A Machine Learning Minimal Residual Method for Solving Quantities of Interest of Parametric PDEs

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Problem definition

We want:

- Solve parametric families of PDEs
- High precision in terms of a Quantity of Interest (QoI)
- Employing coarse meshes in Finite Elements

We consider the abstract variational formulation: Given $\lambda \in \Lambda \subset \mathbb{R}^p$, find $q(u) \in \mathbb{R}$ such that

$$\begin{cases} u \in \mathbb{U} \text{ solves:} \\ B_{\lambda}u = \ell_{\lambda} \in \mathbb{V}^{*}, \end{cases} \Leftrightarrow \begin{cases} u \in \mathbb{U} \text{ solves:} \\ b_{\lambda}(u, v) = \ell_{\lambda}(v), \quad \forall v \in \mathbb{V}. \end{cases}$$

We will use:

- Minimal-residual (MinRes) finite elements
- Artificial neural networks

Introduction to the method (weighted-MinRes)

Given discrete conforming trial $\mathbb{U}_n := \operatorname{span}\{\varphi_1, \ldots, \varphi_n\} \subset \mathbb{U}$, and test $\mathbb{V}_m \subset \mathbb{V}$ spaces such that dim $\mathbb{V}_m > \dim \mathbb{U}_n$, we want to find a discrete solution

$$u_n := \underset{w_n \in \mathbb{U}_n}{\operatorname{argmin}} \|\ell_{\lambda} - B_{\lambda} w_n\|_{(\mathbb{V}_m)^*}, \quad \text{(MinRes method)}$$

To solve the above problem is equivalent to solve the following saddle point problem:

Find
$$(r_m, u_n) \in \mathbb{V}_m \times \mathbb{U}_n$$
 such that:

$$(r_m, v_m)_{\mathbb{V}} + b_{\lambda}(u_n, v_m) = \ell_{\lambda}(v_m), \quad \forall v_m \in \mathbb{V}_m,$$

$$b_{\lambda}(w_n, r_m) = 0, \qquad \forall w_n \in \mathbb{U}_n.$$
(1)

What we do:

We modify the MinRes method by introducing a weighted inner product

 $(\cdot\,,\cdot\,)_{\mathbb{V}} \longrightarrow (\cdot\,,\cdot\,)_{\mathbb{V},\omega}$ in the V space [1]

Example: $H_0^1(\Omega)$

$$(r, v)_{\mathbb{V}, \omega} = \sum_{k=1}^{K} \omega_k \underbrace{\int_{\Omega_k} \nabla r(x) \cdot \nabla v(x) \, dx}_{G_k}$$

We seek for the coefficients $\omega := (\omega_1, \ldots, \omega_m)$, such that solving the system (1)

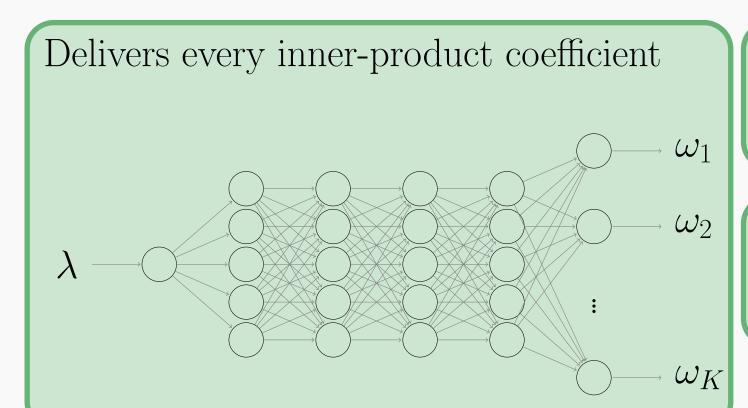
$$\left[\frac{G_{\omega}|B_{\lambda}}{B_{\lambda}^{\top}|0} \right] \left[\frac{\alpha}{\beta} \right] = \left[\frac{L_{\lambda}}{0} \right], \quad \text{with } G_{\omega} = \sum_{k=1}^{K} \omega_{k} G_{k}.$$

delivers $u_n(x) := \sum_{i=1}^n \beta_i(\omega) \varphi_i(x)$ as a good approximation for the QoI q(u).

Obs: See [2] for an extension to Galerkin and least-squares formulations.

