

Towards derandomising Markov chain Monte Carlo

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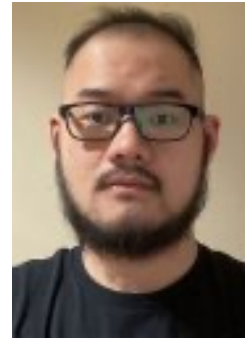
Joint work with



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Hypergraph independent set

Hypergraph $H = (V, \mathcal{E})$

- k -uniform: each hyperedge contains k vertices
- Δ -max degree: each vertex belongs to $\leq \Delta$ hyperedges

Independent set $S \subseteq V$ in hypergraph H

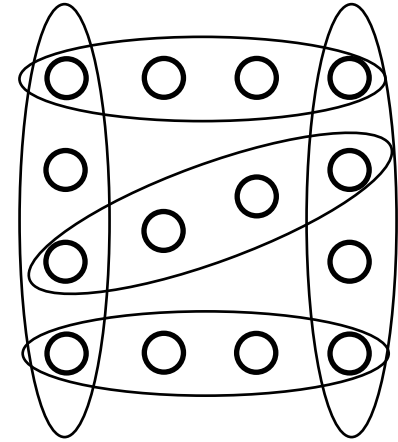
- For any $e \in \mathcal{E}$, $e \not\subseteq S$



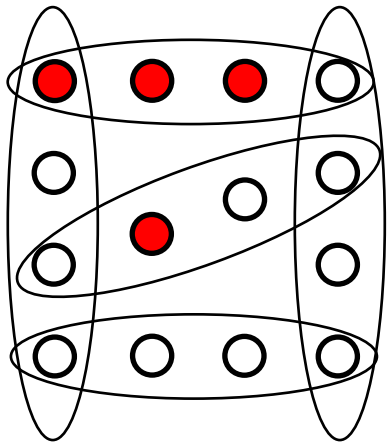
equivalent definition $v \in S$ iff $\sigma(v) = 1$

Independent set $\sigma \in \{0,1\}^V$ in hypergraph H

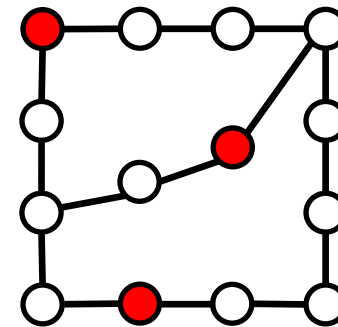
- For any $e \in \mathcal{E}$, there exists $v \in e$ such that $\sigma(v) = 0$



4-uniform with max degree 2



Example: an independent set in 4-uniform hypergraph



Example: an independent set in graph ($k = 2$)

Counting independent sets

Input: a hypergraph $H = (V, \mathcal{E})$

- k uniform and max degree Δ ($k, \Delta = O(1)$)
- number of vertices n

Output: the total number of independent sets in H

Hardness of exact counting

Counting independent sets is **#P complete**

- Hardness result holds even if $k = 2$ and $\Delta = 3$ [Greenhill 2000]

Approximate counting

Approximate counting problem

Input: a hypergraph $H = (V, \mathcal{E})$

- k uniform and max degree Δ ($k, \Delta = O(1)$)
- number of vertices n

an error bound $0 < \epsilon < 1$

Output: a number \hat{Z} such that

$$(1 - \epsilon)Z \leq \hat{Z} \leq (1 + \epsilon)Z$$

Z : the total number of independent sets in H

Approximate counting algorithms

FPTAS (fully polynomial time approximation scheme)

Deterministic algorithm that solves the problem in time $\text{poly}\left(n, \frac{1}{\epsilon}\right)$

FPRAS (fully polynomial time randomised approximation scheme)

Randomised algorithm that **solves** the problem in time $\text{poly}\left(n, \frac{1}{\epsilon}\right)$

output a random number \hat{Z} such that

$$\Pr[(1 - \epsilon)Z \leq \hat{Z} \leq (1 + \epsilon)Z] \geq \frac{2}{3}$$

Graph case ($k = 2$): computational phase transitions

Algorithm

FPTAS in time $\left(\frac{n}{\epsilon}\right)^{O(\log \Delta)}$ [Weitz05]

FPRAS in time $\tilde{O}\left(\frac{n^2}{\epsilon^2}\right)$ [CLV21, ŠVV07]

$$\Delta \leq 5$$

Complexity

The approximate counting is

NP-Hard

$$\Delta \geq 6$$

General hypergraphs ($k > 2$)

Work	Regime	Time
[BGGGŠ 16]	$k \geq \Delta \geq 200$	$\left(\frac{n}{\epsilon}\right)^{O(\log(k\Delta))}$
[Moitra 19]	$k \gtrsim 60 \log \Delta$	
[JPV 21]	$k \gtrsim 7 \log \Delta$	
[HWY 22]	$k \gtrsim 5 \log \Delta$	

FPTAS (deterministic algorithm)

Work	Regime	Time
[BDKo6]	$k \geq \Delta + 2$	$\tilde{O}\left(\frac{n^2}{\epsilon^2}\right)$
[BDKo8]		
[HSZ19]	$k \gtrsim 2 \log \Delta$	
[QWZ22]		

FPRAS (randomised algorithm)

Hardness: the approximate counting is **NP-Hard** if $k \leq 2 \log \Delta - C$ [BGGGŠ 16]

Our result [F., Guo, Wang, Wang, Yin, 22]: there is a **FPTAS** if $k \gtrsim 2 \log \Delta$

Theorem [this work] Let $k \geq 2$ and $\Delta \geq 2$ be two constants s.t.

$$k \geq 2 \log \Delta + 4 \log k + O(1).$$

There is a deterministic algorithm such that

- **Input:** a k -uniform hypergraph with n vertices and max degree Δ , an error bound ϵ
- **Output:** an $(1 \pm \epsilon)$ -approximation to the *number of independent sets*
- **Running time:** $(n/\epsilon)^{O(\Delta^2 k^4)}$

Hardness: NP-Hard if $k \leq 2 \log \Delta - C$ [BGGGŠ 16]

Linear hypergraph: two hyperedges share **at most 1 vertex**

Better condition: Let $\delta > 0$ be a constant. Constants $k \geq \frac{25(1+\delta)^2}{\delta^2}$ and $\Delta \geq 2$ satisfy

$$k \geq (1 + \delta) \log \Delta + 3(1 + \delta) \log k + O(1)$$

Running time: $(n/\epsilon)^{\text{poly}(\Delta k/\delta)}$

Hardness for linear hypergraph: NP-Hard if $k \leq \log \Delta - C$ [QW 22]

Work	Regime
[JPV 21]	$k \gtrsim 7 \log \Delta$
[HWY 22]	$k \gtrsim 5 \log \Delta$

FPTAS (deterministic algorithm)

Work	Regime
[HSZ 21]	$k \gtrsim 2 \log \Delta$
[QWZ 22]	

FPRAS (randomised algorithm)

Q: Why there is a **gap** between the regimes for FPTAS and FPRAS ?

A: Previous FPTASes and FPRASes are based on very **different** techniques.

