

Parallel Algorithm Design: UPC++

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Overview

- Introduction to UPC++
 - Partitioned Global Address Space
- Reduction
 - Distributed objects
- Symmetrisation
 - Avoiding communication
- Stencil

Introduction to UPC++

- C++11 library that supports *Partitioned Global Address Space* (PGAS) programming
 - Similar to OpenMPI in usage (but no in-order delivery of messages)

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- C++11 library that supports *Partitioned Global Address Space* (PGAS) programming
 - Similar to OpenMPI in usage (but no in-order delivery of messages)
- ² UPC++ differs from message passing in MPI in that it doesn't guarantee in-order delivery.¹ For example, if we overlap two successive RMA operations involving the same source and destination process, there are no guarantees regarding which will complete first. The same lack of implicit point-to-point ordering holds for all asynchronous operations (including RMA, RPC, remote atomics, etc). The only way to guarantee ordering is to apply explicit synchronization, e.g. issue a wait on a prior operation before initiating any dependent operation.

https://bitbucket.org/berkeleylab/upcxx/downloads/upcxx-spec-2020.10.0.pdf (1.3 Memory model)

Introduction to UPC++

- C++11 library that supports *Partitioned Global Address Space* (PGAS) programming
 - Usage similar to OpenMPI (but no in-order delivery of messages)
- Single program, multiple data (SPMD) model via processes
 - Global address space
 - No implicit communication
 - Fixed number of processes
- Multiple conduits: SMP (sockets), UDP (ethernet), Infiniband, Cray
 - Here limited to SMP and UDP

Partitioned Global Address Space

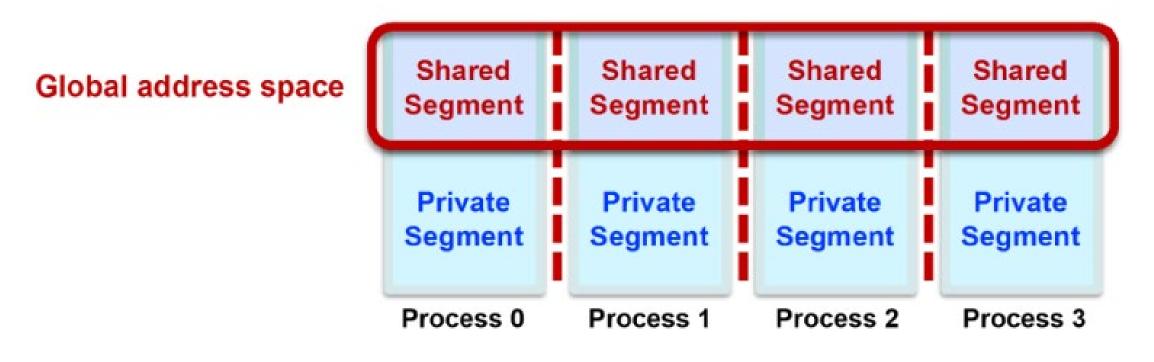


Figure 1.1: Abstract Machine Model of a PGAS program memory

Partitioned Global Address Space

- Shared segment accessible through upcxx::global_ptr<T>
 - Logically consists of raw pointer and an *affinity* (binding of a location in a *shared segment* to a process)
 - Requires synchronization (subject to race conditions)
- As with conventional C++ threads programming, processes can access their respective local memory via a pointer. However, the PGAS abstraction supports a global address space, which is allocated in *shared segments* distributed over the processes. A *global pointer* enables the UPC++ programmer to reference objects in the shared segments between processes as shown in Fig. 1.2. As with threads programming, accesses to shared objects made via global pointers may be subject to race conditions, and appropriate synchronization must be employed.

https://bitbucket.org/berkeleylab/upcxx/downloads/upcxx-spec-2020.10.0.pdf (1.1 Preliminaries)

