

# Chuangqi Wang, PhD

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## Research Background

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Computational modeling for cell imaging, system biology and immunology in infectious disease

Deep learning and machine learning for time course analysis for biomedical data

## Education

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### Ph.D. in Biomedical Engineering

2015 – Oct. 2019

Worcester Polytechnic Institute (WPI), MA, USA

Designated Emphasis: Deep learning, Machine learning, Live cell imaging, Cell Migration

### M.S. in Electronics Engineering and Computer Science

2009 – 2012

Peking University (PKU), Beijing, China

Designated Emphasis: machine learning, robotics, motion planning.

### B.S. in Computer Science

2005 – 2009

Jilin University (with Honors), Changchun, China

## Professional Experience

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### Postdoctoral Associate, MIT

Oct. 2019 – Present

Dr. Douglas Lauffenburger. System Biology/Computational Immunology

### Graduate Research Assistant, WPI

2016 – 2019

Dr. Kwonmoo Lee. (Lab of Quantitative Cellular Imaging, now in Boston Children's Hospital, HMS)

### Research Associate, WPI

2014 – 2015

Dr. Patrick Flaherty (Genomics Lab, now in Statistics Dep. in UMass Amherst)

### Research Associate, Chinese Academy of Sciences

2012 – 2013

Dr. Xinyu Wu. Center for Biomimetic Systems

### Research Associate, Peking University

2009 – 2012

Dr. Hong Liu. Open Lab on human robot interaction

### Undergraduate Research Assistant, Jilin University

Summer 2007 – 2008

Dr. Hongwei Zhao. Embedded wireless video surveillance system

## Publications in Chronological Order

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### System Biology in Infectious disease & Translational Medicine:

1. Y. C Bartsch\*, C. Wang\*, S. Fischinger, C. Atyeo, T. Zohar, J. Burke, A. G Edlow, A. Fasano, A. Schmidt, E. S Fischer, E. J Nilles, L. R Baden, E. Wood Karlson, D. A Lauffenburger, Lael M Yonker# and G. Alter#, Humoral signatures of protective and pathological SARS-CoV2 infection in children, *Nature Medicine*, In press, 2021.
2. Chaillon\*, C. Wang\*, T. Schlub, W. Yu, D. A. Lauffenburger, D. M. Smith, B. Juegl, Tissue Landscap of HIV antibody neutralization susceptibility, *Conference on Retroviruses and Opportunistic Infections (CROI)*, 2021.
3. T. Zohar\*, C. Loos\*, S. Fischinger\*, C. Atyeo\*, C. Wang, M. D. Slein, J. Burke, J. Yu, J. Feldman, B. M. Hauser, T. Caradonna, A. G. Schmidt, Y. Cai, H. Streech, E. T. Ryan, D. H. Barouch, R. C. Charles, D. A. Lauffenburger# & G. Alter#. Compromised humoral functional evolution tracks with SARS-CoV-2 mortality. *Cell*, 183(6), 1508-1519, 2020.

## Cell Imaging & Machine Learning:

4. **C. Wang**, H., Choi, K. Lee. Fine-grained deconvolution of subcellular protrusion heterogeneity by deep feature learning, In Preparation, 2021.
5. K. Vaidyanathan\*, **C. Wang\***, Y. Yu, A. Krajnik, M. Choi, B. Lin, J. Kolega, K. Lee#, Y. Bae#, Machine learning approach reveals heterogeneous responses to FAK and Rho GTPases inhibition on smooth muscle spheroid formation,(In review) *bioRxiv* 927616, 2020.
6. H. Choi, **C. Wang**, X. Pan, M. Cao, J. Brazzo, Y. Bae, K. Lee, Emerging machine learning approaches to phenotyping temporally heterogeneous cellular processes, In review, 2020.
7. F. Zhang, **C. Wang**, A. C. Trapp, P. Flaherty, A global optimization algorithm for sparse mixed membership matrix factorization New Advances in Statistics and Data Science, *Contemporary Biostatistics with Biopharmaceutical Applications*, pp 129-156, Springer, 2019.
8. **C. Wang\***, H. J. Choi\*, S. Kim, A. Desai, N. Lee, D. Kim, Y. Bae, K. Lee, Deconvolution of subcellular protrusion heterogeneity and the underlying actin regulator dynamics from live cell imaging, *Nature Communications*, 9, 1688, 2018.
9. S. Kim\*, **C. Wang\***, B. Zhao, H. Im, J. Min, N. Choi, C. M. Castro, R. Weissleder, H. Lee#, K. Lee#. Deep transfer learning-based hologram classification for molecular diagnostics. *Scientific Reports*, 8:17003, 2018.
10. **C. Wang**, X. Zhang, Y. Chen, K. Lee. vU-net: Accurate cell edge segmentation in time-lapse fluorescence live cell images based on convolutional neural network, *bioRxiv* 191858, 2017
11. **C. Wang**, S. Kang, E. Kim, X. Zhang, H. J. Choi, A. Choi, K. Lee, Edge detection of cryptic lamellipodia assisted by deep learning, *bioRxiv* 181263, 2017