Techniques for FPTAS:

- Dynamic programming on computation tree [BGGGŠ 16]
- Linear programming [Moitra 19] [JPV 21]
- Derandomisation of a marginal recursive sampler [HWY 22, AJ 21]

Techniques for FPRAS:

- **MCMC sampling algorithm** & **reduction from counting to sampling** [HSZ 22, QWZ 22]

The sampling problem

- **Input:** a hypergraph $H = (V, \mathcal{E})$

$$\Omega = \{X \in \{0,1\}^V \mid X \text{ is an independent set in } H\}$$

μ : the uniform distribution over Ω

$$\forall X \in \Omega, \quad \mu(X) = \frac{1}{Z} = \frac{1}{|\Omega|}$$

- **Output:** a random sample $X \sim \mu$.

The approximate sampling problem

- **Input:** a hypergraph $H = (V, \mathcal{E})$ specifying the uniform distribution μ

an error bound $\epsilon > 0$

- **Output:** a random sample $X \in \{0,1\}^V$ such that

$$\text{total variation distance } d_{TV}(X, \mu) \leq \epsilon$$

Counting-to-sampling reduction

Fix the independent set \emptyset , denote it by $\mathbf{0}$

$$\mu(\mathbf{0}) = \frac{1}{Z} \quad \text{approximate } Z \quad \longleftrightarrow \quad \text{approximate } \mu(\mathbf{0})$$

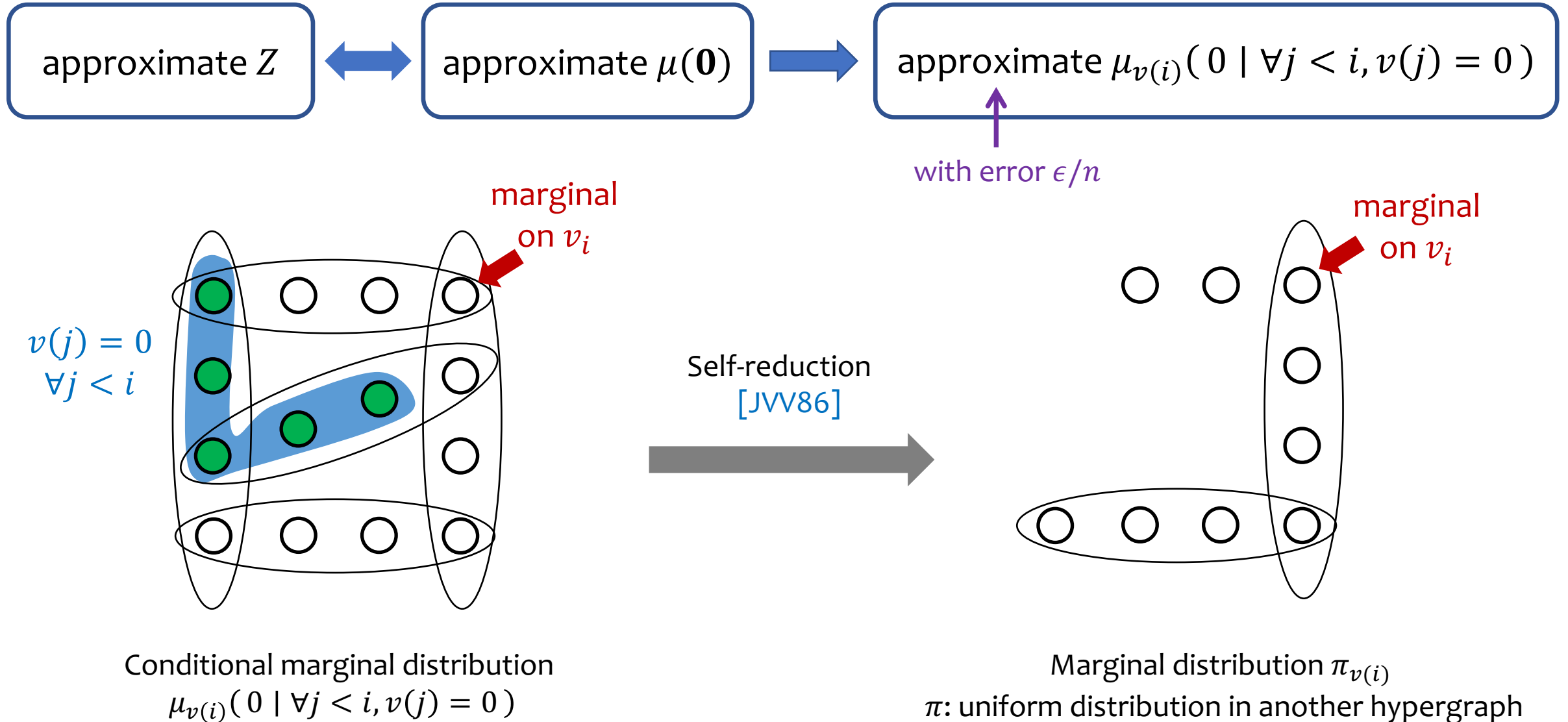
Fix an arbitrary ordering of vertices $V = \{v(1), v(2), \dots, v(n)\}$. By **chain rule**

$$\begin{aligned} \mu(\mathbf{0}) &= \mu_{v(1)}(0) \times \mu_{v(2)}(0 \mid v(1) = 0) \times \dots \times \mu_{v(n)}(0 \mid \forall j < n, v(j) = 0) \\ &= \prod_{i=1}^n \mu_{v(i)}(0 \mid \forall j < i, v(j) = 0) \end{aligned}$$

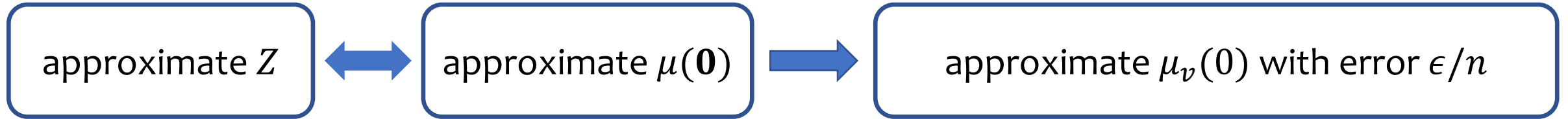
Conditional Marginal distribution $\mu_{v(i)}(\mathbf{0} \mid \forall j < i, v(j) = 0)$

given $X \sim \mu$, conditional on $X_{v(j)} = 0$ for all $j < i$, the prob of $X_{v(i)} = 0$

Counting-to-sampling reduction



Counting-to-sampling reduction



Solve approximate counting problem via sampling algorithm

The sampling algorithm $\mathcal{S}(H, \epsilon)$

- Input: a hypergraph H and error bound ϵ
- Output: a random sample X satisfying $d_{TV}(X, \mu) \leq \epsilon$

The algorithm for estimating $\mu_v(0)$

- Run $\mathcal{S}\left(H, \frac{\epsilon}{2n}\right)$ independently $N = \text{poly}\left(\frac{n}{\epsilon}\right)$ times to get $X^{(1)}, X^{(2)}, \dots, X^{(N)}$
- Compute the value $\hat{m} = \frac{\text{number of } i \text{ with } X_v^{(i)} = 0}{N}$

