

## Fixed Income Derivatives E2025 - Problem Set Week 4

### Problem 1

Let  $W_t$  be a Brownian motion, assume  $s < t < u < v$  and solve the problems below. In doing so, you will need to use that  $W_t$  is Markov and has stationary independent increments. That is, for  $0 < s < t$  we know that  $W_t - W_s | \mathcal{F}_s = W_t - W_s | W_s = w_s \sim N(0, t - s)$ .

- a) Find the conditional distribution of  $W_t$  given  $\mathcal{F}_s$ .
- c) Find  $\mathbb{E}[W_s W_t]$ ,  $\text{Cov}[W_s, W_t]$  and  $\text{Cor}[X_t, Z_t]$ .
- c) Show that  $W_t^2 - t$  is a Martingale.
- d) Find  $\mathbb{E}[W_s W_t W_u]$ .
- e) Find  $\mathbb{E}[W_s W_t W_u W_v]$ .

### Problem 2

Let  $X_t$  and  $Y_t$  be independent Brownian motions for  $t \geq 0$ . Define  $Z_t = \rho X_t + \sqrt{1 - \rho^2} Y_t$ .

- a) Show that  $Z_t$  is a Brownian motion
- b) Find  $\text{Cor}[X_t, Z_t]$ .
- c) Find  $\mathbb{E}[Z_t | X_t = x]$  and  $\text{Var}[Z_t | X_t = x]$ .

Let  $W_t^{(1)}, W_t^{(2)}, \dots, W_t^{(N)}$  be independent Brownian motions and let  $\Sigma$  be an  $M \times N$ -dimensional matrix where row  $i$ ,  $\Sigma_{i\cdot}$ , satisfies  $\|\Sigma_{i\cdot}\|^2 = \Sigma_{i1}^2 + \Sigma_{i2}^2 + \dots + \Sigma_{iN}^2 = 1$ . Define the  $M$ -dimensional vector  $\mathbf{Y}_t = \Sigma \mathbf{W}_t$

- d) Find the covariance matrix of the random vector  $\mathbf{Y}_t$ . Show that the covariance matrix is positive definite?
- e) What is the correlation matrix of  $\mathbf{Y}_t$ ?
- f) What is the distribution of  $Y_t^{(i)}$  and what is the joint distribution of  $\mathbf{Y}_t$ ?
- g) Is  $\mathbf{Y}_t$  a multivariate Brownian motion?

### Problem 3

Consider a stochastic process  $r_t$  for  $t \geq 0$  with dynamics

$$dr_t = (b - ar_t)dt + \sigma dW_t, \quad b > 0$$

- a) Show that the solution  $r(T)$  corresponding to these dynamics are

$$r_T = e^{-aT} r_0 + \frac{b}{a} (1 - e^{-aT}) + \sigma \int_0^T e^{-a(T-t)} dW_t$$

by performing the following steps

- i) Apply Ito's formula to  $f(t, r) = e^{at} r$ .
- ii) Simplify to get an expression for  $d(e^{at} r)$  that does not depend on  $r_t$ .
- iii) Integrate from 0 to  $T$  and solve the time-integral.
- b) Use Ito isometry to show that  $r_T | r_0 \sim N\left(e^{-aT} r_0 + \frac{b}{a} (1 - e^{-aT}), \frac{\sigma^2}{2a} [1 - e^{-2aT}]\right)$ .
- c) Find the limiting distribution of  $r_T$  as  $T \nearrow \infty$ .
- d) If you had to guess, what is your best guess of the  $r$  in the long run? How does the limiting distribution of  $r_T$  depend on  $r_0$  and what is the implication?

**Problem 4**

Suppose that the stochastic process  $S_t$  follows a Geometric Brownian motion and has dynamics

$$\begin{aligned} dS_t &= \mu S_t dt + \sigma S_t dW_t \\ S_0 &= s_0 \end{aligned}$$

- Show that the solution  $S(T)$  corresponding to these dynamics is  $S(T) = s_0 e^{(\mu - \frac{1}{2}\sigma^2)T + \sigma W_T}$ .
- Find  $\mathbb{E}[S(T)]$  in terms of  $s_0$ ,  $\mu$  and  $\sigma$ .
- Find the dynamics of  $Z_t = S_t^m$  and show that  $Z_t$  also follows a geometric Brownian motion.
- Use these results to find  $\mathbb{E}[S^m(T)]$ .

**Problem 5**

Let  $\sigma(t)$  be a given *deterministic* function of time and define the process  $X_t$  by

$$X(t) = \int_0^t \sigma(s) dW_s$$

Also define  $Z(t) = e^{i\omega X(t)}$  where  $i$  is the complex unit and thus a constant and  $\omega$  is also a constant.

- Find the dynamics of  $X_t$ .
- Find the dynamics of  $Z_t$  and show that  $Z_t$  has dynamics

$$\begin{aligned} dZ_t &= -\frac{1}{2}\omega^2\sigma^2(t)Z(t)dt + i\omega\sigma(t)Z_t dW_t \\ Z_0 &= 1 \end{aligned}$$

- Integrate  $dZ_t$  and take expectations to find an expression for  $\mathbb{E}[Z(t)]$ .
- Define  $m(t) = \mathbb{E}[Z(t)]$  and show that  $m(t)$  satisfies the ODE.

$$\begin{aligned} m'(t) &= -\frac{1}{2}\omega^2\sigma^2(t)m(t) \\ m(0) &= 1 \end{aligned}$$

- Argue that  $\mathbb{E}[e^{i\omega X(t)}] = \exp\left(-\frac{1}{2}\omega^2 \int_0^t \sigma^2(s)ds\right)$  and why we can say that  $X(t) \sim N\left(0, \int_0^t \sigma^2(s)ds\right)$ .