Artificial neural networks

We train a neural network nn_{θ} to learn the inner-product piecewise constant.



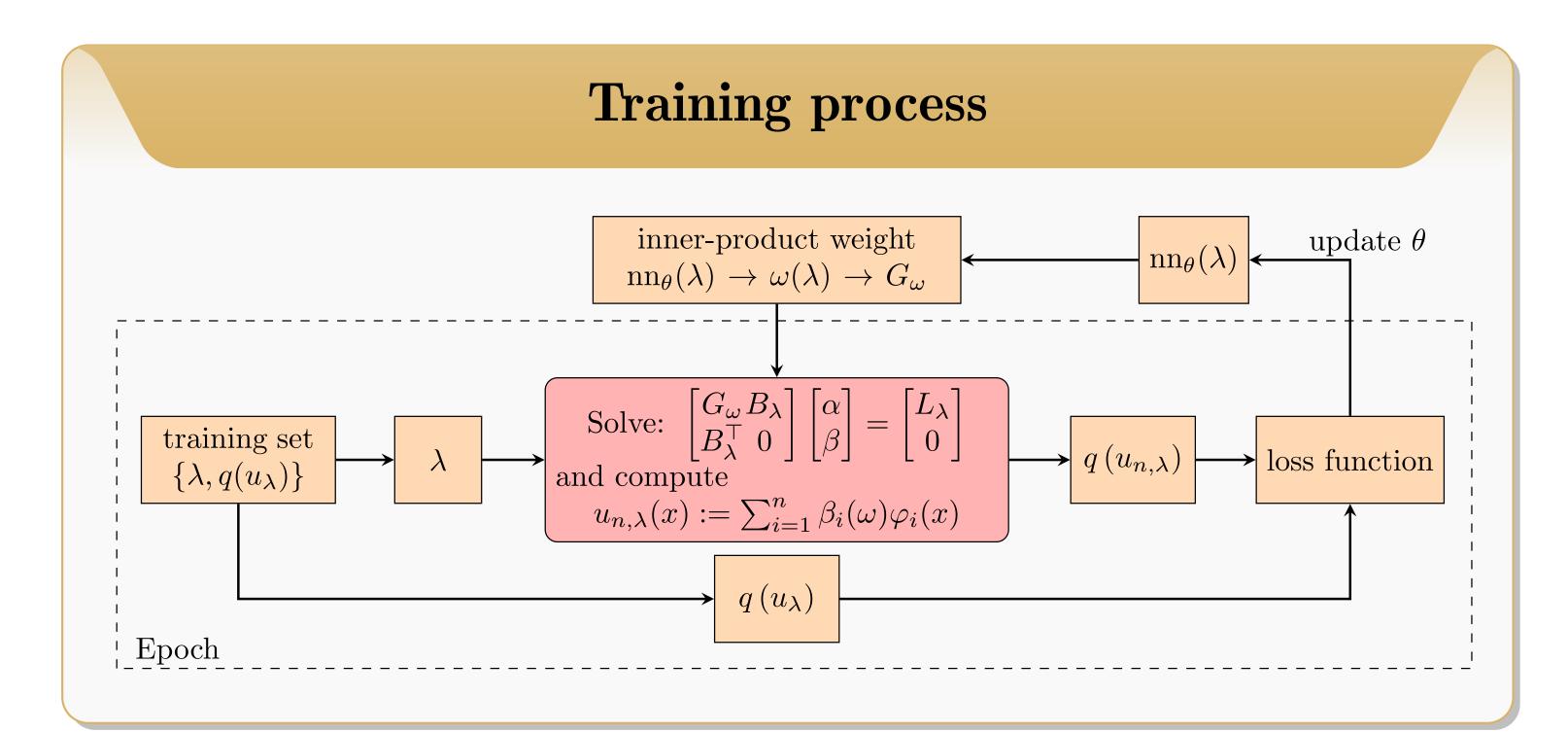
Training set