Partitioned Global Address Space

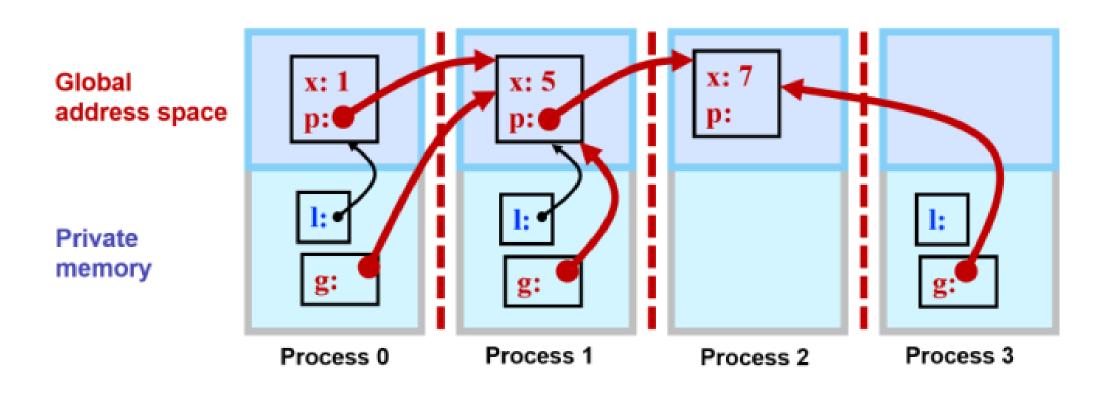


Figure 1.2: Global pointers and shared memory objects in a PGAS model

Overview of important terminology (1)

- Affinity. A binding of each location in a shared or device segment to a particular process (generally the process which allocated that shared object). Every byte of shared memory has affinity to exactly one process (at least logically).
- Shared segment. A region of storage associated with a particular process that is used to allocate shared objects that are accessible by any process.
 - Global pointer. (3) The primary way to address memory in a shared memory segment of a UPC++ program. Global pointers can themselves be stored in shared memory or otherwise passed between processes and retain their semantic meaning to any process.
- ¹⁰ **Local.** (11.2) Refers to an object or reference with affinity to a process in the local team.
- Process. (1) An OS process with associated system resources that is a member of a UPC++ parallel job execution. UPC++ uses a SPMD execution model, and the number of processes is fixed during a given program execution. The placement of processes across physical processors or NUMA domains is implementation-defined.
- 18 **Remote.** Refers to an object or reference whose affinity is not local to the current process.

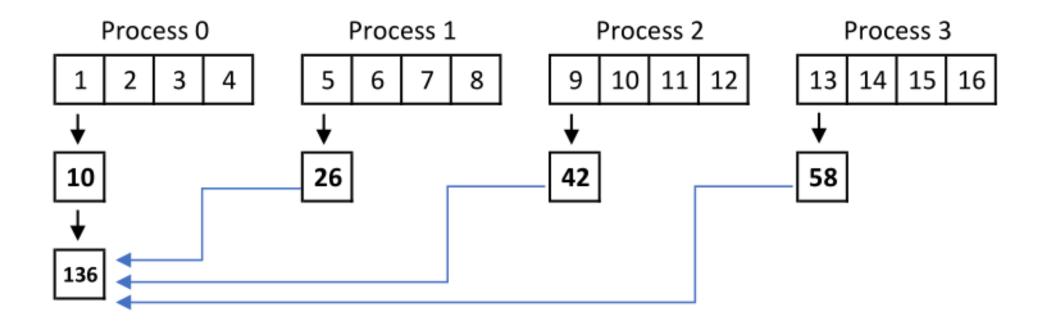
Overview of important terminology (2)

Futures (and Promises). (5) The primary mechanisms by which a UPC++ application interacts with non-blocking operations. The semantics of futures and promises in UPC++ differ from the those of standard C++. While futures in C++ facilitate communicating between threads, the intent of UPC++ futures is solely to provide an interface for managing and composing non-blocking operations, and they cannot be used directly to communicate between threads or processes. A future is the interface through which the status of the operation can be queried and the results retrieved, and multiple future objects may be associated with the same promise. A future thus represents the consumer side of a non-blocking operation. A promise represents the producer side of the operation, and it is through the promise that the results of the operation are supplied and its dependencies fulfilled.

Overview of important terminology (3)

- ³ Collective. A constraint placed on some language operations which requires evaluation of such operations to be matched across all participating processes. The behavior of collective operations is undefined unless all processes execute the same sequence of collective operations.
- A collective operation need not provide any actual synchronization between processes, unless otherwise noted. The collective requirement simply states a relative ordering property of calls to collective operations that must be maintained in the parallel execution trace for all executions of any valid program. Some implementations may include unspecified synchronization between processes within collective operations, but programs must not rely upon the presence or absence of such unspecified synchronization for correctness.