MCMC for hypergraph independent sets

Systematic scan for hypergraph independent sets

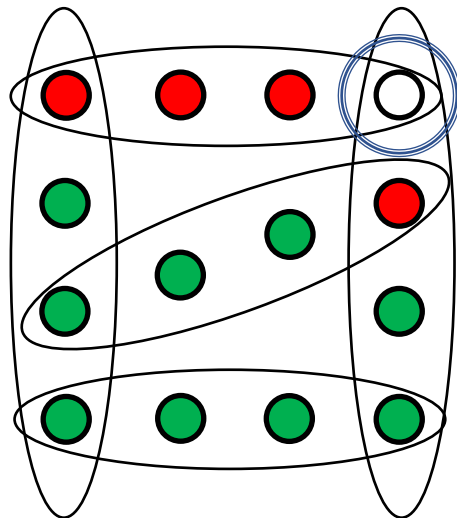
Input: a hypergraph $H = (V, E)$, each $v \in V$ has a unique label in $\{0, 1, 2, \dots, n - 1\}$

Start from an arbitrary independent set $X \in \{0, 1\}^V$

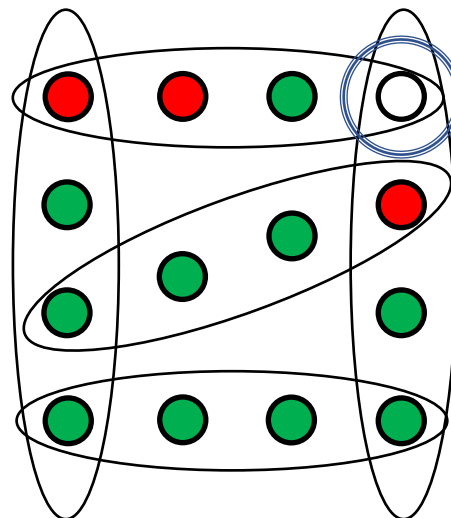
For each t from 1 to T

- Pick the vertex $v \in V$ with $\text{label}(v) = t \bmod n$
- Update $X(v) \sim \mu_v(\cdot \mid X(V \setminus \{v\}))$

Output X



update
 $X_v \leftarrow 0$



update
 $X_v \leftarrow r$
 $r \in \{0, 1\}$ is a uniform random bit

MCMC for hypergraph independent sets

Systematic scan for hypergraph independent sets

Input: a hypergraph $H = (V, E)$, each $v \in V$ has a unique label in $\{0, 1, 2, \dots, n - 1\}$

Start from an arbitrary independent set $X \in \{0, 1\}^V$

For each t from 1 to T

- Pick the vertex $v \in V$ with label $t \bmod n$
- Update $X(v) \sim \mu_v(\cdot \mid X(V \setminus \{v\}))$

Output X

Mixing time of systematic scan [HSZ16, JPV21, HSW21]

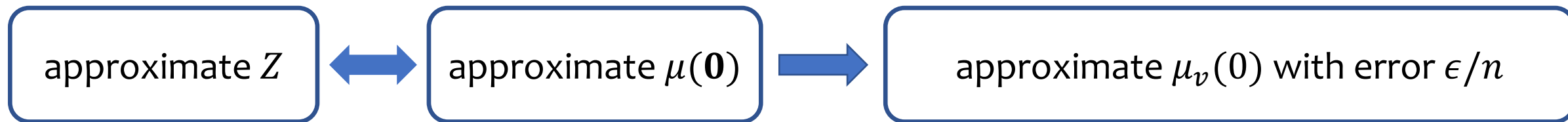
Systematic scan $(X_t)_{t=0}^T$: $X_t \in \{0, 1\}^V$ random independent set after the t -th update

$$k \gtrsim 2 \log \Delta$$



$$d_{TV}(X_T, \mu) \leq \text{poly}\left(\frac{\epsilon}{n}\right), \text{ where } T = O\left(n \log \frac{n}{\epsilon}\right)$$

Approximate counting via MCMC algorithm



↑ solve the problem

Run $O\left(n \log \frac{n}{\epsilon}\right)$ -step **systematic scan** to generate $N = \text{poly}\left(\frac{n}{\epsilon}\right)$ independent samples

$X^{(1)}, X^{(2)}, \dots, X^{(N)} \in \{0,1\}^V$ Full configuration $X \in \{0,1\}^V$