$$\{\lambda^{(1)},\lambda^{(2)},\dots\lambda^{(N_s)}\}$$

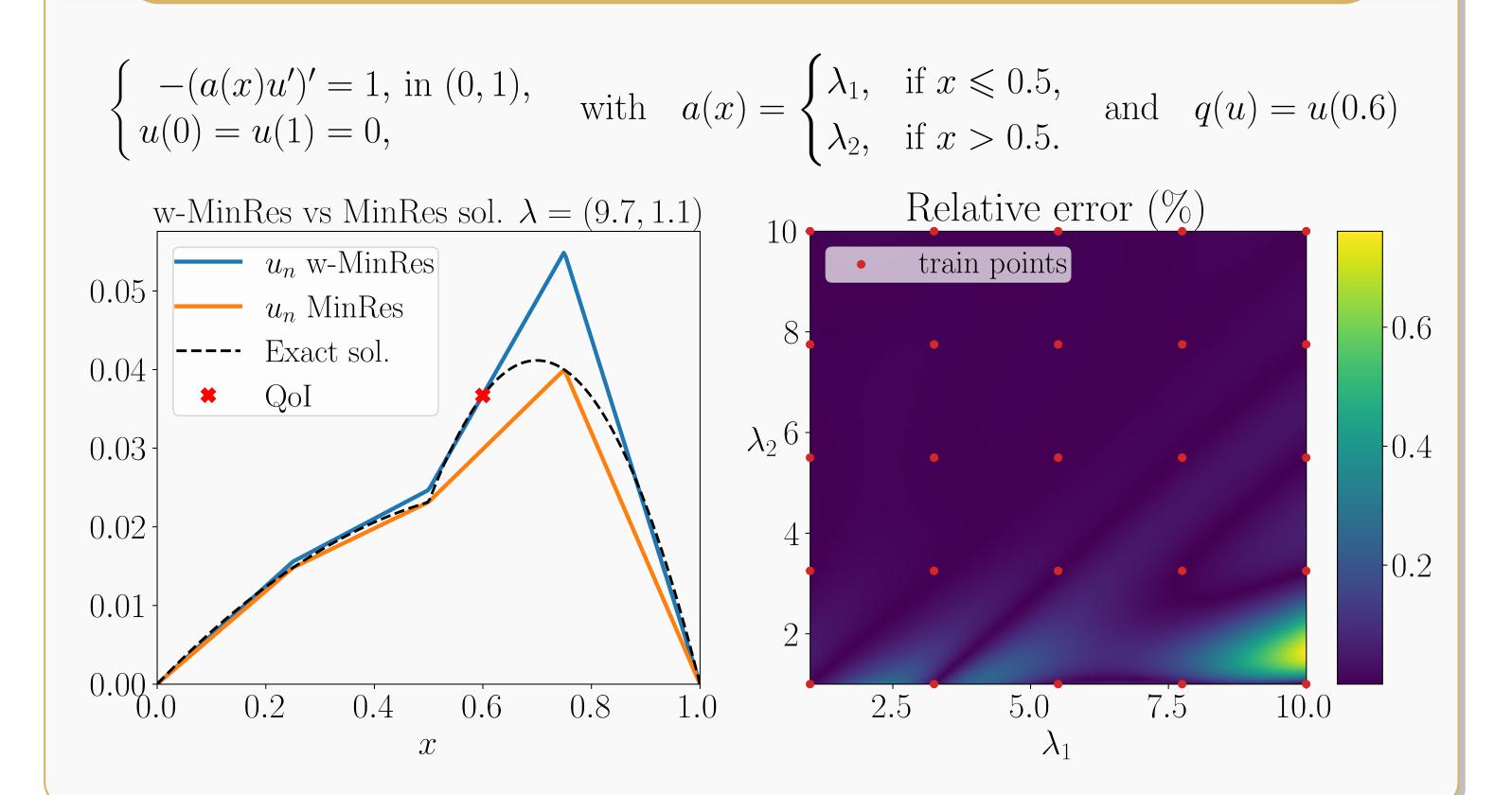
$$\{q(u_{\lambda^{(1)}}),q(u_{\lambda^{(2)}}),\ldots q(u_{\lambda^{(N_s)}})\}$$