• Basic hierarchical reduction



- Basic hierarchical reduction
- Reduce partial sums with **upcxx::dist_object<T>**
 - Order is determined by the user (e.g. equivalent to serial order)

Processes in UPC++ are not automatically aware of new allocations in another process's shared segment, so we must ensure that the processes obtain the global pointers that they require. There are several different ways of doing this; we will show how to do it using a convenient construct provided by UPC++, called a distributed object.

A distributed object is a single logical object partitioned over a set of processes (a team), where every process has the same global name for the object (i.e. a universal name), but its own local value. Distributed objects are created with the upcxx::dist_object<T> type.

https://bitbucket.org/berkeleylab/upcxx/downloads/upcxx-guide-2020.10.0.pdf (Section 5)

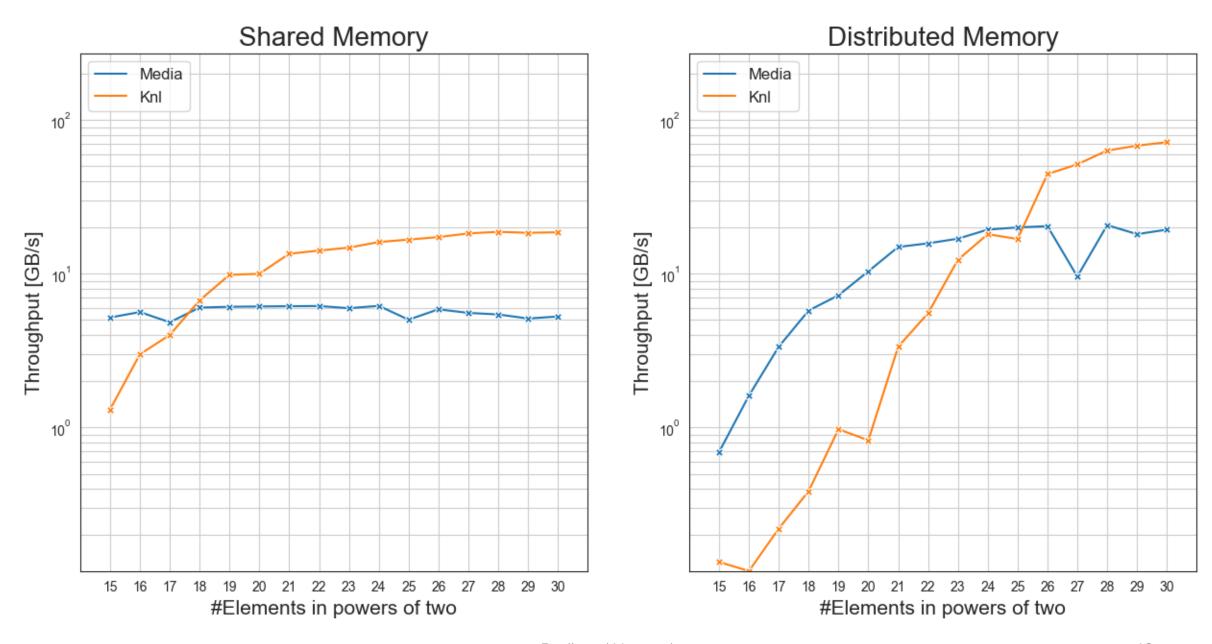
```
// Compute partial sums
double psum(0);
for (int64_t i = 0; i < block_size; ++i) {</pre>
   psum += u[i];
// Assign partial sum to distributed object (universal name, local value)
upcxx::dist object<double> psum d(psum);
// Reduce partial sums with dist object::fetch (communication) on first process.
if (proc id == 0) {
    double res(*psum_d);
    // Partial sums for remaining processes (in ascending order).
    // Can be done asynchronously, e.g. with .then() and upcxx::when all().
    for (int k = 1; k < upcxx::rank_n(); ++k) {</pre>
        double psum = psum d.fetch(k).wait();
        res += psum;
```