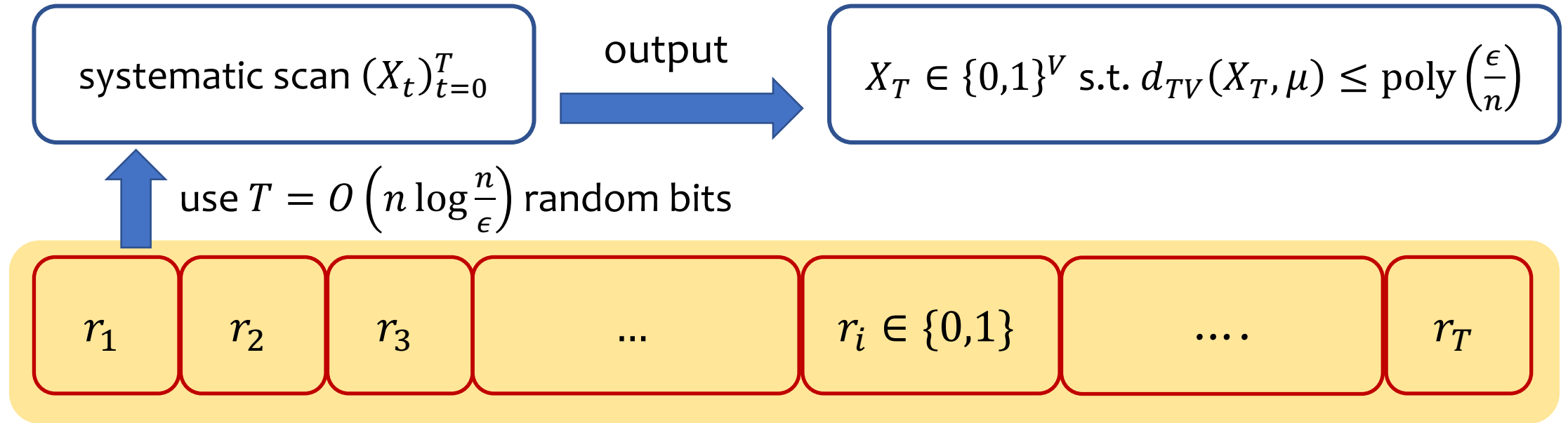
Compute the fraction

$$\hat{m} = \frac{\text{number of } i \text{ with } X_v^{(i)} = 0}{N}$$

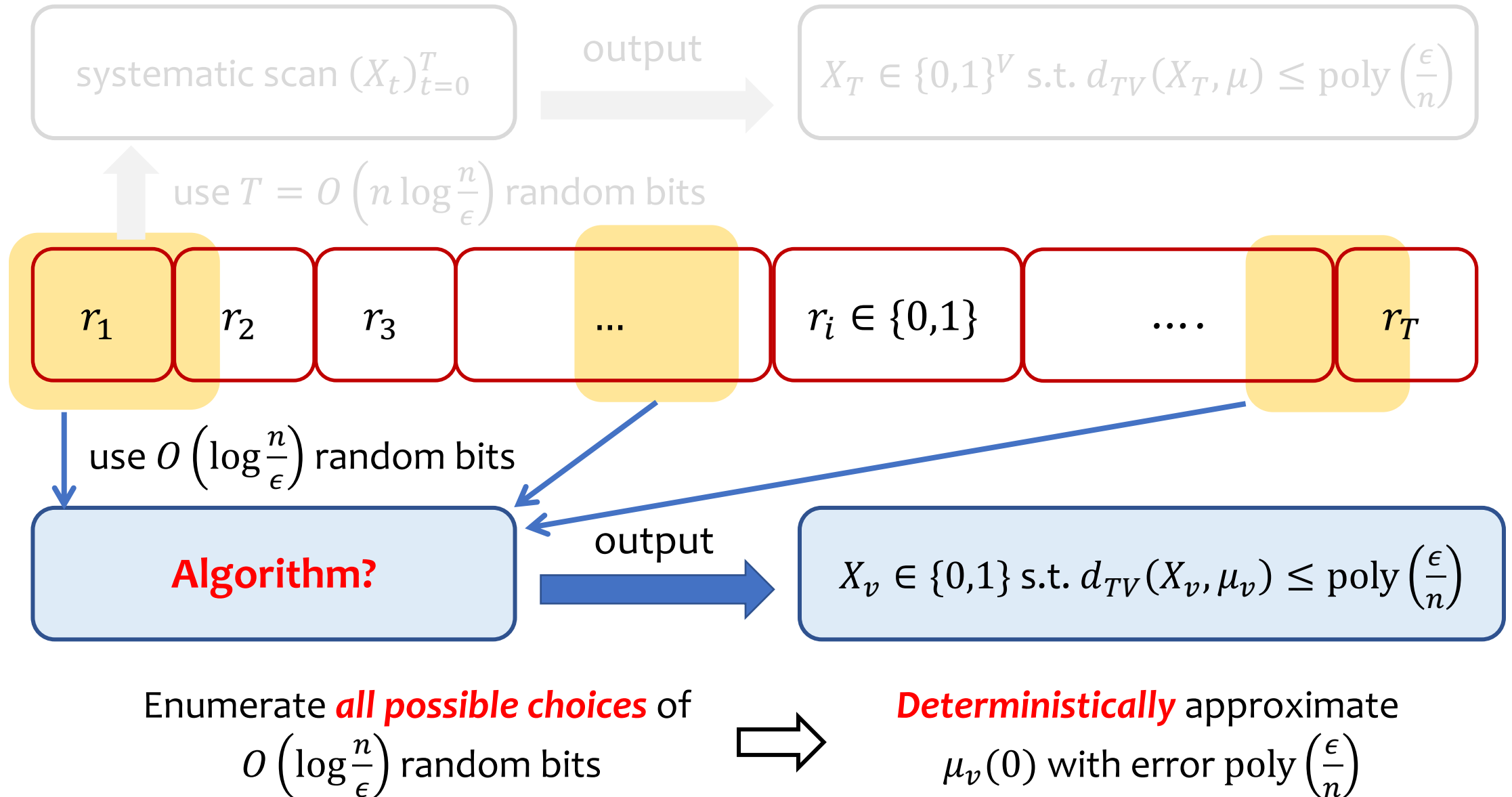
Only use one bit $X_v \in \{0,1\}$

Previous results [HSZ16, JPV21, HSW21]: there is a **FPRAS** if $k \gtrsim 2 \log \Delta$

Our idea: Derandomising MCMC



Our idea: Derandomising MCMC



Our results: log-time sampling via MCMC

Theorem [\[this work\]](#) Let constants $k \geq 2$, $\Delta \geq 2$ satisfying $k \gtrsim 2 \log \Delta$

There is a sampling algorithm such that

Input: a k -uniform hypergraph max degree Δ , a vertex v , an error bound ϵ

Output: a random sample $X_v \in \{0,1\}$ with

$$d_{TV}(X_v, \mu_v) \leq \epsilon$$

Running time & number of random bits used by alg.: $\text{poly}(\Delta k) \log \frac{n}{\epsilon}$

Straightforward derandomisation

- The algorithm uses $\text{poly}(\Delta k) \log \frac{n}{\epsilon}$ random bits
- Enumerate all $\left(\frac{n}{\epsilon}\right)^{\text{poly}(\Delta k)}$ possible assignments for random bits
- Deterministically compute $\Pr[X_v = 0] \in (1 \pm 2\epsilon)\mu_v(0)$ (as $\mu_v(0) \geq 1/2$)

Our results: log-time sampling via MCMC

Theorem [\[this work\]](#) Let constants $k \geq 2, \Delta \geq 2$ satisfying $k \gtrsim 2 \log \Delta$

There is a sampling algorithm such that

Input: a k -uniform hypergraph max degree Δ , a vertex v , an error bound ϵ

Output: a random sample $X_v \in \{0,1\}$ with

$$d_{TV}(X_v, \mu_v) \leq \epsilon$$

Running time & number of random bits used by alg.: $\text{poly}(\Delta k) \log \frac{n}{\epsilon}$

Result on linear hypergraphs [\[this work\]](#)

- Let constants $k \geq 2, \Delta \geq 2, \delta > 0$ satisfying $k \gtrsim (1 + \delta) \log \Delta$ and $k \geq k_0(\delta)$
- Running time & number of random bits used by alg.

$$\text{poly}\left(\frac{\Delta k}{\delta}\right) \log \frac{n}{\epsilon}$$

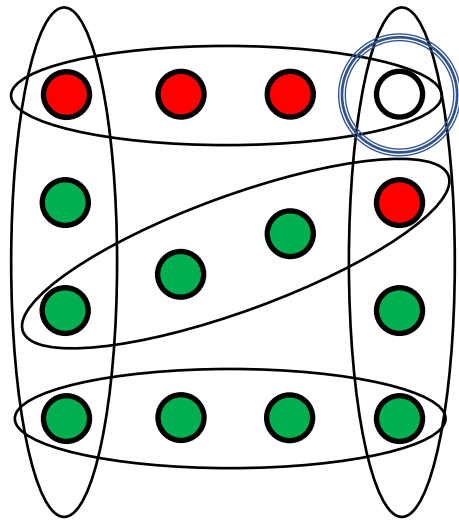
Systematic scan for hypergraph independent sets

Start from an arbitrary independent set $X \in \{0,1\}^V$

For each t from 1 to T

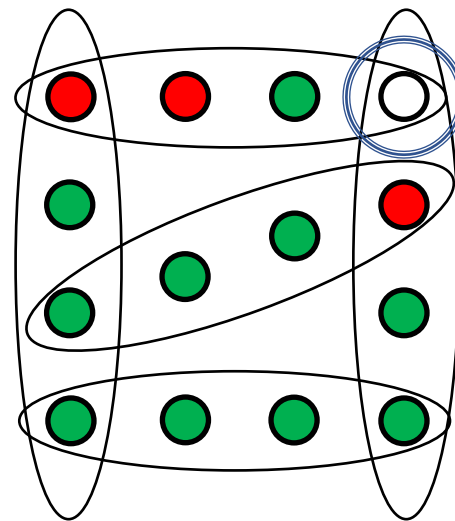
- Pick the vertex $v \in V$ with label $t \bmod n$
- Update $X(v) \sim \mu_v(\cdot \mid X(V \setminus \{v\}))$

