variance.
- ‡ Conditional normality

$$\hat{\beta} | \mathbf{X} \sim \mathcal{N}(\beta, \sigma_u^2 (\mathbf{X}'\mathbf{X})^{-1}) \quad (18)$$

Statistical Inference

- ‡ For all $j = 1, 2, \dots, K$, the t test statistic for $\hat{\beta}_j$ is, given the null-hypothesized value β_j :

$$\frac{\hat{\beta}_j - \beta_j}{\hat{\sigma}_u \sqrt{\Omega_{jj}}} \sim t_{n-K} \quad (19)$$

- ‡ The $\alpha\%$ significance level for β_j is, assuming two-tail test,

$$\hat{\beta}_j - q\hat{\sigma}_u \sqrt{\Omega_{jj}} \leq \beta_j \leq \hat{\beta}_j + q\hat{\sigma}_u \sqrt{\Omega_{jj}},$$

where q is the $(1 - \alpha/2)$ -th quantile of the t_{n-K} distribution.

Confidence Interval for Mean Response

‡ A given observation \mathbf{x} , which is a $K \times 1$ vector, i.e.,
 $\mathbf{x} := [1 \quad x_2 \quad x_3 \quad \cdots \quad x_K]'$

‡ The **in-sample** mean response is $\hat{\beta}'\mathbf{x}$.

‡ Given the unbiased estimate $\hat{\beta}$, the variance of $\hat{\beta}'\mathbf{x}$ is

$$\mathbb{V}(\hat{\beta}'\mathbf{x}) = \mathbb{V}(\mathbf{x}'\hat{\beta}) = \mathbf{x}'\mathbb{V}(\hat{\beta})\mathbf{x} = \sigma_u^2 \mathbf{x}'(\mathbf{X}'\mathbf{X})^{-1}\mathbf{x}. \quad (20)$$

‡ Hence, a $100 \times (1 - \alpha)\%$ confidence interval for the in-sample mean response $\hat{\beta}'\mathbf{x}$ is, with $q := t_{N-K, 1-\alpha/2}$,

$$\hat{\beta}'\mathbf{x} \pm q\sigma_u \sqrt{\mathbf{x}'(\mathbf{X}'\mathbf{X})^{-1}\mathbf{x}} \quad (21)$$

Prediction Interval for a New Observation

- ▮ Suppose a future observation of \mathbf{x} is obtained. Then, by assumption of $u \sim \mathcal{N}(0, \sigma_u^2)$, we have

$$\mathbb{V}(y - \hat{\beta}'\mathbf{x}) = \mathbb{V}(u) + \mathbb{V}(\hat{\beta}'\mathbf{x}) \quad (22)$$

- ▮ Hence, a $100 \times (1 - \alpha)\%$ prediction interval for y is

$$\hat{\beta}'\mathbf{x} \pm q\sigma_u \sqrt{1 + \mathbf{x}'(\mathbf{X}'\mathbf{X})^{-1}\mathbf{x}}. \quad (23)$$

Akaike Information Criterion (1973)

For i.i.d. normally distributed errors,

$$\text{AIC} = T \ln \left(\frac{\text{RSS}}{T} \right) + 2K.$$

For small sample sizes ($T/K \leq 40$), use the second-order AIC:

$$\text{AIC}_c = \text{AIC} + \frac{2K(K+1)}{T-K-1}$$

The smaller AIC is, the better is the model in not over-fitting the data.

Multiple Linear Regression and the Constant Term

✿ Model M : $\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \mathbf{u}$

For $t = 1, 2, \dots, T$,

$$y_t = \beta_1 + \beta_2 X_{2,t} + \beta_3 X_{3,t} + \dots + \beta_K X_{K,t} + u_t,$$

There are K parameters, $\beta_1, \beta_2, \dots, \beta_K$.