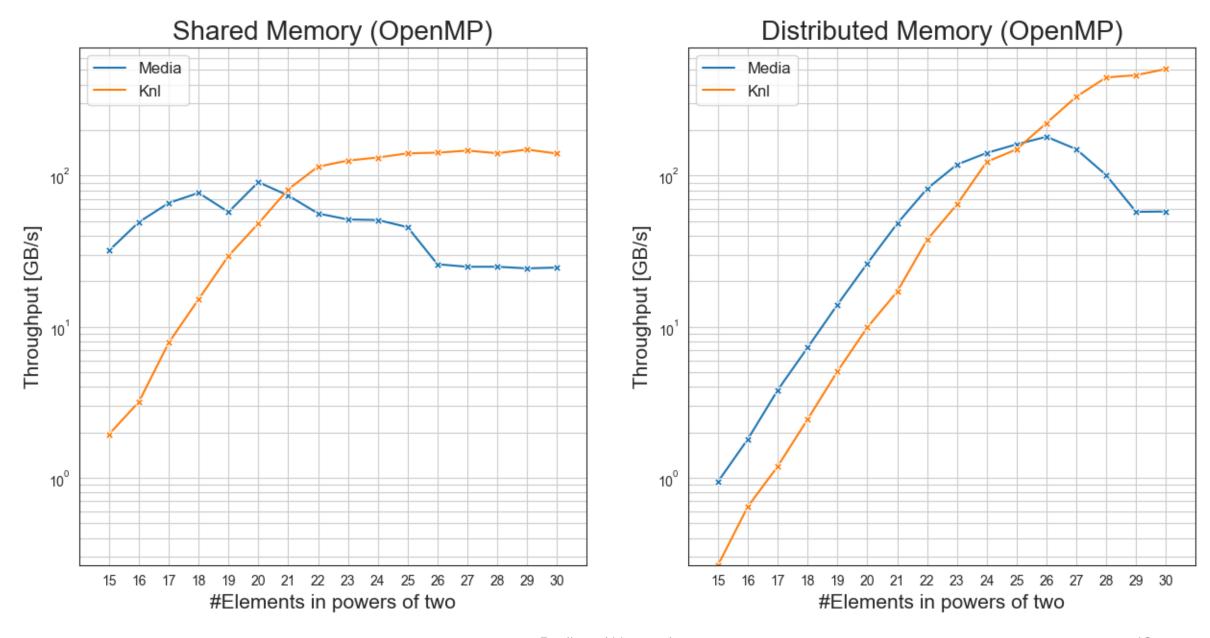
- Basic hierarchical reduction
- Reduce partial sums with **upcxx::dist_object<T>**
 - Order is determined by the user (e.g. equivalent to serial order)
- Reduce partial sums with upcxx::reduce_one
 - Non-deterministic order
 - Simple usage

```
// Create a reduction value for each process
double psum(0);

// Compute partial sums
for (int64_t i = 0; i < block_size; ++i) {
    psum += u[i];
}
double sum = upcxx::reduce_one(psum, upcxx::op_fast_add, 0).wait();</pre>
```

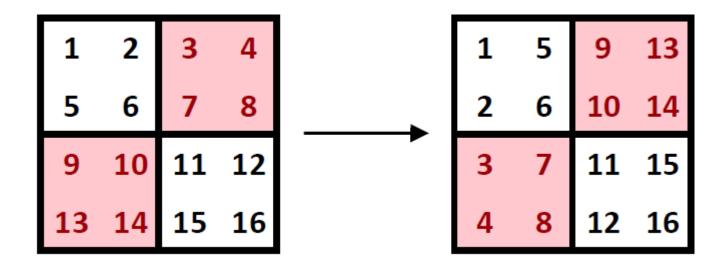
- Throughput
 - size * sizeof(float) * 1e-9 / time
- Benchmarks
 - upcxx::reduce_one
 - 4 processes per SKL node, 64 processes per KNL node
 - Averaged over 100 iterations
- OpenMP
 - 1 process per node, 4 (SKL) or 64 (KNL) OpenMP threads
 - OMP PROC BIND=true, OMP PLACES=cores (NUMA-aware)
 - Higher throughput from lower amount of communication





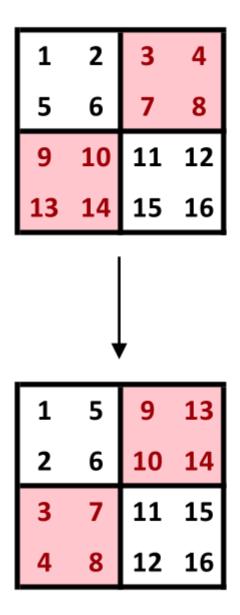
- Data structures for dense matrix
 - Row-major (or col-major)
 - Block matrix for partitioning