Output X



Blocked: X_v is updated to 0

$$\exists e \ni v \text{ s.t. } \forall u \in e \setminus \{v\}, X_u = 1$$



Unblocked: X_v is updated to 0 w.p. 1/2

$$\forall e \ni v, \exists u \in e \setminus \{v\} \text{ s.t. } X_u = 0$$

Systematic scan for hypergraph independent sets

Start from an arbitrary independent set $X \in \{0,1\}^V$

For each t from 1 to T

- Pick the vertex $v \in V$ with label $t \bmod n$
- Update $X(v) \sim \mu_v(\cdot \mid X(V \setminus \{v\}))$

Output X

The t -th transition step of systematic scan

Sample a random bit $r_t \in \{0,1\}$ uniformly at random;

If X is in the **blocked** case ($\forall e$ with $v \in e, \exists u \in e \setminus \{v\}$ s.t. $X_u = 0$)

$X_v \leftarrow 0$;

If X is in the **unblocked** case ($\exists e$ with $v \in e, \forall u \in e \setminus \{v\}$ s.t. $X_u = 1$)

$X_v \leftarrow r_t$

$$r_t = 0$$

in both cases



$$X_v \leftarrow 0$$

Systematic scan for hypergraph independent sets

Start from an arbitrary independent set $X \in \{0,1\}^V$

For each t from 1 to T

- Pick the vertex $v \in V$ with label $t \bmod n$
- Update $X(v) \sim \mu_v(\cdot \mid X(V \setminus \{v\}))$

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Sample a random bit $r_t \in \{0,1\}$ uniformly at random;

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$X_v \leftarrow 0$;

If X is in the **unblocked** case ($\exists e$ with $v \in e, \forall u \in e \setminus \{v\}$ s.t. $X_u = 1$)

$X_v \leftarrow r_t$

If $r_t = 0$ (with probability $1/2$)

decide X_v **immediately** (**no need** to distinguish blocked or unblocked cases)

systematic scan $(X_t)_{t=0}^T$

our goal



output $X_T(v) \in \{0,1\}$

- For any vertex $v \in V$, any time $0 \leq t \leq T$,

$$S(v, t) = \{1 \leq j \leq t \mid \text{vertex } v \text{ is picked in } j^{\text{th}} \text{ step, i. e. } \text{label}(v) = j \bmod n\}$$

- Previous** update time for $v \in V$ **up to time** t :

$$\text{Pred}(v, t) = \begin{cases} \max\{j \mid j \in S(v, t)\} & \text{if } S(v, t) \neq \emptyset \\ 0 & \text{if } S(v, t) = \emptyset \end{cases}$$

Our goal: output the value of $X_T(v) = X_{\text{Pred}(v, T)}(v) \in \{0,1\}$

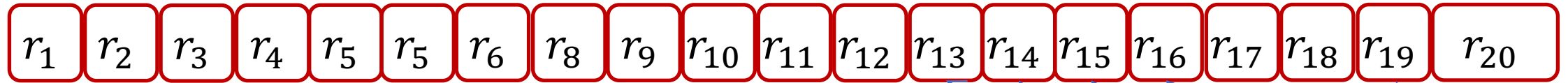
compute the value of v after the last time that v is updated

Resolve(v, t)

- **Input:** $v \in V$ and $1 \leq t \leq T$ such that v is picked at the time t
- **Output:** the random value $X_t(v) \in \{0,1\}$

Random bits for simulating Markov chain up to time T

$t = 19$

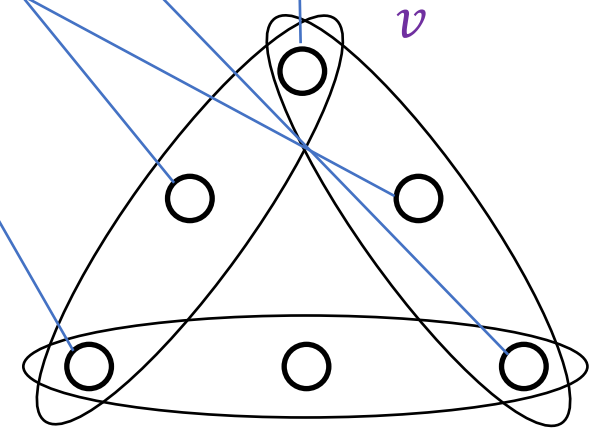


reveal the random bit r_t ;

if $r_t = 0$, **return** 0;

else //distinguish blocked or unblocked cases

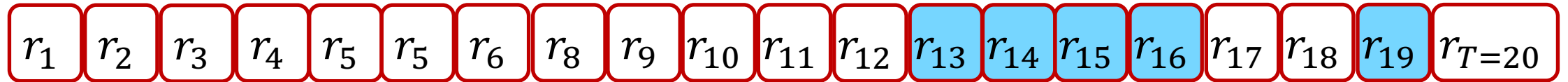
 reveal $r_{\text{pred}(w,t)}$ for **all neighbours** w ;



Resolve(v, t)

- **Input:** $v \in V$ and $1 \leq t \leq T$ such that v is picked at the time t
- **Output:** the random value $X_t(v) \in \{0,1\}$

Random bits for simulating Markov chain up to time T



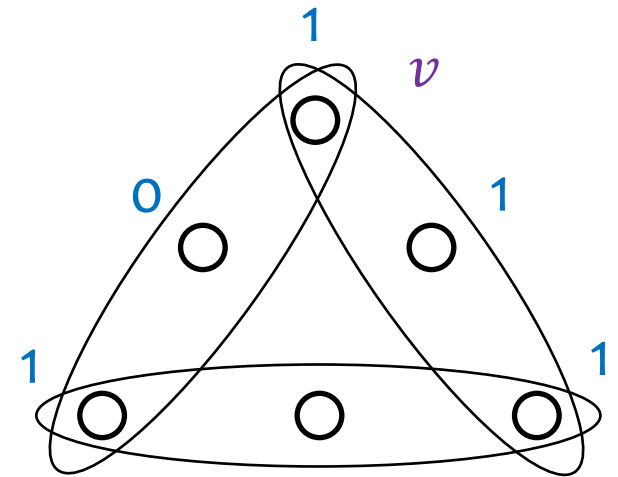
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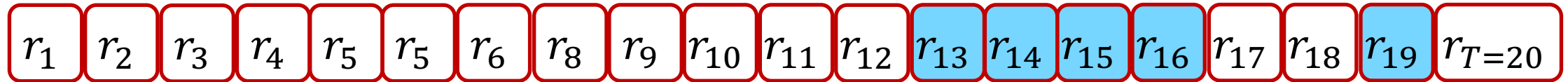
for each hyperedge e incident to v **do**



Resolve(v, t)

- **Input:** $v \in V$ and $1 \leq t \leq T$ such that v is picked at the time t
- **Output:** the random value $X_t(v) \in \{0,1\}$