✿ The first parameter is the y -intercept in Model 1. $X_{1,t} = 1$ being a constant for all t .

$$\mathbf{X}_1 = \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix}$$

Model 1: Simple Linear Regression

✿ If $K = 2$, we are back to Model 1

$$\begin{array}{c}
 \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_T \end{bmatrix} \\
 T \times 1
 \end{array}
 =
 \begin{array}{c}
 \begin{bmatrix} 1 & x_{2,1} \\ 1 & x_{2,2} \\ \vdots & \vdots \\ 1 & x_{2,T} \end{bmatrix} \\
 T \times 2
 \end{array}
 \begin{array}{c}
 \begin{bmatrix} \beta_1 \\ \beta_2 \end{bmatrix} \\
 2 \times 1
 \end{array}
 +
 \begin{array}{c}
 \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_T \end{bmatrix} \\
 T \times 1
 \end{array}$$

✿ Notice that the matrices written in this way are **conformable**.

Numerical Illustration: Data

✿ When $K = 3$,

$$y_t = \beta_1 + \beta_2 x_{2,t} + \beta_3 x_{3,t} + u_t$$

for $t = 1, 2, \dots, 15$.

$$(\mathbf{X}'\mathbf{X})^{-1} = \begin{bmatrix} 2.0 & 3.5 & -1.0 \\ 3.5 & 1.0 & 6.5 \\ -1.0 & 6.5 & 4.3 \end{bmatrix}, \quad \mathbf{X}'\mathbf{y} = \begin{bmatrix} -3.0 \\ 2.2 \\ 0.6 \end{bmatrix}$$

✿ The residual sum of squares (RSS) is $\hat{\mathbf{u}}'\hat{\mathbf{u}} = 10.96$

Calculations in Simple Regression

- ✿ To calculate the coefficients, just multiply the matrix $(X'X)^{-1}$ by the vector $X'y$ to obtain $(X'X)^{-1}X'y$

$$\begin{bmatrix} 2.0 & 3.5 & -1.0 \\ 3.5 & 1.0 & 6.5 \\ -1.0 & 6.5 & 4.3 \end{bmatrix} \begin{bmatrix} -3.0 \\ 2.2 \\ 0.6 \end{bmatrix} = \begin{bmatrix} 1.10 \\ 4.40 \\ 19.88 \end{bmatrix}$$

- ✿ To calculate the standard errors, we need an estimate of σ_u^2 .

$$s^2 = \frac{\text{RSS}}{T - K} = \frac{10.96}{15 - 3} = 0.91$$

- ✿ The variance-covariance matrix of $\hat{\beta}$ is given by

$$s^2(X'X)^{-1} = 0.91(X'X)^{-1} = \begin{bmatrix} 1.82 & 3.19 & -0.91 \\ 3.19 & 0.91 & 5.92 \\ -0.91 & 5.92 & 3.91 \end{bmatrix}$$

Standard Errors and Estimated Model

✿ The variances are on the leading diagonal:

$$\text{var}(\hat{\beta}_1) = 1.82 \qquad \text{SE}(\hat{\beta}_1) = 1.35$$

$$\text{var}(\hat{\beta}_2) = 0.91 \quad \Longleftrightarrow \quad \text{SE}(\hat{\beta}_2) = 0.95$$

$$\text{var}(\hat{\beta}_3) = 3.91 \qquad \text{SE}(\hat{\beta}_3) = 1.98$$

✿ We write

$$\hat{y} = 1.10 - 4.40x_2 + 19.88x_3$$

(1.35) (0.96) (1.98)

Ordinary Least Squares (OLS)'s Goodness of Fit

III Explained sum of squares (ESS) is

$$\text{ESS} := \sum_{i=1}^n (\hat{y}_i - \bar{y})^2$$

III Total sum of squares (TSS) is, with $\mathbf{y}_* := \mathbf{y} - \bar{y}\mathbf{1}$,

$$\text{TSS} := \mathbf{y}_*'\mathbf{y}_* = \sum_{i=1}^n (y_i - \bar{y})^2 = \sum_{i=1}^n (\hat{y}_i - \bar{y})^2 + \sum_{i=1}^n \hat{u}_i^2 \quad (24)$$

$$= \text{ESS} + \text{RSS}. \quad (25)$$

III The cross term $\sum_{i=1}^n (\hat{y}_i - \bar{y})(y_i - \hat{y}_i)$ is zero because of the orthogonality: $\mathbf{X}'\hat{\mathbf{u}} = \mathbf{0}$.