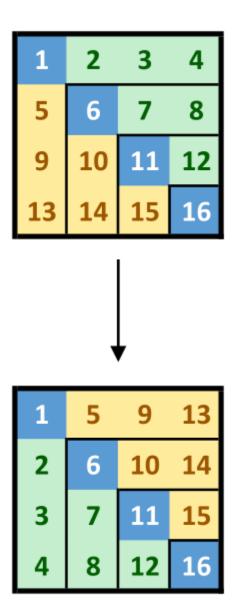
- Data structures for dense matrix
 - Row-major (or col-major)
 - Block matrix for partitioning
 - Communication between blocks for transposition

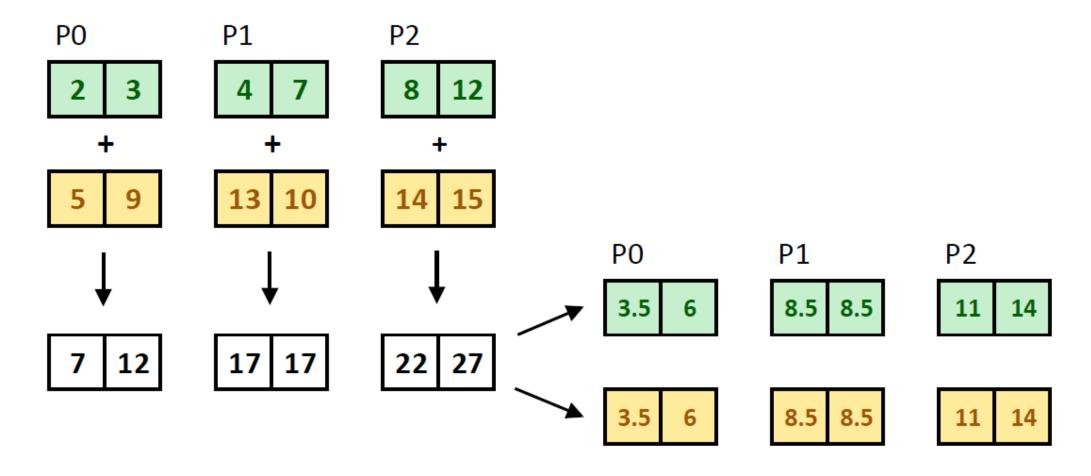


- Data structures for dense matrix
 - Store diagonal, lower and upper matrix separately
 - Store elements symmetrically
 - Lower triangle in *col-major* order
 - Upper triangle in *row-major* order
- Symmetrisation as SAXPY operation

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- Symmetrisation as SAXPY operation
 - Arrays chunked per process:
 - *Diagonal*: dim / nproc
 - Lower triangle: (dim) * (dim-1) / 2 / nproc
 - *Upper triangle*: (dim) * (dim-1) / 2 / nproc