Random bits for simulating Markov chain up to time T



reveal the random bit r_t ;

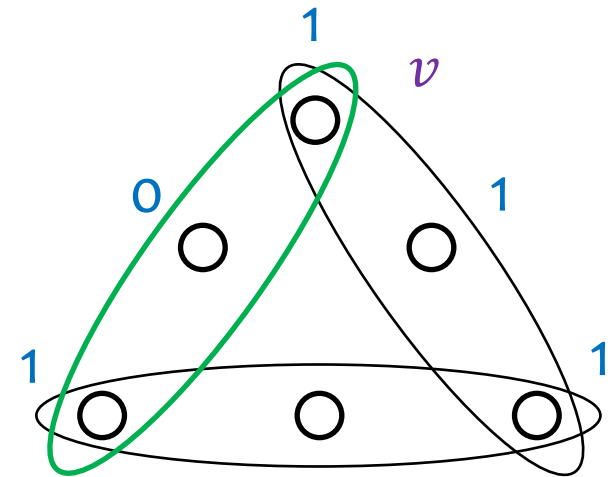
if $r_t = 0$, **return** 0;

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reveal $r_{\text{pred}(w,t)}$ for **all neighbours** w ;

for each hyperedge e incident to v **do**

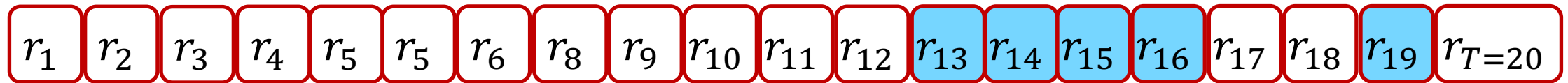
$\left\{ \begin{array}{l} \exists w \in e \setminus \{v\} \text{ s.t. } r_{\text{pred}(w,t)} = 0 \Rightarrow X_t(w) = 0 \end{array} \right.$ **good edge**



Resolve(v, t)

- **Input:** $v \in V$ and $1 \leq t \leq T$ such that v is picked at the time t
- **Output:** the random value $X_t(v) \in \{0,1\}$

Random bits for simulating Markov chain up to time T



reveal the random bit r_t ;

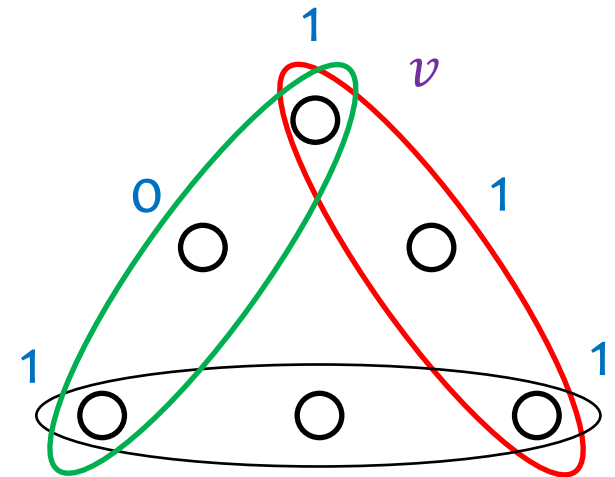
if $r_t = 0$, return 0;

else //distinguish blocked or unblocked cases

reveal $r_{\text{pred}(w,t)}$ for **all neighbours** w ;

for each hyperedge e incident to v do

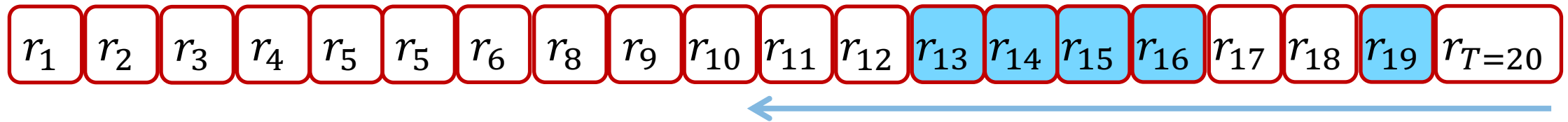
$\left\{ \begin{array}{l} \exists w \in e \setminus \{v\} \text{ s.t. } r_{\text{pred}(w,t)} = 0 \Rightarrow X_t(w) = 0 \text{ good edge} \\ \forall w \in e \setminus \{v\}, r_{\text{pred}(w,t)} = 1 \text{ bad edge (cannot decide } X_t(w)) \end{array} \right.$



Resolve(v, t)

- **Input:** $v \in V$ and $1 \leq t \leq T$ such that v is picked at the time t
- **Output:** the random value $X_t(v) \in \{0,1\}$

Random bits for simulating Markov chain up to time T



reveal the random bit r_t ;

if $r_t = 0$, return 0;

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reveal $r_{\text{pred}(w,t)}$ for **all neighbours** w ;

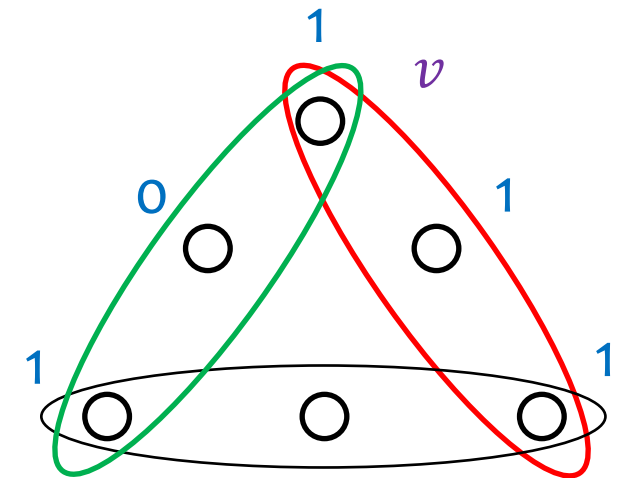
for each hyperedge e incident to v do

• if $\forall w \in e \setminus \{v\}, r_{\text{pred}(w,t)} = 1$ //bad edge

• **If all $w \in e \setminus \{v\}, \text{Resolve}(w, \text{pred}(w, t)) = 1$**

return 0; //blocked case

return 1; //unlocked case



reveal the random bit r_t ;

if $r_t = 0$, return 0;

else //distinguish blocked or unblocked cases

reveal $r_{\text{pred}(w,t)}$ for **all neighbours** w ;

for each hyperedge e incident to v do

- if $\forall w \in e \setminus \{v\}, r_{\text{pred}(w,t)} = 1$ //bad edge
 - If all $w \in e \setminus \{v\}, \text{Resolve}(w, \text{pred}(w, t)) = 1$
return 0; //blocked case

return 1; //unlocked case

Run Resolve recursively **only if**

$$\mathcal{B}: \forall w \in e \setminus \{v\}, r_{\text{pred}(w,t)} = 1$$

$$\Pr[\mathcal{B}] = \left(\frac{1}{2}\right)^{k-1}$$

An informal analysis of the branching process

- Vertex v has $\leq \Delta$ incident hyperedges and each hyperedge has k vertices



$$\mathbb{E}[\text{\#recursive calls}] \leq \Delta k \left(\frac{1}{2}\right)^{k-1} < 1 \Rightarrow k \gtrsim \log \Delta$$