Proof

$$\begin{aligned}
 \sum_{i=1}^n (\hat{y}_i - \bar{y})(y_i - \hat{y}_i) &= \sum_{i=1}^n (\hat{y}_i - \bar{y})\hat{u}_i \\
 &= \sum_{i=1}^n \hat{y}_i \hat{u}_i \quad \left(\text{since } \bar{y} \sum_{i=1}^n \hat{u}_i = 0 \right) \\
 &= \sum_{i=1}^n \left(\mathbf{X}\hat{\beta} \right)_i \hat{u}_i \\
 &= \left(\mathbf{X}\hat{\beta} \right)' \hat{\mathbf{u}} = \hat{\beta}' \mathbf{X}' \hat{\mathbf{u}} = 0.
 \end{aligned}$$

Coefficient of Determination R^2

III In summary,

$$\text{TSS} = \text{ESS} + \text{RSS}$$

$$\sum_t (y_t - \bar{y})^2 = \sum_t (\hat{y}_t - \bar{y})^2 + \sum_t \hat{u}_t^2$$

III Our goodness of fit statistic is $R^2 = \frac{\text{ESS}}{\text{TSS}}$

III But since $\text{TSS} = \text{ESS} + \text{RSS}$, we can also write

$$R^2 = \frac{\text{TSS} - \text{RSS}}{\text{TSS}} = 1 - \frac{\text{RSS}}{\text{TSS}}$$

III R^2 must always lie between zero and one. To understand this, consider two extremes

$$\text{RSS} = \text{TSS} \quad \text{i.e.} \quad \text{ESS} = 0 \quad \text{so} \quad R^2 = \frac{\text{ESS}}{\text{TSS}} = 0$$

$$\text{ESS} = \text{TSS} \quad \text{i.e.} \quad \text{RSS} = 0 \quad \text{so} \quad R^2 = \frac{\text{ESS}}{\text{TSS}} = 1$$

Problems with R^2 as a Goodness of Fit Measure

- R^2 is defined in terms of variation about the mean of y so that if a model is reparameterised (rearranged) and the dependent variable changes, R^2 will change.
- R^2 never falls if more regressors are added. to the regression, e.g. consider:

$$\text{Regression1 : } y_t = \beta_1 + \beta_2 x_{2,t} + \beta_3 x_{3,t} + u_t$$

$$\text{Regression2 : } y_t = \beta_1 + \beta_2 x_{2,t} + \beta_3 x_{3,t} + \beta_4 x_{4,t} + u_t$$

- R^2 will always be at least as high for regression 2 relative to regression 1.

Solution: Adjusted R^2

- ⏏ To get around these problems, a modification is made to take into account the **loss of degrees of freedom** associated with adding extra variables. This modification is known as \bar{R}^2 , or adjusted R^2 :

$$\bar{R}^2 = 1 - \left[\frac{T-1}{T-K} (1 - R^2) \right].$$

- ⏏ So if we add an extra regressor, K increases and unless R^2 increases by a more than offsetting amount, \bar{R}^2 will actually fall.
- ⏏ But there are still problems with the criterion: No distribution for \bar{R}^2 or R^2

R^2 and Adjusted R^2

III The coefficient of determination

$$R^2 := \frac{\text{ESS}}{\text{TSS}} = 1 - \frac{\text{RSS}}{\text{TSS}} \quad (26)$$

III Denoted by \bar{R}^2 , the adjusted R^2 is based on the unbiased variances:

$$\bar{R}^2 = 1 - \frac{\frac{\text{RSS}}{n - K}}{\frac{\text{TSS}}{n - 1}} \quad (27)$$

Takeaways

👉 Vector-matrix approach is “simpler”.

👉 Important concepts

- ★ Variance-covariance matrix of K -vector $\hat{\beta}$
- ★ Diagonal elements of the variance-covariance matrix \implies variance of $\hat{\beta}_i$
- ★ Inference by standard error, t statistic, and p value
- ★ Confidence interval
- ★ Adjusted R^2 , AIC

👉 R^2 increases with K , which is the total number of parameter estimates

👉 Important to select the model with minimum AIC value for a given data set.