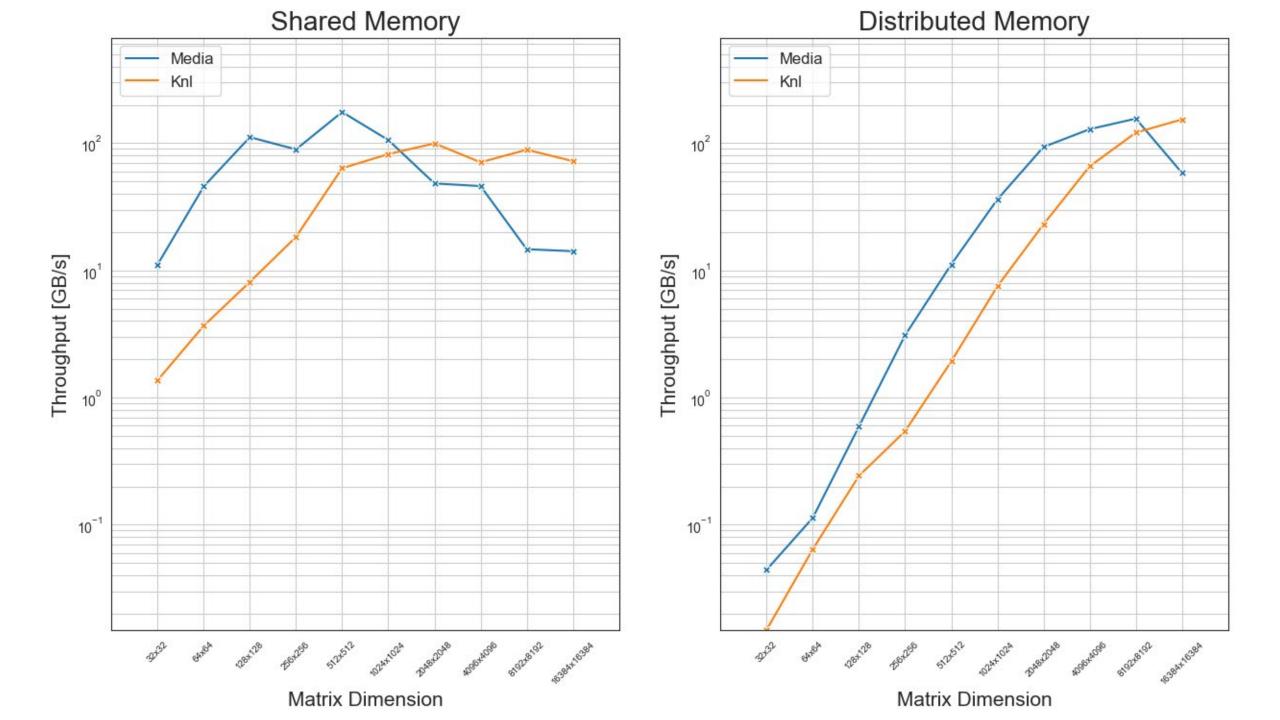


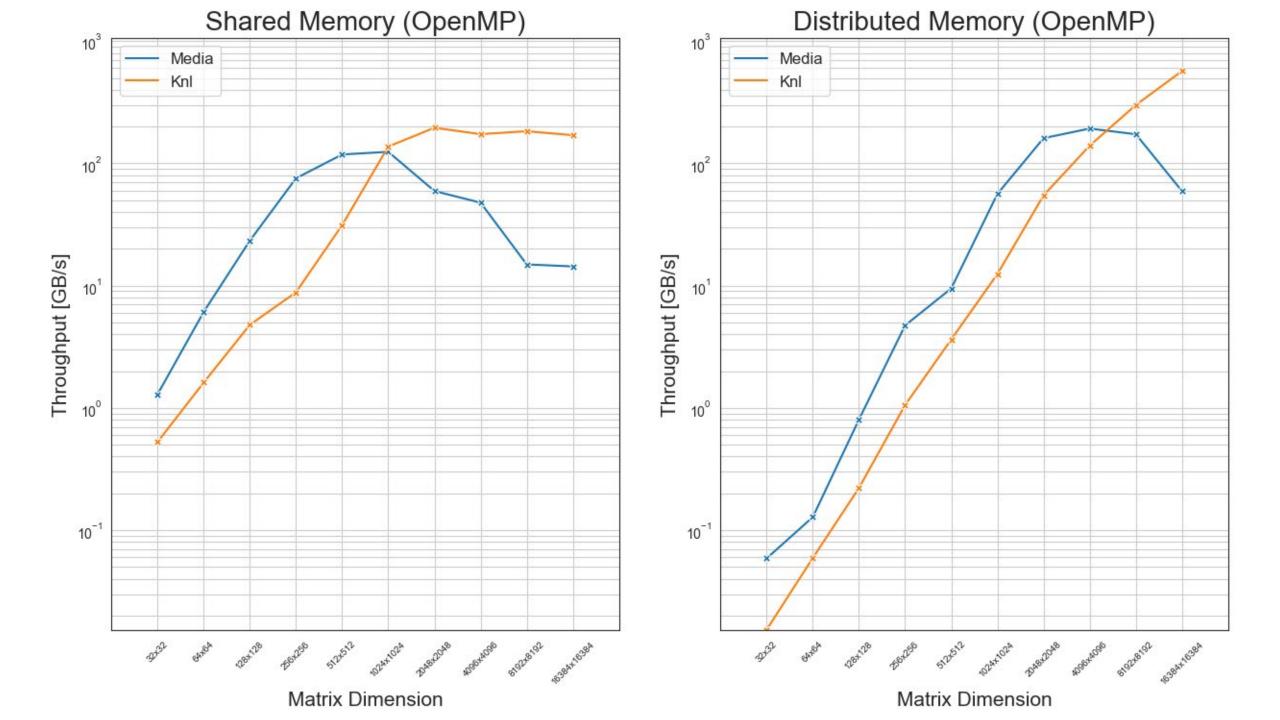




```
// Symmetrize matrix (SAXPY over lower and upper triangle). We only require
// a single for loop because lower and upper triangle are stored symmetrically
// (in col-major and row-major, respectively)
for (index_t i = 0; i < triangle_n; ++i) {
    float s = (lower[i] + upper[i]) / 2.;
    lower[i] = s;
    upper[i] = s;
}
upcxx::barrier(); // ensure symmetrisation is complete</pre>
```