- However, hyperedges share vertices \Rightarrow **dependency** of recursive calls

$$k \gtrsim 2 \log \Delta$$



$$\text{w.h.p. } \{\text{resolve instances}\} = O_{\Delta,k}(\log n)$$

pay extra factor to overcome the dependency

reveal the random bit r_t ;

if $r_t = 0$, return 0;

else //distinguish blocked or unblocked cases

 reveal $r_{\text{pred}(w,t)}$ for **all neighbours** w ;

 for each hyperedge e incident to v do

- if $\forall w \in e \setminus \{v\}, r_{\text{pred}(w,t)} = 1$ //bad edge
 - If all $w \in e \setminus \{v\}, \text{Resolve}(w, \text{pred}(w, t)) = 1$
 return 0; //blocked case

return 1; //unlocked case

Run Resolve recursively **only if**

$$\mathcal{B}: \forall w \in e \setminus \{v\}, r_{\text{pred}(w,t)} = 1$$

$$\Pr[\mathcal{B}] = \left(\frac{1}{2}\right)^{k-1}$$

Better bound for linear hypergraphs (informal analysis)

- Linear hypergraph: two hyperedges share at most 1 vertex

⇒ **dependency** of recursive calls is **much weaker** than the general case

$$k \gtrsim (1 + \delta) \log \Delta$$



$$\text{w.h.p. } \#\{\text{resolve instances}\} = O_{\delta, \Delta, k}(\log n)$$

pay extra δ -factor to overcome the dependency, where $\delta > 0$ is an **arbitrary** constant

Hypergraph colouring

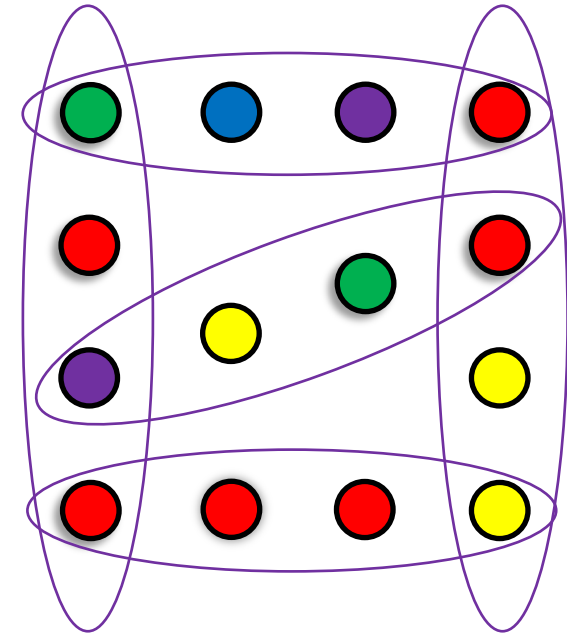
Instance

- a k -uniform hypergraph with max degree Δ
- colour set $[q] = \{1, 2, \dots, q\}$

Hypergraph colouring: $X \in [q]^V$ s.t.

- no hyperedge is monochromatic

$$(\forall e \in \mathcal{E}, |\{X_v \mid v \in e\}| \geq 2)$$



Lovász Local lemma and algorithmic LLL

- find a hypergraph colouring when $q \gtrsim \Delta^{1/k}$ ($q \geq C_k \Delta^{1/(k-1)}$)

Sampling Lovász Local lemma

- sampling / approx. counting hypergraph colourings in the local lemma regime

Previous results for approximate counting

Work	Regime	Algorithm Type
[Frieze, Anastos, 17]	Linear & $q \gtrsim \max\{\log n, \Delta^{1/k}\}$	Randomised
[Guo, Liao, Lu, Zhang, 19]	$q \gtrsim \Delta^{16/k}$	Deterministic
[Jain, Pham, Vuong, 21]	$q \gtrsim \Delta^{7/k}$	

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[Jain, Pham, Vuong, 21]	$q \gtrsim \Delta^{7/k}$	
[Feng, He, Yin, 21]	$q \gtrsim \Delta^{9/k}$	Randomised
[Jain, Pham, Vuong, 21]	$q \gtrsim \Delta^{3/k}$	
[Feng, Guo, Wang, 22]	Linear & $q \gtrsim \Delta^{(2+\delta)/k}$	

Lower Bound [Galanis, Guo, Wang, 21]

MCMC on projected distribution

- NP-Hard for $q \lesssim \Delta^{2/k}$ (general hypergraph) and $q \lesssim \Delta^{1/k}$ (linear hypergraph)

Our results for approximate counting

Work	Regime	Algorithm Type
[Frieze, Anastos, 17]	Linear & $q \gtrsim \max\{\log n, \Delta^{1/k}\}$	Randomised
[Guo, Liao, Lu, Zhang, 19]	$q \gtrsim \Delta^{16/k}$	Deterministic
[Jain, Pham, Vuong, 21]	$q \gtrsim \Delta^{7/k}$	
[F., Guo, Wang, Wang, Yin, 22]	$q \gtrsim \Delta^{3/k}$ Linear & $q \gtrsim \Delta^{(2+\delta)/k}$	<u>Deterministic</u>

Lower Bound [Galanis, Guo, Wang, 21]

- NP-Hard for $q \lesssim \Delta^{2/k}$ (general hypergraph) and $q \lesssim \Delta^{1/k}$ (linear hypergraph)

Counting-to-sampling reduction

Instance: hypergraph $H = (V, \mathcal{E})$ and colour set $[q]$

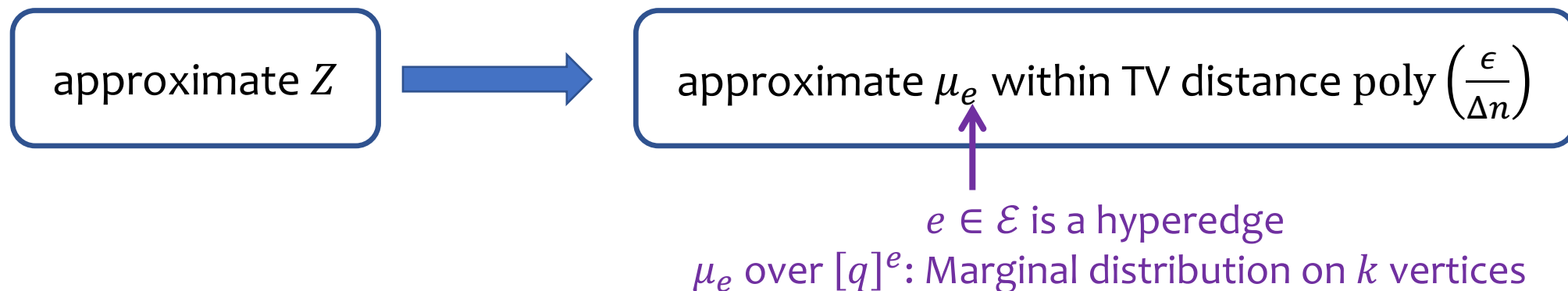
Colouring: $\Omega \subseteq [q]^V$ set of all proper colourings