Loss function

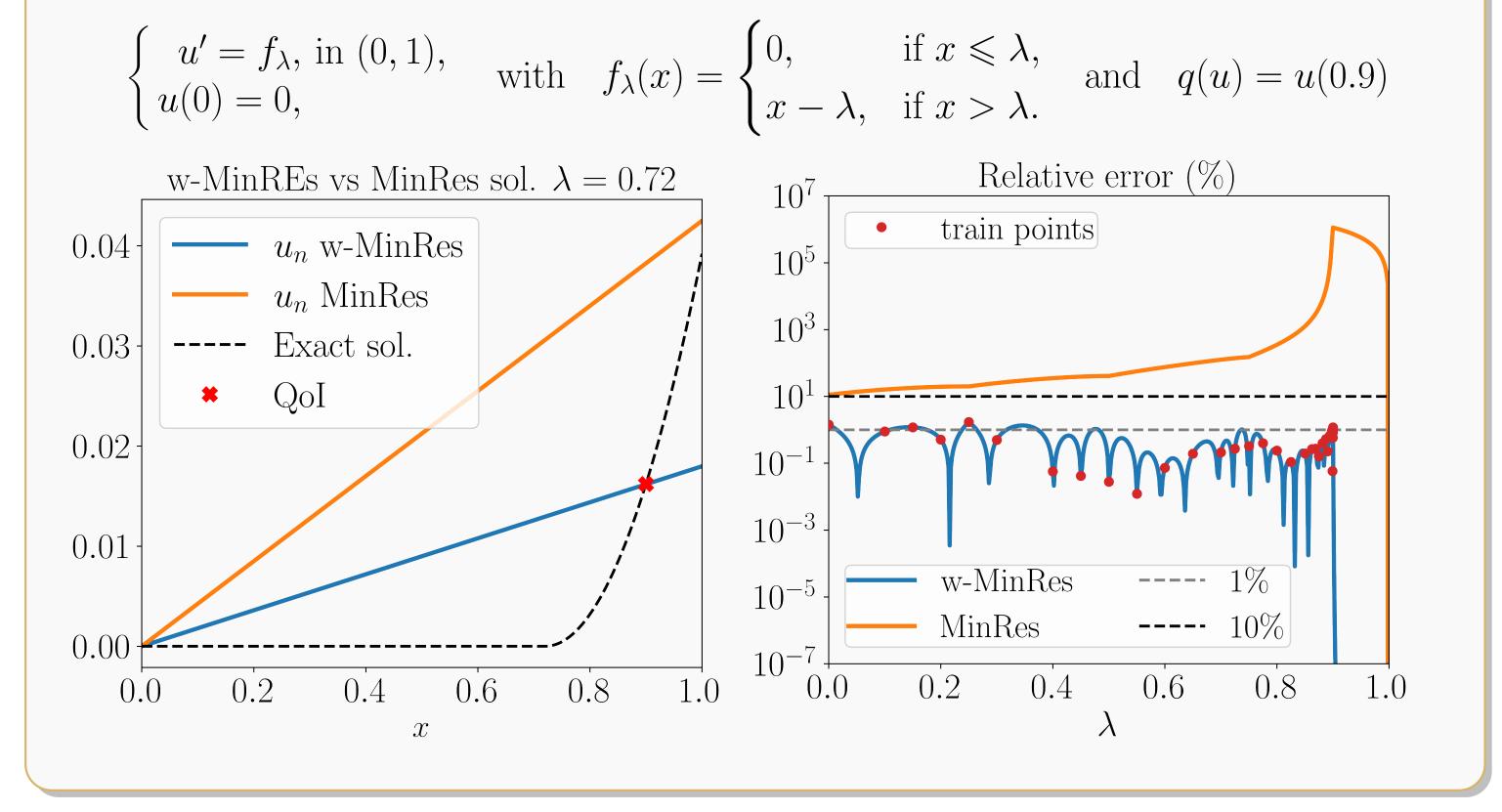
$$\mathcal{L}(\theta) := \frac{1}{N_s} \sum_{i=1}^{N_s} \frac{1}{2} \left| \frac{q(u_{\lambda^{(i)}}) - q(u_{n,\lambda^{(i)}}(\theta))}{q(u_{\lambda^{(i)}})} \right|^2$$



Ex: Diffusion with two parameters (dim $U_n = 4$)



Ex: Advection with parametric rhs (dim $U_n = 1$)



References

- [1] I. Brevis, I. Muga, and K. G. van der Zee, A machine-learning minimal-residual (ML-MRes) framework for goal-oriented finite element discretizations, Comput. Math. Appl., 95 (2021), pp. 186–199.
- [2] I. Brevis, I. Muga, and K. G. van der Zee, Neural control of discrete weak formulations: Galerkin, least-squares and minimal-residual methods with quasi-optimal weights, Comput. Methods Appl. Mech. Engrg., 402 (2022), p. 115716.