- Throughput
 - dim * (dim-1) * sizeof(float) * 1e-9 / time
- Benchmarks
 - Process amount chosen as size allowed
 - e.g. for the KNL cluster, 256 processes for sizes $(1 \le 10)$ up to $(1 \le 14)$.
 - No communication
- OpenMP
 - 1 process per node with up to 64 (KNL) OpenMP threads per node
 - Still measurable improvement from lower amount of processes



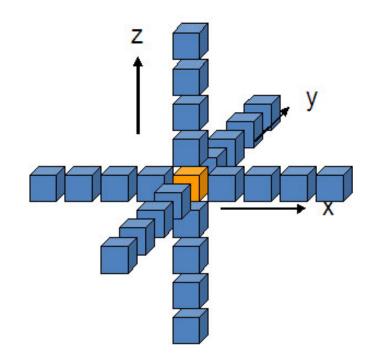


- Implementation using array padding and ghost cells
 - Fetch left and right neighbours separately
 - Synchronize twice in each step

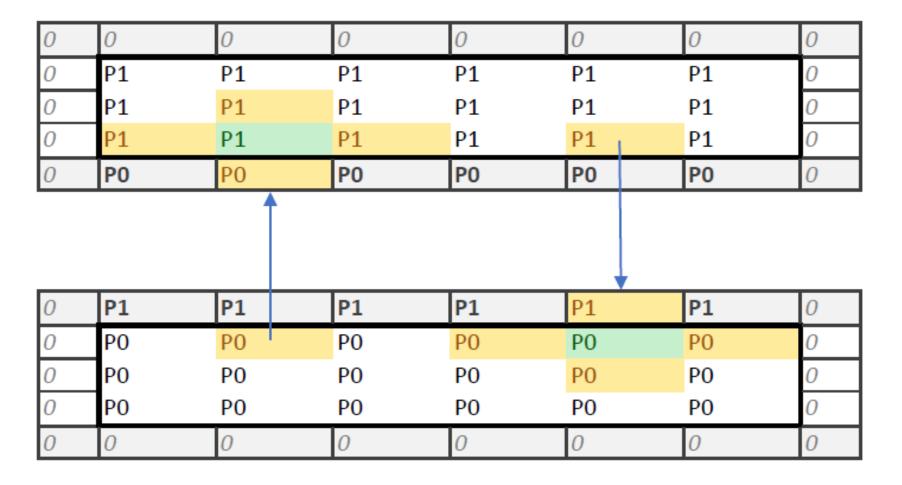
- Precondition: T must be TriviallySerializable. The source and destination memory regions must not overlap. src and dest must not be null pointers, even if count is zero.
- Initiates a transfer of count values of type T beginning at src and stores them in the locations beginning at dest. The source values must not be modified until operation completion is notified.

https://bitbucket.org/berkeleylab/upcxx/downloads/upcxx-spec-2020.10.0.pdf (8.2.2 Remote Gets)

- Implementation using array padding and ghost cells
 - Fetch left and right neighbours separately
 - Synchronize twice in each step
- Split blocks in z-direction