$$Z = |\Omega|$$

Distribution: μ the uniform distribution over all proper colourings

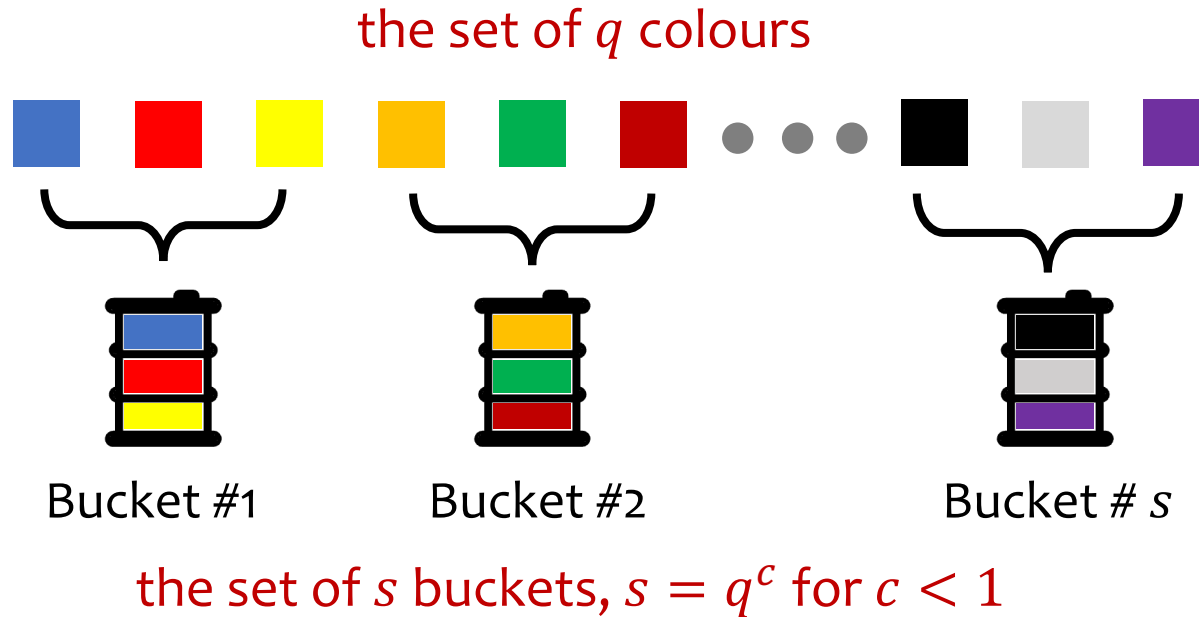
$$\forall X \in \Omega, \quad \mu(X) = \frac{1}{Z}$$

Approximate counting to sampling reduction



MCMC on projected distribution

- The systematic scan on μ **does not work** (connectivity issue)
- Use systematic scan on projected distribution



Balanced projection scheme

$$h: [q] \rightarrow [s]$$

for any $j \in [s]$,

$$|h^{-1}(j)| \in \frac{q}{s} \pm 1$$

Projected distribution π over $[s]^V$ [Feng, He, Yin, 21]

$$Y = \{h(X_v)\}_{v \in V} \sim \pi \text{ if } X \sim \mu$$

Systematic scan for projected distribution

Start from a uniform random $Y \in [s]^V$;

For each t from 1 to T

- Pick the vertex $v \in V$ with label $t \bmod n$
- Update $Y(v) \sim \pi_v(\cdot \mid Y(V \setminus \{v\}))$ conditional marginal distribution induced by π

Output Y

Local uniformity in the local lemma regime

For any $v \in V$, any condition $\sigma \in [q]^{V \setminus \{v\}}$

$$\forall j \in [s], \quad \mu_v(j \mid \sigma) \in \left(1 \pm \frac{1}{s}\right) \frac{|h^{-1}(j)|}{q} \approx \left(1 \pm \frac{1}{s}\right) \frac{1}{s}$$

given any condition, the marginal on v is close to a uniform distribution



Mixing in the local lemma regime: If $T = O\left(n \log \frac{n}{\epsilon}\right)$ then $d_{TV}(\pi, X_T) \leq \frac{\epsilon}{n^2}$

Log-time sampling (informal)

Resolve(v, t)

- **Input:** $v \in V$ and $1 \leq t \leq T$ such that v is picked at the time t
- **Output:** the random value $Y_t(v) \in [s]$

Local uniformity \Rightarrow Marginal lower bound

For any $v \in V$, any condition $\sigma \in [q]^{V \setminus \{v\}}$

$$\forall j \in [s], \quad \mu_v(j \mid \sigma) \gtrsim \left(1 - \frac{1}{s}\right) \frac{1}{s}$$

By **marginal lower bound**, even if $Y_t(V \setminus \{v\})$ is **unknown**, we can decide $Y_t(v)$ w.p.

$$p_{LB} \approx \sum_{j \in [s]} \left(1 - \frac{1}{s}\right) \frac{1}{s} = 1 - \frac{1}{s} \approx 1 - \Delta^{-\Omega(1/k)}$$

Resolve(v, t) (informal description)

- Reveal the randomness used in t -th step
- **With probability** $p_{LB} = 1 - 1/s$
 - Determine the value of $X_t(v)$ and **return**.
- **With probability** $1 - p_{LB}$ get enough information to determine $\mu_v(\cdot | Y_t(V \setminus \{v\}))$
 - Reveal other randomness & call resolve recursively if necessary

How to sample from μ_e using a partial sample from projected distribution π ?

sample Y_M for some $M \subseteq V$



sample X_e conditional on Y_M

How to sample Y_M ?

Resolve(v, t) returns $X_t(v) \in [s]$

Generalise



Resolve(M, t) returns $X_t(M) \in [s]^M$

Summary

Fully Poly-time **deterministic** approximate counting algorithms:

- ✓ Hypergraph independent sets
 - general case $k \gtrsim 2 \log \Delta$
 - linear case $k \gtrsim (1 + \delta) \log \Delta$
 - almost match the **hardness conditions**
- ✓ Hypergraph colourings
 - general case $q \gtrsim \Delta^{3/k}$
 - linear case $q \gtrsim \Delta^{(2+\delta)/k}$
 - match the conditions of **current best randomised algorithms**

Technique



Open problems

Close the **gap** for **hypergraph colouring**

- general case $q \gtrsim \Delta^{3/k}$ v.s. $q \lesssim \Delta^{2/k}$
- linear case $q \gtrsim \Delta^{(2+\delta)/k}$ v.s. $q \lesssim \Delta^{1/k}$

Thank You
Q&A

Faster algorithm for **deterministic** approximate counting

- FPRAS running time $\tilde{O}(n^2/\epsilon^2)$
- FPTAS running time $n^{\text{poly}(k\Delta)}$
- Question: $f(k\Delta)n^c$ running time (can we use pseudorandom generator?)

Sublinear time sampling (related to local access to huge random objects [BRY ITCS2020])

- **Input:** distribution μ over $[q]^V$ and $v \in V$
- **Output:** a sample or an approximate sample from μ_v
- For which μ , it can be solved in sublinear time (say $n^{1-\epsilon}$ time or even $O(\log n)$ time)