



# Software stack

## Development

- Python
- conda and virtual environments
- preferably docker with ubuntu

## Neural nets

- preferably PyTorch
- Tensorflow

## Libraries for 3D data

- Kaolin <https://kaolin.readthedocs.io/en/latest/>
- PyTorch3D <https://pytorch3d.org/>
- PyTorch Geometric <https://pytorch-geometric.readthedocs.io/>
- PyMesh <https://pymesh.readthedocs.io/>

## Visualisation

- In python <https://plotly.com/>
- MeshLab <https://www.meshlab.net/>
- Blender <https://www.blender.org/>



# First technical steps

## Set-up

- Configure environment, install libraries and dependencies (preferably HPC and locally)

## Read and standardize models

- Class for reading mesh data
- Method for standardization (model scaling)
- Method for sanity checks (i.e. broken faces, vertices, normal, waterproof the 3D model)
- Orientation of the model (longest axis along “Z”)

## 3D model manipulation

- Method for voxelization with adjustable resolution
- Method for making cylinder-like holes with certain diameter and location and orientation of the long axis
- Method for making cylinder-like holes with random diameter and location and orientation of the long axis

## Example models

- Vertical hole
- Sandford bunny