## Robotics and Path Planning:

12. H. Liu, **C. Wang**. Collision probability based safe path planning for mobile robots in changing environments. *Applied Mechanics and Materials*. vol. 197. pp. 401-408, (2012).
13. **C. Wang**, B. Chen and H. Liu. Path updating tree based fast path planner for unpredictable changing environments. IEEE International Conference on Robotics and Biomimetics (*ROBIO* 2012). pp. 1529-1535. Guangzhou, China. Dec 11-14, (2012).
14. H. Liu, T. Zhang, **C. Wang**. A 'capacitor' bridge builder based safe path planner for difficult regions identification in changing environments. IEEE/RSJ International Conference on Intelligent Robots and Systems (*IROS*). pp. 3179-3186. Algarve, Portugal. Oct 7-12, 2012.
15. H. Liu, J. Wang and **C. Wang**. Sub-goal choosing and updating strategy based on hierarchy sampling strategy. Journal of Huazhong University of Science and Technology (Natural Science Edition). vol. 39. pp. 208-211, 2011(in Chinese).
16. **C. Wang**, H. Liu, Motion planning method for robots in dynamic environments based on improved particle swarm optimization, the 13th China National Conference on Artificial Intelligence (CAAI 2009). pp. 393-399. Beijing, China. Oct 25-28, 2009 (in Chinese).

\*Equal Contribution, #Co-corresponding authors.

## Selected Talks

Workshop: “System Serology/Machine Learning”, C. Loos, A. Nilsson & C. Wang	2020
A machine learning approach to devonolute the subcellular protrusion heterogeneity	
<b>Oral talk:</b> Single Cell Biology Keystone Symposium, Colorado	January, 2019
<b>Poster:</b> International Society for computational biology (ISCB), Chicago	July 2018
<b>Poster:</b> Graduate Research Innovation Exchange (GRIE), WPI	2017, 2018
<b>Poster:</b> ASCB/EMBO, Philadelphia	December, 2017
Path Updating Tree based fast path planner for unpredictable changing environments	
<b>Oral talk:</b> IEEE International Conference on Robotics and Biomimetics ( <i>ROBIO</i> )	December, 2012

## Awards, Honors and Notable Service

Reviewer in Scientific Reports	2019
Graduate Travel Award, WPI	2017, 2018
Reviewer in New England Statistics Symposium (NESS)	2018
Reviewer in International Conference on Robotics and Automation (ICRA), IEEE/ASME International	
Conference on Advanced Intelligent Mechatronics (AIM)	2013
Session Chair of Motion Planning I in ROBIO	2012
Judge in Shenzhen Youth Robot Competition	2010, 2011
Studying Excellence Award, Peking University	2010
National Endeavor scholarship / National Endeavor scholarship, China Ministry of Education	2006-2008
Outstanding Student Scholarship, Jilin University	2007, 2006

## Professional Skills

**Computation/Statistics:** representation learning (CNN, Autoencoder, LSTM), unsupervised learning (density peaks), supervised learning (MLP, SVM, RF), time series data analysis, convex and global optimization.

**Programming:** Proficient in R, Python, MATLAB and C++. Competent in ImageJ.

## Patents

An Intelligent Education Robot (CN201320117097.5) J. Sun, <b>C. Wang</b> , P. Jiang, etc.	August, 2013
Chinese Academy of Sciences/Shenzhen Institute of Advanced Integration Technology	
A Robot Path Planning Framework inspired by Bionics in Dynamic Environments (CN201310233773.X)	
Peking University. H. Liu, <b>C. Wang</b> , etc.	September, 2013

## Teaching Experience

### **Mentee, WPI**

Melody Yu (Undergraduate Student, Biological Engineering, MIT)	Oct.2020 – Present
Xiang Pan and Yudong Yu (MS student, Biomedical Engineering, WPI)	May. 2018 – May. 2019
Tessa Curtis (REU program, Biomedical Engineering, UNC)	Summer, 2019
Xitong Zhang (MS student, Data Science, WPI)	March, 2017 – May, 2018
Lucy Woodbury (REU program, Biomedical Engineering, University of Arkansas)	Summer, 2018
Yenyu Chen (Undergraduate student, Biomedical Engineering, WPI)	Summer, 2017

### **Teaching Assistant, WPI**

Biomedical Data Analysis, Biomedical Engineering Design, Introduction of Biomedical Engineering

### **Teaching Assistant, Peking University)**

Image Processing, Robot Technologies

2010 - 2012