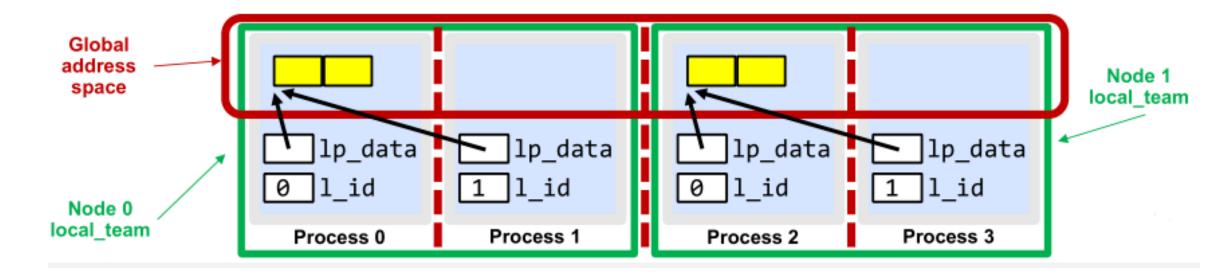
https://software.intel.com/content/www/us/en/develop/articles/3d-finite-differences-on-multi-core-processors.html



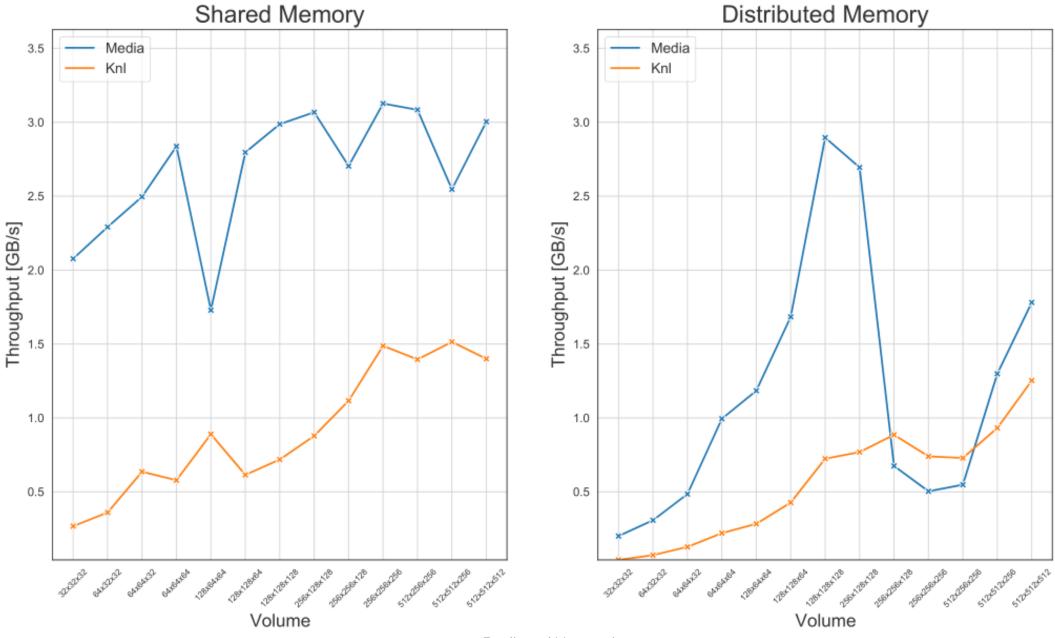
```
// As rget does not allow source values to be modified until operation completion
// is notified, first retrieve all right neighbors, then all left neighbors.
if (proc id != proc n - 1) {
    upcxx::global ptr<float> input r = input g.fetch(proc id + 1).wait();
    upcxx::rget(input_r + n_ghost_offset,
                input + n local - n ghost offset,
                n ghost offset).wait();
upcxx::barrier();
if (proc id != 0) {
    upcxx::global_ptr<float> input_l = input_g.fetch(proc_id - 1).wait();
    upcxx::rget(input_1 + n_local - 2*n_ghost_offset,
                input,
                n ghost offset).wait();
upcxx::barrier();
```

- Possible improvements
 - Latency hiding
 - Compute inner block asynchronously
 - Tiling (x- and y-dimension)
 - Threading models can be combined with UPC++ (OpenMP, std::thread)
 - upcxx::local_team (processes corresponding to a physical node, avoid communication)

- Possible improvements
 - upcxx::local_team



- Throughput:
 - Count only elements in input and output array:
 steps * sizeof(float) * dim_x * dim_y * dim_z * 1e-9 / time
- Benchmarks
 - 4 processes per SKL node, 16 processes per KNL node
 - <u>A</u> Lower dimensions need a smaller amount of processes.
 - Parameters: 5 steps, radius 2



Thank you for your attention!

Questions?